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Finite element model and simple method for predicting consolidation displacement of soft soils exhibiting creep underneath embankments in 2-D condition

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1 **Abstract:** How to predict the long-term deformation of natural soft soils under embankments has
2 been an important yet challenging issue in geotechnical and transportation engineering. The major
3 difficulties lie in consolidation analyses of thick soil layers, modelling of the nonlinear time-
4 dependent stress-strain behaviour of clayey soils, and proper determination of soil parameters.
5 While finite element (FE) software has great advantages and wide applications in consolidation
6 analyses, development of reliable simple methods, which can be conveniently used by engineers,
7 is also needed. In this paper, both a fully coupled FE model and a simplified Hypothesis B method
8 are developed and applied for long-term deformation analyses of two test embankments on the
9 multi-layered Malaysian marine clays. FE simulations are conducted using PLAXIS with a
10 nonlinear 3-D elastic visco-plastic (3-D EVP) model. A series of parametric studies are carried out
11 on the influences of soil parameters and modelling techniques using this FE model. A simplified
12 Hypothesis B method with the nonlinear 1-D EVP model and modifications for 2-D stress
13 diffusion and buoyancy effects is derived and applied for estimating the long-term consolidation
14 settlement curves of the two test embankments. It is found that the fully coupled FE model with
15 the nonlinear 3-D EVP can simulate the long-term embankment displacements with good
16 agreement with measured data. Parametric studies indicate that using averaged soil indices and
17 updating static pore pressure have significant contributions to the accuracy of simulations. The
18 settlements calculated by the improved simplified Hypothesis B method are found in close
19 agreement with FE simulation results and measured data.

20 **Keywords:** soft soils, embankments, consolidation settlement, elastic visco-plastic model,
21 buoyancy

22

23 1 Introduction

24 In recent decades, large numbers of infrastructure facilities such as airports, artificial
25 islands, highways, railways and ports are under planning, construction or service in coastal regions
26 of many countries. There exists a heavy demand for embankment constructions on soft marine
27 soils. Many engineering problems and difficulties related to soft soils have been recognized and
28 reported, such as excessive and continuous settlements, embankment failure, and low speed of
29 consolidation (Folkes and Crooks 1985; Loganathan et al. 1993; Fatahi et al. 2013). Reliable
30 evaluation and prediction of the long-term behaviour of soft soils under human activities and
31 external loadings are still challenging issues.

32 There are two major factors contributing to the time-dependent deformation of soft soils:
33 the consolidation due to gradual dissipation of excess pore water pressure and the creep behaviour
34 of soil skeleton. Analysis of 1-D consolidation is usually based on Terzaghi's 1-D consolidation
35 theory (Terzaghi 1943), and its extended analytical solutions for complicated consolidation
36 problems subjected to multi-layered system, vertical drains, and ramp loadings (Hansbo et al. 1981;
37 Zhu and Yin 2004; Walker et al. 2009; Yin and Zhu 2020). For 3-D consolidation analysis, Biot's
38 3-D consolidation equations (Biot 1956) are most frequently used. The creep behaviour is usually
39 defined as continuous and time-dependent compression of soils under constant effective stress,
40 which is a result of the viscous nature of clayey soils (Feng et al. 2017; Shi et al. 2018). The viscous
41 behaviours of soils include all time-dependent stress-strain behaviours, such as creep, strain rate
42 effect and relaxation. To simulate these effects, researchers have developed 3-D constitutive elastic
43 visco-plastic (EVP) models for clayey soils (Borja and Kavazanjian 1985; Yin and Graham 1999;
44 Vermeer and Neher 1999; Yin et al. 2010). In these constitutive models, the creep of soils is
45 modelled based on an empirical linear formula between the volumetric strain and logarithm of time

46 (i.e. $\Delta\varepsilon = \frac{C_{\alpha e}}{1+e_0} \log t$ or $\Delta\varepsilon = \frac{\psi}{1+e_0} \ln t$) (Ladd et al. 1977; Yin and Graham 1989). Although such
47 relations can achieve satisfactory simulations within a relatively shorter period (e.g. several
48 months or years), concerns have been raised about the infinite creep with time in the formula. A
49 nonlinear logarithmic function for creep was then proposed by Yin (1999), which contains a creep
50 limit at infinity of time. The function was later introduced into a 3-D EVP model (Yin et al. 2002)
51 based on the overstress theory (Perzyna 1963). In theory, this model has advantages in simulating
52 the long-term deformation of clayey soils. However, case studies on natural soil ground are still
53 less reported.

54 Considering the highly nonlinear partial differential equations in both the EVP models and
55 consolidation theory, researchers have relied on finite difference methods (FDM) and finite
56 element methods (FEM) to simulate the coupled effect of consolidation and rheology of soils.
57 Despite of the tremendous advantages of FDM and FEM, the convergence and accuracy of
58 calculations are influenced by the scheme of time steps and proper setting of the numerical models,
59 especially for 3-D or 2-D conditions. In some recent works, de-coupled simplified methods are
60 also being developed with 1-D creep model and conventional theoretical consolidation solutions
61 (Yin and Feng 2017; Feng and Yin 2017, 2018; Feng et al. 2020). However, these simplified
62 methods are still limited to 1-D consolidation condition and their applicability in some
63 embankment analyses is questioned. The nonlinear creep behaviour and the buoyancy effects have
64 not been considered in these studies as well. Besides, the accuracy of FEM, FDM and simplified
65 method relies on parameter selections, which is greatly influenced by the soil uncertainty and
66 experimental technology.

67 To address these issues, this paper will present the methodologies of both FE method and
68 simple method using a nonlinear EVP model with consideration of creep limit for the Malaysian

69 test embankments, which will be examined by measured data. Parametric studies are carried out
70 to reveal the optimization scheme of soils parameter and controlling parameters in the fully
71 coupled FE analysis. A new simplified method based on Hypothesis B with modifications for 2-D
72 stress diffusion and buoyancy effects is proposed and examined by comparison with FE simulation
73 results and measured data. The results show clear evidence for both the accuracy and practicality
74 of the EVP model in predicting the long-term consolidation deformation of soft soil ground under
75 embankments with complicated field conditions.

76

77 **2 Theoretical frameworks of the 1-D and 3-D nonlinear EVP model**

78 ***2.1 1-D nonlinear creep model for clayey soils***

79 It is widely acknowledged that the stress-strain behaviour of clayey soils is time-dependent
80 (Graham et al. 1983; Leroueil et al. 1985; Yin and Graham 1989). One popular way to model the
81 time dependency of soil behaviour is based on the simulation of creep behaviour with
82 mathematical equations. Creep refers to the time-dependent deformation of soil under constant
83 effective stress. In odometer tests, if a normally consolidated clay is subjected to a constant vertical
84 effective stress and sustained for a period, the creep deformation can be described using Yin
85 (1999)'s nonlinear equation:

$$86 \quad \varepsilon_{creep} = \frac{\frac{\psi_0}{V} \ln\left(\frac{t+t_0}{t_0}\right)}{1 + \frac{\psi_0}{V \Delta \varepsilon_l} \ln\left(\frac{t+t_0}{t_0}\right)} \quad (1)$$

87 where ψ_0 is the creep coefficient, $V = 1 + e_0$ is the initial specific volume, t is time, $\Delta \varepsilon_l$ is the
88 creep limit and t_0 is a reference time (*e.g.* one day in standard oedometer tests). According to this

89 function, there is an upper limit of creep deformation, as shown in Eq. (2):

90
$$\lim_{t \rightarrow \infty} \varepsilon_{creep} = \Delta \varepsilon_l \quad (2)$$

91 Fig.1 shows the schematic diagram of the 1-D EVP model for this study. The reference
 92 time line corresponds to the normal compression line measured at t_0 in conventional multi-staged
 93 oedometer tests. Based on Eq.(1) and the concept of equivalent time by Yin and Graham (1989,
 94 1994), the 1-D strain of clay is expressed in the following equation:

95
$$\varepsilon_z = \varepsilon_{z0} + \frac{\kappa}{V} \ln \frac{\sigma'_{zp}}{\sigma'_{z0}} + \frac{\lambda}{V} \ln \frac{\sigma'_z}{\sigma'_{zp}} + \frac{\frac{\psi_0}{V} \ln \left(\frac{t_e + t_0}{t_0} \right)}{1 + \frac{\psi_0}{V \Delta \varepsilon_l} \ln \left(\frac{t_e + t_0}{t_0} \right)}$$

96
$$= \varepsilon_z^r + \frac{\frac{\psi_0}{V} \ln \left(\frac{t_e + t_0}{t_0} \right)}{1 + \frac{\psi_0}{V \Delta \varepsilon_l} \ln \left(\frac{t_e + t_0}{t_0} \right)} \quad (3)$$

96 where σ'_z , ε_z is the current effective stress and strain, $V = 1 + e_0$ is the initial specific volume, κ
 97 is the slope of instant time line (unloading/re-loading line) on the $e - \ln p'$ curve, λ is the slope of
 98 reference time line (normal compression line) on the $e - \ln p'$ curve, σ'_{zp} is the apparent pre-
 99 consolidation pressure on the reference time line, ε_z^r is the “reference strain” at reference time line
 100 under σ'_z , and t_e is the equivalent time. t_e is equal to zero at the reference time line. Therefore,
 101 ε_{creep} in Eq.(1) corresponds to the strain from ε_z^r to ε_z . According to the EVP model (Yin and
 102 Graham 1994), varied t_e corresponds to a family of compression lines parallel to the reference
 103 time line, as shown in Fig.1. The relationship between visco-plastic strain rate $\dot{\varepsilon}_z^{vp}$ and t_e is unique.
 104 $\dot{\varepsilon}_z^{vp}$ can be calculated as:

$$\dot{\varepsilon}_z^{vp} = \frac{\partial \varepsilon_z}{\partial t} = \frac{\partial \varepsilon_z}{\partial t_e} = \frac{\psi_0}{Vt_0} \exp \left[\frac{-V(\varepsilon_z - \varepsilon_z^r)}{\psi_0 \left(1 - \frac{\varepsilon_z - \varepsilon_z^r}{\Delta \varepsilon_l} \right)} \right] \left(1 - \frac{\varepsilon_z - \varepsilon_z^r}{\Delta \varepsilon_l} \right)^2 \quad (4)$$

106

107 **2.2 3-D EVP model with creep limit**

108 In the 3-D space, the mean effective normal stress p' and deviatoric stress q are defined
109 as:

$$110 \quad p' = \frac{tr(\sigma'_{ij})}{3} = \frac{\sigma'_{11} + \sigma'_{22} + \sigma'_{33}}{3} \quad (5a)$$

$$111 \quad q = \sqrt{\frac{3}{2}(s_{ij} : s_{ij})} \quad (5b)$$

$$112 \quad s_{ij} = \sigma'_{ij} - \delta_{ij} p' \quad (5c)$$

$$113 \quad \delta_{ij} = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases} \quad (5d)$$

114 With the associated flow rule, the flow direction of visco-plastic strain is controlled by the plastic
115 potential function g , corresponding to the loading surface. In Yin et al. (2002), the loading surface
116 contained two parts, one above the critical state line and one below the critical state line. Both of
117 them were non-elliptical, with some independent parameters to describe the geometry. However,
118 these parameters might be difficult to determine, especially for engineering applications. Besides,
119 the equations for the loading surfaces are quite complicated, which increases the difficulty in
120 differential equation derivation for implicit calculations in finite element modelling. In the
121 meantime, some researchers adopted single elliptical loading surface based on the modified Cam-
122 clay model, which also revealed good reasonability for various clayey soils (Zhou et al. 2005;

123 Grimstad et al. 2010; Yin et al. 2010; Freitas et al. 2012; Feng 2016; Chen et al. 2021a). Therefore,
 124 to simplify the problem without significantly reducing the accuracy, this study proposes to use the
 125 elliptical loading surface in the modified Cam-clay (MCC) model (Roscoe and Burland 1968):

$$126 \quad g = \frac{q^2}{M^2 p'} + p' - p'_m = 0 \quad (6)$$

127 in which M is the slope of critical state line in $p' - q$ plane of MCC model, p'_m is the
 128 intersection point of surface $g = 0$ and the axis of p' , which represents the “size” of loading
 129 surface, as shown in Fig.2.

130 Based on associated flow rule, the visco-plastic strain rate in the 3-D space is described as:

$$131 \quad \dot{\epsilon}_{ij}^{vp} = S \frac{\partial g}{\partial \sigma_{ij}} \quad (7)$$

132 where S is a scaling function representing the viscosity of the soil and $\frac{\partial g}{\partial \sigma_{ij}}$ is a tensor that controls
 133 the direction of deformation. It is considered that the volumetric visco-plastic strain rate is the
 134 same on the yielding surface, which means $\dot{\epsilon}_v^{vp} = \dot{\epsilon}_{vm}^{vp}$ (Vermeer and Neher 1999; Yin and Graham
 135 1999; Yin et al. 2002; Feng 2016). According to Eq.(7), the value of S can be determined as:

$$136 \quad S = \frac{\dot{\epsilon}_v^{vp}}{\partial g / \partial p'} = \frac{\dot{\epsilon}_{vm}^{vp}}{\partial g / \partial p'} \quad (8)$$

137 The relationship between ϵ_v and ϵ_{vm} is shown in Fig.2, which is two points on the same “elastic
 138 wall” and can be expressed in Eq.(9):

$$139 \quad \epsilon_{vm} = \epsilon_v + \frac{\kappa}{V} \ln \frac{p'_m}{p'} \quad (9)$$

140 According to the 1-D EVP model, the value of $\dot{\epsilon}_{vm}$ can be determined from:

141
$$\dot{\varepsilon}_{vm}^{vp} = \frac{\psi_0}{Vt_0} \exp \left[\frac{-V(\varepsilon_{vm} - \varepsilon_{vm}^r)}{\psi_0 \left(1 - \frac{\varepsilon_{vm} - \varepsilon_{vm}^r}{\Delta \varepsilon_l} \right)} \right] \left(1 - \frac{\varepsilon_{vm} - \varepsilon_{vm}^r}{\Delta \varepsilon_l} \right)^2 \quad (10)$$

142 where $\varepsilon_{vm}^r = \varepsilon_{v0} + \frac{\kappa}{V} \ln \frac{p_{mc}'}{p_0'} + \frac{\lambda}{V} \ln \frac{p_m'}{p_{mc}'}$ is the reference volumetric strain. The parameters can be
 143 calibrated from conventional 1-D or isotropic-stress consolidation tests. p_{mc}' is the size of
 144 “reference yielding surface” calculated by the pre-consolidation pressure σ_{zp}' , as shown in the
 145 following equations:

146
$$p_{mc}' = \frac{q_c^2}{M^2 p_c'} + p_c' \quad (11a)$$

147
$$p_c' = (\sigma_{zp}' + 2K_0^{nc} \sigma_{zp}') / 3 \quad (11b)$$

148
$$q_c = \sigma_{zp}' - K_0^{nc} \sigma_{zp}' \quad (11c)$$

149 where $K_0^{nc} = 1 - \sin \phi' = 1 - \frac{3M}{6+M}$ is the coefficient of effective earth pressure at normal
 150 consolidation state.

151

152 **3 Fully coupled finite element simulations for two embankments in PLAXIS 2D**

153 **3.1 Brief introduction to the algorithm for FE simulations**

154 Using Eqs. (7) to (11), the visco-plastic strain rate of an element of soils under any stress-
 155 strain state can be calculated. The overall strain rate is calculated by:

156
$$\dot{\varepsilon}_{ij} = \dot{\varepsilon}_{ij}^e + \dot{\varepsilon}_{ij}^{vp} = \left(\frac{1}{2G^e} \dot{s}_{ij} + \frac{p'}{3K^e} \dot{\delta}_{ij} \right) + S \frac{\partial g}{\partial \sigma_{ij}'} \quad (12)$$

157 where $\dot{\varepsilon}_{ij}^e$ is the elastic strain rate calculated by the generalized Hooke's law, K^e is the elastic bulk
 158 modulus and G^e is the elastic shear modulus. K^e and G^e are calculated using the slope of instant
 159 time line κ and Poisson's ratio μ , as shown in Eq.(13):

$$160 \quad K^e = \frac{1}{\partial \varepsilon_v^e / \partial p'} = \frac{1}{\partial \left(\frac{\kappa}{V} \ln \frac{p'}{p_0} \right) / \partial p'} = \frac{V p'}{\kappa} \quad (13a)$$

$$161 \quad G^e = \frac{3(1-2\mu)K^e}{2(1+\mu)} \quad (13b)$$

162 In the FE method, the mechanical behaviour can be determined using the Newton-
 163 Raphson's method and Euler's time iteration scheme in each small time-step (Feng et al. 2014; Li
 164 and Yin 2020). The vector of effective stress increment during a time-step is expressed by Eq.(14):

$$165 \quad \Delta \boldsymbol{\sigma} = \mathbf{D} : \Delta \boldsymbol{\varepsilon}^e = \mathbf{D} : (\Delta \boldsymbol{\varepsilon} - \Delta \boldsymbol{\varepsilon}^{vp}) \quad (14)$$

166 The visco-plastic strain increment $\Delta \boldsymbol{\varepsilon}^{vp}$ is calculated by Euler time iteration scheme:

$$167 \quad \Delta \boldsymbol{\varepsilon}^{vp,n} = \Delta t \cdot \left[(1-\theta) \cdot \dot{\boldsymbol{\varepsilon}}^{vp,n} + \theta \cdot \dot{\boldsymbol{\varepsilon}}^{vp,n+1} \right] \quad (15)$$

168 where $\theta \in [0,1]$ is a factor for combining both explicit ($\theta=0$) and implicit ($\theta=1$) methods, n
 169 represents the numbering of time step and Δt is the size of time step. Eqs.(14) and (15) are solved
 170 with Newton-Raphson's iteration:

$$171 \quad \begin{cases} \boldsymbol{\sigma}^{n+1} = \boldsymbol{\sigma}^i + d\boldsymbol{\sigma}^i \\ \dot{\boldsymbol{\varepsilon}}^{vp,n+1} = \dot{\boldsymbol{\varepsilon}}^{vp,i} + \frac{\partial \dot{\boldsymbol{\varepsilon}}^{vp,i}}{\partial \boldsymbol{\sigma}} d\boldsymbol{\sigma} \end{cases} \quad (16)$$

172 where $\boldsymbol{\sigma}^i$ represents the updated stress and $|d\boldsymbol{\sigma}^i|$ is the residual at the iteration step which forces
 173 the iteration to stop when it is smaller enough.

174 The constitutive model is encoded into a dynamic link library (.dll) with FORTRAN
175 language for application in the finite element program PLAXIS (2015). At each calculation step
176 of each node, the current soil state (*e.g.* effective stress vector, strain vector and void ratio) and
177 trial strain increment will be input into the functions defined in the .dll to produce a new stress
178 vector for the next global iteration of the numerical model. The hydraulic behaviours are solved
179 with Biot's 3-D consolidation equations. In this way, the stress-strain relationship is fully coupled
180 with hydraulic behaviours by iteration algorithm.

181

182 **3.2 Soil profiles and soil parameters for the Malaysian test embankments**

183 In order to study the performance of highway embankments on Malaysian marine clay,
184 Malaysian Highway Authority directed construction of several full-scale test embankments
185 from 1988 to 1989 (MHA 1989a, b). For comparison, there are two embankments (Scheme 3/2 and
186 6/6) directly built on the soft soils without measures of soil improvements (*e.g.* vertical drains),
187 which have been monitored for a long time. The stratum under the test embankments contained
188 multiple-layered marine soft soils, as shown in Fig.3. Details of the soil properties are listed in
189 Table 1. The designed filling height is 3 m for Scheme 3/2 and 6 m for Scheme 6/6. Since the
190 completion of construction in September 1989, the vertical and horizontal displacements and
191 excess pore pressure at different depths and positions have been monitored by surface settlement
192 makers, rod settlement gauges, inclinometers and pneumatic piezometers. Obviously, these cases
193 contain multi-layered soft soil ground, multi-staged loading history, long-term monitoring and
194 obvious plane-strain features, which are very suitable for verification of the proposed methods and
195 model.

196 There is a crust cover with a thickness of 1.5 to 2.0 m underneath the fills. The crust mainly
197 consists of weathered dark brown clay with roots and other materials. The average water content
198 is around 60% and compressibility is relatively small. Laboratory studies on specimens from the
199 crust layer demonstrated a pre-consolidation pressure σ'_{zp} of around 110 kPa. As the permeability
200 data is yet unavailable, permeability of the adjacent clay will be used for the crust in this study.

201 The second layer is a soft marine clay with olive green colour, containing thin and
202 discontinuous sand partings and slight organic components such as roots and leaves. This layer,
203 named upper clay layer, has an average thickness of around 5 m. The soil parameters are found
204 more uniform compared with the crust. However, test results on samples from the upper 2.5 m of
205 this layer exhibit high uncertainty, possibly due to the structure effect and soil disturbance. For
206 example, the initial water content, OCR and compressibility of the upper parts are also obviously
207 higher than the lower parts. Therefore, it is necessary to divide the “upper clay” into two layers,
208 namely “upper clay 1” and “upper clay 2” with thickness of 2.5 m for each. Considering the
209 differences of initial void ratio e , the permeability of upper clay 1 should be modified using the
210 following equation:

$$211 \quad \log \frac{k_{v1}}{k_{v2}} = \frac{e_1 - e_2}{C_k} \quad (17)$$

212 where C_k is the permeability index and is assumed to be 0.5 in this study (Tavenas et al. 1983).

213 The third layer is a sandy silty clay layer of 1.6 m and the fourth is a lower clay layer of
214 9.2 m. The water content generally ranges from 50% to 70%. Below these layers follows a thin
215 layer of peat and a stiff sandy clay layer. A layer of fine silty sand is located at the bottom.

216 All soil layers except the sand layer and the fill material are simulated using the nonlinear
217 3-D EVP model. In the EVP model, the value of pre-consolidation pressure σ'_{zp} is important in

218 determination of the visco-plastic strain rate. According to the test results, the depth-dependency
 219 of σ'_{zp} is significant. Therefore, σ'_{zp} for each soil layer is defined using the concept of “pre-over-
 220 consolidation pressure (POP)”, calculated by $POP = \sigma'_{zp} - \sigma'_{z0}$, where σ'_{z0} is the initial in-situ
 221 effective stress. The usage of constant POP forms a piecewise linear distribution of σ'_{zp} with depth,
 222 as indicated in Fig.4. The values of compression index $\frac{C_c}{V}$ ($C_c = \lambda \ln 10$) at different layers is
 223 shown in Fig.5. The values of unloading-reloading index κ were not reported in MHA’s reports
 224 (MHA 1989a,b). Therefore, a proper value of $\kappa = 0.1\lambda$ is used in the simulations (Magnan and
 225 Katan 1989; Balasubramaniam et al. 2007). The secondary consolidation coefficient C_α of soils
 226 from different depth is measured under different vertical stress, which varied from 0.01 to 0.025.
 227 A constant creep coefficient $\psi_0 = \frac{C_\alpha}{\ln 10}$ with the averaged value of C_α is adopted in this study.
 228 Due to lack of long-term oedometer data, creep limit $\Delta\varepsilon_l = \frac{e}{1+e_0}$ is used in this study, which is
 229 the upper bound of $\Delta\varepsilon_l$. All parameters are selected based on the suggested or reported values by
 230 MHA (1989a,b).

231

232 **3.3 Results of FE simulations**

233 FE simulations are carried out for a cross-section of the embankment in PLAXIS 2D using
 234 the plane strain model, since the longitudinal deformation for a road embankment can be neglected.
 235 The numerical model of two embankments, Scheme 3/2 and 6/6, are shown in Fig.3. The
 236 construction is a multi-staged filling process, which can be described by the measured thickness
 237 of fill materials, as shown in Fig.6.

238 Fig.7 presents the settlement curves of the two embankments by FE simulations at different
239 instrumentation points. “S” represents rod settlement gauge buried on the natural surface of the
240 crust layer, while “SM” represents surface markers installed on the surface of the fill after
241 completion of construction. With the parameters determined in the previous section, the simulation
242 results fit well with the monitored results, especially the settlement measured by the surface
243 markers.

244 Fig.8 shows the comparisons between calculated excess pore water pressure in the middle
245 of marine clay with measured data by piezometers. In general, the simulated results are quite close
246 to the monitored results. However, the quality of monitored pore water pressure is still a concern
247 since the fluctuation of data is obvious, especially after a long period in service, which may explain
248 the discrepancy between simulated results and measured data after a long time.

249 Fig.9 shows the lateral displacement at different depths and times from FE simulations and
250 in-situ measurements by inclinometers installed in the soils. The simulation results for Scheme 3/2
251 are reliable, while the results for Scheme 6/6 are less accurate. One possible reason is that the
252 inclinometer of Scheme 6/6 was installed inside the construction area, which could be disturbed
253 by the filling process. For both embankments, lateral deformation is significant, especially at the
254 top 10 meters from the ground surface. The largest lateral deformation tends to occur in the upper
255 marine clay layers in which the volume compressibility and vertical strain are very high.

256

257 **4 Parametric studies in FE simulations with the nonlinear 3-D EVP model**

258 **4.1 Influence of Compressibility**

259 As reported by MHA (1989a), the compression index C_c of tested soil samples is found to
260 have a discrete distribution within a certain range with high uncertainty, especially for the upper

261 clay, as shown in Fig.5. Although the mean values of test data are adopted in Table 1, it is necessary
262 to discuss the variations of results caused by different compressibility. In this sub-section, two
263 additional cases are studied. In the first case, the upper bound of C_c for each layer is used in FE
264 analysis. In the second case, the lower bound of C_c for each layer is used. C_r is 10% of C_c for all
265 cases. Other parameters are kept unchanged from Table 1.

266 Calculated settlements at S5 for the two cases are shown in Fig.10, compared with
267 measured data. The results indicate significant variations between the two sets of compressibility
268 indices. The differences of final settlement at 3000 days between upper bound and lower bound of
269 compressibility are around 0.2 m for Scheme 3/2 and 0.4 m for Scheme 6/6. The differences
270 gradually increase with time due to the consolidation of soils. The results imply that despite of bad
271 quality of measured data, using mean values of compressibility seems to be the optimal solution
272 to this issue.

273

274 **4.2 Influence of Creep Parameters**

275 Creep parameters have significant effects on the time-dependent stress-strain behaviour of
276 soft soils. For the test embankments, one-dimensional creep tests were conducted in laboratory to
277 provide the secondary consolidation coefficient C_α ($C_\alpha = \psi_0 \ln 10$) under different effective
278 stresses using the conventional fitting method $C_\alpha = \frac{\Delta e}{\Delta \log t}$. The values of C_α provided in MHA
279 (1989a) are found discrete, with an upper bound of around 0.025 for the clayey soils. Due to
280 nonlinear creep behaviour of clayey soils (Yin 1999), the creep coefficient is slightly decreased
281 with vertical effective stress. Following this principle, the average creep coefficient of 0.015
282 considering the final surcharge loading is selected as in Table 1. In this parametric study, C_α is

283 increased to its upper bound (*i.e.* 0.025) for all soil layers except the sandy clay layer and the sand
 284 layer. Another important parameter for the EVP model is the creep limit $\Delta\varepsilon_l$, which requires curve
 285 fitting from long-term oedometer tests. It is reported that for some of the marine soils, the values
 286 of creep limit roughly range from 0.03 to 0.06 (Yin 1999; Feng et al. 2017; Chen et al. 2021a). In
 287 this parametric study, one case with $\Delta\varepsilon_l = 0.05$ and another case with $\Delta\varepsilon_l = 1000$ are used for
 288 comparisons with $\Delta\varepsilon_l = \frac{e_0}{1+e_0}$ in Table 1. For $\Delta\varepsilon_l = 1000$, Eq.(1) is very close to the conventional
 289 linear creep model $\varepsilon_{creep} = \frac{\psi_0}{V} \ln\left(\frac{t+t_0}{t_0}\right)$ by Yin and Graham (1989).

290 Fig.11 shows the calculated settlements at S5 with different values of creep parameters.
 291 It can be seen that C_α has a significant influence on the long-term settlements. With $C_\alpha = 0.025$
 292 for the soft clayey layers, the final settlements in 30 years are increased by around 0.25 m for both
 293 Scheme 3/2 and Scheme 6/6. In Scheme 3/2, it can be found that settlements are severely
 294 overestimated with $C_\alpha = 0.025$ even in the first several years. However, the influence of $\Delta\varepsilon_l$ is
 295 relatively minor, especially in the earlier phase. After 1000 days, the settlement with $\Delta\varepsilon_l = 0.05$
 296 becomes visibly smaller than the other cases, while the case with $\Delta\varepsilon_l = \frac{e_0}{1+e_0}$ is still close to
 297 $\Delta\varepsilon_l = 1000$. Such results suggested that the value of $\Delta\varepsilon_l$ does influence the prediction results, but
 298 only for long-term prediction for post-construction settlement. To improve the accuracy of
 299 prediction, $\Delta\varepsilon_l$ should be measured in long-term oedometer tests in laboratory (Yin 1999), rather
 300 than be determined by $\Delta\varepsilon_l = \frac{e_0}{1+e_0}$.

301

302 **4.3 Influence of Updating Static Water Pressure**

303 The FE analysis on the embankments is conducted with the option of “update water
304 pressure” in PLAXIS. With this option, the mesh of the FE model, static porewater pressure and
305 effective stresses are updated with time with consideration of soil deformation, which enables more
306 precise predictions under large deformation in the long term. Fig.12 presents the calculated
307 settlement curves with and without updating static water pressure during the FE analysis.
308 According to the results, the severe overestimation of settlements will occur without updating
309 static water pressure. The reason is that with the continuous settlement of embankments into the
310 groundwater level, the effective loading will be reduced by the buoyancy of water. Therefore, it is
311 necessary to consider this option during the consolidation analysis.

312

313 **5 An improved simplified Hypothesis B methods for calculating consolidation settlements** 314 **at embankment centre with comparisons with measured data**

315 **5.1 Improved simplified Hypothesis B method considering nonlinear creep for 1-D** 316 **consolidation settlement calculations**

317 As shown in previous sections, FE method can be used to simulate the fully coupled and
318 2-D behaviour of an embankment through meshing and iteration techniques in a computer program.
319 Due to the possible convergence difficulties of FE methods, in some cases, handy calculations
320 based on certain assumptions are still widely adopted for simplified predictions of settlement and
321 cross-checking for FE simulations. For 1-D consolidation settlement analysis of a thick layer of
322 soils without creep, Terzaghi’s consolidation theory is the most classical and widely adopted
323 method. Based on Terzaghi’s theory, researchers have developed different theoretical and semi-
324 empirical methods to calculate the consolidation settlements of soils subjected to multi-layered

325 stratum, multi-staged and time-dependent loading and vertical drains (Zhu and Yin 2005; Chen et
 326 al. 2005; Walker et al. 2009; Yin and Zhu 2020). In these solutions, iteration algorithm is not
 327 required, and convergence is no longer a problem. To consider creep deformation, the simplified
 328 Hypothesis B method (Yin and Feng 2017; Feng and Yin 2017; Yin and Zhu 2020) has been
 329 proposed for soft clayey soils based on existing analytical solutions for primary consolidation and
 330 1-D EVP model for creep analysis.

331 Hypothesis B is a theory advocating that viscous compression should be considered during
 332 the “primary consolidation”, opposed to Hypothesis A that the creep only occurs after end of
 333 primary consolidation (Ladd et al. 1977; Mesri and Godlewski 1977). Hypothesis B has been
 334 widely accepted and implemented in most fully coupled analysis methods (Leroueil et al. 1985;
 335 Yin and Graham 1989; Vermeer and Neher 1999; Hinchberger and Rowe 2005; Kellen et al. 2008;
 336 Degago et al. 2011; Watabe et al. 2012; Grimstad et al. 2017). Despite of this, when finite element
 337 software is not adopted, many engineers and construction codes still turn back to Hypothesis A
 338 because it can be easily achieved by hand calculation. There exists an obvious lag between
 339 engineering practice and research development.

340 The intensive of simplified Hypothesis B method is to avoid iterations and meshing in the
 341 fully coupled consolidation analysis and improve the practicality of Hypothesis B. In Chen et al.
 342 (2021b)’s new simplified Hypothesis B method, the total settlement of multi-layered clayey soils
 343 is calculated as:

$$344 \quad S_{totalB} = S_{primary} + S_{creep} = \sum_{j=1}^{j=n} U_j S_{ff} + \sum_{j=1}^{j=n} [\alpha U_j S_{creep,ff} + (1 - \alpha U_j) S_{creep,dj}] \quad (18)$$

for all $t \geq t_0$ ($t \geq t_{EOP,field}$ for $S_{creep,dj}$)

345 where S_{totalB} represents the total settlement with time, j denotes numbering of soil layer, U_j is
 346 the degree of consolidation for the j -layer, α is an empirical parameters ranging from 0 to 1 to

347 considering creep delayed by primary consolidation. Eq. (18) can be reduced to Hypothesis A by
348 setting $\alpha = 0$. Details of the values of α can be found in Yin and Zhu (2020) and Chen et al.
349 (2021b). $\alpha = 0.8$ is frequently used and found effective for general cases. t_0 is the reference time
350 (e.g. one day). $t_{EOP,field}$ is the time needed for “end of primary consolidation (EOP)” of the soil
351 layer, which can be calculated using Walker et al. (2009)’s spectral method for multi-layered soil
352 consolidation problem. S_f equals to the “primary consolidation settlement” under the targeted
353 increment of loading without considering any creep strain. The value of S_f for each layer under
354 each loading is directly determined from the $\varepsilon_z - \log \sigma'_z$ curve according to its stress history, as
355 shown in Fig.13. Considering the nonlinear 1-D EVP model, the calculation of instant creep
356 settlement $S_{creep,f}$ and delayed creep settlement $S_{creep,d}$ for each layer should be derived as Eqs.
357 (19a) and (19b):

$$358 \quad S_{creep,f} = H_j \left[\frac{\frac{\psi_0}{V} \ln \left(\frac{t_e + t_0}{t_0} \right)}{1 + \frac{\psi_0}{V \Delta \varepsilon_l} \ln \left(\frac{t_e + t_0}{t_0} \right)} - (\varepsilon_{zf} - \varepsilon_{zf}^r) \right], \text{ for } t > t_0 \quad (19a)$$

$$359 \quad S_{creep,d} = H_j \left[\frac{\frac{\psi_0}{V} \ln \left(\frac{t_e + t_0}{t_{EOP,field}} \right)}{1 + \frac{\psi_0}{V \Delta \varepsilon_l} \ln \left(\frac{t_e + t_0}{t_{EOP,field}} \right)} - (\varepsilon_{zf} - \varepsilon_{zf}^r) \right], \text{ for } t > t_{EOP,field} \quad (19b)$$

360 where $t_e = t_{ei} + t - t_c / 2$ is the equivalent time in the EVP model, t is the total time of the
361 consolidation stage, t_c is the construction time, ε_{zf} is the final strain under stress σ'_{zf} without
362 considering creep, ε_{zf}^r is the reference strain located at the reference time line under σ'_{zf} , and t_{ei}

363 is the equivalent time at the final state of stress σ'_{zf} and strain ε_{zf} , as shown in Fig.13. The value
 364 of final strain state ε_{zf} can be calculated by Eq. (20):

$$365 \quad \varepsilon_{zf} = \max \left[\varepsilon_{z_total}(\text{last stage}) + \frac{\kappa}{V} \ln \frac{\sigma'_{zf(i)}}{\sigma'_{zf(i-1)}}, \varepsilon_{zp} + \frac{\lambda}{V} \ln \frac{\sigma'_{zf(i)}}{\sigma'_{zp}} \right] \quad (20)$$

366 where $\varepsilon_{z_total}(\text{last stage}) = \varepsilon_{z0} + \sum_{\text{past stages}} (S_f + S_{creep}) / H_j$ is the accumulated strain from previous stages.

367 When $\varepsilon_{z_total}(\text{last stage}) + \frac{\kappa}{V} \ln \frac{\sigma'_{zf}}{\sigma'_{zf}(\text{last stage})} < \varepsilon_{zp} + \frac{\lambda}{V} \ln \frac{\sigma'_{zf}}{\sigma'_{zp}}$, the final state is under normal

368 consolidation and t_{ei} is equal to zero. Otherwise, the soil layer is under over-consolidation state

369 and the value of t_{ei} can be calculated as follows:

$$370 \quad t_{ei} = \exp \left[\frac{\varepsilon_{zf} - \varepsilon_z^r}{\frac{\psi_0}{V} \left(1 - \frac{\varepsilon_{zf} - \varepsilon_z^r}{\Delta \varepsilon_l} \right)} \right] t_0 - t_0$$

$$= \exp \left\{ \frac{\left[(\varepsilon_{zf} - \varepsilon_{zp}) - \frac{\lambda}{V} \log \left(\frac{\sigma'_{zf}}{\sigma'_{zp}} \right) \right]}{\frac{\psi_0}{V} \left(1 - \frac{(\varepsilon_{zf} - \varepsilon_{zp}) - \frac{\lambda}{V} \log \left(\frac{\sigma'_{zf}}{\sigma'_{zp}} \right)}{\Delta \varepsilon_l} \right)} \right\} t_0 - t_0, \quad \text{for } (\varepsilon_{zf} - \varepsilon_z^r) < \Delta \varepsilon_L \quad (21)$$

371 In Eq. (21), when $(\varepsilon_{zf} - \varepsilon_z^r) > \Delta \varepsilon_l$, the stress-strain state of soil is below the limit time line,

372 so the value of t_{ei} is $+\infty$ and $S_{creep,f} = S_{creep,d} = 0$. The major procedures of simplified Hypothesis

373 B method are revealed in Fig.13. More details about the simplified Hypothesis B method can be
374 found in Chen et al. (2021b) and Yin and Zhu (2020).

375

376 ***5.2 Modification of the simplified Hypothesis B method with considerations of stress*** 377 ***reduction underneath 2-D embankments***

378 Under multi-staged loading, the total settlement calculated by Eq.(18) from each loading
379 stage can be superposed as the accumulated total settlement, as shown in Fig.13. For embankments
380 with an unloading stage, the superposition might not be reasonable since the accumulated plastic
381 deformation of soils is dependent of the actual consolidation time.

382 Besides, this method is only limited to 1-D compression, which may differ from the field
383 conditions, especially for road embankments constructed on thick layers of clay, including the
384 cases in this study. Although it can be assumed that the centerline of the embankment is still
385 subjected to 1-D compression and vertical drainage, the stress reduction caused by stress diffusion
386 cannot be neglected. In addition, this method has not considered the effects of buoyancy due to the
387 gradual settlement of embankments into the original ground level, by which the actual surcharge
388 will be reduced with time. Therefore, 1-D simplified methods should be adjusted to simulate the
389 real settlement under the field condition.

390 **(1) Effects of additional stress diffusion**

391 For a finite-length load applied on the infinite soil ground, the vertical stress will decrease
392 with depth due to the diffusion of additional stress. Flamant (1892) developed an elastic solution
393 for stress distribution with depth for the case of a strip load applied on a semi-infinite half-space
394 of homogeneous isotropic soils. Flamant's solution can be used to calculate the stress distribution
395 under a strip loading by integral (Gong and Xie 2014). Further to consider the geometry of

396 embankments, Osterberg (1957) developed a series of solutions for external loadings in the shape
 397 of triangle, strip, and embankment (trapezoid) and provided influence charts for engineers' use.
 398 However, as noticed by previous researchers (Schmertmann 2005; Wang et al. 2019), both
 399 Flamant's solution and Osterberg's charts are elastic solutions and should not be directly adopted
 400 in settlement analysis for soft clayey soils, since the stress-strain behaviours of soft soils are much
 401 different from elastic materials. Besides, the existing elastic solutions usually require chart method,
 402 which is not convenient and time-consuming. A new formulation for vertical stress reduction based
 403 on the FE simulations will be more suitable. Considering the boundary conditions that

404 $\lim_{\frac{z}{B} \rightarrow \infty} \Delta\sigma'_{zf} \left(\frac{z}{B} \right) = 0$ and $\Delta\sigma'_{zf}(0) = Q'$, the simplest mathematical model of additional stress

405 distribution can be assumed as the following hyperbolic function:

$$406 \quad \Delta\sigma'_{zf}(z) = \frac{Q'}{1 + z/B} \quad (22)$$

407 where $\Delta\sigma'_{zf}$ is the additional vertical stress, Q' is the loading applied on the surface, z is the depth,
 408 B is the width at the middle of the embankment, which is simplified as a strip load, as shown in
 409 Fig.14. The larger B , the closer to 1-D case. For a multi-staged constructed embankment, different
 410 values of B will be considered independently for each stage of Q' . In this way, the influence of
 411 special geometry of embankment, for example, Scheme 6/6 in this study, can be taken into account.

412 Fig.14 presents the distribution of total additional vertical stress at the center with depth by

413 FE simulations, elastic solution and Eq.(22). The ratio of $\frac{\Delta\sigma'_{zf}}{Q'}$ for Scheme 6/6 was calculated by

414 $\frac{\Delta\sigma'_{zf1} + \Delta\sigma'_{zf2} + \Delta\sigma'_{zf3}}{Q'_1 + Q'_2 + Q'_3}$ from three independently analyzed trapezoids. It can be found that the

415 $\frac{\Delta\sigma'_{zf}}{Q}$ for two embankments exhibits decreasing trend with depth, in which $\frac{\Delta\sigma'_{zf}}{Q}$ for Scheme
416 3/2 decreased more sharply due to the smaller length. Prediction results by the proposed method
417 in this study are fairly close to the results by FE simulation, while elastic solutions by Flamant and
418 Osterberg tend to overestimate $\frac{\Delta\sigma'_{zf}}{Q}$ at different depths. Therefore, Eq.(22) is considered
419 effective to be used in the simplified hypothesis B method. Compared with the 1-D simplified
420 method (Chen et al. 2021b), only one additional parameter, B , is introduced in the updated
421 equations.

422 It should be noted that this method only serves as a simplified way for correcting the 1-D
423 settlement curves at the centre of embankments. The deformations caused by rotations and torsion
424 are neglected. The influences of plastic deformation on the stress diffusion mode during the
425 superposition of multi-stage loadings are not considered either. Therefore, this method does not
426 apply to embankments with large horizontal and shear strains, as well as locations away from the
427 centre line.

428 (2) Effects of buoyancy

429 With the settlement of soils, part of the surcharge from the embankment will be
430 compensated by the buoyancy force of groundwater. In the FEM analysis, the buoyancy effect is
431 considered by updating water pressure for each calculation step. In simplified methods, the
432 buoyancy effect may be calculated with a simple approach. Considering a soil layer subjected to
433 an initial vertical surcharge Q , the actual effective surcharge Q' can be estimated as:

$$434 \quad Q' = Q - \gamma_w S' \quad (23)$$

435 where S' is the total actual settlement of the soil layer, γ_w is the unit weight of water. The actual
 436 consolidation settlement can be approximated as $S' = UHm_v Q'$, where H is the initial thickness
 437 of the soil. Therefore, substituting Eq. (23) to $S' = UHm_v Q'$, we have:

$$438 \quad S' = UHm_v (Q - \gamma_w S') \quad (24)$$

439 Eq. (24) can be re-organized as:

$$440 \quad S' = \frac{UHm_v Q}{(1 + UHm_v \gamma_w)} \quad (25)$$

441 Finally, substituting $UHm_v Q = S$ into Eq. (25), the following expression is obtained:

$$442 \quad S' = \frac{S}{1 + S\gamma_w / Q} \quad (26)$$

443 Therefore, the actual settlement S' considering buoyancy can be directly adjusted from the
 444 original calculated settlement S without buoyancy correction. For multi-layered and multi-staged
 445 cases, it is assumed that Eq.(24) is still effective, to avoid the iterations and integration of stress-
 446 strain relations at different layers. Finally, the time-dependent settlement by Eq.(18) should be
 447 corrected as:

$$448 \quad S'(t) = \sum_i \frac{S_i(t)}{1 + S_i(t)\gamma_w / Q_i} \quad (27)$$

449

450 **5.3 Calculation results by the 2-D simplified Hypothesis B method compared with FE** 451 **simulation and in-situ measurement**

452 All parameters are kept the same as in the FE simulation. The compressibility m_v for each

453 layer is calculated by $m_v = \frac{S_f}{H_j \Delta \sigma_{zf}}$. The soil parameters are input to the Walker et al. (2009)'s

454 spectral method for calculations of U_j and then S_{totalB} by Eq.(18) in each stage. The empirical
455 factor $\alpha = 0.8$ in Eq.(18) is used for analysis. For comparison, a case with $\alpha = 0$ (*i.e.*, Hypothesis
456 A method) is studied.

457 Using the improved simplified Hypothesis B method, the settlement curves at the centre of
458 embankments can be obtained. Fig.16 shows the comparisons between the calculation results by
459 FE method (2-D FEM), simplified Hypothesis B method with modifications for stress diffusion
460 and buoyancy (new SBM), original simplified Hypothesis B method without modifications
461 (original 1-D SBM), Hypothesis A method, and measured data. According to Fig.16, the results by
462 the new SBM agree well with the FE simulations and in-situ measurements. Results from original
463 SBM show obvious overestimation compared with improved SBM and FEM. Results from
464 Hypothesis A, in which creep only occurs after the end of primary consolidation, exhibit
465 underestimations of settlement. Therefore, the proposed simple method with considerations of
466 Hypothesis B, 2-D stress diffusion and buoyancy effect is effective for embankment analysis.

467 According to these results, the proposed simple method is promising in predicting the
468 settlements of the embankments in both convenience and accuracy. It can be done in an Excel
469 spreadsheet and does not require solving complicated equations for force equilibrium and 3-D
470 consolidations or solution charts. However, since the equations are empirically based, further
471 examinations for more general cases based on public database are necessary. The current method
472 is only applicable to the settlements of centre lines under the embankments with small horizontal
473 and shear strain and without an unloading stage. For further studies, the effects of deviatoric stress
474 and shear stress, displacements at different positions and directions, and the unloading-reloading
475 stages should be taken into consideration.

476

477 6 Conclusions

478 To study the long-term and time-dependent consolidation settlement of embankments, a
479 nonlinear three-dimensional elastic visco-plastic (3-D EVP) model with a creep limit is improved
480 and encoded in both finite element program and simple method. Simulations on two test
481 embankments constructed on multi-layered Malaysian marine soft soils with a complicated
482 construction history were conducted with the EVP model. The results of FE simulations are
483 compared with in-situ measured data for verifying the suitability and accuracy of the nonlinear 3-
484 D EVP model. Parametric studies on the parametric optimization and modelling techniques are
485 conducted and presented with discussions. An improved simplified Hypothesis B method is
486 proposed with considerations of creep limit, 2-D effects in distribution of stress, and buoyancy
487 effects for consolidation settlement analysis of the test embankments. This new improved
488 simplified method is also verified with measured data and FE simulations. Based on the works
489 presented above, several important conclusions can be summarized as follows:

- 490 (1) The nonlinear 3-D EVP model incorporating Yin (1999)'s nonlinear creep function and the
491 modified Cam-Clay model is suitable and accurate for simulating time-dependent
492 consolidation settlements of full-scale embankments on natural soft soils. The computed
493 settlements, horizontal displacements, and excess pore water pressure dissipation are
494 reliable and reasonable with comparisons to the in-situ measured data.
- 495 (2) The parametric studies reveal the importance of parameter selection in computational
496 simulations. Generally, the use of mean values of soil parameters (*e.g.* C_c , C_r , C_α) is the
497 optimal way for getting good modelling results.

- 498 (3) As for the long-term creep behaviour, $\Delta\varepsilon_l$ obtained from oedometer test is an important
499 parameter, although assuming $\Delta\varepsilon_l = \frac{e_0}{1+e_0}$ is still acceptable in a relatively short course.
- 500 (4) The update of static water pressure in fully coupled FE analysis has a major influence on
501 the simulation results. Without this option, the final settlements are severely overestimated.
- 502 (5) The Hypothesis A method and original simplified Hypothesis B method have obvious
503 limitations in the prediction of consolidation settlements for the highway embankments.
- 504 (6) The improved simplified Hypothesis B method considering stress diffusion and buoyancy
505 with two simple equations achieves reliable predictions compared with measured data and
506 FE simulations. Further improvements are recommended to include the shear behaviour
507 and the unloading-reloading behaviour of soils, towards a more rigorous yet easily-
508 implemented approach beyond the simple superposition for multi-staged loading cases.

509

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518

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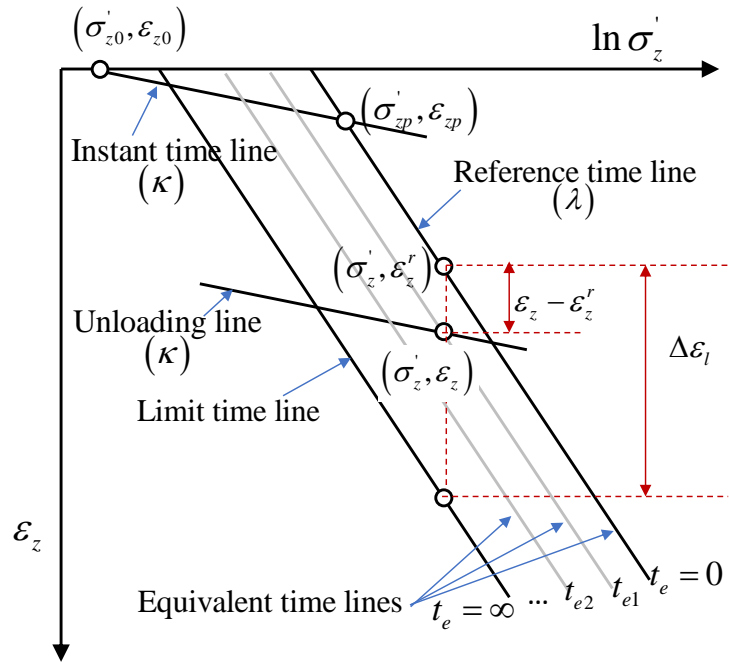


Fig.1. Schematic diagram of the 1-D EVP model

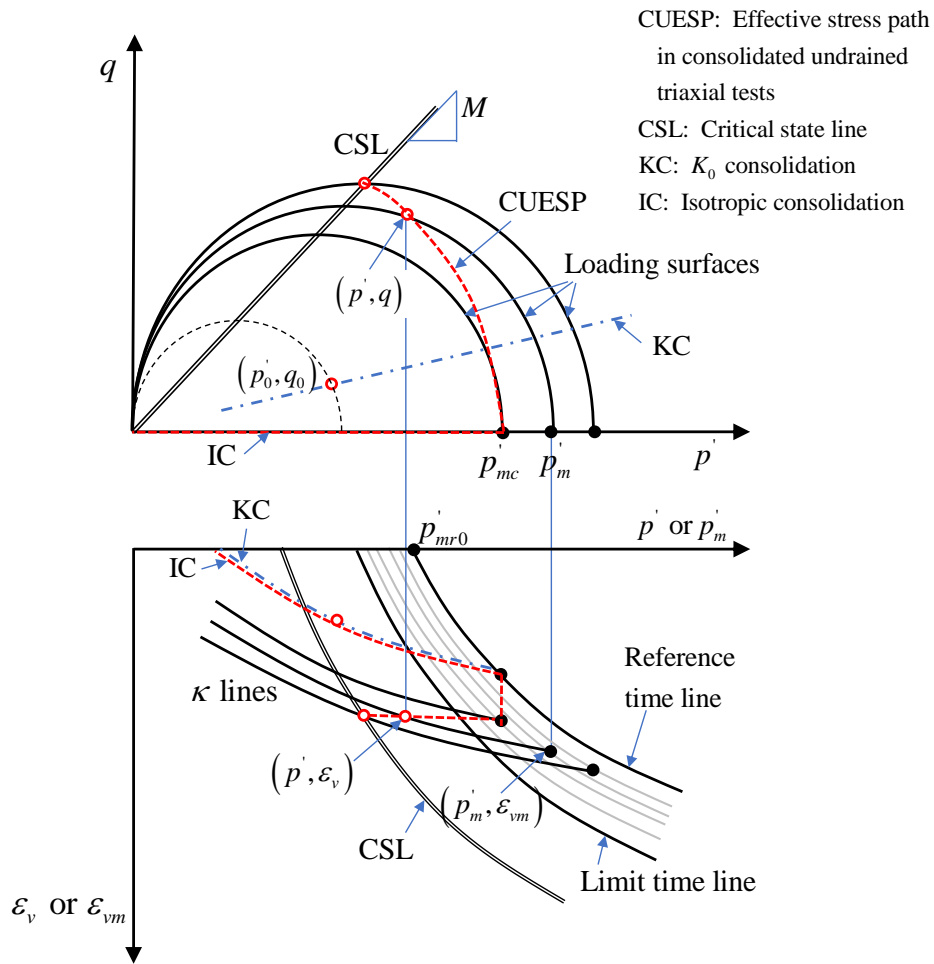


Fig.2. Schematic diagram of the 3-D EVP model

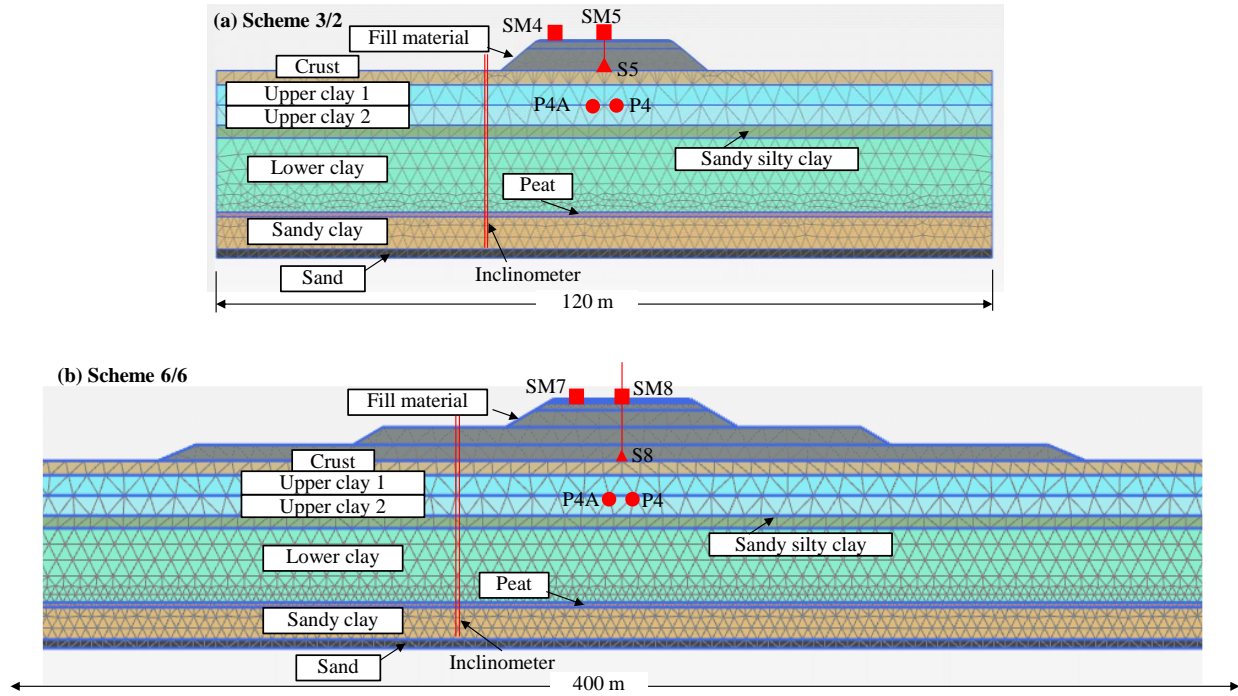


Fig.3. Profiles of the two embankments and their meshed numerical models

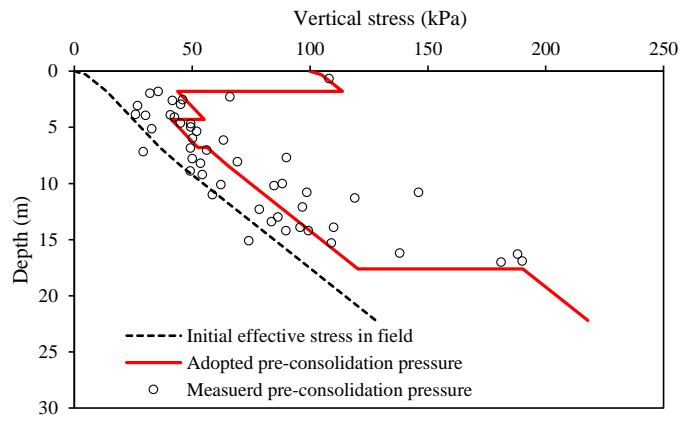


Fig.4. Initial effective stress and pre-consolidation pressure profiles of soils with depth (after MHA, 1989a)

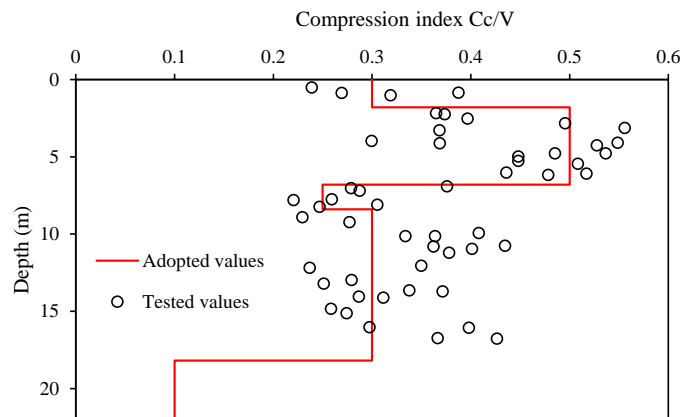


Fig.5. Compression index profile of soils with depth (after MHA, 1989a)

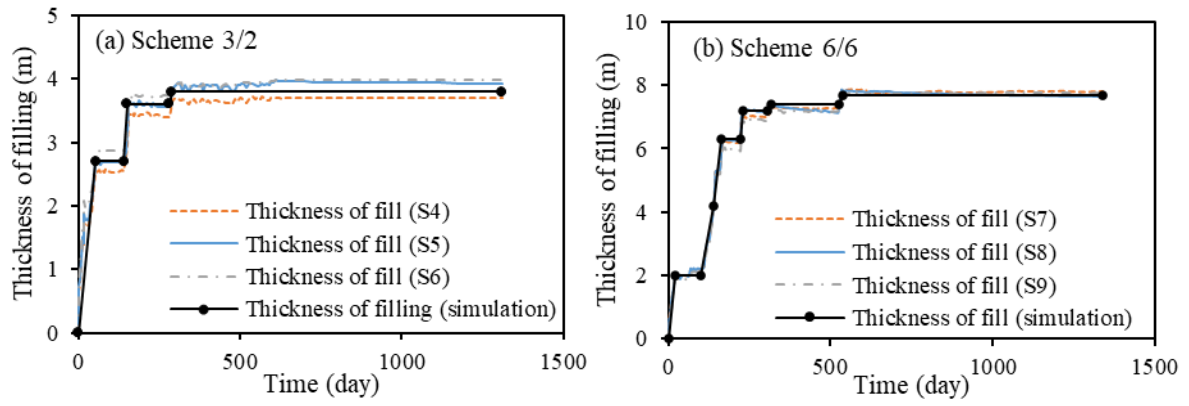


Fig.6. Thickness of fill with time at the center of embankments of Schemes 3/2 and 6/6

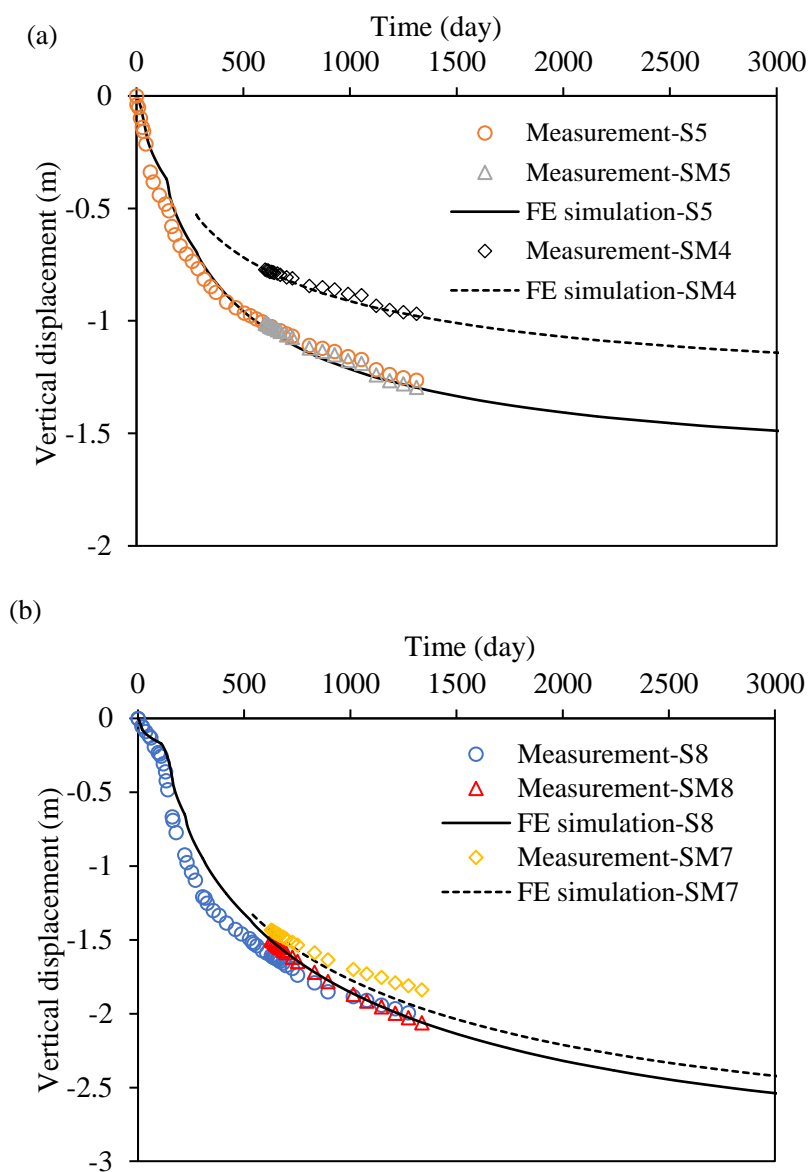


Fig.7. Vertical displacements (settlements) at the different positions of embankments with time by FE simulations and measurement: (a) Scheme 3/2 and (b) Scheme 6/6

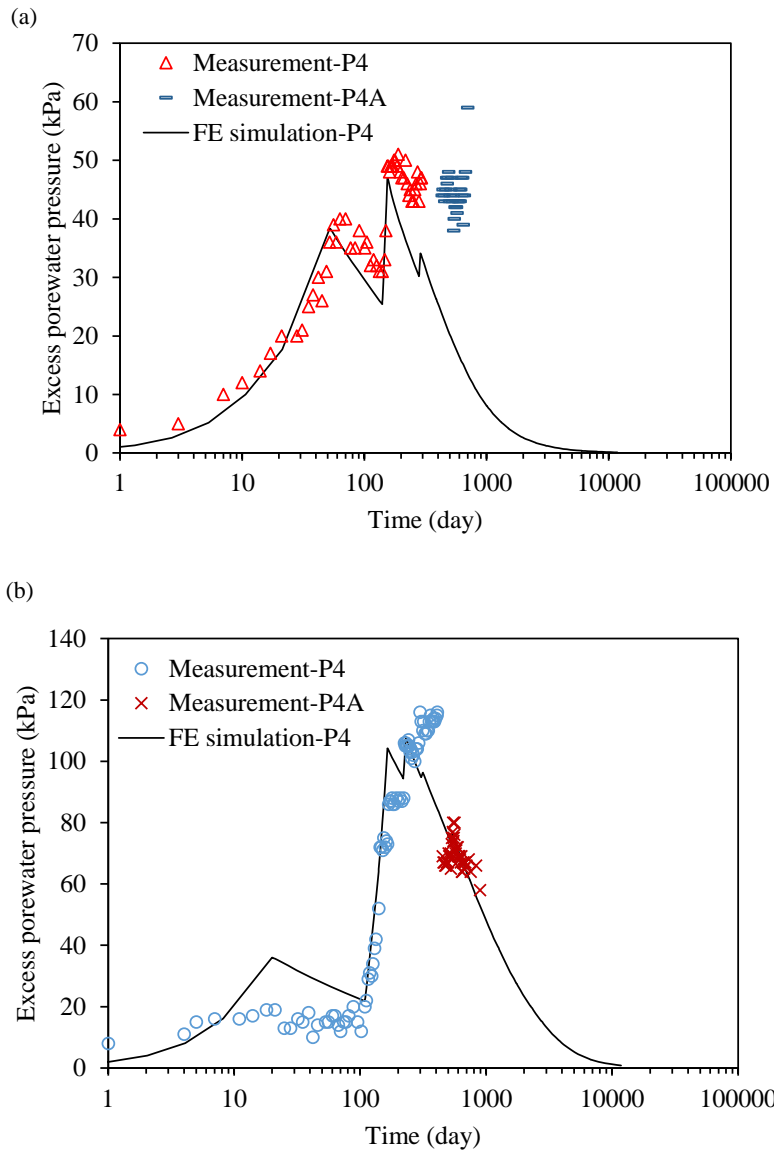


Fig.8. Excess pore water pressures with time by FE simulations and measurement: (a) Scheme 3/2 and (b) Scheme 6/6

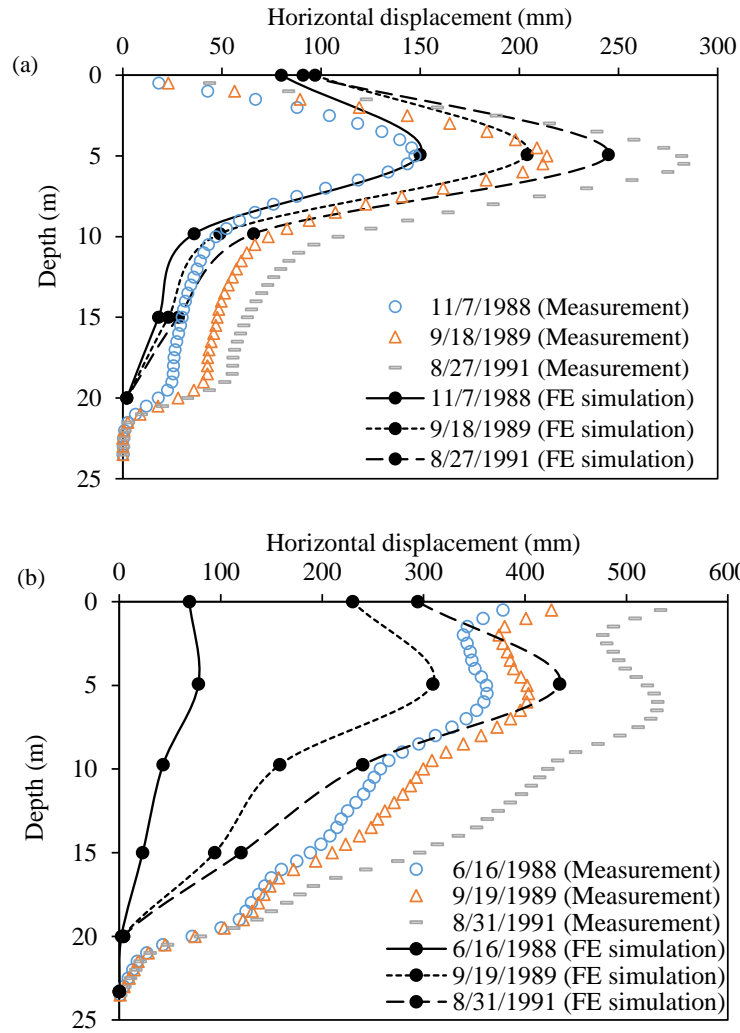


Fig.9. Profiles of horizontal displacements with depth on different dates by FE simulations and measurement: (a) Scheme 3/2 and (b) Scheme 6/6

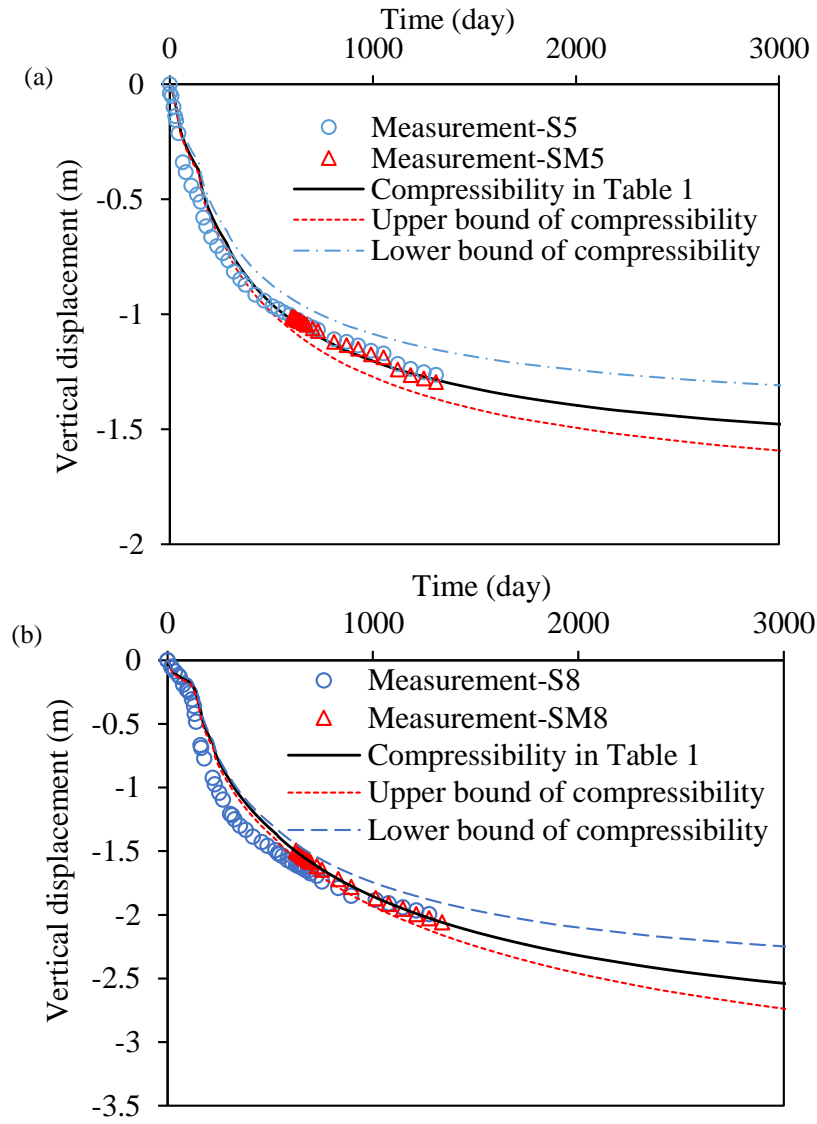


Fig.10. Effects of compressibility parameters on the settlement calculations: (a) Scheme 3/2 and (b) Scheme 6/6

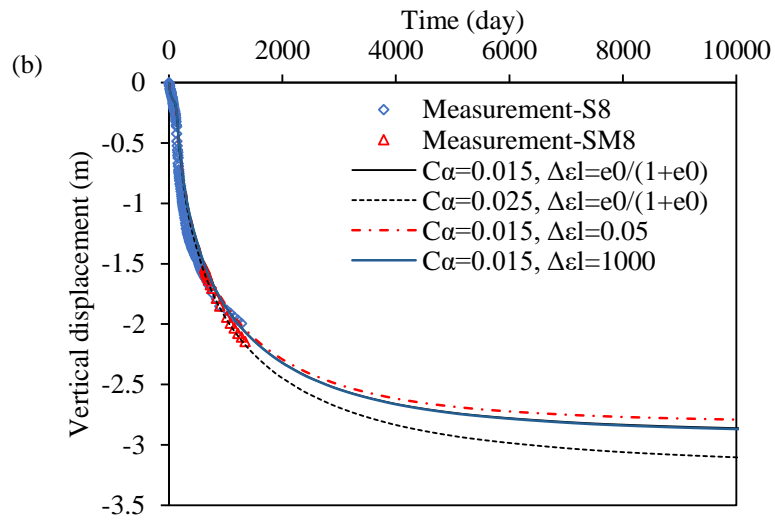
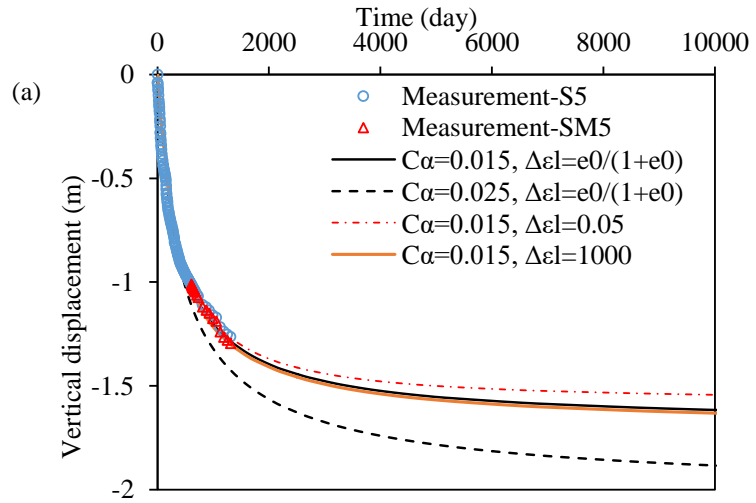


Fig.11. Effects of creep parameters on the settlement calculations: (a) Scheme 3/2 and (b) Scheme 6/6

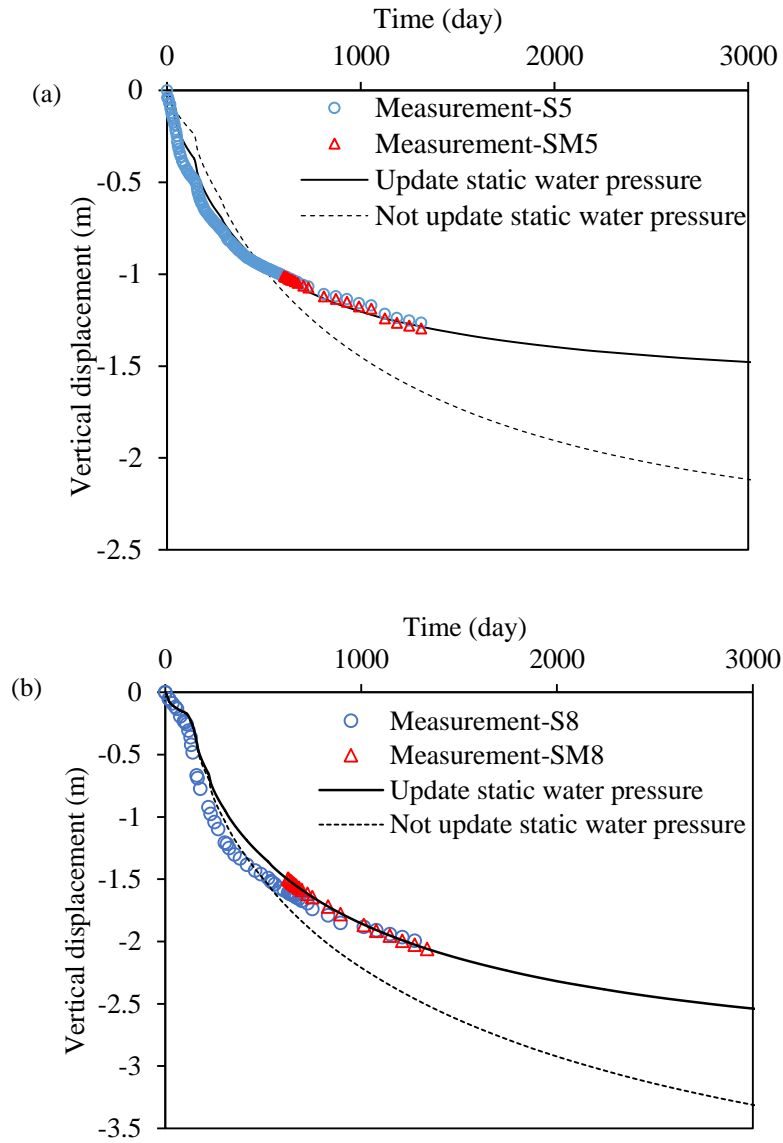


Fig.12. Effects of updating static water pressure on the settlement calculations: (a) Scheme 3/2 and (b) Scheme 6/6

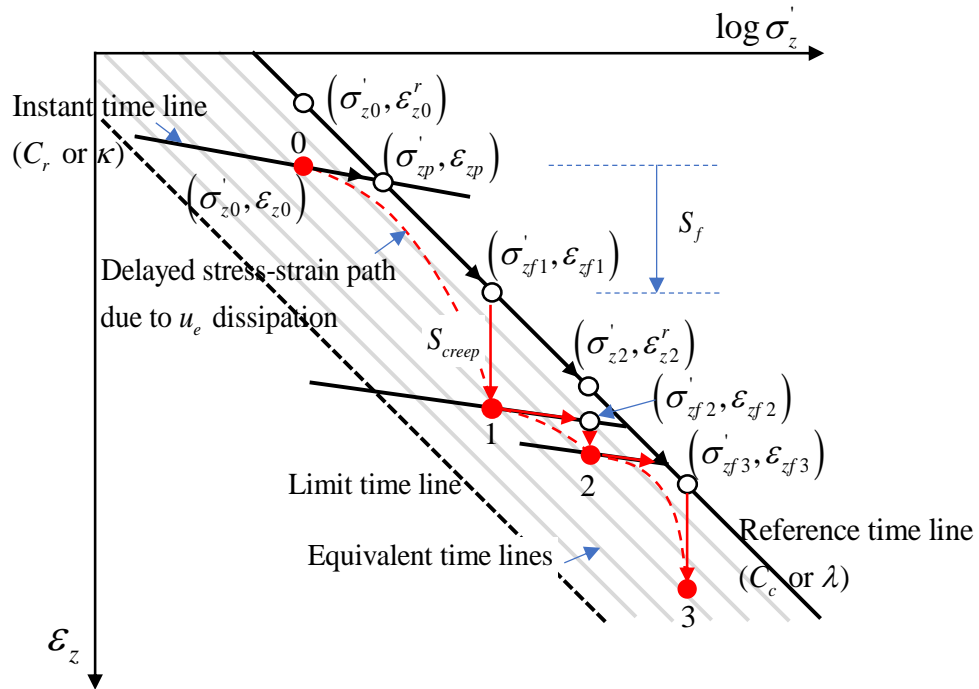


Fig.13. Calculation of creep compression in a 1-D simplified Hypothesis B method (SBM) for multi-staged loading (schematic diagram)

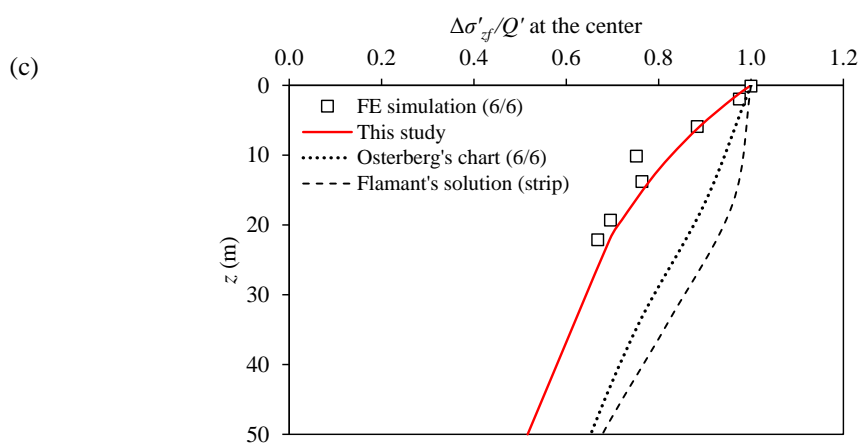
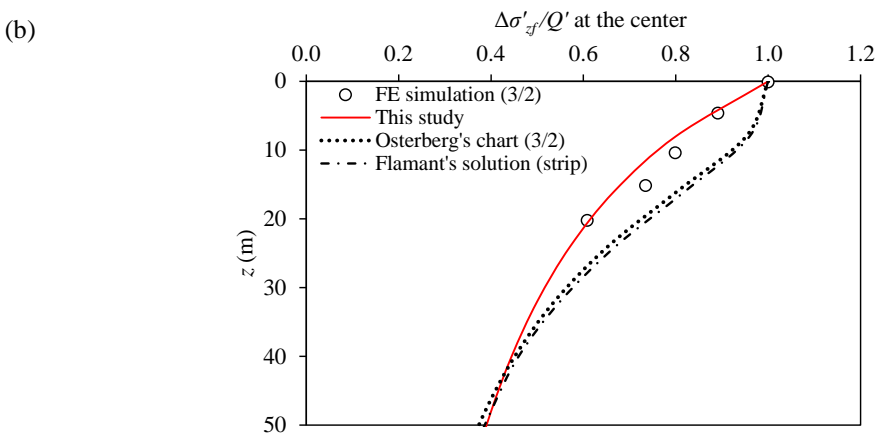
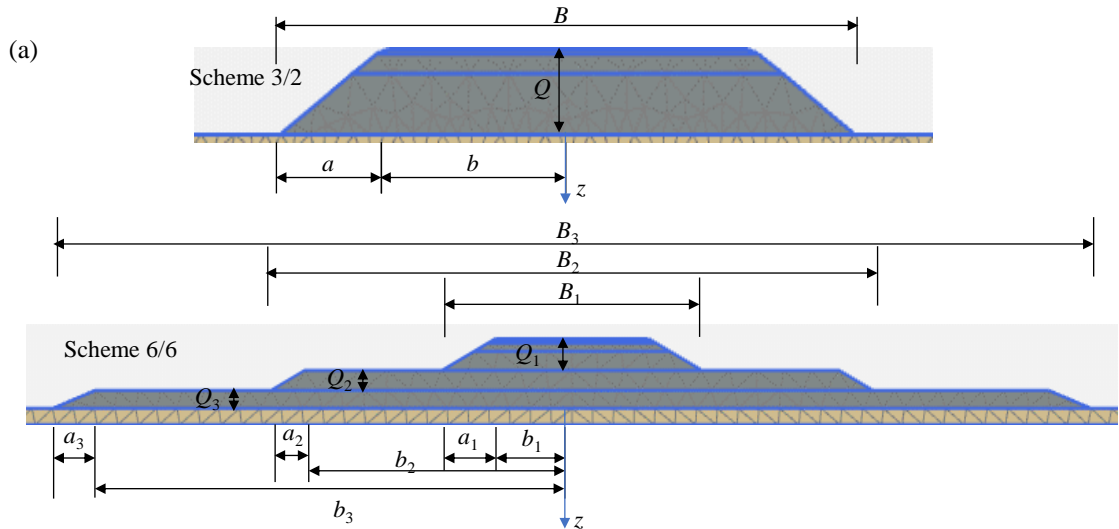


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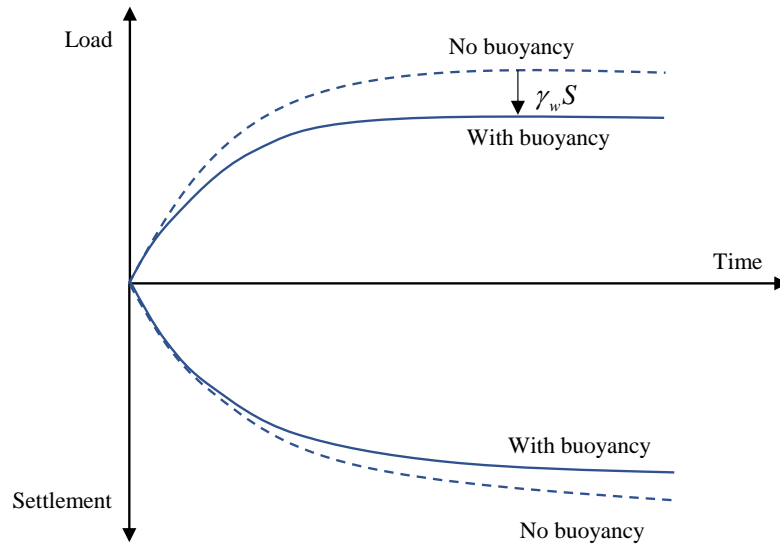


Fig.15. Illustration of buoyancy effect on the embankment loading

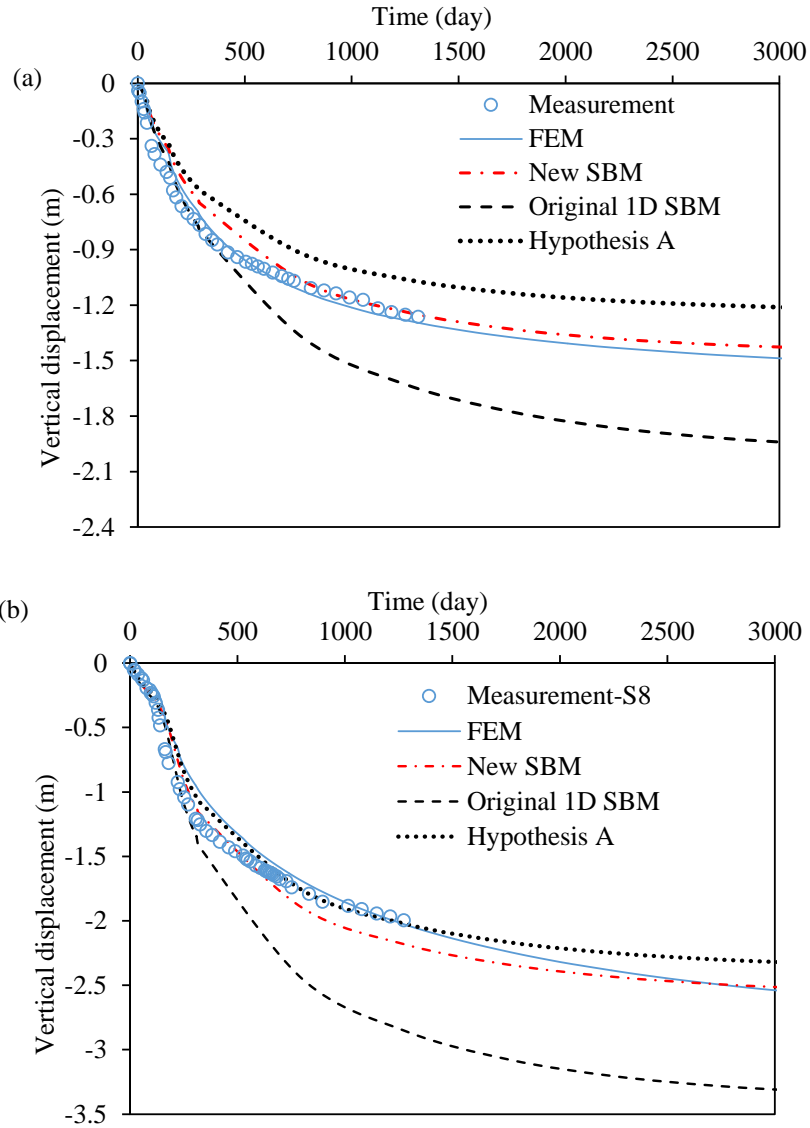


Fig.16. Vertical displacements (settlements) at the center from the simplified Hypothesis B method, FE simulations, and measurement: (a) Scheme 3/2 and (b) Scheme 6/6

