



## 19 **Introduction**

20 The mechanical behavior of granular materials is closely related to the characteristics of  
21 particles, such as size, shape, crushability, and packing (Jin et al. 2018; Kawamoto et al. 2018;  
22 Wang and Arson 2018; Xiao et al. 2019; Yang et al. 2018; Zhang et al. 2020; Zhou et al. 2013).  
23 Understanding the effect of these characteristics on the macroscopic behavior of granular  
24 materials is of significant importance for their engineering applications (Jin et al. 2016; Jin et  
25 al. 2018; Wang and Yin 2020; Yin et al. 2018; Zhang et al. 2019). It is well-acknowledged that  
26 particle size plays an important role in determining the macroscopic behavior of granular  
27 materials, which is called the particle size effect.

28 The effect of particle size on the macroscopic shear strength, as a fundamental issue of granular  
29 materials, has been extensively studied. Marsal (Marsal 1967) conducted a series of large-scale  
30 triaxial tests (specimens 113 cm in diameter) on three different rockfill materials which have  
31 parallel gradations. And he found that the specimen with a larger mean particle size has a lower  
32 shear strength. Later, Marschi *et al.* (1972) also performed triaxial tests on rockfill materials of  
33 different sizes. Different from Marsal's tests, Marschi *et al.* adjusted the size of specimens so  
34 that the ratio of maximum particle size and specimen size was fixed for all tests. The results  
35 showed that the peak shear strength decreases with the increase of particle size, and they  
36 proposed that the particle size effect is due to the increased amount of particle breakage in  
37 specimens with larger particles. This finding was later simulated and verified in (Hu et al. 2018;  
38 Yin et al. 2017). In the true triaxial tests on rockfill materials by Xiao *et al.* (Xiao et al. 2014),  
39 the friction angle was found to decrease with the increase of particle size. Results from other  
40 studies indicated that the particle breakage decreases the shear strength and is a source of  
41 particle size effect (Daouadji et al. 2001; Frossard et al. 2012; Lade and Bopp 2005). However,  
42 in some other studies, the opposite conclusion on the effect of particle size, i.e. the shear  
43 strength increases with the increase of particle size, was reported. Gupta found that the internal

44 friction angle of the river bed material increases with the increase of particle size. However,  
45 when he replaced the river bed material with blasted material, this angle decreases with particle  
46 size (Gupta 2016). Islam et al. (Islam et al. 2019) conducted a series of direct shear tests on  
47 particle samples with particle size ranging from 0.075 mm to 1.18 mm, and they found that  
48 both the shear strength and internal friction angle increase with the increase of particle size.  
49 Other studies (Alias et al. 2014; Cao et al. 2020) also stated that both the peak and residual  
50 shear strengths increase with particle size. The particle size effect was also investigated using  
51 the discrete element method (DEM) (Cil et al. 2020). Results showed that the peak shear  
52 strength increases with the increase of particle size while the residual strength is not affected  
53 by particle size (Jiang et al. 2018; Sitharam and Nimbkar 2000). In these simulations, however,  
54 particles were assumed uncrushable. To sum up, although efforts have been made to investigate  
55 the effect of particle size on the shear strength of granular materials, no consensus has been  
56 made reached on this issue. In addition, the influence of particle breakage on the size effect is  
57 still not clear.

58 The objective of this study is to investigate the particle size effect with the role of particle  
59 breakage. To achieve this goal, a series of biaxial tests are simulated with DEM on sand  
60 specimens of different particle sizes and reference tensile strengths. The flexible boundary  
61 imposed by the latex membrane in experiments is modeled by the flexible-bonded particle  
62 approach. The soil particles are crushable, and the crushing process obeys the sequential  
63 breakage model proposed by one of the authors (Wang et al. 2019). The macroscopic behavior  
64 in the biaxial tests with different particle sizes are compared and analyzed. In addition, particle  
65 breakage and its effect on shear strength are discussed in depth from micro to macro.

66

## 67 **DEM simulation of biaxial test considering particle breakage**

68 Particle breakage is a common phenomenon in civil engineering, pharmaceutical industry, and  
69 mineral industry (Chen et al. 2020; Coop et al. 2004; Wang and Arson 2016; Wang and Yin  
70 2020; Zhou et al. 2019). In a granular assembly, particle breakage occurs when the internal  
71 stress of a particle exceeds the material's strength. Particle breakage plays an important role in  
72 determining the properties and behaviors of granular materials, such as internal friction angle,  
73 permeability, yielding stress, volume change, etc. (Karatza et al. 2019; Lade et al. 1996;  
74 Shahnazari and Rezvani 2013; Yin et al. 2020). In recent years, the X-ray micro-computed  
75 tomography (X- $\mu$ CT), which allows the characterization of particle size, shape, movement and  
76 interaction nondestructively, has been widely used in the analysis of particle breakage (Seo et  
77 al. 2020; Zhao et al. 2020). The high-resolution images from X- $\mu$ CT have been successfully  
78 employed to identify broken particles, classify broken modes, and provide realistic particle  
79 shapes of fragments, and significantly expanded our knowledge on the micro-mechanisms of  
80 particle breakage (Alikarami et al. 2015; Druckrey and Alshibli 2016; Karatza et al. 2018).  
81 Despite its advantages in producing realistic and quantitative data of particle breakage, it is still  
82 challenging for X- $\mu$ CT to obtain the contact forces within a granular assembly, which play an  
83 important role in the determination of particle breakage. On the other hand, DEM could easily  
84 calculate the contact force between particles according to contact laws, and simulate the  
85 movement and breakage of particles. Another advantage of DEM is that it is very convenient  
86 to control the mechanical properties of soil particles (such as particle strength in this study),  
87 which significantly increases the controllability and repeatability of the virtual experiments.  
88 Therefore, the DEM is adopted in this study to analyze the particle size effect.

89 In the DEM model in this study, biaxial tests are simulated with sand specimens with a  
90 dimension of 9.7 mm $\times$ 2.34 mm $\times$ 18 mm. The specimens are prepared with the isotropic  
91 compression method, and the flexible-bonded particle approach is used to simulate the rubber

92 membrane in the experiment (Zhang et al. 2020). The model parameters were previously  
93 calibrated against the experimental results of biaxial tests on sand specimens by Alshibli and  
94 Sture (Alshibli and Sture 2000). Good agreement was achieved between the simulation results  
95 and experimental observation. Detailed information about the specimen preparation and  
96 calibration can be found in the Appendix of this paper. A summary of the DEM parameters  
97 used in the biaxial simulations is shown in Table 1.

98 In DEM, two common methods to simulate particle breakage are the cluster method and  
99 replacement method. In the cluster method, crushable particles are represented by bonded  
100 elements (usually elementary spheres), and particle breakage is simulated by the bond breakage.  
101 In this method, micro-cracks occur in a particle before a major breakage event and can be  
102 tracked by the number of broken bonds. The shape of fragments truly depends on the stress  
103 distribution in the crushable particle, but precise models are usually computationally expensive  
104 due to a large number of spheres in each cluster. In addition, the initial porosity of a specimen  
105 made of clusters is much higher than experimental measurements due to the internal voids. In  
106 the replacement method, once a particle breaks, it is replaced by several smaller fragments (Cil  
107 and Buscarnera 2016). The replacement method is more effective because the number of  
108 particles in DEM is equal to the number of soil particles. The size, shape and arrangement of  
109 fragments are often related to the contact forces and positions of the mother particle, and must  
110 be specified in the replacement model. And the conservation of mass and energy are also  
111 important considerations during the replacement.

112 The breakage model presented in Figure 1 is used for this study, which is a combination of  
113 cluster and replacement methods. This model was proposed by the authors in a previous study  
114 of particle breakage in oedometer test (Wang et al. 2019). Based on the sequential breakage  
115 mechanism characterized from XCT images of oedometer tests with zeolite particles, this

116 breakage model could simulate particle breakage of multiple generations with two different  
117 breakage modes, i.e. the particle splitting modeled by replacement method and the  
118 comminution modeled by bond breakage. In the first generation, the particle splits into two  
119 fragments once the maximum normal contact force reaches a threshold. Each fragment has a  
120 roughly hemispherical shape with 17 balls bonded with parallel bonds, as shown in Figure 1.  
121 The 17 balls are inscribed in the mother particle to minimize the mass (volume) loss in the  
122 replacement. The breakage plane is determined by the directions of principal stresses and the  
123 position of the contact with maximum normal force. In the following generations, breakage can  
124 be simulated with either replacement method or cluster method depending on the maximum  
125 normal contact force and stresses within parallel bonds. The mass loss is an important  
126 consideration in the replacement method, and previous studies show that it doesn't have a  
127 strong influence on simulation results when it is below a critical value, i.e. 47% according to  
128 Ciantia *et al.* (2015). A common assumption of the volume loss is that it is formed by fine  
129 particles generated during the breakage which have a small influence on the macroscopic  
130 mechanical behavior. The mass loss in the breakage model in Figure 1 is 46%, which is below  
131 the critical value. It is also important to mention that the internal voids within fragments  
132 account for a large portion of the mass loss, which has a very slight effect on the soil behavior.  
133 At last, it is also important to mention that there is also some energy loss in the replacement  
134 process, which does not have a significant effect on the simulation results under the quasi-static  
135 loading condition. As proved by many researchers, in a single particle crushing test, the  
136 strength of a particle increases when the particle size decreases (McDowell and Bolton 1998;  
137 Wang and Arson 2016). To account for this effect, the Weibull theory is adopted in this model  
138 to predict the strength for particles and parallel bonds of various sizes. To sum up, compared  
139 to previous breakage models, the current model has high computational efficiency without a  
140 large number of elementary balls at the beginning; considers multiple generations of breakage

141 under both splitting and comminution modes; contains non-spherical fragments made of  
142 bonded spherical particles. A detailed description of the failure mechanism and breakage model  
143 can be found in (Wang et al. 2019).

144 The main micro-mechanical parameters associated with the breakage model are the reference  
145 tensile strength in the Weibull theory ( $\sigma_{t0}$ ), the Weibull modulus ( $m$ ), the normal and shear  
146 bond strengths ( $\bar{\sigma}_c$  and  $\bar{\tau}_c$ ), the parallel bond normal and shear stiffnesses ( $\bar{k}_n$  and  $\bar{k}_s$ ). In this  
147 study,  $\sigma_{t0}$  represents the tensile strength of the particle with  $d=1$  mm, and it ranges from 1.5  
148 to 2.5 MPa in different tests to simulate particles with various crushability. Weibull modulus  
149 is chosen as 4.5 according to experimental results (Lobo-Guerrero and Vallejo 2006). Both  $\bar{\sigma}_c$   
150 and  $\bar{\tau}_c$  are assumed to follow the Weibull theory with the same  $\sigma_{t0}$  and  $m$  of soil particles.

151 The equivalent normal and shear stiffness,  $\pi R^2 \bar{k}_n$  and  $\pi R^2 \bar{k}_s$ , are also equal to the stiffness  
152 of soil particles. In order to reduce the computation cost, the smallest breakable particle size is  
153 set as 0.175 mm, which enables a maximum replacement generation of two. Particles below  
154 this size threshold are often excluded from force chains (Desu and Annabattula 2019), and have  
155 a very slight effect on the shear strength when they account for less than 20% total weight  
156 according to Habib et al. (Taha et al. 2019).

157 In this study, 32 biaxial tests are simulated with the above-mentioned sample preparation  
158 method and breakage model, which are summarized in Table 2. Both loose and dense  
159 specimens are simulated with  $d_{50}$  ranging from 0.22 to 0.55 mm are prepared. The following  
160 macro- and micro-mechanical analysis focus on the test results from S1 to S16 with the lower  
161 and upper bounding particle sizes of 0.22 and 0.55 mm. And tests S17 to S32 show similar  
162 behaviors. Parallel particle size distributions (PSDs) are used in the DEM simulations, in which  
163 cumulative particle weight curves are parallel to each other with different  $d_{50}$ . With this method,

164 each  $d_{50}$  corresponds to a specific PSD with a known shape for the cumulative particle weight  
165 curve. Therefore, for a given  $d_{50}$ , the DEM simulation could focus on the effect of particle size  
166 with an otherwise similar PSD. Besides crushable particles, uncrushable particles ( $\sigma_{t0}$  equal  
167 to infinity) are also used in some tests for comparison.

168

## 169 **Particle size effect**

### 170 **Particle size effect on shear strength**

171 Figure 2 shows the evolution of principal stress ratio ( $\sigma_1 / \sigma_3$ ) and volumetric strain with axial  
172 strain in the biaxial tests. In general, typical shear behaviors in experiments are successfully  
173 reproduced in the numerical tests. The tests with dense specimens exhibit obvious post-peak  
174 strain-softening behavior, while loose specimens only show hardening behavior. In terms of  
175 the volume change, tests with dense specimens slightly contract at first and then experience  
176 continuous dilation. Note that to main a constant particle volume in calculating the void ratio,  
177 the volume loss is simplified as virtual fine particles whose positions are assumed to be the  
178 same with the fragments generated from the same mother particle. With otherwise similar  
179 conditions, tests with dense specimens tend to have larger volumetric strains than the loose  
180 ones. The effect of particle breakage is obvious. As the reference tensile strength  $\sigma_{t0}$  decreases  
181 from 2.5 MPa to 1.5 MPa (increase crushability), the peak shear strength significantly  
182 decreases in coarse specimens ( $d_{50} = 0.55$  mm). As a result, the post-peak strain softening  
183 behavior becomes milder in tests S2 and S3 compared with that in tests S1, and even disappears  
184 in tests S4, as shown in Figure 2(a). On the other hand, the effect of  $\sigma_{t0}$  on the shear behaviors  
185 of specimens with  $d_{50} = 0.22$  mm is much less evident. When  $\sigma_{t0}$  is decreases, there is a very  
186 slight decrease in peak shear strength for the dense specimens (Figure 2(c)). For the loose



187 specimens, peak and residual shear strengths remain stable regardless of particle crushability  
188 (Figure 2(g)). This result can be attributed to the low crushability for fine particles. Previous  
189 studies show that the strengths of sand particles follow the Weibull statistics, and large particles  
190 are more vulnerable to breakage due to lower tensile strengths (Huang et al. 2020; Wang and  
191 Arson 2016). In the biaxial tests in this study, the percentage of crushed particles is higher in  
192 specimens with  $d_{50} = 0.55$  mm than that in specimens with  $d_{50} = 0.22$  mm, which is consistent  
193 with the results from previous studies and explains the significant decrease of peak shear  
194 strength for coarse particles with the increase of particle crushability. The detailed information  
195 on particle breakage during the biaxial tests will be presented in the next subsection.

196 The peak and residual stress ratios in the biaxial tests are summarized in Figure 3(a) and (b)  
197 respectively for the dense and loose specimens. It is evident from the figures that particle  
198 breakage plays an important role in determining the shear strength. For the dense specimens in  
199 Figure 3(a), the peak stress ratio increases with the increase of particle size when there is  
200 no/very slight particle breakage (uncrushable particles or particles with  $\sigma_t = 2.5$  MPa and 2.0  
201 MPa). However, when the particle crushability is high ( $\sigma_t = 1.5$  MPa), the peak stress ratio  
202 decreases with the increase of particle size. On the other hand, the particle breakage has a very  
203 low effect on the residual shear strength. In Figure 3(a), tests with different particle crushability  
204 ( $\sigma_t$ ) exhibit a similar residual stress ratio, and this ratio slightly increases with particle size.  
205 This result is consistent with another study in which a relatively stable residual state was found  
206 for tests with different particle crushability (Ma et al. 2016). In terms of loose specimens in  
207 Figure 3(b), the peak and residual stress ratios are similar because there is no shear band  
208 formation. In addition, both peak and residual stress ratios slightly increase with the increase  
209 of particle size, despite the difference in particle crushability. In other words, the particle size  
210 effect is very mild in loose specimens.

## 211 **Evolution of particle breakage**

212 Particle breakage has a strong influence on the shear strength of granular materials, and it is  
213 often deemed as the reason for the particle size effect (Daouadji et al. 2001; Hassanlourad et  
214 al. 2008; Xiao et al. 2014). To illustrate this mechanism, the evolution of particle breakage in  
215 the biaxial tests with different particle sizes and reference tensile strengths are presented and  
216 discussed.

217 Figure 4 and Figure 5 show the particle displacement and crushed particles in dense specimens  
218 at the end of shearing (tests S1 and S5 are not presented due to no particle breakage). It can be  
219 seen from the figures that the sand specimens are separated into several blocks with distinct  
220 particle displacements, and inter-particle shear movement mainly happens at the interface  
221 between the contacting blocks. The interfaces between these blocks have strong localization of  
222 shear deformation and are usually called shear bands (Alshibli and Sture 1999; Zhu and Yin  
223 2019). Different types of shear bands are observed in the tests, such as parallel band in S2 and  
224 S3, reflected band in S4, diagonal band in S6 and S7, and X-shaped band in S8. It is worth  
225 noting that all these patterns of shear bands are common in experiments (Desrues and Viggiani  
226 2004), and the difference comes from the various microscopic imperfections in the specimens.  
227 Particle breakage occurs in all the tests, but the number and locations of crushed particles are  
228 strongly affected by the reference tensile strength  $\sigma_{t0}$ . In general, the number of crushed  
229 particles increases with the decrease of  $\sigma_{t0}$ . In tests S2 and S6 with  $\sigma_{t0}$  equal to 2.5 MPa, the  
230 percentages of crushed particles are very low and no obvious region of concentration of crushed  
231 particles can be identified. As  $\sigma_{t0}$  decreases to 2.0 MPa (tests S3 and S7), the number of  
232 crushed particles is increased and the crushed particles tend to concentrate in the regions of  
233 shear bands. A further decrease of  $\sigma_{t0}$  to 1.5 MPa significantly increases the number of

234 crushed particles, as shown by the results of tests S4 and S8 respectively in Figure 4(c) and  
235 Figure 5(c).

236 The particle displacement and crushed particles in loose specimens, i.e. tests S10 to S12 are  
237 presented in Figure 6. Note that because tests S14 to S16 show similar evolution patterns with  
238 tests S10 to S12, their results are not repeated here. Different from the failure pattern in dense  
239 specimens in Figure 4 and Figure 5, no obvious shear band can be observed in the loose  
240 specimens. In addition, the lateral expansion of loose specimens is much milder than the dense  
241 ones. The positions of crushed particles are randomly distributed in the whole specimen,  
242 compared with those concentrated within in the shear band for dense specimens. As expected,  
243 the number of crushed particles increases with the decrease of the reference tensile strength. In  
244 addition, extensive particle breakage occurs near the top and bottom loading platens, see Figure  
245 6(c). This phenomenon is in agreement with experimental observations in (Karatza et al. 2019;  
246 Tsoungui et al. 1999), which can be explained by the lower coordination number for the  
247 particles near the loading platen (Wang and Arson 2016).

248 The evolutions of particle breakage ratio (number of crushed particles/ number of total particles)  
249 and bond breakage ratio (number of broken bonds/ number of total bonds) with axial strain in  
250 different tests are summarized in Figure 7. The particle breakage ratio describes the percentage  
251 of particles that are subjected to splitting failure. For dense specimens in Figure 7(a) and (b),  
252 the particle breakage ratio increases rapidly at the early stage of shearing until reaching a peak  
253 stress ratio. In the post-peak softening stage, particle breakage ratio continues to increase but  
254 at a slower rate. While for the loose specimens in Figure 7(c) and (d), the breakage ratio  
255 increases with vertical strain in an almost linear pattern. The final breakage ratio is very  
256 sensitive to the reference tensile strength of particles. For example, the final breakage ratio  
257 increases by around 500% with  $\sigma_{t0}$  decreasing from 2.5 MPa in S10 to 1.5 MPa in S12. In

258 addition, the particle size also has a strong influence on the final breakage ratio. Compared the  
259 results from coarse specimens in Figure 7(a) with those from fine specimens in Figure 7(b), the  
260 increase of particle size results in a significant increase in the particle breakage ratio. Besides  
261 the splitting failure, the comminution is also one of the important failure modes of sand  
262 particles (Seo et al. 2020) and can be qualitatively characterized by the bond breakage ratio  
263 (Harireche and McDowell 2003). In all the tests in Figure 7(e) to (h), the bond breakage ratios  
264 increase rapidly at the beginning of tests, and soon reach a relatively stable value until the end  
265 of the tests. In other words, the percentage of particles subjected to comminution failure  
266 remains almost constant during the test. In addition, similar to the particle breakage ratio, the  
267 bond breakage ratio also increases with the decrease of  $\sigma_{t0}$ . Note that because a particle may  
268 have several bonds within a cluster, a bond breakage does not guarantee the generation of new  
269 fragments. It is well-known that particle breakage is always accompanied by volumetric  
270 compression (Coop et al. 2004; Lade et al. 1996), and therefore a specimen with higher  
271 breakage ratio and bond breakage ratio usually has a lower shear strength.

272 Besides the particle breakage ratio, the position of particle breakage is also important because  
273 the shear failure of a crushable granular material is often associated with the breakage  
274 concentration within the shear band. The crushed particles at different loading strains in test  
275 S8 are shown in Figure 8. At the very early stage of shearing ( $\varepsilon_{zz} = 1\%$ ), only a small amount  
276 of particles are crushed, which are randomly distributed within the specimen. At the peak state  
277 ( $\varepsilon_{zz} = 3\%$ ), an increased number of particles are crushed, as shown in Figure 8(b). Due to the  
278 particle breakage, strong force chains cannot develop within the specimen. Therefore,  
279 specimens with a low reference tensile strengths ( $\sigma_{t0}$ ) usually have a reduced peak strength.  
280 At this stage, although the number of crushed particles accounts for more than 50% of the final  
281 crushed particles at the end of the test, there is no obvious breakage concentration. In the post

282 peak stage, as the vertical strain continues to increase, particle breakage starts to concentrate  
283 in the two diagonal directions forming an X-shape shear band. At this stage, because the  
284 deformation of the specimen mainly localizes in the shear band region, the shear resistance is  
285 dominated by the interparticle shear force at the interface. As the vertical strain continues to  
286 increase from 10% to 15%, almost all breakage happens within the shear band.

287 The particle size distributions at different stages in dense specimens are presented in Figure 9.  
288 In all the tests, as the strain increases, particles continue to break, generating smaller particles  
289 and increasing fine contents. At the same time, the distributions move leftward due to the  
290 reduction of large particles. Similar shift patterns of distribution curves are often observed in  
291 tests with crushable granular materials (Einav 2007; Wei et al. 2018). As the reference tensile  
292 strength decreases from 2.5 MPa to 1.5 MPa, an obvious increase of fine content can be  
293 observed. It is worth mentioning that to avoid high computational cost the minimum particle  
294 size is set as 0.022 mm.

295

## 296 **Micromechanical analysis**

297 In this section, the particle size effect will be further investigated at the microscale. Because  
298 the failure and shear strength of a specimen is closely related to the development of shear band,  
299 the location of shear band should be determined first. In this study, the grain rotation based  
300 method proposed by one of the authors is adopted to identify the shear band (Zhu and Yin  
301 2019). In this method, particles with high rotation are determined based on the particle rotation  
302 distribution  $\beta_v(\omega)$ , which is defined as the volumetric percentage of particles with a rotation  
303 angle larger than  $\omega$  in a small loading increment. And the zone with a concentration of high  
304 rotation particles is the location of shear band. Figure 10 shows the evolution of void ratio  
305 inside shear band along with vertical strain for dense specimens. In order to obtain the void

306 ratio inside shear band, a number of measure spheres are placed within shear band, and the  
307 average measured void ratio is adopted. Note that loose specimens are not showing because no  
308 shear band is generated in biaxial tests with loose specimens. As shown in Figure 10, void  
309 ratios in different specimens are similar at the beginning, and then start to diverge at the vertical  
310 strain of 3%. With otherwise similar conditions, the specimen with uncrushable particles yields  
311 the highest void ratio inside shear band. The final void ratio decreases with the decrease of  
312 particle strength. The results are reasonable as the voids among large particles are filled with  
313 fines produced by breakage. Similar results that particle breakage decreases the dilation of  
314 granular materials is also reported in (Ghafghazi et al. 2014; Yu 2017). Therefore, the  
315 volumetric dilation of shear band, which is induced by the rearrangement of particles and  
316 contributes to the shear strength, is weakened by particle breakage. In terms of the particle size  
317 effect, the final void ratio increases with the increase of particle size when  $\sigma_{t0}$  is high, such as  
318 0.815 for S5 and 0.84 for S1. However, when the particles are weak and vulnerable to breakage,  
319 the final void ratio decreases with particle size, such as 0.79 for S8 and 0.77 for S4. This  
320 relationship is consistent with the macroscopic volume change in Figure 2.

321 Previous studies showed that the coordination number is closely related to the particle breakage,  
322 and particles with a high coordination number are more resistive to breakage (Lim and  
323 McDowell 2007). Figure 11 shows the evolutions of coordination number in tests S1 and S3.  
324 Before shearing, the coordination number is around 5.1 for particles inside and outside of shear  
325 band. For both tests with uncrushable (S1) and crushable (S3) particles, the coordination  
326 number decreases significantly at the beginning of shearing and then becomes stable. The  
327 decrease of the coordination number can be explained by the dilation of the dense specimens  
328 during the biaxial shear tests. As expected, particles inside the shear band have a lower  
329 coordination number compared to particles outside. In addition, particles in test S3 have a  
330 higher average coordination number than that in S1 due to particle breakage. According to

331 Figure 7(a) and 7(c), extensive particle breakage happens with the vertical strain ranging from  
332 0.01 to 0.05 in test S3, which corresponds to a coordination number in the range from 4.0 to  
333 4.4. This observation is in agreement with previous studies based on XCT that splitting and  
334 fragmentation are the dominant modes when the coordination number is less than 5.6 (Karatza  
335 et al. 2019). In other tests, the evolutions of coordination number are similar and the particle  
336 size shows a very slight effect on the coordination number.

337 According to previous studies, the interparticle friction force plays an important role in the  
338 shear resistance of granular material, and the specimen with a larger interparticle friction  
339 coefficient tends to have higher shear strength (Antony and Kruyt 2009; Huang et al. 2014;  
340 Yang et al. 2012). Therefore, the friction utilization ratio,  $u_{UR}$ , is proposed here to investigate  
341 the relationship between interparticle friction force and shear strength. The friction utilization  
342 ratio is defined as the ratio of current interparticle shear force ( $F_s$ ) and maximum shear force  
343 ( $F_{s\_max}$ ). With the linear contact model in this study,  $F_{s\_max}$  is given as  $\mu F_n$ , where  $F_n$  is the  
344 interparticle normal force. For a sand specimen, particle contacts have different  $u_{UR}$  depending  
345 on their stress states. A specimen with a higher average  $u_{UR}$  usually indicates that stronger  
346 resistance to particle movement and rearrangement, and thus has a higher shear strength. The  
347 probability density functions of friction utilization ratio and the average ratio of all contacts are  
348 shown in Figure 12. It is clear from the figure that although the specimens have different  
349 particle sizes and reference tensile strengths, they share a similar distribution for the friction  
350 utilization ratio. From Figure 12(a), the  $u_{UR}$  decreases with the decrease of reference tensile  
351 strength of particles, indicating a lower percentage of shear resistance capacity has been used  
352 to resist the external loads. As a result, the peak shear also decreases with a low reference  
353 tensile strength of particles. Compare the results in Figure 12(a) and (b), when the mean particle  
354 size increases from 0.22 to 0.55 mm,  $u_{UR}$  also increases in tests with low particle crushability

355 (S5 versus S1, S6 versus S2, and S7 versus S3). While in test S4 and S8 with high particle  
356 crushability,  $u_{UR}$  decreases with the increase of particle size. This relationship is consistent  
357 with the relationship between particle size and peak stress ratio in Figure 3. For the loose  
358 specimens in Figure 12(c) and (d), the  $u_{UR}$  is always lower than those of the corresponding  
359 dense specimens. Therefore, loose specimens have lower peak strengths than the corresponding  
360 dense specimens.

361

## 362 **Conclusions**

363 In this study, a series of biaxial tests have been conducted with DEM to explore the particle  
364 size effect of sand. The soil particles are crushable, and the crushing process obeys the  
365 sequential breakage model proposed by one of the authors (Wang et al. 2019). The shear  
366 strength in tests with different particle sizes and reference tensile strengths have been compared  
367 and analyzed. Then the evolution of particle breakage and its relationship with shear strength  
368 has been discussed. Finally, the micro-mechanical analysis in terms of void ratio inside shear  
369 band and interparticle shear force has been conducted. The main conclusions of this study are:

370 (1) For a granular assembly, the relationship of peak shear strength and particle size depends  
371 on the crushability of particles and the relative density of specimens. The shear strength of a  
372 dense specimen increases with the increase of particle size when particles are uncrushable or  
373 strong (have a high reference tensile strength). On the other hand, when the crushability of  
374 particles is high, the shear strength decreases with the increase of particle size. In addition, the  
375 particle size effect is very mild in loose specimens.



376 (2) The particle size and crushability have a very slight effect on the residual shear strength of  
377 granular material. After shearing, the residual strengths of both loose and dense specimens are  
378 similar, despite of the obvious differences in particle size, relative density, and crushability.

379 (3) At the microscale, the relationship of shear strength and particle size is positively related to  
380 the friction utilization ratio. The friction utilization ratio generally describes to what extent the  
381 capacity to resist interparticle sliding is utilized. This ratio generally increases with the increase  
382 of particle size, which results in an increasing peak shear strength. However, when there is  
383 extensive particle breakage, the friction utilization ratio as well as peak strength decrease with  
384 the increase of particle size.

385

## 386 **Data Availability Statement**

387 All data, models, or code that support the findings of this study are available from the  
388 corresponding author upon reasonable request.

389

## 390 **Acknowledgement**

391 The financial support provided by the GRF project (Grant No. 15209119, R5037-18F) from  
392 the Research Grants Council (RGC) of Hong Kong is gratefully acknowledged.

393

## 394 **Appendix: Calibration of DEM samples and parameters**

### 395 **DEM Samples**

396 The schematic diagram of the model for biaxial tests is shown in Figure A1(a). The PSDs in  
397 DEM simulations and experiments are shown in Figure A1(b), with average particle sizes of

398 0.22 mm and 0.55 mm respectively for F-sand and M-sand. The method proposed by Wood  
399 and Maeda (Wood and Maeda 2008) to calculate the maximum and minimum void ratios in  
400 2D is slightly modified to account for the 3D condition in this study. Firstly, a large number of  
401 randomly generated particles are subjected to an isotropic compression of 100 kPa with the  
402 inter-particle friction coefficient equal to 0.0. Once the system becomes stable, the inter-  
403 particle friction coefficient is changed to the final value (0.5) and then the DEM calculation  
404 starts again. After the system reaches equilibrium, the current void ratio of the specimen is  
405 determined as the minimum void ratio ( $e_{\min}$ ). Similarly, the loosest specimen with the  
406 maximum void ratio ( $e_{\max}$ ) can be generated in the same way with the inter-particle friction  
407 coefficient set as 1.0 during the initial isotropic compression. Then the DEM model for biaxial  
408 test is prepared as follows: (1) particle generation at specified relative density; (2) isotropic  
409 compression until a target confining pressure of 100 kPa; (3) flexible boundary replacement  
410 according to the flexible-bonded particle approach (Zhang et al. 2020).

411 After the generation process, the specimen is sheared by moving the top and bottom walls  
412 towards the specimen, and the constant confining pressure is kept by applying forces to the  
413 membrane particles. The membrane is made of equal-sized particles with simple cubic packing,  
414 and the radii of these particles are 0.11 mm. The overlap between contacting particles is 0.5  
415 times the radius, i.e. 0.0505 mm. To avoid the soil particles puncturing the flexible membrane,  
416 a high value is chosen for both the tensile and shear strengths of the parallel bonds. The  
417 magnitude of force applied to a membrane particle is the product of the equivalent area of the  
418 particle and the confining pressure. The forces applied to the membrane particles are  
419 continuously adjusted during the simulation to account for an evolving equivalent area. For the  
420 two walls in the Y direction, their positions are fixed to provide a plane strain condition. The  
421 test stops when the axial strain reaches 15%.

## 422 DEM Parameters

423 The DEM model was calibrated against the results of biaxial tests by Alshibli and Sture  
424 (Alshibli and Sture 2000). The calibrated parameters will be briefly introduced in the following.

425 The particle density  $\rho$  is chosen as  $2650 \text{ kg/m}^3$ , which is close to natural sands. The normal  
426 and shear stiffness of particles,  $k_n$  and  $k_s$ , are  $5 \times 10^7 \text{ N/m}$  to guarantee that the average  
427 overlap ratio, defined as the ratio of overlap length and particle diameter, is lower than 1%.

428 Note that the linear contact model with a fixed stiffness rather than the nonlinear elastic model  
429 is adopted for this study, because the bulk behavior of granular materials is qualitatively similar

430 with either model according to the comparisons made by the authors and Ji *et al.* (2006). The  
431 friction coefficient of soil particles,  $\mu$ , is chosen as 0.5 as a rule of thumb. In order to consider

432 the particle shape of sand particles in the experiments, the rolling resistance method is adopted  
433 for soil particles. Rather than physically approximating the angular particles with clusters or

434 clumps, the rolling resistance method is a numerical method to simulate the non-spherical  
435 particles (Ai *et al.* 2011; Yang *et al.* 2017). In this method, a rotational torque is applied to

436 resist the rolling at the contact to account for the interlocking between the two contacting  
437 angular particles. The rolling resistance coefficient ( $\mu_r$ ), contact effective radius ( $\bar{R}$ ), and

438 normal contact force ( $F_n$ ) determine the maximum limiting value of the torque as  $\mu_r \bar{R} F_n$ .

439 Previous studies showed that this method is able to reproduce both macro- and microscopic  
440 behaviors of granular material with a coefficient smaller than 0.3, beyond which the mechanical

441 properties remains almost the same (Liu *et al.* 2018; Zhao *et al.* 2018). In this study, the  
442 calibrated  $\mu_r$  for the particle-particle and particle-wall contacts are respectively 0.15 and 0.0.

443 The values of  $\mu_r$  do not change during the tests, and the particle shape evolution is ignored for  
444 simplicity. It is also assumed that  $\mu_r$  at the particle-wall contact is 0.0. The stiffness of the

445 parallel bond,  $\bar{k}_n$  and  $\bar{k}_s$ , are set as  $1.0 \times 10^{10} \text{ N/m}^3$ , so that the equivalent normal and shear

446 stiffness, given by  $\pi R^2 \bar{k}_n$  and  $\pi R^2 \bar{k}_s$ , are much lower than soil particles. The tensile and shear  
447 strengths of parallel bonds are  $1.0 \times 10^{27}$  N/m<sup>2</sup>, which is high enough to avoid soil particles  
448 puncturing the flexible membrane. A summary of the DEM parameters used in the biaxial  
449 simulations is shown in Table 1.

450 The macroscopic behaviors from DEM simulation and experiments are shown in Figure A1(c)  
451 and (d). For both dense and medium dense specimens, the DEM simulations and experiments  
452 have a reasonable good match in terms of the evolutions of principal stress ratio and volumetric  
453 strain.

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671



672 **Tables**

673

**Table 1. Parameters used in DEM simulations**

Particle type	Parameters	Values
Soil particle	Density $\rho$ (kg/m <sup>3</sup> )	2650
	Normal and shear stiffness $k_n$ and $k_s$ (N/m)	$5 \times 10^7$
	Frictional coefficient $u$ (-)	0.5
	Rolling resistant coefficient $\mu_r$ (-)	0.15
	Density $\rho$ (kg/m <sup>3</sup> )	800
Membrane particle	Normal and shear stiffness of parallel bond $\bar{k}_n$ and $\bar{k}_s$ (N/m <sup>2</sup> )	$1.0 \times 10^{10}$
	Frictional coefficient $u$ (-)	0.0
	Normal and shear strength of parallel bond $\bar{\sigma}_c$ and $\bar{\tau}_c$ (N/m <sup>2</sup> )	$1.0 \times 10^{27}$

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**Table 2. Summary of biaxial tests conducted with DEM**

Test name	$d_{50}$ (mm)	$\sigma_{r0}$ (MPa)	Relative density	Test name	$d_{50}$ (mm)	$\sigma_{r0}$ (MPa)	Relative density
S1	0.55	$\infty$	89.0%	S17	0.30	$\infty$	89.0%
S2	0.55	2.5	89.0%	S18	0.30	2.5	89.0%
S3	0.55	2.0	89.0%	S19	0.30	2.0	89.0%
S4	0.55	1.5	89.0%	S20	0.30	1.5	89.0%
S5	0.22	$\infty$	89.0%	S21	0.40	$\infty$	89.0%
S6	0.22	2.5	89.0%	S22	0.40	2.5	89.0%
S7	0.22	2.0	89.0%	S23	0.40	2.0	89.0%
S8	0.22	1.5	89.0%	S24	0.40	1.5	89.0%
S9	0.55	$\infty$	44.5%	S25	0.30	$\infty$	44.5%
S10	0.55	2.5	44.5%	S26	0.30	2.5	44.5%
S11	0.55	2.0	44.5%	S27	0.30	2.0	44.5%
S12	0.55	1.5	44.5%	S28	0.30	1.5	44.5%
S13	0.22	$\infty$	44.5%	S29	0.40	$\infty$	44.5%
S14	0.22	2.5	44.5%	S30	0.40	2.5	44.5%
S15	0.22	2.0	44.5%	S31	0.40	2.0	44.5%
S16	0.22	1.5	44.5%	S32	0.40	1.5	44.5%

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677

678 **Figure captions**

679 Figure 1. Schematic diagram of breakage model with the combination of replacement and  
680 cluster method

681 Figure 2. Principal stress ratio and void ratio versus vertical strain from biaxial tests on: dense  
682 specimens with  $d_{50}=0.55$  mm ((a) and (b)); dense specimens with  $d_{50}=0.22$  mm ((c)  
683 and (d)); loose specimens with  $d_{50}=0.55$  mm ((e) and (f)); loose specimens with  
684  $d_{50}=0.22$  mm ((g) and (h))

685 Figure 3. Effect of particle size on the peak and residual principal stress ratio of dense  
686 specimens (a) and loose specimens (b) (note that (a) and (b) share the same legend)

687 Figure 4. Particle displacement field and crushed particles for test S2 (a), S3 (b) and S4 (c)

688 Figure 5. Particle displacement field and crushed particles for test S6 (a), S7 (b) and S8 (c)

689 Figure 6. Particle displacement field and crushed particles for test S10 (a), S11 (b) and S12  
690 (c)

691 Figure 7. Evolution of particle breakage ratio ((a) to (d)) and bond breakage ratio ((e) to (h))  
692 in biaxial tests

693 Figure 8. Crushed particles at different loading strains in test S8 at 1% (a); 3% (b); 10% (c);  
694 15% (d)

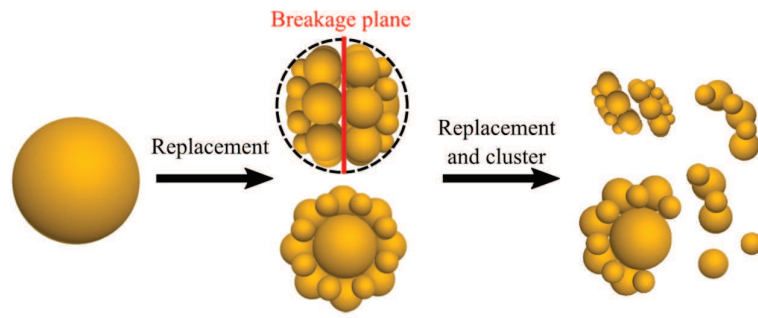
695 Figure 9. Particle size distribution of dense crushable specimens at different vertical strains:  
696 (a)S2 and S6; (b) S3 and S7; (c) S4 and S8

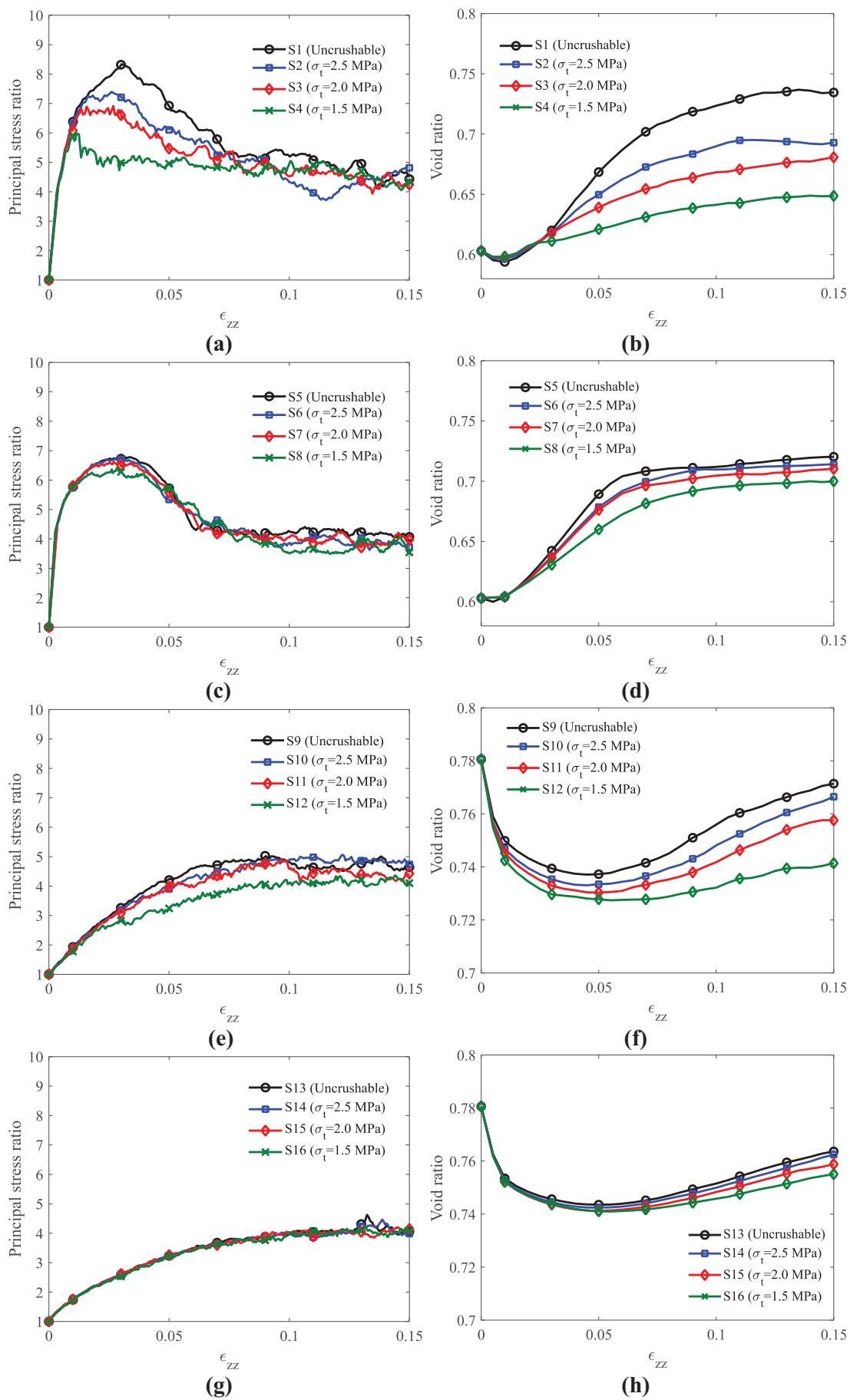
697 Figure 10. Evolution of void ratio inside shear band in biaxial tests with dense specimens for:  
698 tests S1 to S4 with  $d_{50}=0.55$  mm (a); tests S5 to S8 with  $d_{50}=0.22$  mm (b)

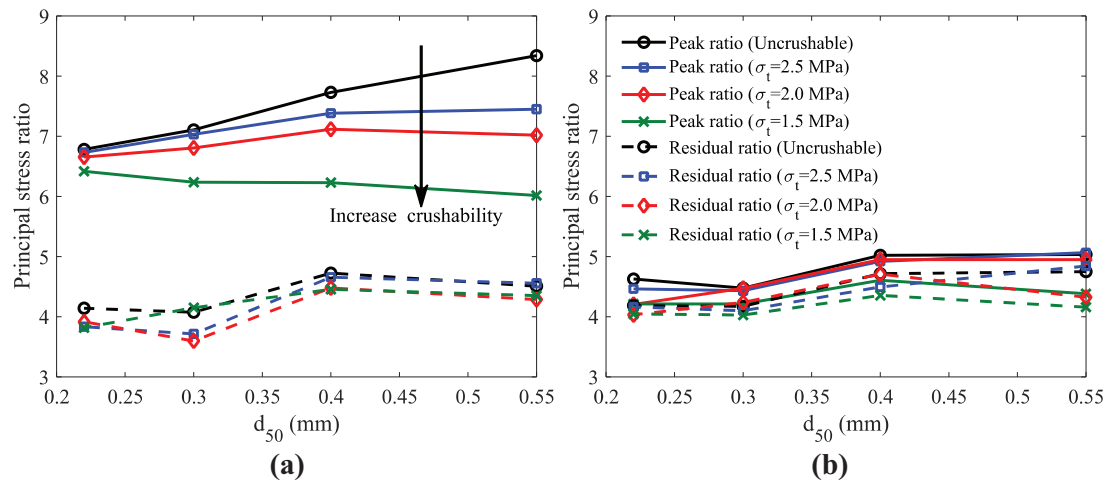
699 Figure 11. Evolution of coordination number in test S1 (a) and test S3 (b)

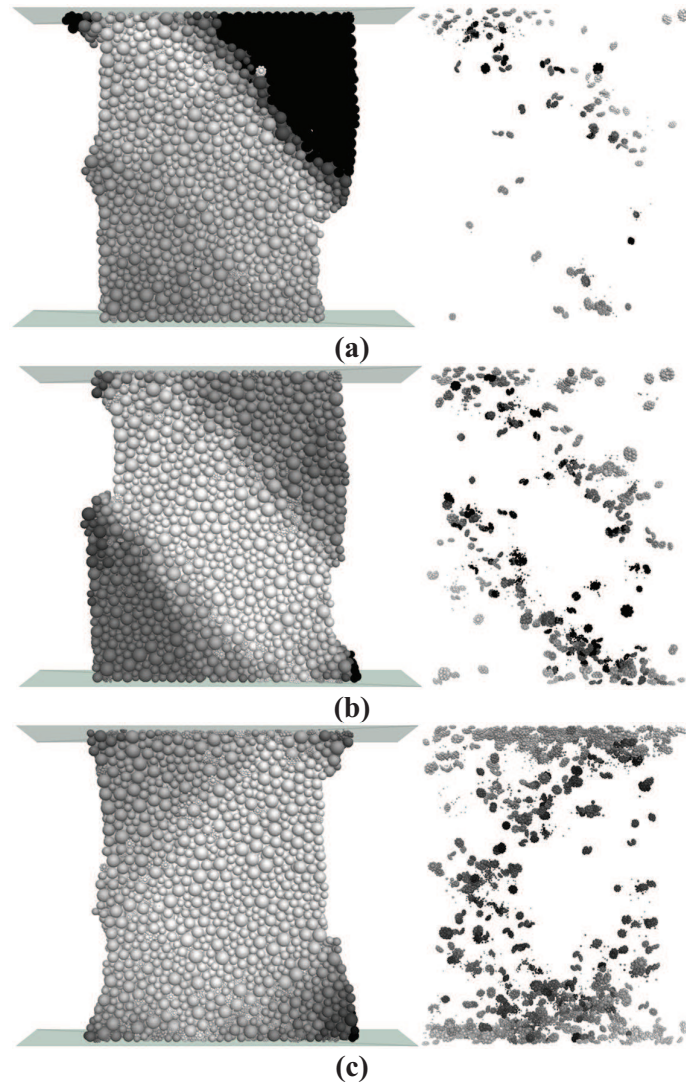
700 Figure 12. Probability density functions of friction utilization ratios at peak state for: tests S1  
701 to S4 with  $d_{50}=0.55$  mm at dense state (a); tests S5 to S8 with  $d_{50}=0.22$  mm at dense  
702 state (b); tests S9 to S12 with  $d_{50}=0.55$  mm at loose state (c); tests S13 to S16 with  
703  $d_{50}=0.22$  mm at loose state (d)

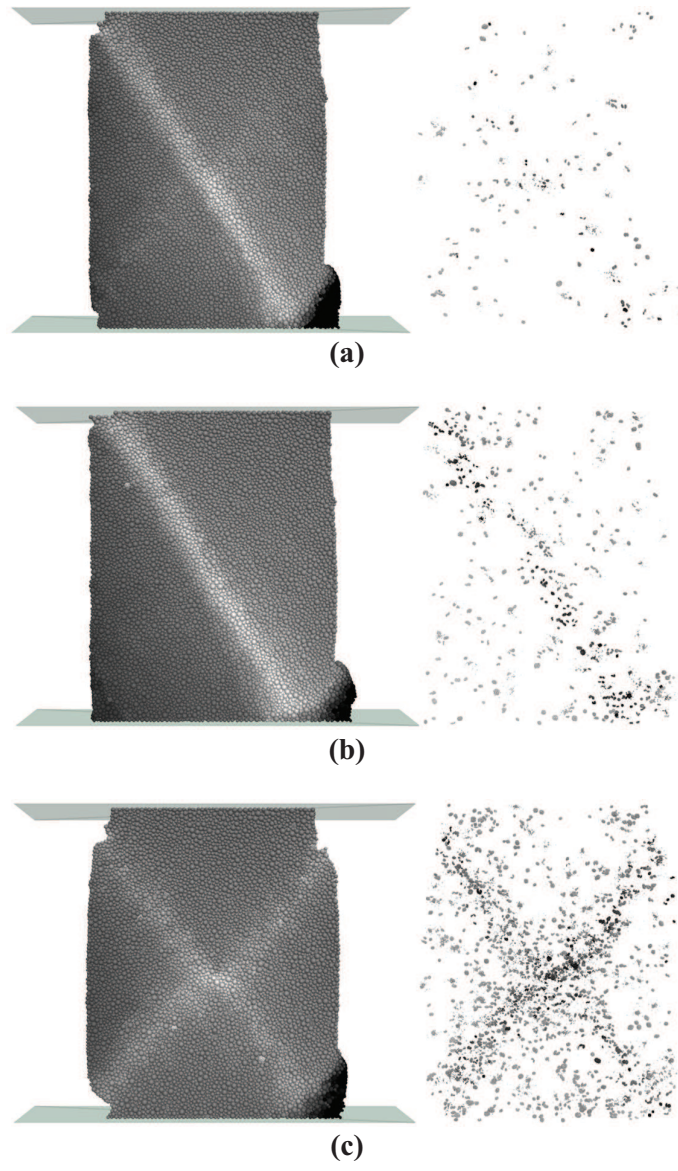
704 Figure A1: (a) Equivalent area of a particle; (b) grain size distribution of soil samples; (c) and  
705 (d) comparison of the results of biaxial tests from experiments and DEM simulations



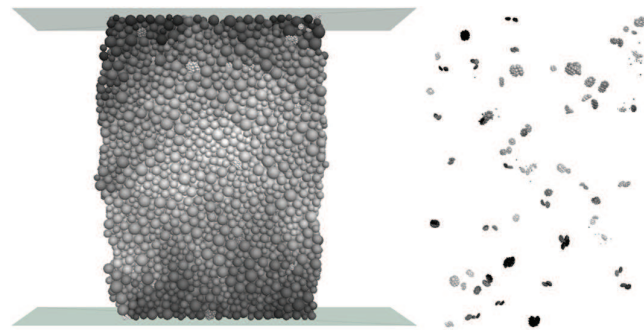




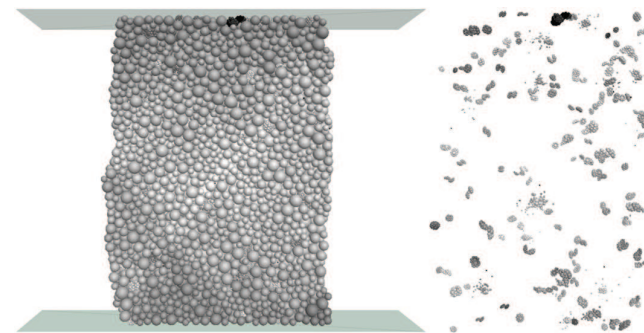




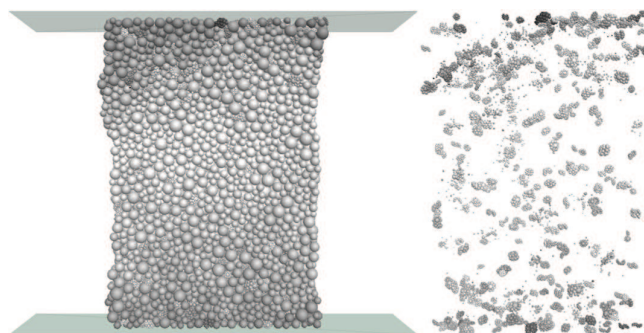




(a)



(b)



(c)

