

# Coupling deep learning and multi-objective genetic algorithms to achieve high performance and durability of direct internal reforming solid oxide fuel cell

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## Abstract

Direct internal reforming (DIR) operation of solid oxide fuel cell (SOFC) reduces system complexity, improves system efficiency but increases the risk of carbon deposition which can reduce the system performance and durability. In this study, a novel framework that combines a multi-physics model, deep learning, and multi-objective optimization algorithms is proposed for improving SOFC performance and minimizing carbon deposition. The sensitive operating parameters are identified by performing a global sensitivity analysis. The results of parameter analysis highlight the effects of overall temperature distribution and methane flux on carbon deposition. It is also found that the reduction of carbon deposition is accompanied by a decrease in cell performance. Besides, it is found that the coupling effects of electrochemical and chemical reactions cause a higher temperature gradient. Based on the parametric simulations, multi-objective optimization is conducted by applying a deep learning-based surrogate model

as the fitness function. The optimization results are presented by the Pareto fronts under different temperature gradient constraints. The Pareto optimal solution set of operating points allows a significant reduction in carbon deposition while maintaining a high power density and a safe maximum temperature gradient, increasing cell durability. This novel approach is demonstrated to be powerful for the optimization of SOFC and other energy conversion devices.

**Keywords:** Solid oxide fuel cell; Carbon deposition; Deep learning; Multi-objective optimization; Global sensitivity analysis

## Nomenclature

$c_p$	specific heat capacity, $\text{kJ kg}^{-1} \text{K}^{-1}$
$D$	gas diffusivity, $\text{m}^2 \text{s}^{-1}$
$E_{\text{eq}}$	open circuit voltage, V
$F$	faraday's constant, $\text{C mol}^{-1}$
$J$	electrochemical reaction rate, $\text{A m}^{-3} \text{s}^{-1}$
$K$	permeability, $\text{m}^2$
$j_0$	exchange current density, $\text{A m}^{-3}$
$n_e$	number of electrons transferred per reaction
$p$	gas pressure, Pa or atm
$P$	power density, $\text{W m}^{-2}$
$R$	universal gas constant, $\text{J mol}^{-1} \text{K}^{-1}$
$R_B$	Boudouard reaction rate, $\times 10^{-6} \text{mol g}_{\text{cat}}^{-1} \text{s}^{-1}$
$R_{\text{MC}}$	methane cracking reaction rate, $\times 10^{-6} \text{mol g}_{\text{cat}}^{-1} \text{s}^{-1}$

1	$S$	source term, $\text{kg m}^{-3} \text{s}^{-1}$ , $\text{mol m}^{-3} \text{s}^{-1}$ or $\text{W m}^{-3}$
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3		
4	$S_i$	Sobol sensitivity index
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6	$T$	temperature, K
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8		
9	$V$	variance
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11		
12	$x$	mole fraction
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14		
15	$y$	mass fraction
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18	Greek letters	
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20		
21	$\alpha$	transfer coefficient in anode
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24	$\varphi_{\text{ele}}$	electric potential, V
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27	$\varphi_{\text{ion}}$	ionic potential, V
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29		
30	$\gamma$	adjustable parameter
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33	$\eta$	overpotential, V
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35		
36	$\kappa$	thermal conductivity, $\text{W m}^{-1} \text{K}^{-1}$
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38	$\sigma$	conductivity, $\text{S m}^{-1}$
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41	$\mu$	viscosity, $\text{kg m}^{-1} \text{s}^{-1}$
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44	$v$	velocity, $\text{m s}^{-1}$
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47	$\rho$	density, $\text{kg m}^{-3}$
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49	Subscripts and superscripts	
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52	a	anode
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55	act	activation
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58	avg	average
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1	c	cathode
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3	eff	effective
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5	ele	electron
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7	f	fluid
8		
9	grad	gradient
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11	i	gas species
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13	ion	ion
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15	m	reaction order
16		
17	ohm	ohmic
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19	op	operating
20		
21	out	output
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23	s	solid
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### Abbreviations

25	ANN	artificial neural network
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27	CDR	carbon deposition rate
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29	DIR	direct internal reforming
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31	DL	deep learning
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33	DNN	deep neural network
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35	GSA	global sensitivity analysis
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37	MOGA	multi-objective genetic algorithm
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39	MSR	methane steam reforming reaction
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1	RMSE	root-mean square error
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3	R <sup>2</sup>	squared correlation coefficient
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6	SOFC	solid oxide fuel cell
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9	S/M	steam/methane ratio
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12	WGS	water gas shift
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## 1. Introduction

19 Growing concerns over fossil fuel shortages and environmental issues have led to widespread  
20 interest in new environmental-friendly power generation technologies [1]. Among these  
21 technologies, the Solid Oxide Fuel Cells (SOFCs) enable a direct transformation of the  
22 chemical energy of the fuel into electricity and heat by the high-efficiency electrochemical  
23 reactions [2]. The high operating temperature (600-1000 °C) confers SOFCs an advantage of  
24 being the most attractive subsystem of combined heat and power systems [3].

33 The Ni-based composite exhibits high electrocatalytic activity and has good thermal and  
34 chemical stability, thus becoming the most commonly used anode material [4]. The Ni phase  
35 is also a good catalyst for a variety of internal reforming reactions, while the high temperature  
36 can facilitate the cleavage of chemical bonds. This gives SOFCs excellent fuel flexibility and  
37 also offers the possibility for direct internal reforming (DIR) of hydrocarbon fuels [5], i.e.,  
38 methane. The DIR can significantly reduce the total cost and complexity of the SOFC systems.  
39 As the heat generated by SOFC can be effectively utilized for endothermic reforming reaction  
40 occurring in the anode, the DIR also helps improve the SOFC system overall efficiency. But at  
41 the same time, the use of hydrocarbon fuels can cause carbon deposition in the SOFC anode,  
42 which may block the passage for gas transport or even destroy the anode structure, degrading  
43 the SOFC performance and durability. For methane fueled SOFCs, two main carbon deposition

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reactions are involved inside the anode:



According to the typical operating conditions of SOFCs, the amorphous carbon is the most possible form of carbon deposition [6]. As the amount of carbon deposition increases, a carbon film can be formed on the surface of Ni catalyst and cover the electrochemical active sites, which will result in severe performance degradation. In recent years, substantial research has been conducted on alleviating the impact of carbon deposition [7-10]. Several constructive strategies have been proposed, including the development of carbon-resistant anode materials by replacing Ni-based catalyst with perovskite oxides or by modifying/doping the Ni-based catalysts [7,8], adding a mix-conducting interlayer between electrolyte and anode [9], and using a separate on-cell catalyst reforming layer on the top of the support layer [10].

In addition to the material and structure optimizations, the easiest and most cost-effective strategy is to identify proper operating conditions with a low risk of carbon deposition [11]. Adding a large amount of steam to hydrocarbon fuels to achieve a large steam/carbon ratio (S/C) and lowering the operating temperature have been proven to efficiently inhibit carbon deposition [12]. Suitable operating conditions are one of the necessary prerequisites to suppress carbon deposition and improve cell performance. Some studies have used numerical approaches such as thermodynamic analysis to qualitatively characterize the carbon deposition process [13-17]. The C-H-O ternary diagram is often used to determine the carbon deposition boundary of SOFCs fueled with hydrocarbons [13]. Muramoto et al. [14] systematically constructed the C-H-O diagrams of high-pressure SOFCs and determined the carbon deposition regions under high operating pressure. Subotić et al. [15] depicted the carbon deposition boundary considering different forms of carbon formation in the C-H-O diagram. In addition,

1 carbon activity is often used as an important indicator to assess whether carbon deposition can  
2 occur or not [16,17]. However, the above methods can only qualitatively predict the possibility  
3 of carbon deposition and cannot be used as a tool for quantitative optimization.  
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7 Generally speaking, there is a trade-off between cell durability and performance, and the same  
8 is true for carbon deposition. Increasing S/C and reducing operating temperature is not  
9 favorable for maintaining high cell performance and system efficiency, so optimization work  
10 must be performed under conditions that take into account both cell performance and carbon  
11 deposition. However, this type of optimization is challenging by experimental investigation,  
12 considering the time and cost involved in extensive experimental testing. For comparison,  
13 numerical approaches are very powerful tools for SOFCs performance prediction and  
14 parameter optimization, e.g., a large number of multi-scale models have been developed and  
15 used for design optimization at microstructure level [18], single-cell or stack level [19-21], and  
16 system-level [22,23]. Numerical studies have also been carried out on the catalytic reactors  
17 [24,25] and DIR-SOFC, such as applying Generalized Least Squares method to study  
18 methane/steam reforming kinetics [26], developing a transient model to study the transient  
19 response of reforming reactions inside cell [27], establishing a microstructure-oriented  
20 mathematical model to investigate the multi-physics transport phenomena at a microscopic  
21 perspective [28]. However, these approaches are usually computationally intensive and  
22 challenging to achieve multi-objective optimization of cell performance and carbon deposition  
23 as described above. Combining multi-physics models with relevant data-driven algorithms  
24 such as machine learning and genetic algorithms can be an effective methodology [29]. For  
25 example, some studies have employed genetic algorithms to reformers to achieve optimal  
26 catalyst distribution [30], improve efficiency [31] and reduce carbon deposition [32]. However,  
27 no such optimization of parameters for achieving both high performance and durability of  
28 direct internal reforming SOFC (DIR-SOFC) can be found in the literature.  
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In this paper, a novel optimization framework is proposed for improving the electrochemistry and carbon deposition performance of DIR-SOFC. This framework combines multiple numerical methods, such as the multi-physics model, machine learning algorithm, global sensitivity analysis (GSA), and multi-objective genetic algorithm (MOGA). The experimentally validated multi-physics model comprehensively considers the internal heat and mass transfer process as well as chemical and electrochemical reactions. The dataset generated by the multi-physics model is used to train a deep neural network (DNN) to get a surrogate model. Then the global sensitivity analysis is performed to find the most sensitive operating parameters. Finally, the MOGA with constraint-handling strategy is applied to find the optimal trade-off between cell output performance and carbon deposition under a certain temperature gradient. This optimization process can also be applied to the performance optimization of a wide range of energy conversion devices.

## 2. Methods

### 2.1 Framework for the DIR-SOFC optimization

Fig. 1 shows the optimization flowchart for cell performance and carbon deposition. First, by comprehensively considering the internal heat and mass transfer processes as well as chemical and electrochemical reactions, a multi-physics model of DIR-SOFC is developed to obtain the cell performance under different operating conditions. Next, the validated physical model is used to perform the parametrical analysis and to generate the datasets for training the deep learning-based surrogate model. The trained deep neural network can accurately characterize the relationship between inputs (operating conditions) and outputs (cell performance parameters). Then the surrogate model is integrated into a sensitivity analysis algorithm to identify the significance of operating conditions. Meanwhile, a multi-objective optimization is carried out by setting the surrogate model as a fitness function to obtain the optimum trade-off solution that maximizes cell performance and minimizes the risk of carbon deposition.



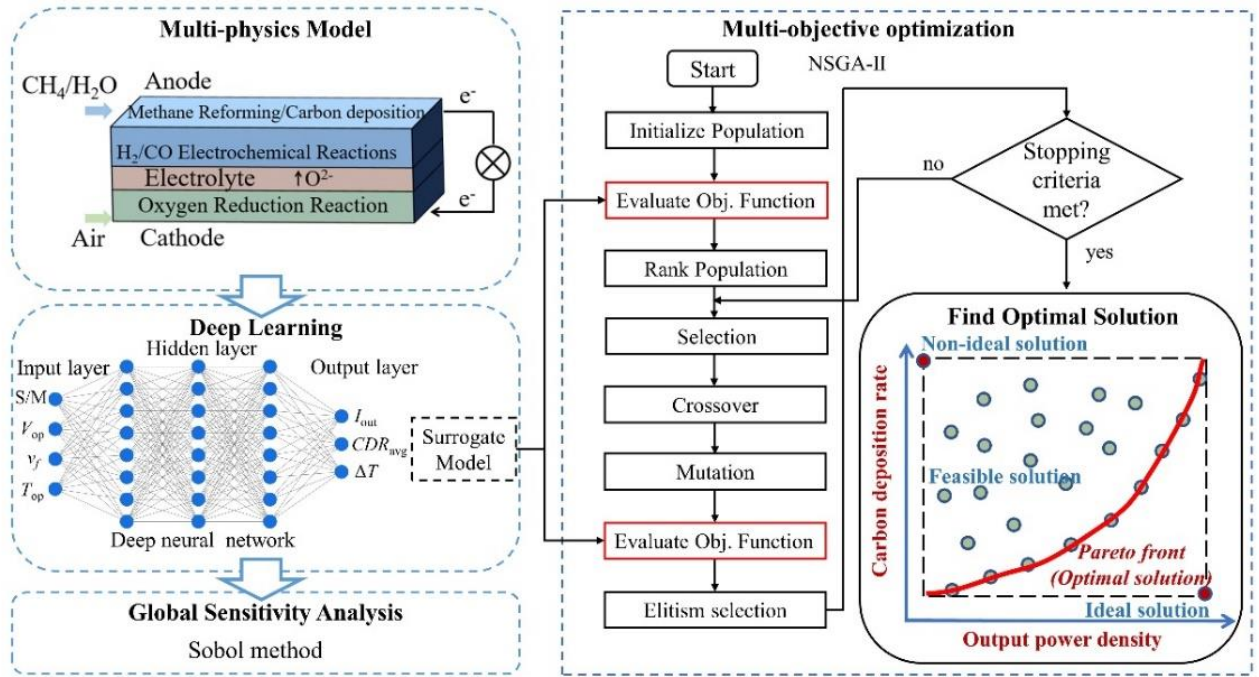


Fig. 1. Optimization flowchart for the electrochemistry and carbon deposition performance of DIR-SOFC

## 2.2 Multi-physics model development

The planar anode-supported SOFC is the optimal cell configuration at the present stage. The Ni-based cermet composites have excellent catalytic activity for internal reforming reactions of hydrocarbon fuels. At the three-phase boundary of the anode, the reforming reaction products ( $H_2$  and  $CO$ ) will simultaneously react with the oxygen ions produced by the cathode oxygen reduction reaction, generating electricity, heat, and gas products. A two-dimensional multi-physics SOFC model is developed, and the parameters of geometry and electrodes are listed in Table 1 [33].

Table 1. Cell parameters.

Parameters	Value
Cell length (mm)	80

Channel height (mm)	2
Anode support layer thickness ( $\mu\text{m}$ )	570
Anode functional layer thickness ( $\mu\text{m}$ )	30
Electrolyte thickness ( $\mu\text{m}$ )	15
Cathode thickness ( $\mu\text{m}$ )	30
Electrode (anode and cathode) porosity	0.4
Electrode (anode and cathode) permeability ( $\text{m}^2$ )	$1.18\text{e-}12$
Electrode (anode and cathode) tortuosity	3
Volume fraction of electron conductor	0.5
Electric conductivity of anode ( $\text{S m}^{-1}$ ) [33]	$4.2 \times 10^7 T^{-1} \exp(-1200T^{-1})$
Electric conductivity of cathode ( $\text{S m}^{-1}$ ) [33]	$9.5 \times 10^7 T^{-1} \exp(-1150T^{-1})$
Ionic conductivity ( $\text{S m}^{-1}$ ) [33]	$6.92 \times 10^4 \exp(-9681T^{-1})$

### 2.2.1 Conservation equations

The multi-physics model comprehensively considers the momentum, heat, and mass transfer as well as the electron/ion transfer processes. The corresponding conservation equations are summarized in Table 2. Among them, the widely used dusty gas model is used to characterize the multi-component diffusion process inside the porous anode. The equations used to calculate the effective parameters in the porous media are also listed in Table 2. The detailed expressions of effective diffusion coefficients and other related parameters can be found in [19].

Table 2. Governing equations.

Description	Governing equations	Computational domains
Mass	$\nabla \cdot (\rho v) = S_m$	Channels, Electrodes

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	$\rho(v \cdot \nabla)v = \nabla \cdot \left[ -p + \mu(\nabla v + (\nabla v)^T) \right]$	Channels
Momentum	$\frac{\rho}{\varepsilon}(v \cdot \nabla)\frac{v}{\varepsilon} = \nabla \cdot \left[ -p + \frac{\mu}{\varepsilon}(\nabla v + (\nabla v)^T) - \frac{2}{3}\frac{\mu}{\varepsilon}(\nabla \cdot v) \right] - \mu K^{-1}v$	Electrodes
Species	$\nabla \cdot \left( -\rho y_i \sum_{j \neq i}^n D_{\text{eff},ij} \nabla x_j + \rho v y_i \right) = S_i$	Channels, Electrodes
Energy	$\nabla \cdot (\rho c_p v T) = \nabla \cdot (\kappa_{\text{eff}} \nabla T) + S_T$	All domains
Electronic charge	$0 = \nabla \cdot (\sigma_{\text{ele}}^{\text{eff}} \nabla \phi_{\text{ele}}) + S_{\text{ele}}$	Electrodes
Ionic charge	$0 = \nabla \cdot (\sigma_{\text{ion}}^{\text{eff}} \nabla \phi_{\text{ion}}) + S_{\text{ion}}$	Electrodes, Electrolyte
<i>Effective parameters</i>		
Effective diffusion coefficient ( $D_{\text{eff}}$ )	$D_{\text{eff}} = \frac{\varepsilon}{\tau} \left( \frac{\sum_{j \neq i} \frac{x_j}{D_{ij}}}{1 - x_j} + \frac{1}{D_{k,ij}} \right)^{-1}$	Porous electrodes
Effective thermal conductivity ( $\kappa_{\text{eff}}$ )	$\kappa_{\text{eff}} = (1 - \varepsilon) \kappa_s + \varepsilon \kappa_f$	Porous electrodes
Effective electron/ion conductivity ( $\sigma_{\text{eff}}$ )	$\sigma_{\text{eff}} = \left( \frac{1 - \varepsilon}{\tau} \right) \sigma_0$	Porous electrodes

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### 2.2.2 Chemical model and carbon formation

The chemical reactions of DIR-SOFC include a series of heterogeneous reaction kinetics. The methane steam reforming (MSR) and water gas shift (WGS) reactions take a leading part in these reactions as follows:



The reaction kinetics of these two reactions are implemented into the multi-physics model. The detailed reaction rates expressions of MSR and WGS can be expressed as [34,35]:

$$R_{\text{MSR}} = k_{\text{rf}} \left( p_{\text{CH}_4} p_{\text{H}_2\text{O}} - \frac{p_{\text{CO}} (p_{\text{H}_2})^3}{K_{\text{pr}}} \right) \quad (5)$$

$$R_{\text{WGS}} = k_{\text{sf}} \left( p_{\text{H}_2\text{O}} p_{\text{CO}} - \frac{p_{\text{H}_2} p_{\text{CO}_2}}{K_{\text{ps}}} \right) \quad (6)$$

where  $R_{\text{MSR}}$  and  $R_{\text{WGS}}$  ( $\text{mol m}^{-3} \text{ s}^{-1}$ ) are the reaction rates of methane steam reforming reaction and water gas shift reaction, respectively.  $k_{\text{rf}}/k_{\text{sf}}$  are the forward reaction constants, and  $K_{\text{pr}}/K_{\text{ps}}$  are the equilibrium constants.

One of the objectives of this work is to minimize carbon deposition without significantly decreasing cell performance. Two carbon formation pathways are considered to be the main sources of Ni-based anode coking: methane cracking reaction and Boudouard reaction, as given in Eqs. (1) and (2). The carbon activity has been used in many studies as a criterion to assess the possibility of carbon deposition [16,17]. However, it has been pointed out that the actual carbon deposition rate is not a function of carbon activity [36]. In the present study the equations based on chemical reaction kinetics are used to calculate the carbon deposition rate [36,37]:

$$R_{\text{MC}} = p_{\text{H}_2}^2 (\exp(-12516.98T^{-1} + 0.26416)) \cdot \frac{p_{\text{CH}_4}}{p_{\text{H}_2}^2} - \exp(-13024.01T^{-1} - 0.00317) \quad (7)$$

$$R_{\text{B}} = p_{\text{CO}} (-\exp(-11093.005T^{-1} - 2.178)) \cdot \frac{p_{\text{CO}_2}}{p_{\text{CO}}} + \exp(-3595.868T^{-1} - 11.692) \quad (8)$$

where  $R_{\text{MC}}$  and  $R_{\text{B}}$  ( $\text{mol g}_{\text{cat}}^{-1} \text{ s}^{-1}$ ) are the reaction rates of methane cracking and Boudouard reaction, respectively. It is important to note that these reaction rates are only used to evaluate the magnitude of carbon deposition and are not included as the chemical reaction source terms

in the multi-physics model.

### 2.2.3 Electrochemical model

H<sub>2</sub> and CO are the main products of internal reforming reactions, which can directly participate in the electrochemical reactions:



The electrons generated in the anode flow through the external circuit to the cathode to produce electric current. By assuming a constant voltage operation, the relationship between output voltage ( $V$ ), equilibrium potential ( $E_{\text{eq}}$ ), and overpotentials ( $\eta$ ) can be expressed as:

$$V = E_{\text{eq}} - \eta_{\text{act}} - \eta_{\text{ohm}} \tag{10}$$

where  $\eta_{\text{act}}$  and  $\eta_{\text{ohm}}$  (V) are the activation overpotential and the ohmic overpotential, respectively.  $\eta_{\text{act}}$  can be calculated as:  $\eta_{\text{act}} = \varphi_{\text{ele}} - \varphi_{\text{ion}} - E_{\text{eq}}$ .  $\varphi_{\text{ele}}$  and  $\varphi_{\text{ion}}$  are the electric potential and electrolyte potential, respectively.  $\eta_{\text{ohm}}$  is determined by Ohm's law. When H<sub>2</sub> or CO is used as fuel, the equilibrium potentials can be expressed as [34]:

$$\begin{aligned}
 E_{\text{eq,H}_2} &= 1.253 - 0.00024516T + \frac{RT}{2F} \ln \left[ \frac{p_{\text{H}_2} (p_{\text{O}_2})^{0.5}}{p_{\text{H}_2\text{O}}} \right] \\
 E_{\text{eq,CO}} &= 1.46713 - 0.0004527T + \frac{RT}{2F} \ln \left[ \frac{p_{\text{CO}} (p_{\text{O}_2})^{0.5}}{p_{\text{CO}_2}} \right]
 \end{aligned} \tag{11}$$

The electrochemical reaction rates ( $J$ , A m<sup>-3</sup> s<sup>-1</sup>) can be calculated by adopting the Butler-Volmer equation:

$$J = j_0 \left( \exp \left( \alpha \frac{n_e F}{RT} \eta_{\text{act}} \right) - \exp \left( -(1-\alpha) \frac{n_e F}{RT} \eta_{\text{act}} \right) \right) \tag{12}$$

$$j_0 = \frac{\gamma_i RT}{n_e F} \left( \frac{p_i}{p_{\text{ref},i}} \right)^m \exp \left( -\frac{E_{\text{act}}}{RT} \right) \tag{13}$$

where  $j_0$  (A m<sup>-3</sup>) is the exchange current density,  $\gamma_i$  is the prefactor for species  $i$ . Since the

1 electrochemical oxidation activity of H<sub>2</sub> is higher than that of CO, the prefactor of H<sub>2</sub> is set to  
2 2.2 times that of CO [34].  
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#### 4 2.2.4 Numerical procedure 5

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7 The related coupled equations are implemented in COMSOL Multiphysics which discretizes  
8 the partial differential equations using the finite element method. The solving process is  
9 performed with the built-in PARDISO direct solver with advantages in multiprocessing  
10 architecture. For boundary conditions, the velocity inlet and the pressure outlet are used as  
11 boundary conditions for the momentum equation, while the inlet is set to the operating  
12 temperature and the external boundary other than the outlet is set to adiabatic. For electric  
13 potential solving, the upper boundary of the anode is set to the ground, the lower boundary is  
14 set to the operating voltage, and the rest is set to electrical insulation.  
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26 Meanwhile, the model validation on the multi-physics model is performed while maintaining  
27 the operating conditions, cell materials, and geometrical parameters consistent with the  
28 experiment [38]. As shown in Fig. 2(a), the polarization curves obtained from simulation  
29 results fit well with the experimental data at different operating temperatures.  
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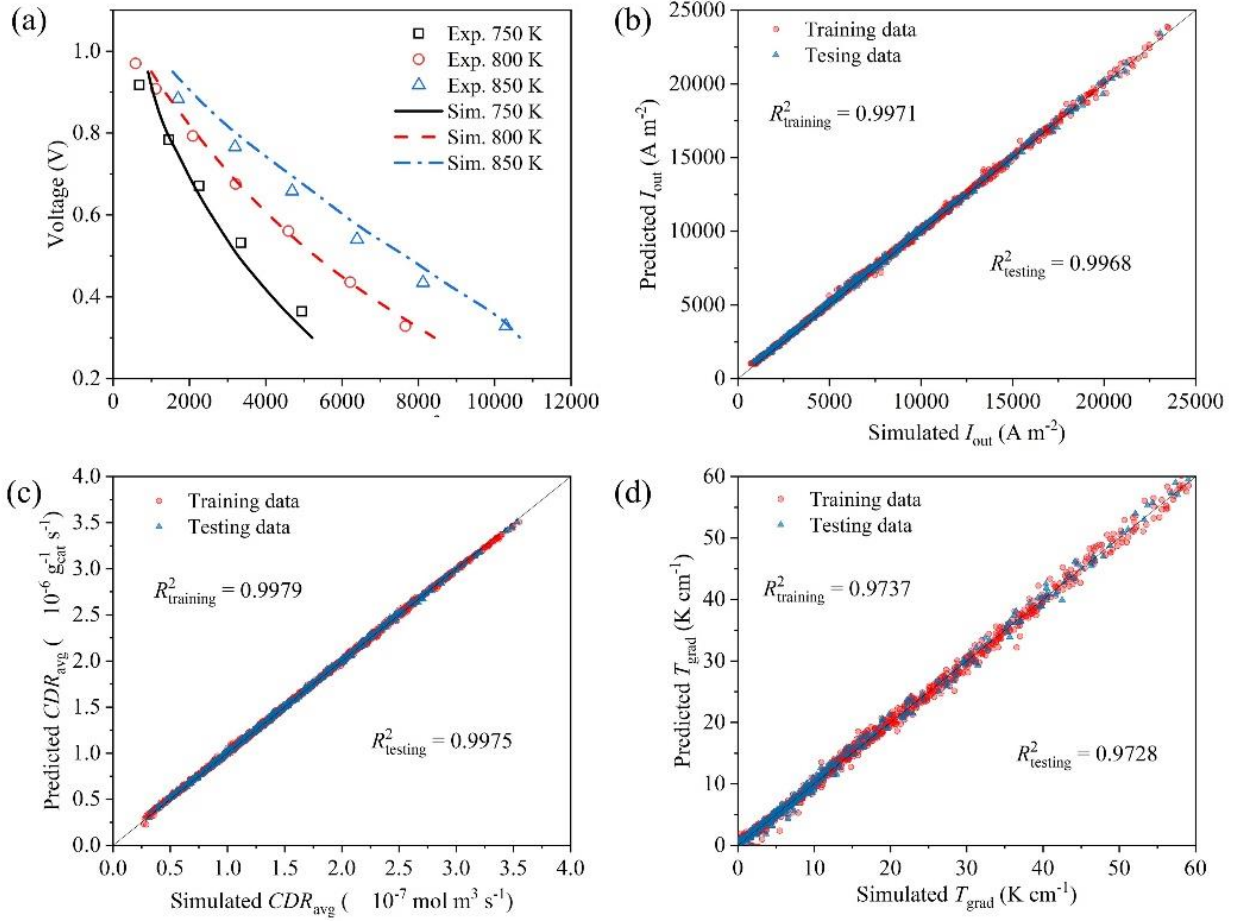


Fig. 2. Comparison of polarization curves between simulation results and experiment data (a).

Comparison of predicted and simulated results for the training set and testing set: output current density (b), average carbon deposition rate (c), and maximum temperature gradient (d).

### 2.3 Deep-learning-based surrogate model

#### 2.3.1 Deep neural network

Deep learning (DL) is a branch of artificial intelligence (AI) method based on the artificial neural network (ANN). Deep neural network (DNN), a biologically inspired computing scheme, can be considered as a stacked neural network with multiple layers. Like the biological neurons in the human brain, DNN consists of multiple sets of artificial neuron nodes, each of which combines the inputs linearly and passes the inputs through linear or nonlinear activation functions [39]. As a kind of black-box model, DNN has been shown to have the capability to

capture deep relationships between inputs and outputs in the absence of physical models [40]. The adopted DNN structure is shown in Fig. 1, which includes three hidden layers, as well as four inputs and three outputs. Each of the three hidden layers has 8 neurons. Four operating conditions that have a significant impact on electrochemical and carbon deposition performance are selected as inputs: steam/methane ratio (S/M), operating voltage ( $V_{op}$ ), inlet fuel velocity ( $v_f$ ), and operating temperature ( $T_{op}$ ). In addition to the output current density ( $I_{out}$ ) and the average carbon deposition rate ( $CDR_{avg}$ ), the maximum temperature gradient ( $T_{grad}$ ) is also used as an output parameter to evaluate the cell thermo-mechanical performance. Then, the deep learning-based surrogate model can be expressed as:

$$(I_{out}, CDR_{avg}, T_{grad}) = f(S/M, V_{op}, v_f, T_{op}) \quad (14)$$

where the  $CDR_{avg}$  is one of the optimization criteria for the following multi-objective genetic algorithms which is calculated as the sum of carbon generation:  $CDR_{avg} = R_{MC} + R_B$ . Meanwhile, another optimization criteria, power density ( $P_{out}$ ), is calculated as:  $P_{out} = I_{out} V_{op}$ . In addition,  $T_{grad}$  denotes the maximum temperature gradient along the flow direction, which is employed as an optimization constraint to characterize the thermal-mechanical endurance.

A total number of 1882×7 datasets is randomly split into a training set (80%) and a testing set (20%). The ranges of input parameters are shown in Table 3. The sizes of epoch and batch are 2000 and 32, respectively. The deep learning algorithm is implemented through Python 3.8. The DNN is constructed by Keras 2.4.3.

Table 3. Operating parameters as DNN inputs.

Parameters	Value
Steam/methane ratio (S/M)	1-4



Operating voltage ( $V_{op}$ , V)	0.4-0.8
Inlet fuel velocity ( $v_f$ , m s <sup>-1</sup> )	0.2-0.4
Operating temperature ( $T_{op}$ , K)	1023-1173

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### 2.3.2 Prediction performance

The root-mean square error (RMSE) and squared correlation coefficient ( $R^2$ ) is chosen as the criteria to evaluate the prediction performance of the deep learning-based surrogate model:

$$RMSE = \sqrt{\frac{1}{N} \sum_{i=1}^N (x_i - x_{i,p})^2} \quad (15)$$

$$R^2 = 1 - \frac{\sum_{i=1}^N (x_i - x_{i,p})^2}{\sum_{i=1}^N (x_i - \bar{x}_i)^2} \quad (16)$$

where  $x_i$  is the simulation result using the multi-physics model;  $x_{i,p}$  is the surrogate model predicted result;  $\bar{x}_i$  is the mean value of multi-physics model simulated results. Fig. 2(b)-(c) show the comparison between simulated results and predicted results. The values of  $R^2$  are also marked in the figure and are all larger than 0.97. The RMSE of the training set and testing set are 0.0184 and 0.0227 respectively and both remain at a low level. Also, there is no overfitting in the model. Therefore, the surrogate model has good prediction accuracy.

### 2.4 Global sensitivity analysis

The global sensitivity analysis aims at determining how uncertainty in different input parameters affects the final output of the model. It helps to understand the effects of individual physical quantities and the coupling of different physical quantities on the output parameters of a nonlinear complex model (such as a multi-physics fuel cell model). In this work, a variance-based sensitivity analysis called the Sobol method [41] is introduced to assess the importance of fuel cell operating conditions on output performance and carbon deposition. In

1 addition, the above DNN-trained surrogate model can perform fast prediction of cell  
 2 performance, which also compensates for the drawback of the Sobol method which is  
 3 computationally intensive.  
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6 According to the Sobol method, any physical model can be represented as:  $y = f(\mathbf{x})$ , where  
 7  $\mathbf{x}$  is the vector of input parameters  $\{x_1, x_2, \dots, x_n\}$ ,  $y$  is the univariate model output. For the  
 8 multi-physics SOFC model,  $\mathbf{x}$  can be the operating conditions, and  $y$  is the related cell  
 9 performance parameter. This function can be decomposed as follows:  
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$$16 \quad y = f_0 + \sum_{i=1}^d f_i(x_i) + \sum_{i=1}^d f_{ij}(x_i, x_j) + \dots + f_{1,2,\dots,d}(x_1, x_2, \dots, x_d) \quad (17)$$

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 21 At the same time, the decomposition of total variance  $V(y)$  can be expressed as:

$$22 \quad V(y) = \sum_{i=1}^k V_i + \sum_{i \leq j \leq k} V_{ij} + \dots + V_{1,2,\dots,k} \quad (18)$$

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 27 where  $V_i, V_{ij}, \dots, V_{1,2,\dots,k}$  are the partial variances of  $f_i, f_{ij}, \dots, f_{1,2,\dots,k}$ , respectively. Then the  
 28 Sobol sensitivity index is stated as follows:  
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$$32 \quad S_{i_1 \dots i_k} = \frac{V_{i_1 \dots i_k}}{V} \quad (19)$$

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 37 Here, the first-order sensitivity index  $S_i$  evaluates the importance of individual input parameter  
 38  $x_i$  on model output. The second-order sensitivity index  $S_{ij}$  evaluates the importance of the  
 39 coupling of  $x_i$  and  $x_j$ . The input parameters selection and the range of values are the same as in  
 40 the deep neural network section above. The global sensitivity analysis and multi-objective  
 41 optimization program described below, are implemented through an in-house python code.  
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## 49 **2.5 Optimization algorithm**

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 51 For practical engineering problems, it is often necessary to optimize multiple objectives. There  
 52 may be some conflict between these optimization objectives, meaning that improving one  
 53 objective inevitably worsens the others [42]. The multi-physics optimization of SOFC is a  
 54 typical nonlinear problem for which there is no single solution that can optimize each objective  
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1 simultaneously [43,44]. The multi-objective genetic objective algorithm has the capability to  
 2 excavate the diverse region of solution space and is suitable for solving problems related to  
 3 SOFC multi-objective optimization. The optimal solution set of MOGA (called Pareto  
 4 optimum set) is illustrated in terms of the Pareto front, which is derived from the fitness  
 5 function values in the objective space.  
 6

7 The optimization of DIR-SOFC in this work is focused on maximizing the power density ( $P_{out}$ )  
 8 and minimizing the average carbon deposition region ( $CDR_{avg}$ ), which are called objective  
 9 functions. In practice, the amount of carbon deposited accumulates over time. Accordingly, we  
 10 set the carbon deposition rate as an optimization criterion to obtain the best long-term  
 11 performance. At the same time, the maximum allowable temperature gradient ( $T_{grad}$ ) along the  
 12 direction of the gas channel is used as a constraint. We can reasonably assume that the cell will  
 13 not tolerate thermos-mechanical instability at levels below  $T_{grad}$ , and the cell performance does  
 14 not deteriorate due to temperature gradients during the entire operation. The typical fuel cell  
 15 operating conditions such as  $v_f$ ,  $T_{op}$ ,  $V_{op}$ , and S/M are set as the decision variables. The  
 16 optimization problem of DIR-SOFC can then be described as:  
 17

$$\begin{cases} \text{Find the optimal solution } X = \{S/M, V_{op}, v_f, T_{op}\} \\ \text{Max } P_{out}, \text{ Min } CDR_{avg} \\ \text{Subjected to } \{T_{grad} \leq T_{grad}^{Max}\} \end{cases} \quad (20)$$

18 The non-dominated sorting genetic algorithm-II (NSGA-II) with constraint-handling strategy  
 19 is adopted to find the Pareto front in this work. The work flowchart of NSGA-II is shown in  
 20 Fig. 1. The detailed procedure can be found in the original paper [45]. The DNN-trained  
 21 surrogate model is employed in the calculation of fitness values. The integration of the  
 22 surrogate model and NSGA-II can greatly accelerate the optimization process.  
 23

24 Besides, a decision-making method named TOPSIS (Technique for Order Preference by  
 25 Similarity to an Ideal Solution) [46,47] is employed to select the optimal trade-off point. It is  
 26

vital to select the optimal solution from a variety of options for practical applications. However, because all solutions from the Pareto front have the same optimization level, it is hard to find the optimal alternative by sorting the fitness function values in the Pareto front. The TOPSIS chooses the options that are closest to the positive-ideal solution and the ones that are farthest away from the negative-ideal solution. The selection process of TOPSIS can be divided into several steps which are listed in Table 4.

Table 4. The TOPSIS selection process.

Step	Description	Variables and equations
<i>Step 1</i>	Create an evaluation matrix $((x_{ij})_{m \times n})$ with $m$ alternatives and $n$ objectives.	$(x_{ij})_{m \times n}$
<i>Step 2</i>	Obtain the normalized matrix $((r_{ij})_{m \times n})$	$r_{ij} = \frac{x_{ij}}{\sqrt{\sum_{i=1}^m x_{ij}^2}},$ $i = 1, 2, \dots, m, j = 1, 2, \dots, n$
<i>Step 3</i>	Multiply the weights $(w_j)$ with the normalized matrix to form the weighted normalized matrix $((v_{ij})_{m \times n})$	$v_{ij} = r_{ij} \times w_j,$ $i = 1, 2, \dots, m, j = 1, 2, \dots, n$
<i>Step 4</i>	Determine the positive-ideal alternative ( $A^+$ ) and the negative-ideal alternative ( $A^-$ )	$A^+ = \left( \begin{array}{c} \min [v_{11}, \dots, v_{m1}], \min [v_{12}, \dots, v_{m2}], \\ \dots, \min [v_{1n}, \dots, v_{mn}] \end{array} \right)$ $A^- = \left( \begin{array}{c} \max [v_{11}, \dots, v_{m1}], \min [v_{12}, \dots, v_{m2}], \\ \dots, \min [v_{1n}, \dots, v_{mn}] \end{array} \right)$
<i>Step 5</i>	Calculate the distance between the target alternative and $A^+$ ( $d_i^+$ ) and the distance between the target alternative and the $A^-$ ( $d_i^-$ )	$d_i^+ = \sqrt{\sum_{j=1}^n (v_{ij} - A_j^+)^2},$ $i = 1, 2, \dots, m, j = 1, 2, \dots, n$ $d_i^- = \sqrt{\sum_{j=1}^n (v_{ij} - A_j^-)^2},$ $i = 1, 2, \dots, m, j = 1, 2, \dots, n$

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- Step 6* Calculate the relative closeness to the ideal solution of alternatives ( $C_i$ )
- $$C_i = \frac{d_i^+}{d_i^+ + d_i^-},$$
- $i = 1, 2, \dots, m$
- Step 7* Rank the alternatives according to  $C_i$ , and the one shortest to the ideal solution is the optimal solution .
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15 **3. Results and discussion**

16  
17 **3.1 Results of sensitivity analysis**

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20 The global sensitivity analysis can help to clarify the input-output relationship and the  
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22 multivariable interactions among the input parameters. Besides, a more reasonable parameter  
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24 analysis can be performed based on the results of global sensitivity analysis. The first- and  
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26 total-order of Sobol' indices are depicted as blue and red columns, respectively. The first-order  
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28 Sobol' indices reflect the univariate effect of individual input parameters on the variance of  
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30 outputs, while the total-order Sobol' indices represent both contributions of individual and  
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32 interactive input parameters. We define individuals with the values of total-order Sobol' indices  
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34 larger than 0.1 as the sensitive parameters. Furthermore, if the total-order Sobol' index of an  
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36 individual is substantially larger than its first-order index, there will be higher-order  
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38 interactions with other input parameters.  
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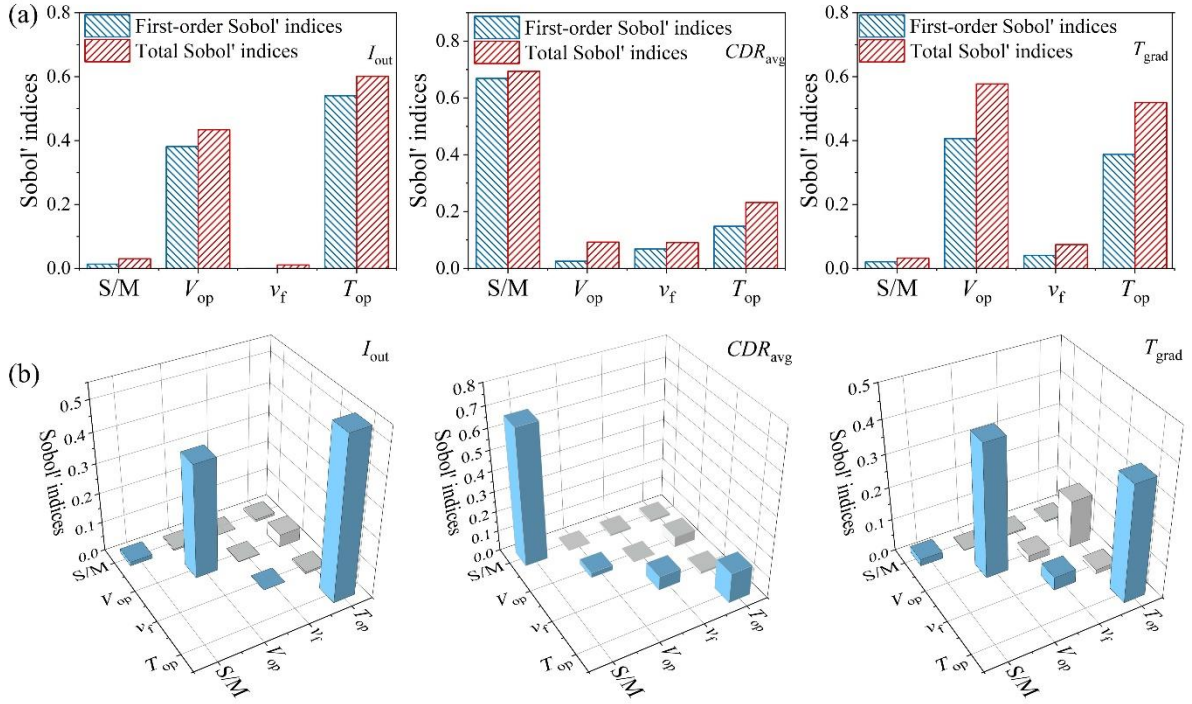


Fig. 3. Total, first-order (a) and second-order (b) Sobol' indices for the sensitive parameter.

As shown in Fig. 3(a), the sensitive parameters of output current density are  $V_{op}$  and  $T_{op}$ . The cell electrochemical performance is closely related to the  $V_{op}$  and  $T_{op}$ . For average carbon deposition rates, the sensitive parameters are S/M and  $T_{op}$ . This means that the effective way to minimize the carbon deposition rates is to control the steam/methane ratio and operating temperature. Both output current density and average carbon deposition rates exhibit strong first-order sensitivity to operating parameters. The contributions of different input parameters to the total variance are more complex for the maximum temperature gradient compared to the output current density and carbon deposition rates. The  $V_{op}$  and  $T_{op}$  have the most significant effect with high total-order indices of 0.406 and 0.357, respectively. The temperature gradient shows a lower sensitivity to S/M and  $v_f$ . Meanwhile, the univariate effects of four input parameters are insignificant. The differences between first- and total-order indices for temperature gradient are more remarkable, which highlights the interaction effects between each parameter. As depicted in Fig. 1(b), the contributions of two-parameter interactions are

1 plotted as 3D histograms. The first- and second-order indices are shown in blue and grey bars,  
2 respectively. For the output current density, the pairwise interaction of  $V_{op}$  and  $T_{op}$  shows a  
3 relatively minor influence with a lower second-order index (0.043). And the other pairwise  
4 interactions can be neglected. Similarly, the sensitive parameters exhibit some pairwise  
5 interactions for carbon deposition rates. The remarkable pairwise interactions between  $V_{op}$  and  
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7  $T_{op}$  suggest that it is more efficient to control these two parameters simultaneously to minimize  
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9 the temperature gradient.  
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12 The global sensitivity analysis performed above can also provide effective strategies for  
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14 parameter analysis. The operating voltage and temperature have significant effects on output  
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16 current density and temperature gradient. For cell performance and carbon deposition rates, the  
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18 effects of the univariate sensitive parameter will be of interest. The analysis on pairwise  
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20 interaction effects will help to optimize the cell temperature distribution.  
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### 29 ***3.2 Parameter analysis***

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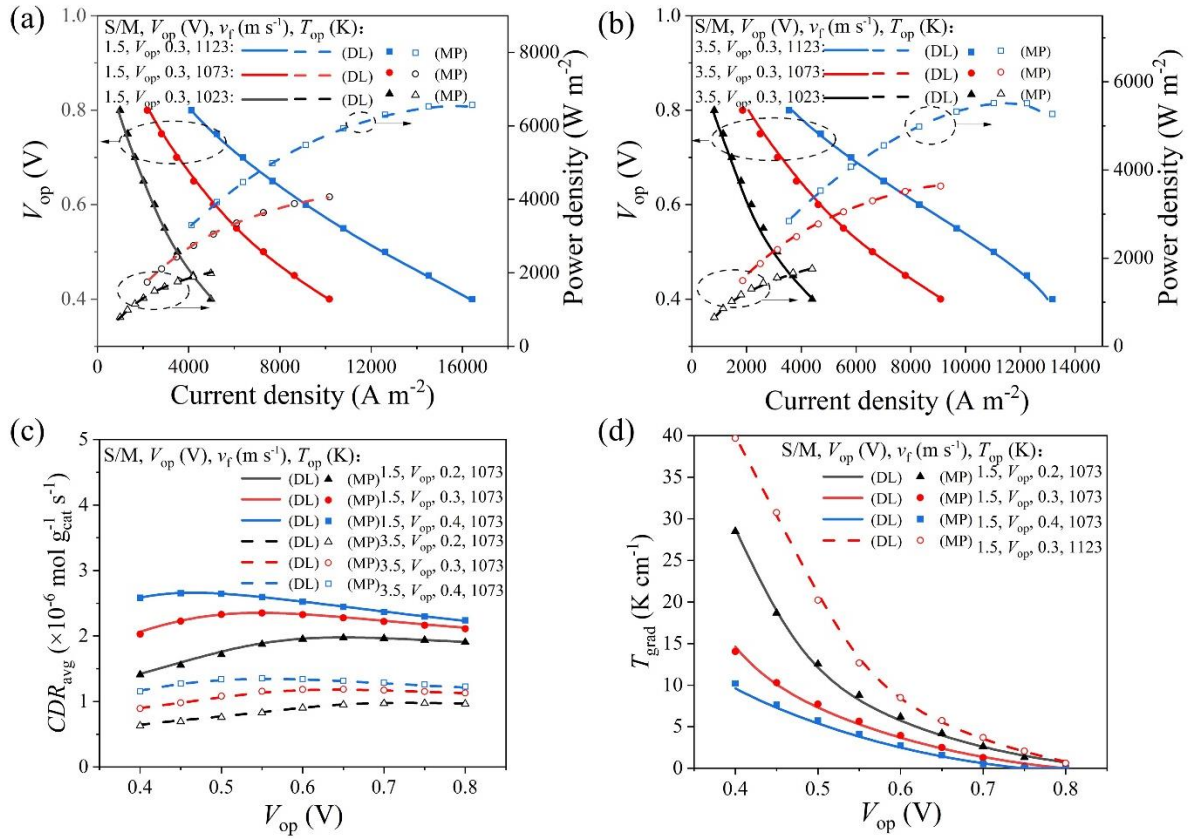


Fig. 4. The effects of sensitive parameters on cell performance (a) and (b), carbon deposition (c), and temperature gradient (d).

Based on the results of global sensitivity analysis, the effects of sensitive parameters on cell performance, carbon deposition, and temperature gradient obtained by the surrogate model are shown in Fig. 4. Meanwhile, some of the operating points calculated by the multi-physics model are plotted as controls. The results comparison between the multi-physics model and surrogate model proves the accuracy of the surrogate model in predicting the output parameters. Fig. 4(a) and (b) display the changes of current density-voltage and power density-voltage curves with the increase of operating temperature. For DIR-SOFC, the cell performance significantly increases with increasing temperature (Fig. 4(a)). When the operating temperature is increased from 1023 K to 1073 K and 1123 K, the maximum output power density is raised from 2019.4  $W m^{-2}$  to 4051.0  $W m^{-2}$  and 6540.8  $W m^{-2}$ , respectively. At the same time, it is



1 found that under low operating voltage and high S/M conditions (Fig. 4(b)), the increment in  
2 current density slightly decreases at an operating temperature of 1123K, which will be  
3 discussed in the following section. The results of global sensitivity analysis reflect that the S/M  
4 significantly affects the carbon deposition rates, which is consistent with what is shown in Fig.  
5 4(c). The larger S/M accelerates the methane steam reforming reaction and a higher methane  
6 conversion rate is beneficial to alleviate the carbon deposition [48]. At the same time, the  
7 overall average carbon deposition rates increase with the decreasing operating voltage and then  
8 decrease. That is, the decrease in operating voltage within a certain range leads to an increase  
9 in power density but also an increase in the amount of carbon deposition, meaning that there is  
10 a trade-off between cell performance and carbon deposition. This optimal operating point is  
11 the objective of the following multi-objective optimization work. The effects of sensitive  
12 parameters on the temperature gradient are shown in Fig. 4(d). The strong endothermic  
13 reforming reactions (MSR) result in a large temperature gradient along the cell length direction  
14 [49]. As the decrease of operating voltage, the accumulation of electrochemical heats increases  
15 the temperature gradient. For example, the maximum temperature gradient can be increased  
16 from 0.01 K cm<sup>-1</sup> to 14.62 K cm<sup>-1</sup> at an operating temperature of 1073 K and an inlet velocity  
17 of 0.3 m s<sup>-1</sup>. Meanwhile, increasing the operating temperature will significantly increase the  
18 maximum temperature gradient. The combined effects of the chemical reaction heats, the  
19 electrochemical reaction heats, and the temperature distribution inside the cell are responsible  
20 for the above phenomenon and are discussed in detail below. Also, understanding this  
21 phenomenon helps to clarify the optimization objectives and improve the cell thermal  
22 performance.  
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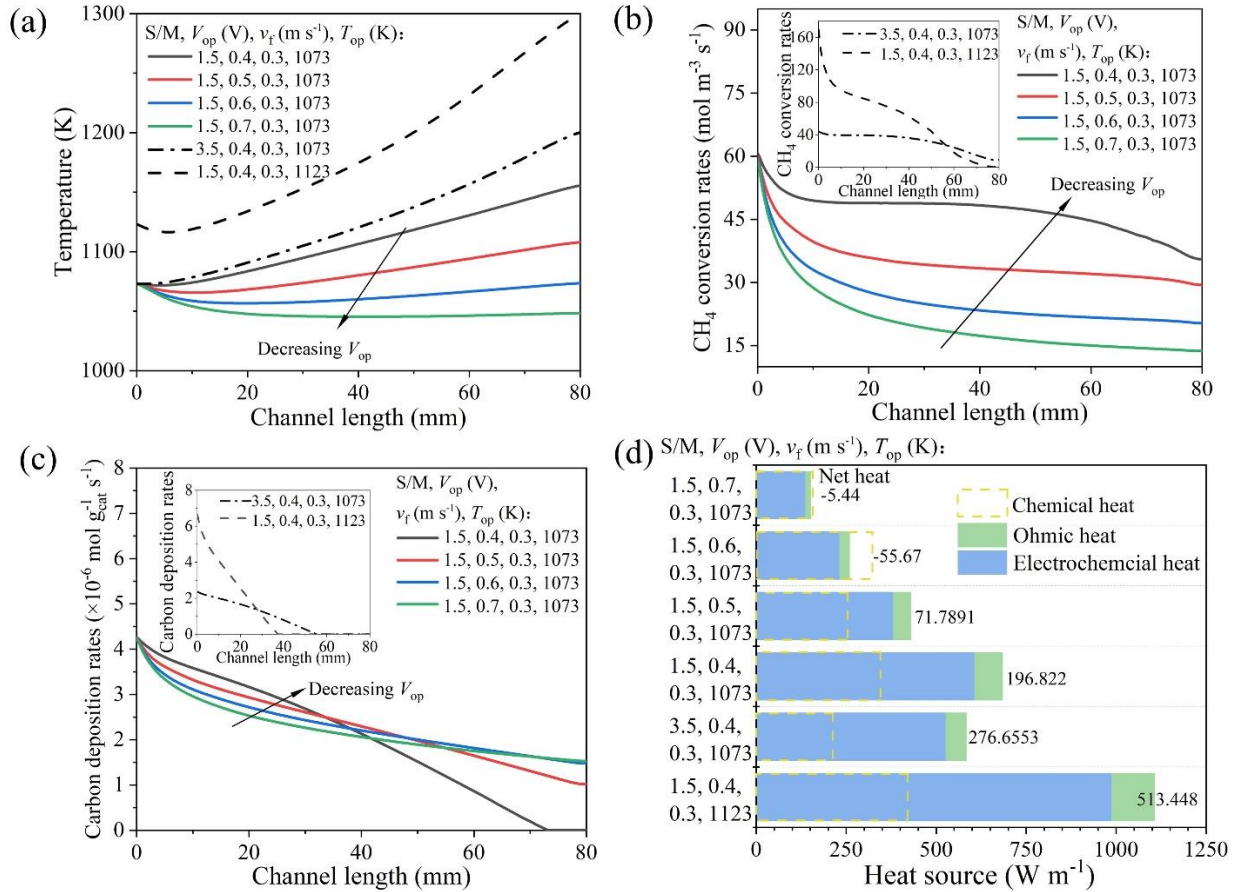


Fig. 5. Temperature (a),  $CH_4$  conversion rates (b), and carbon deposition rates (c) distribution along the channel length direction obtained by the multi-physics model. Heat sources under different operating conditions (d).

In order to further clarify the effects of heat and mass transfer under different working conditions, the results obtained by the multi-physics model are depicted in Fig. 5. The overall temperature distribution significantly affects cell performance and carbon deposition. As shown in Fig. 5(a), the overall temperature gradually increases as the operating voltage decreases. The maximum temperature difference increases from 27.5 K at 0.7 V to 82.5 K at 0.4 V. At the same time, the increase of overall temperature also accelerates the methane conversion reaction (Fig. 5(b)), causing the overall methane conversion rates to increase with decreasing voltage. Higher temperature and lower voltage will accelerate the electrochemical

conversion of hydrogen and carbon monoxide to be more favorable for the methane conversion reaction. Fig. 5(c) shows the distribution of carbon deposition rates along the channel direction. Overall the carbon deposition rates decrease along the channel direction as the methane is gradually consumed. For lower  $V_{op}$  (0.4 V), the carbon deposition rate can be reduced to zero due to the complete consumption of methane. Besides, the chemical reaction heats, electrochemical reaction heats, and ohmic heats are plotted as stacked bars (Fig. 5(d)). It should be noted that the solid-filling part of each bar represents the electrochemical and ohmic exothermic heat for each operating condition. The dashed line represents the chemical endothermic heat. Both electrochemical and ohmic heats increase with the decrease of operating voltage. At higher  $V_{op}$  (0.7 and 0.6 V), the chemical heats are larger than the electrochemical and ohmic exothermic heats, the cell is in a state of heat absorption. As the further decreasing of  $V_{op}$ , the cell changes from heat absorption to an exothermic state. The value of net heat decreases from  $-5.44 \text{ W m}^{-1}$  at 0.7 V to  $196.8 \text{ W m}^{-1}$  at 0.4 V. In addition to the effects of operating voltage, two cases considering the effects of operating temperature and S/M ratio are shown in Fig. 5(a). At lower operating voltage (0.4 V), increasing  $V_{op}$  causes the cell temperature distribution to show a trend of slightly decreasing and then increasing along the channel direction. The methane conversion rate also has a large increase, especially on the inlet side. At the same time, the values of the three kinds of heat have a large increase (Fig. 5(d)). In addition, increasing the S/M ratio has a significant effect on reducing carbon deposition. The above results are strongly correlated with the distribution of each gas component under the related condition and are discussed in the next section.

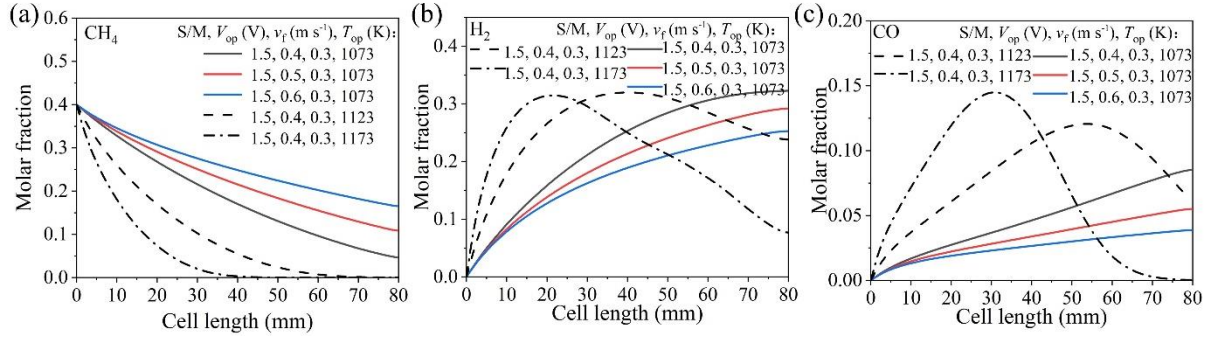


Fig. 6. Molar fraction distribution along channel length direction for CH<sub>4</sub> (a), H<sub>2</sub> (b), and CO (c).

Fig. 6(a), (b), and (c) represent the distribution of CH<sub>4</sub>, H<sub>2</sub>, and CO, respectively. As mentioned in the previous section, reducing  $V_{op}$  and increasing  $T_{op}$  are favorable for methane conversion. The molar fractions of H<sub>2</sub> and CO also increase along the channel length direction. By further increasing  $T_{op}$  to 1173 K, the methane is fully converted in the upstream region of the cell, and the molar fraction of H<sub>2</sub> and CO reaches a maximum and decreases in the subsequent range due to the consumption by electrochemical reactions. Recall from Fig. 5(a), when methane is converted rapidly, the electrochemical and ohmic heat in the downstream region is more than the chemical reaction heat absorption, resulting in a tendency for the cell temperature to slightly fall and then rise. This phenomenon is more pronounced for conditions where the methane is completely consumed. Then recall from Fig. 4(b), at higher  $T_{op}$  and larger S/M, less methane flux leads to complete conversion of methane. The H<sub>2</sub> and CO cannot maintain a high concentration or even drop in the second half of the cell (Fig. 6(b) and (c)). This is the reason for the small reduction in increment of current density at high temperatures and large S/M conditions in Fig. 4(b).

### 3.3 Results of multi-objective optimization

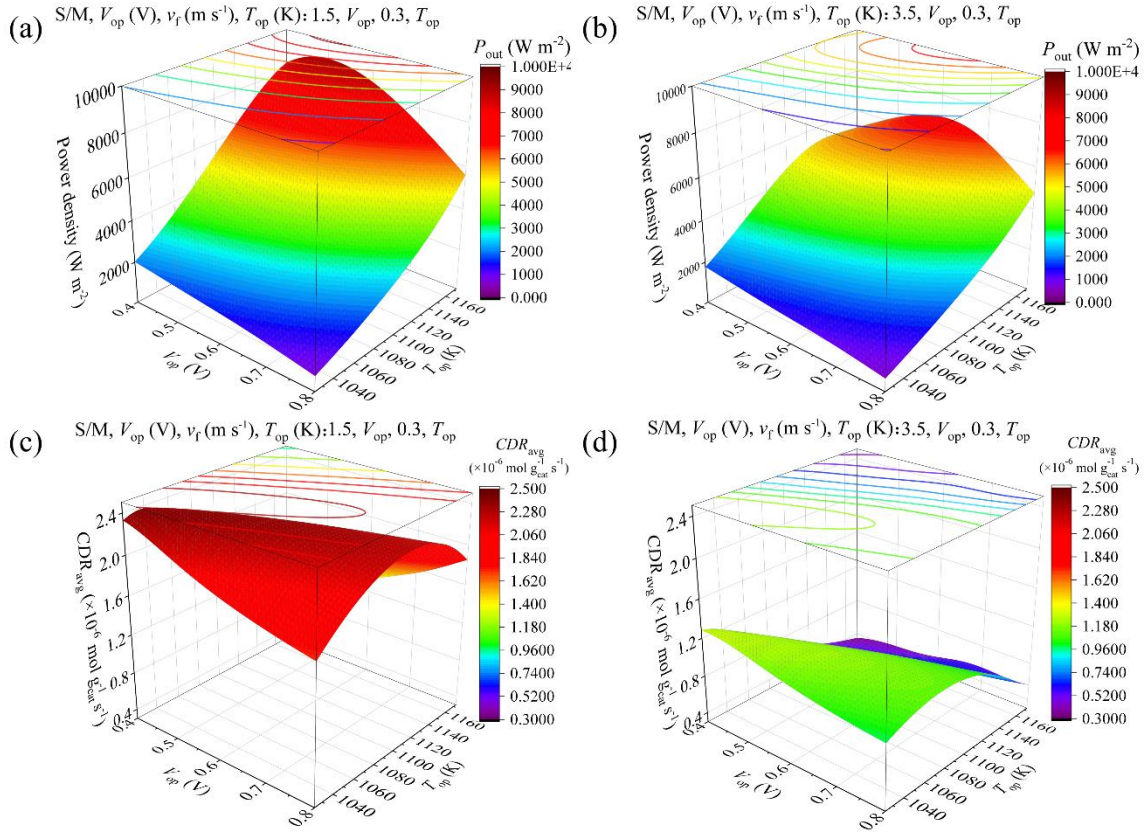


Fig. 7. Surface plots of surrogate model prediction: output power density with (a) low S/M ratio and (b) high S/M ratio; average carbon deposition rate (c) low S/M ratio and (d) high S/M ratio.

The results of the parametrical analysis above show that the cell performance and carbon deposition are influenced simultaneously by the various operating conditions. The surface plots obtained from the surrogate model are shown in Fig. 7, according to which the best combination of operating conditions for optimizing cell performance and carbon deposition can be quickly found. As shown in Fig. 7(a) and (b), at lower and higher S/M ratios (1.5 and 3.5), the maximum output power density can reach  $9135.1 \text{ W m}^{-2}$  and  $6987.9 \text{ W m}^{-2}$ , respectively. Meanwhile, the cell output power density is maximized at the lower operating voltage of 0.4-0.5 V. Decreasing  $V_{op}$  and increasing  $T_{op}$  can significantly improve cell performance. For carbon deposition (Fig. 7(c) and (d)), we can find that increasing S/M is an effective measure to inhibit carbon

deposition. The maximum carbon deposition rate of lower S/M ( $2.383 \times 10^{-6} \text{ mol g}_{\text{cat}}^{-1} \text{ s}^{-1}$ ) is about 1.9 times larger than that of higher S/M ( $1.284 \times 10^{-6} \text{ mol g}_{\text{cat}}^{-1} \text{ s}^{-1}$ ). It is evident that the method of enhancing cell performance may increase the risk of carbon deposition. Finding the trade-off between cell performance and carbon deposition through surface plots can be challenging.

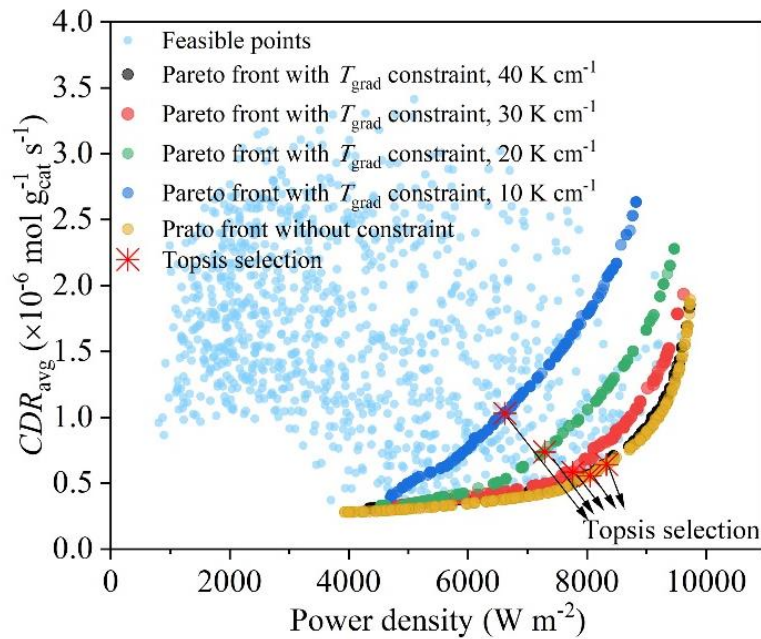


Fig. 8. Pareto fronts under different maximum temperature gradient constraints.

In this section, the deep learning-based surrogate model is implemented as the fitness function of MOGA. The trade-off (Pareto front) between output power density and carbon deposition rate for a given temperature gradient constraint is depicted in Fig. 8. The non-uniform distribution will raise a critical challenge to the thermal management of cells and stack. The temperature gradient causes thermal stress, and the excessively high temperature facilitates the coarsening process of Ni particles which is not desirable to long-term cell stability [18]. To prevent thermomechanical failure, the maximum temperature gradient should not exceed 10 K

1 cm<sup>-1</sup> [50]. The weights assigned to output power density and carbon deposition rate in the  
2 TOPSIS selection process are 0.7 and 0.3, respectively.  
3

4 As the temperature gradient constraint decreases, the cell operating on the Pareto front suffers  
5 both a decrease in performance and more severe carbon deposition. The maximum power  
6 densities on the Pareto fronts are 8823.42 W m<sup>-2</sup> (10 K cm<sup>-1</sup>), 9467.2 W m<sup>-2</sup> (20 K cm<sup>-1</sup>), 9625.3  
7 W m<sup>-2</sup> (30 K cm<sup>-1</sup>), 9729.3 W m<sup>-2</sup> (40 K cm<sup>-1</sup>) and 9731.0 W m<sup>-2</sup> (no constraint), respectively.  
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9 The minimum average carbon deposition rates on the Pareto fronts for different temperature  
10 gradient constraints are very close. This multi-objective optimization framework can be used  
11 to achieve good performance output and resistance to carbon deposition during operation while  
12 maintaining a small temperature gradient (<10 K cm<sup>-1</sup>) by adopting the operating conditions  
13 on the Pareto fronts. Under different constraints, the working points selected by TOPSIS and  
14 their output parameters are listed in Table 5. The maximum output power density on the Pareto  
15 fronts can reach 9731.0 W m<sup>-2</sup> with no temperature gradient constraint, but the average carbon  
16 deposition rate has also reached 1.89×10<sup>-6</sup> mol g<sub>cat</sub><sup>-1</sup> s<sup>-1</sup>. For the TOPSIS selection of 10 K cm<sup>-1</sup>  
17 constraint, the output power density is 6618.9 W m<sup>-2</sup>, and the average carbon deposition rate is  
18 1.03 ×10<sup>-6</sup> mol g<sub>cat</sub><sup>-1</sup> s<sup>-1</sup>. From the results of TOPSIS selection, it is possible to sacrifice 32.0%  
19 of cell performance to achieve a 45.5% reduction in carbon deposition, while ensuring that the  
20 maximum temperature gradient is within 10 K cm<sup>-1</sup>. The results show that a temperature  
21 gradient control of 10 K cm<sup>-1</sup> can be achieved using this optimization framework, which can  
22 further be applied to the real-time control of DIR-SOFC to regulate the temperature gradient  
23 in real-time and obtain optimal performance simultaneously.  
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55 Table 5. The parameters of optimal working points are selected by TOPSIS.  
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	10 K cm <sup>-1</sup>	20 K cm <sup>-1</sup>	30 K cm <sup>-1</sup>	40 K cm <sup>-1</sup>	No
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					constraint
S/M	2.63	3.19	3.58	3.0	3.31
$V_{op}$ (V)	0.708	0.647	0.580	0.407	0.490
$v_f$ (m s <sup>-1</sup> )	0.399	0.398	0.398	0.4	0.4
$T_{op}$ (K)	1173	1173	1173	1173	1173
$P_{out}$ (W m <sup>-2</sup> )	6618.9	7288.7	7761.3	8328.2	8049.3
$CDR_{avg}$ ( $\times 10^{-6}$ mol g <sub>cat</sub> <sup>-1</sup> s <sup>-1</sup> )	1.030	0.737	0.584	0.641	0.556
$T_{grad}$ (K cm <sup>-1</sup> )	9.1	19.9	29.8	39.3	44.1

## Conclusions

In this study, a novel framework for optimizing the electrochemistry and carbon deposition performance of DIR-SOFC is proposed. A multi-physics model is established to perform parameter analysis and generate a dataset. The dataset is then used to train a deep neural network (DNN) which acts as a surrogate model. The surrogate model can quickly and accurately predict cell output performance, carbon deposition rates, and maximum temperature gradient. Based on the surrogate model, the Sobol method and NSGA-II are applied to perform the global sensitivity analysis and the multi-objective optimization. Based on the multi-objective optimization results, the resulting operating conditions can be selected to achieve real-time control of cell performance, carbon deposition, and temperature during the actual operation of the DIR-SOFC. The proposed optimization framework can be extended to other aspects of SOFC optimization, such as training neural networks to rapidly obtain electrode performance under different microstructures and using multi-objective optimization to obtain electrode microstructures for optimal performance and durability. The above workflow can also



1 be applied in other energy conversion devices to achieve fast multi-objective optimization. The  
2 major findings and conclusions are listed below:  
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4 (1) The electrochemical performance of the cell is mainly affected by the univariate changes  
5 of operating voltage and temperature. Carbon deposition is influenced by the univariate  
6 changes of steam/methane ratio and operating temperature. The maximum temperature  
7 gradient is mainly the result of the pairwise interactions of operating voltage and operating  
8 temperature. In other words, the most effective way to improve thermomechanical performance  
9 is to adjust all the two sensitive parameters simultaneously.  
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11 (2) The maximum power density is usually generated at lower operating voltages, but this  
12 condition causes a large temperature gradient. As the decrease of operating voltage, the  
13 accumulation of electrochemical heats will increase the temperature gradient. Meanwhile, the  
14 overall temperature distribution and steam/methane ratio play a crucial role in the carbon  
15 deposition rates. There is a trade-off between carbon deposition and cell output performance.  
16 Reducing carbon deposition often comes at the cost of some cell performance.  
17

18 (3) The Pareto fronts under different temperature gradient constraints are obtained by the multi-  
19 objective genetic algorithms (MOGA). This optimization tool achieves a significant reduction  
20 in carbon deposition rates while maintaining a high output power density and a safe maximum  
21 temperature gradient ( $<10 \text{ K cm}^{-1}$ ).  
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