

1 **Prediction of Human Restorative Experience for Human-Centered Residential**
2 **Architecture Design: A Non-Immersive VR–DOE-Based Machine Learning Method**

3 Yuxuan Zhang¹, Bo Xiao², Mohamed Al-Hussein³, and Xinming Li^{4,*}

4 **Abstract**

5 Nowadays, the topic of restorative experience in built environments has attracted more attention
6 because of the increasing stress levels in modern society. Researchers have sought to identify the
7 architectural features that influence a person’s perceived restorative experience to achieve
8 human-centered architectural designs. However, the relevant design knowledge is
9 unsystematically scattered, making it difficult for designers to interpret information and make
10 informed decisions in practice. This paper explores the feasibility of machine learning in
11 capturing the restorative quality of design alternatives, thereby providing decision support for
12 proactive architectural design analysis. To deal with feature selection and the uncertainty
13 associated with affective modeling, a framework is introduced that integrates design of
14 experiments and machine learning methods. The human restorative experience is assessed within
15 non-immersive VR environments using self-reported psychometric scales. Consequently,
16 general regression neural network is revealed as superior to other machine learning methods in
17 forecasting the restorative experience.

18
19 **Keywords:** Human-centered design; Restorative experience; Prediction model; Machine
20 Learning; Virtual Reality; Design of Experiment; Residential design; Built environment.

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22 **1 Introduction**

23 Currently intrinsic to our daily lives, stress has been identified as a critical health issue that
24 impacts multiple spheres of our society. For example, it entails expressive costs for healthcare
25 systems, thus significantly affecting the economy [1]. The socio-urban context of extended
26 periods of time spent indoors and increased urban densification has led researchers to investigate
27 the expressive impacts of built environments on our mental well-being and to explore how design
28 can help mitigate urban stress [2]. Previous studies have found that poorly designed buildings
29 can negatively impact a person's psychological state by causing stress, anxiety, depression, and
30 even violent behavior [3–5]. Greater focus has been placed on the affective experience elicited
31 by architectural design attributes within the domain of human-centered architectural design.
32 Specifically, the restorative potential of built environments, i.e., the capability to reduce mental
33 fatigue, improve productivity, and relieve stress, has attracted considerable interest in recent
34 years [6]. There is widespread agreement that particular design attributes of built environments
35 can influence our mental resilience or foster restorative experiences [7,8]. However, the relevant
36 knowledge to support experience-focused architectural design is scattered across several
37 disciplines, such as architecture, psychology, and sociology. In addition, the information
38 available in the early design stages is often vague, incomplete, and inconsistent [9,10]. Moreover,
39 analytical models and tools to facilitate the decision-making process in the early stages of the
40 design of built environments focused on emotional wellness are still scarce. Under this
41 circumstance, the designer is compelled to judge vaguely and subjectively the experience-related
42 quality of the design alternatives. Therefore, how to reduce the uncertainty and subjective bias
43 of human assessment while increasing efficiency in identifying the optimal design alternative
44 regarding the quality of experience criteria has been an area of great interest among researchers.
45 Among researchers in design domains, there is a common belief that measuring the user
46 experience of a product is the foremost step in improving such experience [9]. If the complex
47 nonlinear relationship between design attributes and quality of experience can be established
48 using mathematical methods, then it is possible to identify the design alternative with the highest
49 quality of affective experience while eliminating the influence of subjective assessment [9].
50 Specifically, if we could construct prediction models that can be applied to forecast restorative
51 experience values for each design alternative, the alternatives could be ranked by their restorative
52 potential and thus the designer could detect faults, conduct further improvements, and make the
53 appropriate decision on the design alternative, resulting in a more objective and efficient
54 evaluation and development process in the early design stages.

55 In the field of architectural design, attempts to use machine learning to predict building
56 performance in aspects such as environmental comfort have been made along with the
57 development of information and communication technology. It is believed that the convergence
58 between design and machine learning can address multifactor problems by finding connections
59 between variables (i.e., input, internal, and output variables) without explicit knowledge on the
60 physical behavior of the system [11,12]. Therefore, to evaluate the restorative quality of design
61 alternatives in support of the decision-making process for the design of built environments
62 focused on emotional wellness, this research aimed to develop machine learning models to
63 predict individual restorative experiences using design attributes. Evidently, success in obtaining
64 a reliable machine learning model depends heavily on the choice of input variables and the
65 available dataset [13]. The restorative experience addressed in this study can only be measured
66 with people's feedback; conducting such experiments on a large scale is usually time-consuming
67 and expensive in terms of the massive effort required for participant recruitment and data
68 collection [14]. An optimization of data collection for training machine learning models is
69 necessary to maintain the quality of the dataset and eliminate the number of experiments
70 conducted for data generation. Though several studies have associated the effect of design
71 attributes on restorative quality of built environment, few discussions on the interaction effect of
72 design attributes (i.e., the effect of one independent variable on an outcome depends on the state
73 of another independent variable) are present in the literature. What's more, earlier studies have
74 demonstrated different prediction performances among various machine learning models [15–
75 19]. These performance differences emphasize the impact of the problem context and provide a
76 strong reason to test several techniques for developing machine learning models.

77 In this regard, this study develops an integrated framework using non-immersive virtual reality
78 (VR) and design of experiment (DOE) to leverage machine learning techniques in predicting the
79 restorative quality of the built environment. The proposed method is intended to optimize the
80 data collection process and address the complexity and uncertainty in modeling the human
81 affective experience. The predictive performance of multiple machine learning models is
82 compared for further prediction model selection to support the decision-making in human-
83 centered architectural design. This approach could greatly help designers and decision makers
84 improve the efficiency of design, selection, and successive iteration processes by using a genetic
85 algorithm that employs specialized knowledge [20]. In addition, this study sought to identify the
86 interaction effect of design attributes on the perceived restorative experience in the built
87 environment, minimizing bias in estimating model parameters [21].

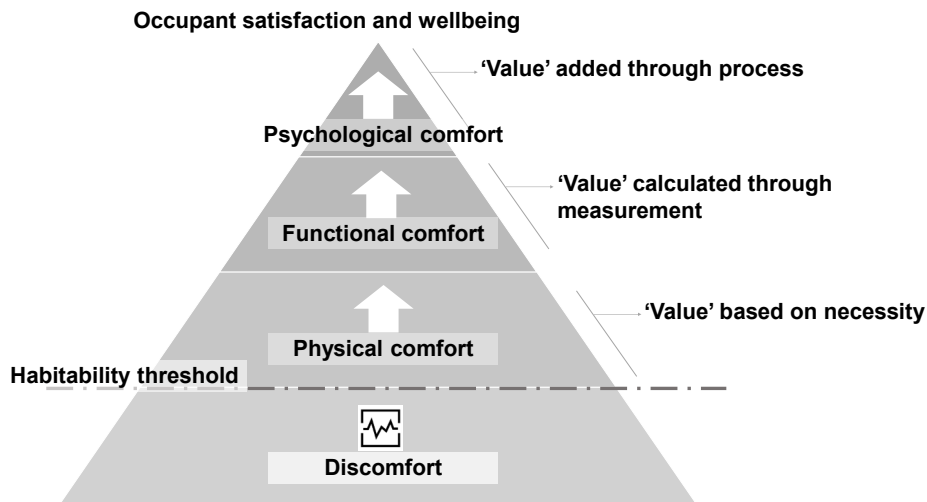
88 While a great number of studies related to restorative design have been conducted in the area of
89 institutional construction [22–24], there have been few empirical investigations into residential
90 design, despite the fact that emotional support and relaxation are major functions of the home
91 environment [25]. As such, the focus of the present study is on residential buildings. Meanwhile,
92 a generic kitchen model is used as a pilot study in our research since its essential functional
93 elements (e.g., storage unit, stove, and oven) are generally the same among different households
94 regardless of occupant differences in cultural background or personal preference. Thus, further
95 investigation is needed on the affective needs for other building types. In addition, although this
96 study aimed to quantify and represent the restorative experience of built environments using a
97 single value, it cannot guarantee the superiority of a design. The quantitative value obtained by
98 a predictive model is intended to be an indicator with the potential to evaluate the relative strength
99 of a design alternative.

100 The remainder of the present paper is organized as follows. Firstly, the literature pertaining to
101 qualitative and quantitative research on affective design and machine learning methods for
102 affective experience modeling to clarify the point of departure. Secondly, the research
103 methodology and scope are proposed and described in Section 3. A detailed discussion on the
104 non-immersive VR-DOE-based method for data collection is illustrated in Section 4. Section 5
105 presents the data analysis and machine learning models for restorative experience modeling.
106 Section 6 discusses the experimental findings and the predictive modeling results. Finally,
107 Section 7 concludes by highlighting the applicability and limitations of these research findings.

108 **2 Literature Review**

109 **2.1 Affective Design in Built Environment**

110 Affective design usually focuses on the emotional and mental communication between the user
111 and the products [26]. For decades, efforts have been made to understand the correlation between
112 built environments and corresponding human affective experience and utilize such correlation as
113 a foundation for human-centered building improvement in architectural domains [27,28].
114 According to Vischer’s environmental comfort model (see Figure 1), psychological comfort is
115 the highest level in the hierarchy for achieving occupant satisfaction, and it refers to a sense of
116 belonging, ownership, and control over an environment in which stress also plays a critical role
117 [29,30].



118

119

Figure 1. Habitability pyramid (source: Vischer [30])

120 There is consensus among scholars that specific characteristics of architectural environments
 121 could help people in reducing anxiety and recovering from cognitive fatigue and stress, thus
 122 increasing the overall satisfaction level attributable to built environments. Previous studies
 123 showed that design attributes, such as interior colors, views (through windows), lighting, and
 124 layout of the room, can serve as significant predictors in assessing the satisfaction level in
 125 healthcare facilities [22,23,31–33]. Various design elements in birthing centers, such as shapes
 126 and angles of walls, ceilings, and fixtures, were also found to be associated with women’s
 127 affective experience and birth outcomes [34]. The golden ratio design principle was also found
 128 to affect a person’s emotional response in an eye-tracking-based experiment [35]. The above-
 129 mentioned findings, equally, provide concrete evidence for designers optimizing affective design.
 130 For instance, decorative fountains have been increasingly used in healthcare facilities, as they
 131 can serve as positive distractions that reduce patients’ stress levels [36]. Many hospital designs
 132 integrate gardens or modify the traditional waiting area in terms of the general layout, color
 133 scheme, or furniture in order to improve the mood, the physiological state, and the overall
 134 occupant satisfaction level.

135 Even though the qualitative evidence can provide designers with referable case studies and
 136 additional information, it is imperative that the designers have extensive experience and domain
 137 knowledge for interpreting the research findings and integrating credible research evidence in
 138 support of implementing relevant approaches in the design process. In this regard, many scholars
 139 have been attempting to quantitatively measure the effect of architectural design attributes on
 140 human experience. Ergan et al. conducted a crowdsourcing-based experiment to examine
 141 occupants’ emotional reactions to various design attributes, such as window design, ceiling

142 height, color, and space layout; in the experiment, the participants were asked to select their
143 preferred space in a pair of bipolar scales and rate the preferred space with a semantic value [37].
144 To measure the human experience in a more objective manner, Ergan et al. also
145 incorporated body area sensor networks (i.e., EEG, GSR, and PPG) to evaluate people's
146 experience related to stress and anxiety under predefined different design scenarios [38].
147 Likewise, Martinez-Soto et al. used eye-tracking data to investigate people's reaction toward
148 environment with different restorative potential. Gao and Zhang adopted the measure of physical
149 measurement (i.e., skin conductance) and psychological scale to identify the patient's experience
150 toward design characteristics.

151 Overall, these studies have clearly indicated the quantitative relationship between architectural
152 design attribute and human experience. Nevertheless, compared to other building design
153 frameworks such as LEED and Living Building Challenge (LBC), affective design still lacks
154 clear analytical models and tools for practical application in current practice. Many experiments
155 in the context of affective design were usually conducted through a one-factor-at-a-time (OFAT)
156 method-based experiment design or by simultaneously altering multiple design attributes. This
157 poses a challenge in interpreting the independent or interactive effects of the variable (i.e., design
158 attribute) of primary interest. Thus, in this study, a machine learning method trained by data
159 collected using fractional factorial experiment design is used to model the relationship between
160 restorative experience and design attributes to predict the restorative quality of design
161 alternatives in support of the early design process.

162 **2.2 Prediction Models for Affective Design**

163 Models are frequently referred to as efficient media for synthesizing and communicating
164 knowledge during the design process. A model could be regarded as an abstraction used to
165 explain concepts and their relationships, which are too complex to be otherwise illustrated; for
166 example, the affective experience of architectural designs in this case [39].

167 In design domains, numerous attempts have been made to model the relationship between design
168 attributes and the user's affective experience using machine learning methods [40]. These models
169 can be generally categorized as multiple linear regression, artificial neural networks (ANNs),
170 support vector machines (SVMs), and fuzzy inference systems (FISs) [19]. Specifically, multiple
171 linear regression is widely used in the domain of affective modeling because of its easy
172 implementation and interpretation [41]. Lanzotti and Tarantino applied logistic regression (i.e.,
173 a variant of linear regression) to predict users' perceived quality toward the interior design of
174 trains [41]. Park et al. utilized linear regression models to model the user affective experience of
175 mobile phones, which showed satisfactory performance in terms of goodness of fit [42]. However,

176 this modeling was performed under the assumption that design attributes are linear with respect
177 to a user's affective experience [19]. Thus, the uncertainty and bias in questionnaire data are
178 typically neglected in the regression model. Compared with linear regressions, ANN models have
179 been shown to be more capable of handling the nonlinear nature of human perception phenomena.
180 Many neural networks have been adopted to depict the nonlinear relationship between user
181 affective experience and product features for affective designs such as designs for motorcycle
182 helmets, paddle tennis rackets, mobile phones, and office chairs [19,43,44]. For instance, a radial
183 basis function was introduced by Chen et al. [45] to evaluate the cultural influence on affective
184 experience. This function attempts to model data uncertainty by simulating the bell-shaped
185 distribution in fuzzy-based systems. Similarly, Ling et al. [18] incorporated a wavelet function-
186 based ANN to perform an affective design for mobile phones. Although ANNs can capture the
187 nonlinearity between affective experience and the related design attributes, the unexplained
188 behavior of the network, labeled the "black-box," reduces trust in the solutions [46]. In this regard,
189 support vector regression (SVR), an extension of the SVM, is suggested as an alternative method
190 for mapping the nonlinearity of feature space. The SVM is a popular machine learning tool, first
191 identified by Vapnik, who observed its excellent performance in solving sparse and noisy data
192 that usually exist in real-world problems such as pattern recognition [43]. In the design domain,
193 SVR has been successfully adopted in predicting user affective responses based on product
194 attributes [44,45]. Yang and Shieh [44] employed SVR to develop a model for predicting
195 consumer affective responses to product forms. Fan et al. [45] proposed an SVR approach to
196 model the relationship between design attributes and customers' affective responses.
197 Interestingly, Chan et al. [19] reviewed the literature that reports on the use of ANNs and SVR
198 for affective modeling and found that SVR models perform better overall compared with neural
199 network models. Moreover, taking advantage of its interpretability with which the developed
200 model can be interpreted, verified, and improved by human experts, FIS, also known as a fuzzy
201 rule-based model, was introduced by Lai et al. [46] in mobile phone design to handle the
202 nonlinearity and fuzziness of human affective experience [50]. Similarly, this fuzzy rule-based
203 modeling approach was also adopted in designing cars and office chairs [20,47,48].
204 In summary, this section provides a brief discussion of the general machine learning methods
205 used to determine the relationship between human affective experience and design attributes.
206 Even though many studies address the customer's affective needs for product designs, the
207 relevant research in built environment design remains limited. Therefore, this study aims to
208 assess the feasibility of using typical machine learning models (i.e., linear regression, ANN,
209 SVM, and FIS) in predicting human affective experience of built environment.

210 3 Research Methodology

211 The primary objective of this study is to develop data-driven prediction models to evaluate
212 restorative quality of design alternatives in support of the decision-making process for human-
213 centered architectural design. To achieve this goal, a careful feature selection and data collection
214 is necessary to deliver meaningful predictive modeling results. Accordingly, the present study
215 proposes an integrated VR-DOE-based machine learning method to predict the restorative
216 experience of the built environment. The data collection optimization was performed using the
217 DOE method so that the input variable and data were properly selected to provide the most
218 unbiased and precise results commensurate with the desired expenditure of time and effort. The
219 use of DOE method also enables one to identify the output variation caused by the effect of the
220 interaction among factors, providing researchers with a better understanding of the relationship
221 between the restorative quality and the design attributes of the built environment, as well
222 as explains more about the variability in the dependent variable [21]. Here, fractional factorial
223 design was the DOE method used for experiment design, as it makes it possible to obtain a
224 reasonable amount of training data through a fewer experiments number and screen the effect of
225 each factor. Meanwhile, linear regression and three other machine learning modeling methods
226 (artificial neural network, support vector regression, and fuzzy inference system) are employed
227 to develop models to predict the restorative quality of a space, given its particular design
228 attributes, and a comparative analysis of the performance of each predictive model is then
229 conducted. In addition, this study incorporates relevant psychometric scales to scientifically
230 measure the human-perceived restorativeness in virtual reality simulated environments, in order
231 to maximize the utility of predictive models.

232 The steps of the research methodology are presented in Figure 2. The first and foremost step is
233 to perform a comprehensive review of the available literature on architecture and psychology to
234 identify the architectural design attributes that potentially influence the restorative- or stress-
235 related human experiences (see section 4.1). The second step is to design and perform
236 experiments, to investigate human responses related to restorative experiences under various
237 combinations of design attributes, and collect data. A two-level fractional factorial design is
238 employed to generate various combinations of design attributes for the experiments (see section
239 4.2), wherein the setting of each experimental run is generated in the form of a 360-degree
240 panorama (i.e., VR image-based models) using Autodesk Revit®. This allows a careful yet
241 effortless evaluation of the design model using any mobile or VR device (see section 4.3). These
242 VR image-based design models are then used in the experiment to assess the restorativeness of

243 the built environment. Additionally, a questionnaire is developed using psychometric scales (i.e.,
 244 perceived restorativeness scale and restoration-supportive built environment scale), based on the
 245 previously reported studies on perceived restorativeness (see section 4.4) [49–51]. Once the
 246 questionnaire and the VR panorama-based models for each experimental run are prepared and
 247 examined through a pilot test, the online experiment is launched through emails and social media
 248 platforms to collect data (see section 4.5). The collected data are subsequently preprocessed, and
 249 the corresponding results are analyzed for statistical significance (see section 5.1 and 5.2). Once
 250 the input features are selected, multiple machine learning models are used to predict the
 251 restorative qualities of the built environment using design attributes (see section 5.3). Finally, a
 252 regression performance analysis of the developed predictive models is performed to identify the
 253 most appropriate models that can forecast the overall restorative quality of a built environment
 254 with several design alternatives.

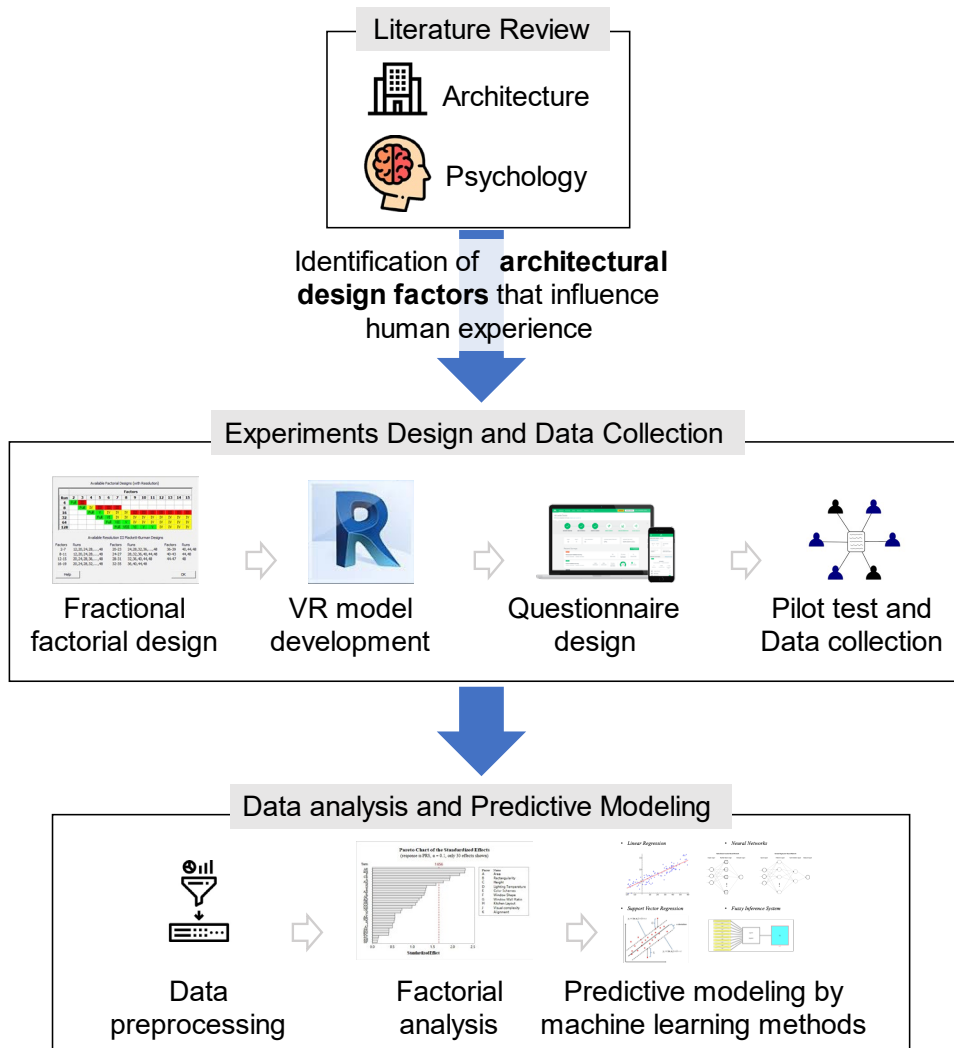


Figure 2 Research methodology

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257 4 Experiments Design and Data Collection for Human Restorative Experience

258 4.1 Architectural Design Attributes

259 Many architectural design attributes have been found to be related to human-perceived
260 restorativeness in the built environment [22,37]. It is generally believed that design attributes that
261 support fascination, curiosity, or involuntary attention can be credited for enhancing recovery
262 from mental fatigue [34]. Table 1 lists the eight architectural design attributes commonly related
263 in the literature to restorativeness- and stress-related experiences.

264 Table 1. Architectural design attributes associated with human restorativeness- and stress-related
265 experience in the literature

Architectural design attributes	References
Exposure to nature and indoor plant	[52–57]
Presence/absence, dimensions, shapes of windows	[23,58–63]
Openness/Spaciousness of spaces	[64–68]
Lighting	[69–72]
Finish color scheme	[73–80]
Visual complexity	[1,81–83]
Space layout	[33,37,84–87]
Spatial alignment	[37,88,89]

266 *Window Designs and Access to Natural Elements*

267 Access to natural elements and the presence of windows are the components most frequently
268 discussed in the study of human restorative experience in built environments. Research suggests
269 that increased exposure to bright light effectively reduces depression and improves the mood of
270 occupant-users, even for people hospitalized with severe depression [55–57]. In this context,
271 windows in built environment settings have been of great interest among scholars. Pati et al.
272 indicated that the presence of windows has a positive impact on stress reduction, while Nejati
273 supported that a window enhances the perceived quality of the overall experience of a physical
274 environment [23,61]. Moreover, Lowenhaupt Collins pointed out that the perceived quality of a
275 window's view is intimately related to the window's dimension and shape [62]. Generally, higher
276 occupant satisfaction and visual comfort are associated with higher window-to-wall ratio (i.e.,
277 30%) than with a lower window-to-wall ratio (i.e., 15%), as showed in Taehoona et al.[63].

278 *Spaciousness of Spaces*

279 The perceived spaciousness of an interior space has been correlated with a reduction in the feeling
280 of stress and anxiety. Previous studies indicate that ceiling height, aspect ratio, and square
281 footage are the main attributes that determine how people experience a space. That is, the larger
282 the horizontal areas and the higher the ceiling height, the more spaciousness people perceive and,
283 ultimately, the more comfortable they feel in the environment [64,66–68].

284 *Lighting*

285 Lighting has been considered a potential source of fascination to restore attention and promote
286 the use of unintentional attention by augmenting one's perception of the environment [69]. Both
287 the illuminance level and the correlated color temperature have been associated with attention
288 restoration through the perception of brightness and the quality of color environments [72].
289 According to Manav, the color temperature of 4000k was preferred to 2700K for the perception
290 of comfort and spaciousness, while an illumination level of 2000 lx was preferred to 500 lx for
291 impressions of comfort, spaciousness, brightness perception, and color saturation [72].

292 *Color Scheme*

293 The choice of colors in architectural design plays a significant role in the process of attention
294 restoration for individuals, as it is associated with one's feeling of serenity or agitation, which in
295 turn impacts one's stress level [77–79]. Generally, warm color schemes involving shades of
296 orange, yellow, and brown help people increase their awareness, whereas cold color schemes,
297 including shades of green, blue, and grey, help people focus on visual and mental tasks [80].

298 *Visual Complexity*

299 Visual complexity is associated with visual attention and comfort with regard to the assumption
300 that design attributes that enable one to capture involuntary attention can facilitate mentally
301 restorative processes. The amount of detail in visual stimuli affects a person's ability to be
302 effortlessly attentive [83]. In studies on visual perception [1], people have shown a preference
303 for designs with greater visual complexity.

304 *Space Layout*

305 The layout of space (i.e., symmetry of objects in the interior environment) has also been
306 identified as an influential design attribute, altering environmental perceptions [37]. A
307 symmetrical space layout increases the perceived quality of the environment and affects occupant

308 satisfaction [33]. Enquist and Arak found that people appreciate greater symmetry and that
309 symmetrical patterns hold an almost universal appeal for humans [86,87].

310 *Spatial Alignment*

311 Spatial alignment allows the brain to identify similarities and differences among elements, which
312 effectively draws visual attention to one important region by enhancing that region's visual
313 saliency [89]. Based on their human experience and a built environment-related experiment,
314 Ergan et al. concluded that people associate the experience of pleasure and aesthetics with the
315 presence of spatial alignment and show greater preference for aligned spaces [37].


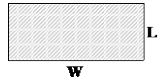


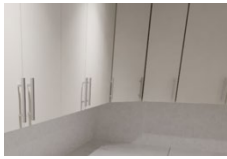



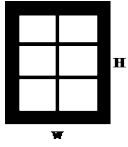
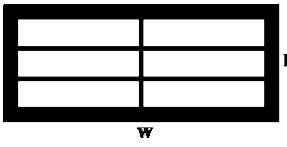
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317 Based on the literature review and given the context of this study, the following 10 design
318 attributes that are typical of architectural design elements in residential environments were
319 selected and investigated in this study: 1) room size, 2) rectangularity of room shape, 3) ceiling
320 height, 4) light temperature, 5) visual complexity, 6) room layout symmetry, 7) window-to-wall
321 ratio, 8) window aspect ratio, 9) finish color scheme, and 10) space alignment.

322 **4.2 Experiments Design**

323 Statistical experimental design is frequently performed in experiment planning, as it allows
324 appropriate data to be collected and analyzed in order to deliver valid and objective conclusions.
325 The present study endeavored to establish a 'balanced' dataset that comprehensively represents
326 all sample populations for predictive model development so that the model can characterize the
327 relationship based on the data rather than merely 'memorizing' the training data of over- or
328 under-represented populations [90]. To obtain uniformly distributed data over the investigated
329 attributes and reduce the total number of experiments (design alternatives) required, the
330 fractional factorial design approach was employed in this study to develop a balanced dataset.
331 Specifically, two levels were assigned to each design attribute, as presented in Table 2. It should
332 be noted that the space-A and space-B in the table are only meant to illustrate the different values
333 of design attributes. The experiment aimed to gather response data from people regarding the
334 extent of their perceived restorativeness in a setting that combines various interior design
335 attributes. Compared to randomized controlled trial design, factorial design allows the researcher
336 to comprehensively evaluate the influence of multiple attributes and detect interaction effects
337 among these attributes [91]. However, for a study with many independent variables, full factorial
338 design can lead to an excessive number of experimental runs and data, i.e., in this study, 1,024
339 experimental runs are required for full factorial design. In this context, fractional factorial design
340 is considered a cost-efficient experiment design because it requires fewer experimental runs

341 while maintaining the same level of statistical power [92]. In this study, the restorative quality
342 of each design alternative (experimental run) was evaluated by the participants, and a greater
343 number of experimental runs would significantly affect the respondent's cognitive burden and
344 the relative costs associated with data collection. Thus, in this study, a $1/2^5$ factorial experiment
345 design was conducted to examine the effect of the 10 aforementioned architectural design
346 attributes at a two-level resulting in 32 experimental runs, which supports the selection of input
347 features for further predictive modeling [93]. Table 3 presents the 32 experimental runs (design
348 alternatives) of this study, as generated by the Minitab statistics software. Each run represents a
349 combinatorial design alternative modeled later using Revit and evaluated in the later experiment.
350
351

352 Table 2. List of attributes and their levels with two unlabeled design alternatives in the
 353 experiment

Design attributes	Space-A	Space-B
Room size	110 ft ²	210 ft ²
Rectangularity of room shape	 Square	 Narrow Rectangle
Ceiling height	Slightly low	Slightly high
Light temperature	 Warm-white	 Daylight
Visual complexity	 Moderately low	 Moderately high
Room layout symmetry	 Asymmetric	 Symmetric
Window-to-wall ratio	Slightly low	Moderately high
Window aspect ratio	 Vertical	 Horizontal

Finish color
scheme



Clean-White

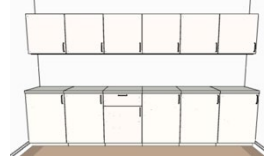


Modern Rustic

Spatial
alignment



Unaligned



Aligned

354

355

356 Table 3. Experimental runs of design alternatives selected by fractional factorial design

Run	Attributes									
	Room size	Rectangularity of room shape	Ceiling height	Light temperature	Finish color scheme	Window aspect ratio	Window to wall ratio	Room layout symmetry	Visual complexity	Space alignment
1	210 ft ²	Narrow rectangle	Low	Daylight	Modern rustic	Horizontal	Low	Symmetric	High	Unaligned
2	110 ft ²	Square	Low	Warm-white	Modern rustic	Vertical	Low	Asymmetric	High	Unaligned
3	110 ft ²	Narrow rectangle	High	Daylight	Modern rustic	Horizontal	Low	Asymmetric	High	Aligned
4	210 ft ²	Square	High	Warm-white	Clean-white	Vertical	High	Asymmetric	Low	Unaligned
5	110 ft ²	Narrow rectangle	High	Warm-white	Clean-white	Vertical	High	Asymmetric	High	Aligned
6	110 ft ²	Narrow rectangle	High	Warm-white	Modern rustic	Vertical	Low	Symmetric	Low	Unaligned
7	210 ft ²	Narrow rectangle	High	Warm-white	Clean-white	Horizontal	Low	Symmetric	Low	Aligned
8	110 ft ²	Square	High	Daylight	Clean-white	Vertical	Low	Asymmetric	Low	Aligned
9	110 ft ²	Square	High	Warm-white	Modern rustic	Horizontal	High	Asymmetric	Low	Aligned
10	110 ft ²	Square	Low	Warm-white	Clean-white	Vertical	High	Symmetric	Low	Aligned
11	110 ft ²	Narrow rectangle	Low	Warm-white	Modern rustic	Horizontal	High	Symmetric	High	Aligned
12	110 ft ²	Narrow rectangle	Low	Warm-white	Clean-white	Horizontal	Low	Asymmetric	Low	Unaligned
13	110 ft ²	Narrow rectangle	Low	Daylight	Clean-white	Vertical	Low	Symmetric	High	Aligned
14	110 ft ²	Narrow rectangle	High	Daylight	Clean-white	Horizontal	High	Symmetric	Low	Unaligned
15	210 ft ²	Square	High	Daylight	Modern rustic	Horizontal	Low	Asymmetric	Low	Unaligned
16	210 ft ²	Square	Low	Daylight	Modern rustic	Vertical	High	Asymmetric	High	Aligned
17	210 ft ²	Square	Low	Daylight	Clean-white	Vertical	Low	Symmetric	Low	Unaligned
18	110 ft ²	Square	Low	Daylight	Modern rustic	Horizontal	Low	Symmetric	Low	Aligned
19	210 ft ²	Narrow rectangle	High	Daylight	Modern rustic	Vertical	High	Symmetric	Low	Aligned
20	110 ft ²	Square	High	Warm-white	Clean-white	Horizontal	Low	Symmetric	High	Unaligned
21	110 ft ²	Narrow rectangle	Low	Daylight	Modern rustic	Vertical	High	Asymmetric	Low	Unaligned
22	210 ft ²	Narrow rectangle	High	Warm-white	Modern rustic	Horizontal	High	Asymmetric	High	Unaligned

23	210 ft ²	Square	Low	Warm-white	Clean-white	Horizontal	Low	Asymmetric	High	Aligned
24	210 ft ²	Square	High	Daylight	Clean-white	Horizontal	High	Symmetric	High	Aligned
25	110 ft ²	Square	High	Daylight	Modern rustic	Vertical	High	Symmetric	High	Unaligned
26	210 ft ²	Narrow rectangle	High	Daylight	Clean-white	Vertical	Low	Asymmetric	High	Unaligned
27	210 ft ²	Square	High	Warm-white	Modern rustic	Vertical	Low	Symmetric	High	Aligned
28	210 ft ²	Narrow rectangle	Low	Daylight	Clean-white	Horizontal	High	Asymmetric	Low	Aligned
29	210 ft ²	Narrow rectangle	Low	Warm-white	Modern rustic	Vertical	Low	Asymmetric	Low	Aligned
30	210 ft ²	Square	Low	Warm-white	Modern rustic	Horizontal	High	Symmetric	Low	Unaligned
31	110 ft ²	Square	Low	Daylight	Clean-white	Horizontal	High	Asymmetric	High	Unaligned
32	210 ft ²	Narrow rectangle	Low	Warm-white	Clean-white	Vertical	High	Symmetric	High	Unaligned

357

358 4.3 Virtual Reality Model Generation

359 It would be impractical to provide 32 real room settings with defined design attributes for the
360 purpose of the experiment. Thus, following the DOE results, each experimental run (design
361 alternative) was represented in a VR-based 360-degree panoramic model (see Figure 3). The
362 basic geometry, structure, and design setting of the virtual environment and objects (e.g., cabinet,
363 countertop, sink, light fixture) were configured in a building information model in Revit (2019).
364 Autodesk Cloud Rendering was then used to render the design into high-resolution stereo
365 panoramas that could be shared via a website URL. Participants could then use either a
366 smartphone with cardboard VR viewer or a desktop to access the VR panorama.

367 A number of studies have demonstrated that there is not a significant difference in terms of
368 occupant perception between physical spaces and well-designed VR environments [63,94–97].
369 Moreover, using VR models rather than static images to represent design configurations allows
370 for a continuous stream of congruent stimuli that deliver a vivid illusion of reality to the
371 participant. This has to do with the concept of “presence,” the subjective feeling of “being in a
372 virtual environment,” which determines the effectiveness of a VR simulation. On the other hand,
373 to ensure adequate visual fidelity among various VR display platforms (e.g., smartphone-based
374 VR and desktop-VR paradigms), the devices used in the experiment (VR display type and
375 resolution configurations) were recorded. Although the interaction fidelity and immersion level
376 provided by the two display systems used are different, their influence on emotional elicitation

377 may not be significant [98–103]. Meanwhile, an assumption was made in this study that a
378 satisfactory sense of presence provided by the VR model can ensure sufficient emotional
379 stimulation of participants, since the emotional elicitation effect is strongly associated with the
380 feeling of presence in a VR platform [104]. Therefore, multiple questions adopted
381 from Heydarian et al. [105] assessing the realism of the VR environment compared to the
382 physical world were included in the questionnaire in order to verify the validity of the developed
383 VR model.
384



385
386 Figure 3 Screenshots of VR models for experimental runs
387

388 4.4 Design of Questionnaire

389 During the experiment, participants were expected to assess the restorative quality of a room
390 setting and describe their relevant experience by filling out a questionnaire, which consisted of
391 two parts: a) background questions and b) restorative experience measurement.

392 4.4.1 Background Questions

393 Prior to the questions measuring one's restorative experience, the questionnaire asked for
394 demographic information, including age, gender, and education level, and past experiences with
395 architectural design, virtual reality models, and built environments as settings for restorative
396 experiences. The additional background questions regarding past experiences with architectural
397 design, virtual reality models, and built environments were intended to examine the influence of
398 these experiences on the interpretation of results pertaining to perceived restorativeness.
399 Moreover, the Ishihara color blindness test was added as a core module in the demographic

400 information portion of the questionnaire to identify and eliminate the potential influence of
401 participants with color blindness.

402 **4.4.2 Restorative Experience Measurement**

403 To measure the human-perceived restorativeness of the built environment in a reliable and
404 quantifiable manner [106], two self-reported restorativeness scales—the Perceived
405 Restorativeness Scale (PRS) by Hartig et al. [49,51] and the Built Environment Restoration
406 Support Scale (BERS) by Fischl and Garling [107]—were incorporated in this study as part of
407 the questionnaire. Self-reported restoration experience assessment, as an explicit measure, has
408 been widely used in studies on environmental restorativeness to quantify individual’s
409 psychological reactions [50,106,108]. Specifically, the selected self-reported scale, PRS, is one
410 of the most widely used measures addressing the extent to which certain environmental settings
411 have restorative qualities, and its validity has been proven by sufficient psychometric analysis in
412 terms of content, construct, convergent, discriminant, and criterion-related validity [50,106].
413 This scale has been credited for its generalizability and sensibility in identifying differences in
414 perceived restorativeness in a given environment on the part of participants of various ages,
415 health levels, and nationalities. However, PRS is rarely used for indoor environments. In
416 comparison, the BERS was explicitly proposed to assess the restorative quality of the built
417 environment but rarely examined in previous studies. Since limited attempts have been made to
418 examine the validity of the BERS, it was included in the questionnaire only as a supplemental
419 measure to the PRS.

420 In the PRS measurement, perceived restorativeness is assessed using four dimensions, namely,
421 the feelings of “being away,” “fascination,” “coherence,” and “compatibility,” based on Kaplan
422 and Kaplan’s Attention Restoration Theory [109,110]. Given this paper’s focus, the interested
423 reader can refer to the cited references [51,111] for a detailed description of each restorativeness
424 dimension. The PRS measurement developed by Hartig et al. [49,51] uses either 26 or 16 items.
425 This study adapted the 16-item method to make it more suitable for use in research contexts
426 where the evaluated scenario comprises indoor built environments [51]. As a result, 17 seven-
427 point Likert-scale questions (see Table 4) were proposed in the questionnaire to measure the
428 participants’ perceived restorativeness. Moreover, to measure restorative experience in a
429 standardized, plausible, and relevant context, emotion-provoking methods that put participants
430 under psychological stress before exposure to configured environmental settings have been
431 commonly used in previous studies to ease the restoration effect measurement [22,112]. Thus, a
432 scenario description adapted from Lindal and Hartig [65] was provided to participants before
433 moving on to the restorativeness measurement for the contextual stimuli control: *Imagine it is*

434 *afternoon. You are walking home from work alone. You are mentally exhausted from intense*
 435 *concentration at work, and you appreciate having a chance to stroll and recover.* The purpose
 436 of this affective description was to specify a condition of directed attention fatigue and to
 437 emphasize for participants the range of variation in compatibility due to factors other than a
 438 change in the physical environment [65].

439 It is noteworthy that the developed questionnaire was reviewed by six researchers in the field of
 440 architectural design and ergonomics before being sent to prospective respondents. These
 441 researchers were asked to provide feedback on the visual noticeability of the design attributes as
 442 the visual stimulus component of the environmental settings, as well as on the validity of each
 443 questionnaire item in terms of wording, format, content, and clarity. Based on the researchers'
 444 feedback, the VR models and questionnaire were modified and finalized.

445 Table 4. Measurement items in questionnaire

Dimensions		Questionnaire Items
	Being Away	Spending time here gives me a break from my day-to-day routine.
		Being here helps me to relax my focus on getting things done.
	Fascination	This place is fascinating.
		This place draws my attention without any effort on my part.
		My attention is drawn to many interesting features in this space.
		I want to get to know this place better.
Perceived Restorativeness Scale (PRS)	Coherence	There is much to explore and discover in this space.
		There is too much going on in this space.
		This is a confusing place.
		There is a great deal of distraction in this space.
Compatibility		It is chaotic in here.
		This space fits my character.
		I can do things I enjoy in this space.
		Sometimes even a small space can feel like a whole world of its own.
		It can seem like it is enough room to become completely engaged in this space and not concern yourself with anything beyond its walls.
		It is easy to see how things are organized in this space.
		I could find ways to enjoy myself in a place like this.

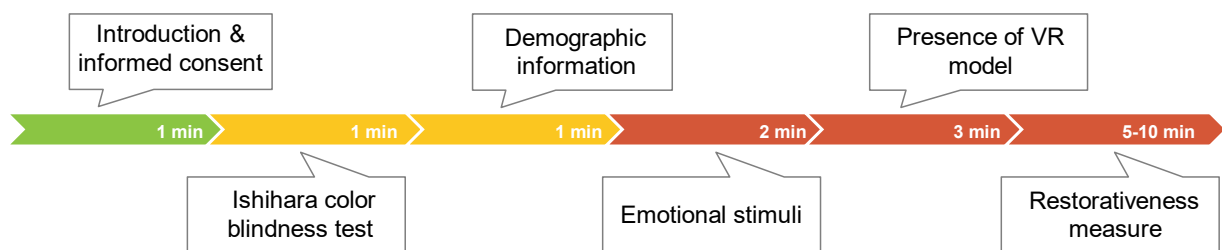
Built Environment Restoration
Support Scale (BERS)

Recall one of those times when you worked hard on a project that required intense and prolonged effort. Remember how it felt. You probably reached a point where you could tell that your ability to work effectively had started to decline and that you needed a break. You needed to do something during the break to restore your ability to work effectively on the project. Put yourself in that mindset now, and then please rate your satisfaction level toward the presented design as a setting in which to take a break and restore your ability to work effectively.

446

447 **4.5 Participant Recruitment and Data Collection**

448 Data collection was conducted via the Internet. Participants received an invitation letter through
449 e-mail that contained a link to the online questionnaire. Participants were invited to complete the
450 experiment voluntarily, and could withdraw at any time. A total of 32 VR models (one for each
451 experimental run) were assessed in this study. Figure 4 shows the procedure for a single
452 experimental session. After the introduction and background information section, participants
453 were given 2 min to read a paragraph of affective text (i.e., stimulus material for eliciting stressful
454 feelings) as stated in Section 4.4.2 [22,112]. Then, a 3-min non-immersive VR experience of the
455 configured design was provided, where the exposure duration was determined in reference to
456 previous lab-based human affective-related experiments [38,113–116]. Afterward, participants
457 were asked to evaluate their perceived restorativeness experience by answering the next section
458 of the questionnaire. An access link was made available in every question so that the participant
459 could re-visit the VR environment as needed to reduce memory load and improve the accuracy
460 of the affective judgment. Each experimental session took approximately 13-20 minutes on
461 average to complete.



462

463 Figure 4 Overview of a single experimental session

464 5 Data Analysis and Prediction

465 Once the responses were collected through the experiments, data preprocessing and analysis were
466 then performed to identify the meaningful input features for the development of prediction
467 models. In this study, five machine-learning models, namely, linear regression, radial basis
468 function neural network (RBFNN), general regression neural network (GRNN), SVR, and FIS,
469 were developed to predict the human restorative experience toward the built environment. Their
470 predictive performance was also compared using performance metrics for further model selection.

471 5.1 Data Pre-Processing

472 Data preprocessing aimed to clear responses that did not meet certain criteria, such as incomplete
473 responses, responses that were given too quickly (“speeder” responses), inconsistent responses,
474 and outlier responses [117,118]. Specifically, to ensure the credibility of the experimental results,
475 four indices—(a) total response time, (b) response patterns (i.e., *LongString*), (c) Mahalanobis
476 distance, and (d) Cronbach’s alpha—were calculated based on the response data, and data
477 cleaning was performed accordingly. For example, the speeder and inattentiveness responses can
478 be easily identified through the respondents’ response times and patterns. The response time
479 measures the total time needed by the respondent to complete the questionnaire. A much shorter
480 response time indicates that the respondent may be speeding through questions and paying little
481 attention to providing an assessment. The response pattern is analyzed to identify respondents’
482 careless responses (for example, a respondent who consistently provides the same answer).
483 Following the method proposed by Johnson [119], an index termed *LongString* was used to
484 compute the maximum number of items with identical consecutive response on a single page
485 [117–119]. As for the outlier responses, the Mahalanobis distance, denoted as *MD* in Equation
486 1, was computed for each response for the same design alternative, measuring the multivariable
487 distance between each response vector and the mean of the sample vector, which indicates the
488 individual responses outside the distribution. Moreover, with respect to the internal consistency
489 of the measures, Cronbach’s alpha (see Equation 2) was estimated to reflect the extent to which
490 the question was inter-correlated in measuring the participants’ perceived restorative experience.
491 In alignment with previous works, a of at least 0.7 was also used in this study to indicate adequate
492 internal consistency of responses [120].

$$MD^2 = (r - \hat{r})^T \cdot C^{-1} \cdot (r - \hat{r}) \quad (1)$$

493 where r is the vector of the response; \hat{r} is the vector of mean value; and C is the covariance
494 matrix of these two variables’ vectors.

495

$$\alpha = \frac{n}{n-1} \left(1 - \frac{\sum \sigma_i^2}{\sigma_x^2} \right) \quad (2)$$

496 where n is the number of responses; σ_i^2 is the variance of questionnaire item i ; and σ_x^2 is the total
497 variance of the questionnaire.

498

499 **5.2 Factorial Analysis**

500 To detect which architectural design attributes and which interactions between attributes
501 influence one's perceived restorativeness to the greatest extent, an analysis of variance (ANOVA)
502 was performed on the remaining dataset (i.e., after data pre-processing) using Minitab 18
503 statistical software. The main effect of a design attribute was measured by the corresponding
504 change in the output, i.e., the restorative experience associated with the change made at the level
505 of that design attribute averaged over other design attributes. The interaction effect (i.e., two-
506 way interaction between variables A and B) is defined as the average difference between the
507 main effect by A at the high level of B and the effect of A at a low level of B. Note that the
508 significance of a design attribute or its effect on restorative experience is determined by its p-
509 value [121].

510 **5.3 Predictive Modeling for Restorative Experience**

511 As reported in previous studies, prediction models developed using machine-learning methods
512 may show different prediction performances under various problem contexts [16–20]. To explore
513 the capability of machine-learning models in affective modeling for built environments, linear
514 regression and three other typical machine-learning methods (ANN, SVR, and FIS) were tested
515 to develop the prediction models for human restorative experience. These three machine learning
516 models were adapted from a comprehensive literature review conducted by Chan et al. [19] that
517 examined 94 research publications and summarized the machine-learning methods used to model
518 the relationship between the affective quality of a product and its design attributes. Among the
519 machine-learning methods discussed in the study by Chan et al., we focused on models with a
520 lower variance capable of characterizing the relationship from a small dataset in order to mitigate
521 the risk of overfitting (considering that it is impractical to conduct such data collection
522 experiments on a large scale, given the associated cost and effort). As a result, three machine-
523 learning methods were selected due to their generic applicability and their ability to handle noisy
524 and nonlinear small datasets, as proven in previous studies [19].

525 The inputs to the machine-learning models included the selected variables identified as
526 statistically significant based on the factorial analysis in the previous step, while the output was

527 the numeric measurement of the reported restorative experience. To begin, the dataset was
528 divided into a training set and a validation set. The overall dataset was divided into training and
529 testing sets based on the principle that the size of the dataset for machine learning should be
530 roughly ten times the degrees of freedom in the model, which means approximately 100 sample
531 points are needed for a 10-variable model. Although we would like to have kept as many samples
532 as possible in the training dataset to provide more features for training, an inordinately small
533 testing set may have resulted in unacceptably high variance in the performance assessment results.
534 Thus, 100 responses (83%) were used for training and 20 responses (17%) for testing. Due to the
535 limited sample sizes, k-fold cross-validation was applied to the training set to mitigate the risk
536 of overfitting and to enhance the model fitting and generalization. The training set was initially
537 used to identify the optimal model parameter with 5-fold cross-validation. The parameter setting
538 achieving good performance in minimizing the averaged 5-fold cross-validation error for both
539 the training set and the testing set was determined to be the optimal solution. Subsequently, the
540 parameters obtained were adapted in order to train/fine-tune a model using the entire training set
541 (i.e., 100 responses). Accordingly, the trained models were evaluated on the validation set (i.e.,
542 20 responses), and performance metrics of RMSE and R^2 were used to evaluate the predictive
543 performance of the models. All design and training of the machine-learning models was
544 performed in MATLAB 2020b. It should be noted that the optimal parameters of each method
545 were determined based on the best prediction performance via grid search in the parameter space
546 after multiple trial-and-error tests. The following subsections describe the process of developing
547 the machine-learning models.

548 **5.3.1 Linear Regression Model**

549 Linear regression model (see Equation 3) predicts the output, i.e., perceived restorativeness in
550 the built environment, as a weighted sum of the input features. Each weight ω_i of the input
551 features in the model can be determined by the least-squares method as well as maximum
552 likelihood estimation. To maximize the precision of predictors in a model, insignificant variables
553 were eliminated in a stepwise manner during the regression process. A threshold of 0.1 regarding
554 the variables' statistical significance (i.e., p-value < 0.1) was applied during the linear regression
555 to avoid an underspecified regression model, in accordance with the limitation of the sample size
556 and the subjective nature of self-reported surveys. All individual factors and the lower terms of
557 interaction factors with significant effects were included in the linear model to present the model
558 hierarchy.

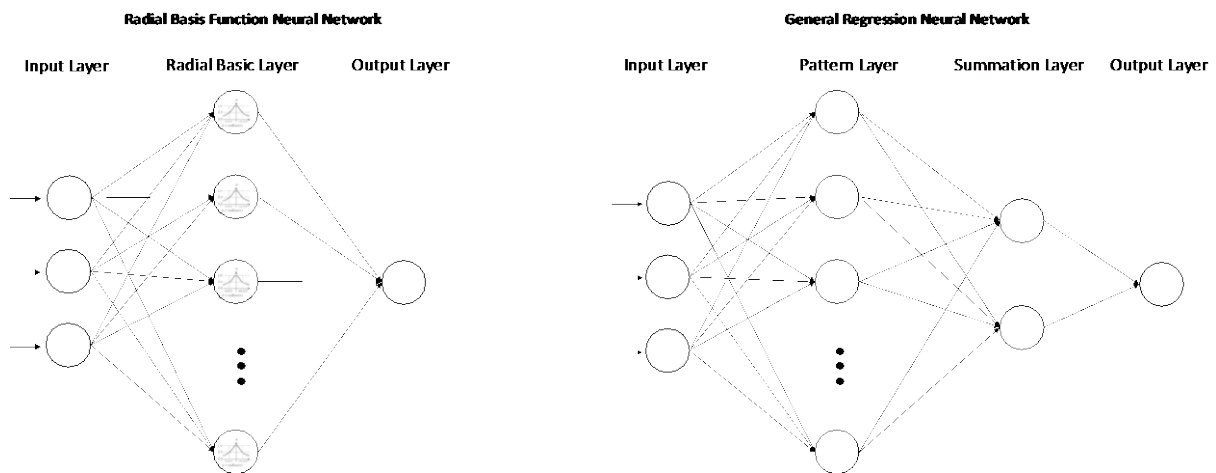
$$Y = f(x) = \sum_{i=1}^n \omega_i x \quad (3)$$

559 **5.3.2 ANN Model**

560 To choose a neural network architecture, multiple factors are considered, such as a simple model
 561 architect, strong capability for nonlinear fitting, generalization for new data, and tolerance for
 562 small sample size and high noise by human subjectivity in an affective design. Inspired by
 563 previous studies and data characteristics [122–127], the radial basis function neural network
 564 (RBFNN) and the general regression neural network (GRNN) were used in this study because of
 565 their ability to achieve global optimization with strong robustness and fault tolerance [124]. At
 566 times, it should be noted, they have even demonstrated better accuracy and training speed than
 567 other neural networks with simple architecture, e.g., multilayer perceptron networks [128,129].
 568 Figure 5 shows their respective architectures.

569 The RBFNN is a three-layer feedforward network that uses radial basis function as its activation
 570 function. The output of this result can then be expressed as a scalar function of input vectors, as
 571 shown in Equation 4. Here, $\varphi(x, x_c)$ denotes the radial basis function whose output depends on
 572 the Euclidean distance to the center x_c . To calculate the center of the radial, the Gaussian function
 573 (see Equation 5) was used on each hidden unit as the transfer function. The value coming out of
 574 the hidden layer (i.e., radial basic layer) is multiplied by a weight associated with the node and
 575 passed to the output layer. Then, the output layer accumulates up the weighted values and
 576 presents this sum as the network’s output.

577



578

579

Figure 5 Architectures of the RBFNN and the GRNN

580

581

$$Y = f(x) = \sum_{j=1}^m w_j \varphi_j(x, x_c) \quad (4)$$

$$\varphi(x, x_c) = \exp\left(-\frac{\|x - x_c\|^2}{2\sigma^2}\right) \quad (5)$$

582 where x_c is the center vector; w_j is the connection weight from the hidden unit to the output unit;
 583 σ is the width of the Gaussian function; and $\|x - x_c\|$ represents the distance input to the center
 584 of the basis function.

585
 586 The GRNN is a variation to the radial basis neural networks and consists of four parts: the input
 587 layer, the pattern layer, the summation layer, and the output layer. This model is known for its
 588 ability to achieve global optimization with strong robustness and fault tolerance. The mathematic
 589 representation of the GRNN can be seen into Equation 6, where w_k is the activation weight of
 590 the pattern layer node k and $K(x, x_k)$ is the radial basis function kernel.

$$f(x) = \frac{\sum w_k K(x, x_k)}{\sum K(x, x_k)} \quad (6)$$

591
 592 During the network design and training process, the smoothing factor of the kernel functions to
 593 train these two neural networks was set at 0.3 as a trade-off between the model generalizability
 594 and the fast-changing function.

595 **5.3.3 SVR Model**

596 Support vector regression applies a line referred to as *hyperplane* to describe the trend of the data.
 597 Rather than minimizing the error between the observed and predicted values, SVR aims to fit the
 598 best line within a threshold value so that as many samples as possible can be included to enhance
 599 model reliability. To obtain the SVR model, the regression process can be formed as the
 600 optimization problem outlined in Equation 7 [130].

$$\text{Minimize: } \frac{1}{2} \|\omega\|^2 \quad (7)$$

$$\text{subject to } \begin{cases} y_i - \omega_i \cdot \phi(x) - b_i \leq \varepsilon \\ \omega_i \cdot \phi(x) + b_i - y_i \leq \varepsilon \\ i = 1, 2, \dots, l \end{cases}$$

601 where y_i is the observed output; weighted vector ω_i and bias b_i are the parameters for the
 602 prediction of an observed data; and ε is the epsilon margin that serves as a threshold for the
 603 difference between the prediction and the observed outputs.

604

605 The performance of the SVR model depends heavily on its parameters, such as the kernel
 606 function parameter, the regulation parameter, and the width of the epsilon-insensitive band. It is
 607 necessary to optimize the training parameters for better generalization performance and to
 608 eliminate the overfitting problem, given the limited sample size [131]. During the training
 609 process, SVR employed a Gaussian function as the kernel function and the sequential minimal
 610 optimization algorithm (SMO) to find the optimal solution. The best performance was found
 611 when the Kernel scale was 2.154 and Edsilon was 0.535.

612 **5.3.4 FIS Model**

613 To obtain a fuzzy inference system from the data, the foremost step is to divide the data space
 614 into fuzzy clusters. Following Park and Han's instruction, this study employed the fuzzy
 615 subtractive clustering algorithm (FSC), an unsupervised algorithm, to identify potential clusters
 616 among the input data [20]. The FSC can automatically estimate a fair number of clusters based
 617 on the density (potential) of data points in a space where a cluster center is one of the clustered
 618 data [132,133]. Consequently, 10 rules (10 clusters) were generated based on the optimal
 619 combination of fuzzy clustering parameters. The local model of each rule was then expressed
 620 using the Takagi–Sugeno–Kang (TSK) model in a mathematical manner. The regression
 621 parameters of the local models were further determined by the linear least-squares estimation
 622 technique and represented as outlined in Equation 8.

$$\text{For } x \in C_k, \text{ THEN } Y_{PR} = a_0 + \sum_{j=1}^M a_j x_j \quad (8)$$

623 where x_j is the j^{th} dimension of data point; M is the overall dimension of design elements (i.e.,
 624 equal to 10 in this case); and a_0 are the regression parameters; C_k refers to the k^{th} cluster.

625 **5.3.5 Assessment of Prediction Performance**

626 The accuracy of the predictive result is reflected in the prediction error; thus, measuring and
 627 analyzing the magnitude of the prediction error is of great significance in terms of demonstrating
 628 the accuracy of the prediction result [134]. Root mean square error (RMSE) is a standard metric
 629 that expresses the average deviation between the predicted value and the observed value, and it
 630 is commonly used to compare the performance of machine-learning regression models [44,124].
 631 However, it is difficult to ascertain the quality of a predictive model by merely looking at a
 632 singular value of RMSE. For instance, an RMSE value of 0.4 alone does not intuitively indicate
 633 whether or not a model performs well in predicting restorative quality. This shortcoming can be
 634 addressed with the use of another performance indicator, R-squared (R^2), which gives the
 635 percentage of output variance that can be explained by the independent variables in the model

636 [135]. Compared to RMSE, R^2 is more informative in indicating the model prediction
637 performance, where an R^2 value of 0.8 means that the evaluated model explains 80% of the
638 variation within the data, regardless of the ranges and distributions of the ground truth values
639 [135]. Therefore, in the present study, both RMSE and R^2 were used to assess the goodness-of-
640 fit of the prediction models, where a high R^2 value and a low RMSE in all possible regression
641 methods is considered to be indicative of a better fit in modeling the relationship between
642 perceived restorativeness and architectural design attributes.

643 In addition, the scatterplots of the observed data against the predicted data were further employed
644 to illustrate the distribution pattern of the prediction error, (i.e., a constant variance of error across
645 the various levels of the dependent variable). In other words, the scatterplots of observed vs.
646 predicted PRS scores in our study revealed whether the predictive model could perform
647 equivalently in predicting various levels of dependent variables. For instance, the scatterplots of
648 observed vs. predicted PRS scores in our study revealed whether the predictive model could
649 perform equivalently in predicting various design settings with different PRS scores [136].

650 **6 Results and Discussion**

651 A summary of the main findings from the experiment together with analytical results regarding
652 predictive modeling are provided in the section.

653 **6.1 Demographic Characteristics**

654 A total of 144 participants took part in the experiment, and 120 responses (data points) were used
655 for further data analysis and prediction model development after data cleaning has been carried
656 out to remove any incomplete or unqualified responses. Data reliability was tested with Cronbach
657 alpha and the result of 0.824 suggests a good internal consistency of survey responses, which
658 means the online questionnaire results are able to reliably measure a person's perceived
659 restorative experience under specific interior design settings. The distribution of the participants
660 in terms of demographic characteristics (age, gender, and education level) is outlined in Table 5.
661 Participants were queried as to their background knowledge and relevant experience with respect
662 to interior design, and only 4.2% of participants stated they do not have any experience or
663 knowledge of interior design. Moreover, more than 50% of participants had interior design
664 experience or were familiar with the basic principle. In terms of virtual reality models, 70.8% of
665 participants stated they have prior experience with VR techniques and gave the VR model a score
666 of 5.43 out of 7 ($SD=0.72$) in terms of its sense of presence, indicating that the virtual model is
667 an adequate representation of the physical environment for the purpose of measuring user
668 experience [137]. During the experiment, no significant differences were found for age, gender,

669 and level of education, which suggests the demographic variables did not influence the responses
670 in the present study. However, the attitude of a respondent with respect to whether or not the
671 kitchen is a relaxed place in the home was found to be significantly associated with the result of
672 the respondent's response for restorativeness measure (p-value = 0.03). This finding is consistent
673 with previous research findings that a person's previous experience or their environment-related
674 attitude would influence their perception of the environment [138,139].
675

676 Table 5. Demographic information of participants

		Number of participants	Proportion
Gender	Female	34	28.33%
	Male	86	71.67%
Age range	18–24	4	3.33%
	25–34	70	58.33%
	35–44	27	22.50%
	45–54	14	11.67%
	55–64	5	4.17%
Education level	Some college training but no degree	13	10.83%
	High school degree or equivalent (e.g., GED)	5	4.17%
	Bachelor’s degree	66	55.00%
	Graduate degree	36	30.00%

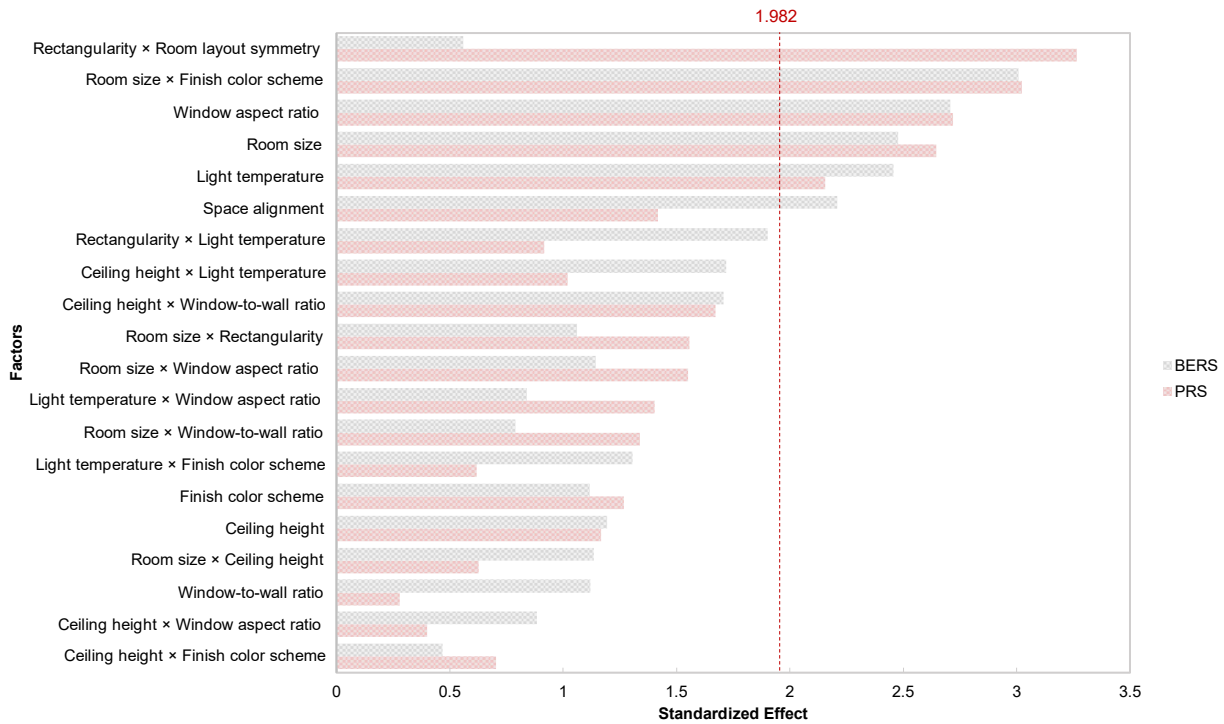
677

678 **6.2 Factorial Analysis of Design Attributes**

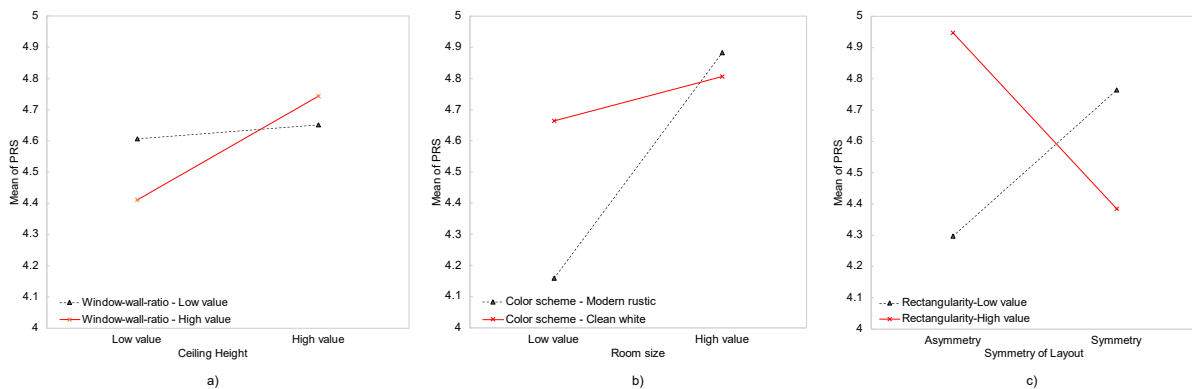
679 The Pareto chart in Figure 6 summarizes the top 20 input variables with significant main and
680 interaction effects according to the results of the factorial analysis. The bars for each variable
681 represent the absolute values of standardized effects of design attributes and their interactions on
682 human-perceived restorative experience as measured by PRS and BRES. The reference line of
683 1.982 is plotted to indicate the 95% significance level, meaning that if a bar crosses the reference
684 line, this indicates that the variable is determined as being influential to the output change at a
685 statistical significance level of 0.05 (p -value < 0.05). Therefore, at the protected significance
686 level (i.e., 95% significance level), the main effects of window aspect ratio, room size, and light
687 temperature were significantly influential to restorative experience results measured by both PRS
688 and BERS, revealing the strong relationship between the design feature and human-perceived
689 restorativeness in environments. However, finish color scheme and ceiling height contribute a
690 statistically significant difference to the result of PRS score, but fail the significance hypothesis
691 test for the BRES measure, which may be explained by the expression of BRES leading the
692 participant to focus more on assessing the feeling of “being away” and “fascination” in

693 environments while neglecting the concept of “coherence.” Similarly, the difference in
694 interaction effect of Rectangularity × Room layout symmetry according to PRS and BERS
695 measures could also be explained the same way. The significant interaction effect of
696 Rectangularity × Room layout symmetry was evident in terms of the output of “coherence”
697 feeling in PRS measure (p-value < 0.05); in contrast, the same interaction effect failed the
698 hypothesis test for the BERS measure. For this reason, PRS is used as the only target output in
699 the data analysis that follows.

700 In terms of interaction effects, the six two-way interaction effects of Rectangularity × Room
701 layout symmetry; Ceiling height × Window-to-wall ratio; Room size × Finish color scheme;
702 Rectangularity × Light temperature; Room size × Visual complexity; and Light temperature ×
703 Window aspect ratio were identified as contributing to the results of PRS measure in the present
704 study. Three examples of interaction effects with the most significant standardized effect are
705 plotted in Figure 7, illustrating the mean PRS score versus two levels of design attributes under
706 different settings of other variables. As shown in Figure 7a, if the ceiling height of a room is low,
707 a low window-to-wall ratio (indicated by the black dashed line) is associated with a higher score
708 of PRS and restorative experience, whereas in the scenario in which a room has a high ceiling,
709 the participant found the high window-to-wall ratio offers a more restorative experience
710 according to the PRS score. Likewise, in a rectangular kitchen, as depicted as the red line in
711 Figure 7c, the participant found the asymmetrical layout could provide them a more
712 restorative experience in comparison to a symmetrical layout, although the symmetry of a space
713 is usually positively associated with higher perceived restorativeness in environments as shown
714 in the case of square-shape kitchen space. Moreover, looking at Figure 7b, it is apparent that the
715 room size has a significant influence on a person’s perceived restorativeness under a modern
716 rustic color setting. In contrast, the PRS score appeared to be less affected by room size when
717 the color scheme is clean-white.



718
719 Figure 6 Pareto chart of the standardized effects for responses using PRS and BERS scales
720



721
722 Figure 7 Plots for interaction effects of (a) Ceiling height × Window-wall ratio, (b) Room size
723 × Finish color scheme, and (c) Room layout symmetry × Rectangularity
724

724 6.3 Comparison of Predictive Modeling Results

725 Multiple machine learning methods were applied using the response data to build the prediction
726 model. As suggested by the factorial analysis results in Section 4.2 (i.e., that all design attributes
727 should be incorporated into the linear model according to the significance level of effects and the
728 model hierarchy), a total of ten design attributes—(1) room size, (2) rectangularity of room shape,
729 (3) ceiling height, (4) light temperature, (5) visual complexity, (6) room layout symmetry, (7)
730 window-to-wall ratio, (8) window aspect ratio, (9) finish color scheme, and (10) space
731 alignment—were set as the dependent variable inputs for the other machine learning methods.
732 Moreover, the extent to which the participant believes a kitchen is a relaxed place is also included

733 as a context input variable to assess the perceived restorative quality in environments during
734 modeling as their significant correlation was argued by other scholars and supported by the result
735 of the factor analysis in the present study. Meanwhile, as has already been noted in the factorial
736 analysis (i.e., Section 6.2), the description used to measure BERS might cause the participant to
737 focus more on the “being away” and “fascination” aspects while assessing the restorativeness of
738 the environments. The PRS score was used as the only target output for the predictive modeling.
739 It should also be noted that PRS was more thoroughly examined for construct validity and
740 generalizability compared to BERS. Also, PRS has more scale items to rate than BERS, which
741 reduces the risk of internal inconsistency [106].

742 As a result, a total number of five predictive models were developed, of which the machine
743 learning methods used to develop the models include linear regression, neural networks (i.e.,
744 GRNN and RBFNN), support vector regression (SVR), and fuzzy inference system (FIS). The
745 comparison of their prediction performance using training and testing sets is shown in Table 6.
746 It is apparent that three artificial intelligence methods, i.e., SVR, neural network, and FIS, all
747 have better predictive performance than the linear regression. The R-squared value of linear
748 regression indicates that this model is capable of explaining only 36.00% of the variation in
749 human-perceived restorative experience in the validation set. However, some scholars have
750 argued that the interpretation of R-squared value varies depending on the research area. Any
751 study involving an attempt to predict human behavior, such as in psychology, typically tends to
752 yield lower R-squared values in comparison to engineering problems due to the non-linearity of
753 human nature, as previously discussed herein [140,141]. Additionally, to obtain more in-depth
754 insight into the performance of GRNN, RBFNN, FIS, and SVR models, their respective best
755 model structures and fitness plots were used to compare the prediction performance. Among the
756 four prediction models, the GRNN and RBFNN neural networks have similar statistical
757 performance in terms of low RMSE scores and high R-squared values. Comparing GRNN and
758 RBFNN, the performance of the former is only slightly better. This result is consistent with the
759 experiment conducted by Chen et al. [124], which studies the human emotional response to
760 various aircraft cockpit designs. Moreover, since GRNN is a single-pass associative memory
761 feedforward neural network, its computation time for training is relatively shorter than that of
762 other artificial neural networks.

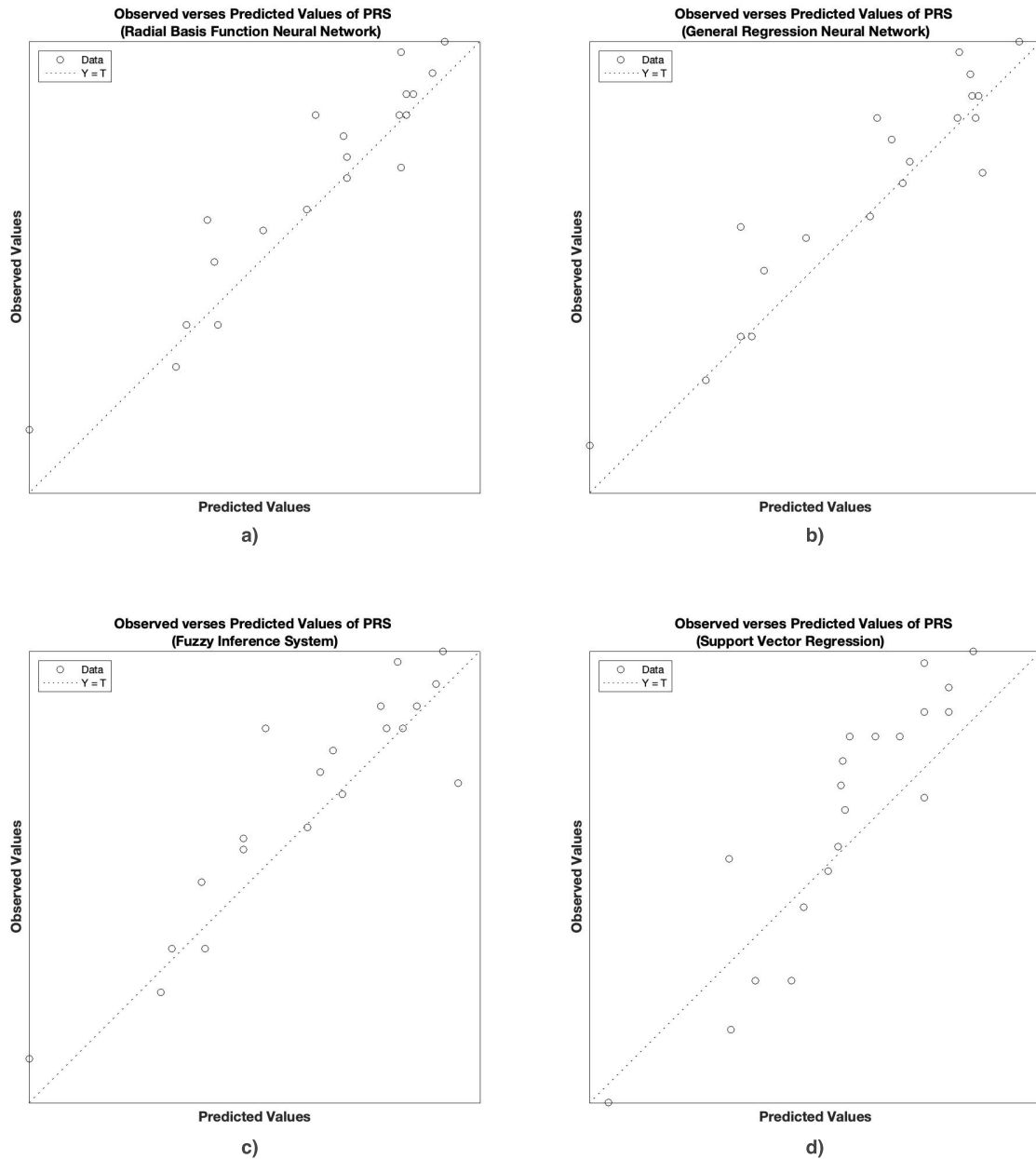
763 Figure 8 further demonstrates the scatterplots of observed data against predicted data using each
764 of the four artificial intelligence models. The x -axis is the predicted PRS score by predictive
765 model and the y -axis is the observed value. Therefore, the closeness of data points to the
766 regressed diagonal line indicates the goodness-of-fit of the models. The plots for GRNN, RBFNN,

767 and FIS (see Figure 8a, 8b, 8c) are quite similar in terms of the slope of goodness-of-fit as well
768 as the data pattern, and their predicted values are relatively close to the corresponding observed
769 PRS values in comparison to those predicted by the SVR model (see Figure 8d). While assessing
770 the performance of models for their applicability in predicting the target output, it should be
771 noted that both the average error of regression and the distribution or the pattern of prediction
772 error should be taken into consideration. From these scatterplots, the residual distribution can be
773 observed by measuring the distance from the data points to the diagonal line. Ideally, the
774 distribution should be symmetrical around the diagonal line, indicating reliable standard errors
775 of regression coefficients. However, as shown in the support vector regression scatterplot (Figure
776 7d), the distribution of data points indicates that the SVR model has relatively poor performance
777 when predicting the cases with various PRS values, as these data points can be seen to be
778 crowding below the diagonal line when $PRS < 4$ and gathering above the line when $PRS > 4$.
779 Overall, GRNN, RBFNN, and FIS models perform reasonably well in predicting the PRS score
780 of a room based on the design attributes when compared to linear regression and SVR models.
781 The results also suggest that the GRNN model is superior to RBFNN and FIS in terms of PRS
782 score forecasting among the validation datasets.

783 Table 6. Performance values of machine learning methods

Machine learning method	RMSE		R-squared	
	Train	Test	Train	Test
Linear regression	0.4025	0.5214	60.91%	36.00%
SVR	0.3742	0.3289	69.70%	73.19%
Neural networks	RBFNN	0.2676	83.14%	82.85%
	GRNN	0.2670	83.21%	84.11%
FIS	0.2819	0.2922	81.29%	78.85%

784



785
786 Figure 8. PRS values observed and predicted by four machine learning models

787 **7 Conclusions and Future Work**

788 The affective experience of occupant-users is vital for the perceived usability of residential
789 buildings and should be considered in the early design phases. Although many studies have
790 attempted to identify the architectural design attributes that most influence the human affective
791 experience, the fragmented and ambiguous nature of the relevant information makes its use in
792 human-centered architectural designs challenging. This study aimed to construct prediction
793 models that could be applied to forecast values of experiential quality for each residential design
794 alternative in order for the design practitioner to easily capture the affective quality of the design

795 and further improve user satisfaction with the design, regardless of the designer's experience,
796 skills, and subjective opinion. Such prediction models lay a foundation for developing analytical
797 models and tools to facilitate the decision-making process at the early stages of design to ensure
798 an emotional wellness-focused built environment. It should be noted that conventional machine
799 learning methods for affective design usually require large datasets for feature selection and to
800 ensure the delivery of meaningful results. This can be time-consuming and expensive for studies
801 with human subject. This work thus contributes to the body of knowledge on human–building
802 interaction by introducing a non-immersive VR-DOE-based machine learning method that
803 optimizes the data collection process and addresses the inherent complexity and uncertainty in
804 modeling the affective experience.

805 In this study, VR technologies were employed not only to produce a controllable and valid
806 experimental environment, but also to demonstrate various combinations of design attributes and
807 environment settings. This study also employed fractional factorial design for highly efficient
808 experiment planning and screening for significant factors. The results show that an interior's
809 spaciousness and color scheme were the most noticeable and influential attributes in the human
810 restorative experience, consistent with the findings from previous studies. In addition, significant
811 interaction effects were identified for Ceiling height \times Window-to-wall ratio, Room size \times Finish
812 color scheme, and Room layout symmetry \times Rectangularity of room shape, which had often been
813 overlooked in previous studies. Moreover, five machine learning models were proposed to
814 represent the restorative experience in the built environment and compared in terms of their
815 prediction performance. The results suggest that the GRNN model was superior in describing the
816 nonlinear relationship between design attributes and human affective experience in comparison
817 to the predictive models developed using the other four machine learning methods, i.e., linear
818 regression, fuzzy inference system, support vector regression, and RBFNN. Taken together, these
819 findings add to the rapidly expanding field of human-centered environmental design and form a
820 basis for the future development of a decision support system for designers in wellness-focused
821 architectural design (considering that the relevant knowledge is scattered across several
822 disciplines).

823 Despite its valuable contributions, this study was subject to several limitations. First, the
824 participants recruited were mostly characterized as highly educated and young, which may
825 influence the generalizability of the results. Second, the factors related to personal subjective
826 experience, such as cultural differences or preference bias toward specific design settings, should
827 also be included in future studies to enhance the quality of affective modeling. Third, the
828 feasibility of using human physiological responses, such as electrocardiogram (ECG),

829 electroencephalogram (EEG), skin conductance (SC), or blood oxygen to measure human
830 affective response toward environmental stimuli have been explored by many researchers
831 [2,22,38,113,115,142]. Although the causal quantitative relationship between biosensing data
832 and the perceived restorativeness is still under investigation and inconclusive [2,115], it is still
833 believed that the use of objective human physiological response measures in combination with
834 self-reported restorativeness scales in future research would be of great help in eliminating the
835 potential biases in self-report assessments and better understanding the complex interaction
836 between built environment and human experience [143]. Likewise, further validation using
837 actual residential design scenarios should also be carried out, whereby the restorative quality of
838 design, evaluated using predictive models, could be analyzed based on the feedback provided by
839 professional architects to improve the ecological validity of the predictive model. In addition, an
840 assumption was made during the experiment that a satisfying sense of presence provided by VR
841 models could promise sufficient emotional stimulus received by participants; to improve the
842 accuracy of prediction results from the non-immersive VR-based method, further improvement
843 of incorporating the variable of VR display platforms into analysis should be also investigated in
844 future work. Overall, insights gained from further research are also expected to contribute to the
845 early stages of projects by providing designers with more scientific feedback on their designs.

846

847

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