

Optimizing UAV Hyperspectral Imaging for Urban Tree Chlorophyll and Leaf Area Index Retrieval

Shanshan Wei , Tiangang Yin , Bo Yuan, Kim Hwa Lim , Soo Chin Liew , and Andrew J. Whittle 

Abstract—Uncrewed aerial vehicle (UAV) based hyperspectral imaging offers a flexible method for monitoring urban trees. However, its effect on estimating biochemical and biophysical parameters is still unknown. This article examines how spatial and spectral resolution, solar zenith angle (SZA), and diffuse solar irradiance (SKYL) affect chlorophyll content (C_{ab}) and leaf area index (LAI) estimation using narrow-band indices (NBIs) through three-dimensional radiative simulations. The results show that spatial resolution minimally affects C_{ab} estimation but significantly impacts LAI, with finer resolutions improving correlation with NBIs. In contrast, spectral resolution has little effect on LAI but greatly influences C_{ab} , with a 2-nm resolution providing stronger correlations, while resolutions coarser than 6 nm are less sensitive. The C_{ab} estimation prefers oblique SZAs, while LAI favors nadir SZAs. SKYL has little effect on C_{ab} and minor impact on LAI. Sunlit pixels outperform shaded ones for C_{ab} estimation, even at 2-m resolution, while entire-crown pixels show the highest LAI correlation. Different NBI strategies significantly affect LAI estimation but not C_{ab} . A consistent conclusion emerges from the analysis of correlations between UAV hyperspectral imagery, with varying spatial and spectral resolutions, and corresponding C_{ab} field measurements. This suggests that the knowledge revealed by the radiative transfer model is applicable to real-world conditions and improves understanding of natural processes without direct measurements. This article enhances the understanding of the influence of observation configurations on C_{ab} and LAI estimation, offering insights to optimize UAV-based hyperspectral imaging and guide future satellite sensor development for tree monitoring.

Index Terms—Chlorophyll content (C_{ab}), hyperspectral remote sensing, leaf area index (LAI), uncrewed aerial vehicles (UAVs).

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I. INTRODUCTION

URBAN trees are essential for promoting urban biodiversity, advancing environmental sustainability, and enhancing climate resilience. They provide a variety of ecosystem services, including enhancing thermal comfort [1], mitigating air and noise pollution [2], sequestering carbon [3], and managing stormwater [4]. However, structural failures of unhealthy trees can present a danger to people and property. Monitoring the health of urban trees can reduce these risks, but currently involves a labor-intensive process relying on human inspection.

Remote sensing offers a more efficient solution for tree monitoring. Two key plant traits, chlorophyll content (C_{ab}) and leaf area index (LAI), are commonly quantified for plant health monitoring [5], [6], [7], [8], [9], [10], [11], [12], [13]. The rapid advancements in imaging spectroscopy and uncrewed aerial vehicle (UAV) provide enhanced flexibility in both spatial and spectral resolutions, enabling data capture under various solar zenith angles (SZAs), and diffuse ratios of solar irradiance (SKYL). However, notable gaps exist in understanding how these flexibilities of UAV configurations influence the retrieval of canopy C_{ab} and LAI.

Higher spatial resolutions enable detailed inspection of individual trees but reduce flight efficiency. Some studies prefer higher spatial resolution images and a resolution finer than 4 cm has been recommended for optimal C_{ab} estimation in sugar beet crops [14]. Additionally, higher spatial resolution images are beneficial for improving LAI estimation [15]. Conversely, other studies suggest that coarse spatial resolution can perform similarly to high spatial resolution at a lower cost [16], [17]. These differing opinions underscore the need to examine the influence of spatial resolution on tree C_{ab} and LAI estimation and to determine the optimal resolution for these parameters.

Hyperspectral images are typically believed to enhance the detection of subtle spectral variations related to plant traits, with narrow-band indices (NBIs) outperforming multispectral images for C_{ab} and LAI estimation [18], [19], [20], [21], [22], [23], [24], [25], [26]. Nevertheless, higher spectral resolutions may increase the costs of data acquisition, processing, and retrieval. Hence, determining the optimal spectral resolution for C_{ab} and LAI estimation is crucial for advancing UAV applications.

Previous UAV images were commonly acquired around noon with an SZA close to nadir [27], [28], [29], [30], [31], to increase the proportion of sunlit leaves [28], [29]. The sunlit leaves demonstrated an advantage for C_{ab} estimation [13], [34], [35], [36]. However, the nadir SZA also amplifies the background's influence by increasing the proportion of sunlit background. Urban tree spectra are particularly susceptible to contamination

by background with high diversity and spectral complexity [11], [37], [38], [39]. Sunlit background may exacerbate this influence. Specific observation times (e.g., 15:00 h) with oblique SZAs have been proposed to mitigate background influence for wheat row crops [33]. However, the background of urban trees differs significantly from that of row crops. Thus, the optimal SZAs for C_{ab} and LAI estimation for urban trees remain unknown.

Hyperspectral images captured under clear sky conditions are usually used for C_{ab} and LAI estimation even though UAVs can capture hyperspectral images under diverse illumination conditions [34]. Recent studies showed that even under the lowest overall irradiance with the thickest cloud cover, the signal-to-noise ratio (SNR) of hyperspectral images is adequate for retrieving foliar traits [35]. Moreover, recent studies have demonstrated the usability of hyperspectral images acquired during varying illumination and cloudy conditions for C_{ab} estimation [36]. However, there is a lack of studies exploring the influence of SKYL to the C_{ab} and LAI estimation.

This article aims to identify the optimal observation configurations for estimating the C_{ab} and LAI of urban trees using hyperspectral images. We focus on two significant aspects that influence C_{ab} and LAI estimation with hyperspectral imaging: 1) sensor settings, including spatial and spectral resolutions, and 2) illumination conditions, including SZA and diffuse ratio. This article is significant not only for estimating vegetation parameters using UAV-based instruments but also for providing valuable insights into appropriate spatial and spectral resolution selection for upcoming satellite missions.

II. DATA AND METHODS

Given the challenges in obtaining extensive reliable field measurements (for C_{ab} and LAI) and expenses involved in deploying UAVs to acquire hyperspectral images with diverse spatial/spectral resolutions under different SZA and SKYL conditions, this article utilized a modeling framework. This modeling framework simulates hyperspectral data for realistic trees to evaluate the impact of observation configurations on C_{ab} and LAI estimation. Here, we use the PROSPECT-5 model [37], [38] integrated with discrete anisotropic radiative transfer (DART) model [45], [46], [47], [48] to simulate UAV hyperspectral images of urban trees.

A. Hyperspectral Images Simulation

The DART scene dimensions were set to 40 m \times 40 m, with an individual three-dimensional (3-D) tree model positioned at the scene center. Details about the 3-D tree model are provided in [43]. The DART scene incorporated six different backgrounds, including dry soil, wet soil, sand, grass, concrete, and asphalt, to reflect the complex backgrounds of urban trees. The optical properties of these backgrounds were randomly chosen from the urban background spectral database [36]. For grass backgrounds, the LAI of the grass was assigned a random value between 0 and 1. The leaf spectral properties were simulated by PROSPECT with variable input parameters suitable for trees. The SZA was set to 0°, 15°, 30°, and 45° that correspond to nadir and oblique directions. The view zenith angle (VZA) was set to

TABLE I
SIMULATION PARAMETER VARIATION FOR THE NBIS SELECTION

	Parameters	Min	Max	Mean	Std
Leaf scale	Brown pigment	0	0.2	0	0.1
	Chlorophyll ($\mu\text{g cm}^{-2}$)	10	80	40	30
	Structure coefficient	1.5	2.5	1.9	0.4
	Equivalent water thickness ($\mu\text{g cm}^{-2}$)	0.002	0.042	0.015	0.01
	Leaf mass per area (g cm^{-2})	0.002	0.033	0.008	0.01
	Anthocyanin ($\mu\text{g cm}^{-2}$)	0	4	2	2
Canopy scale	Leaf percentage	100%, 50% , and 10%			
Illumination condition	SKYL	0, 0.2, 0.4, 0.6, 0.8, 1			
	SZA (°)	0°, 15°, 30°, 45°			
Background	Reflectance property	Dry soil, wet soil, grass, asphalt, concrete, and sand			

0° to represent the nadir view for most UAV-based observations. The SKYL was set to 0, 0.2, 0.4, 0.8, and 1.0, with 0 being direct illumination and 1 being fully overcast. The input parameters of the simulation are described in Table I.

To explore the influences of spatial resolution on C_{ab} and LAI estimation, the spatial resolution was set to 0.1, 0.5, 1.0, and 2.0 m for each type of background. Similarly, the spectral resolution was set to 2, 6, 10, and 14 nm for wavelenths spanning from 400 to 1000 nm to explore the influence of spectral resolution on C_{ab} and LAI estimation. The resultant images from DART simulations were applied with 5% random multiplicative noise to mimic realistic situations. In total, 69 120 (720 \times 6 \times 4 \times 4) hyperspectral images were simulated for subsequent NBIS evaluations for C_{ab} and LAI estimation.

Observation configurations can affect the reflectance distribution of simulated image pixels and the overall reflectance spectrum, as illustrated by selected examples from the simulated datasets in Fig. 1. A spatial resolution of 0.1 m preserves details of a tree. In comparison, a lower resolution of 2 m blurs the same tree, yet sunlit and shaded pixels of its crown remain visible [Fig. 1(a)]. As the SKYL increases, the contrast between sunlit and shaded pixels decreases, with shadows almost vanishing at a SKYL value of 1.0 [Fig. 1(b)]. The proportion of shaded leaves increases with more oblique SZA values [Fig. 1(c)]. Additionally, hyperspectral images with a spectral resolution of 2 nm capture detailed canopy responses with dense narrow bands, while a lower spectral resolution of 16 nm results in much sparser observations, particularly in the 700 to 780 nm red-edge region [Fig. 1(d)].

B. UAV Hyperspectral Images Aquisition

Two hyperspectral UAV flight campaigns were conducted over Bishan-Ang Mo Kio Park, Singapore (Lat: 1.363°, Long: 103.845°) on 10 October 2020 and on 27 February 2021

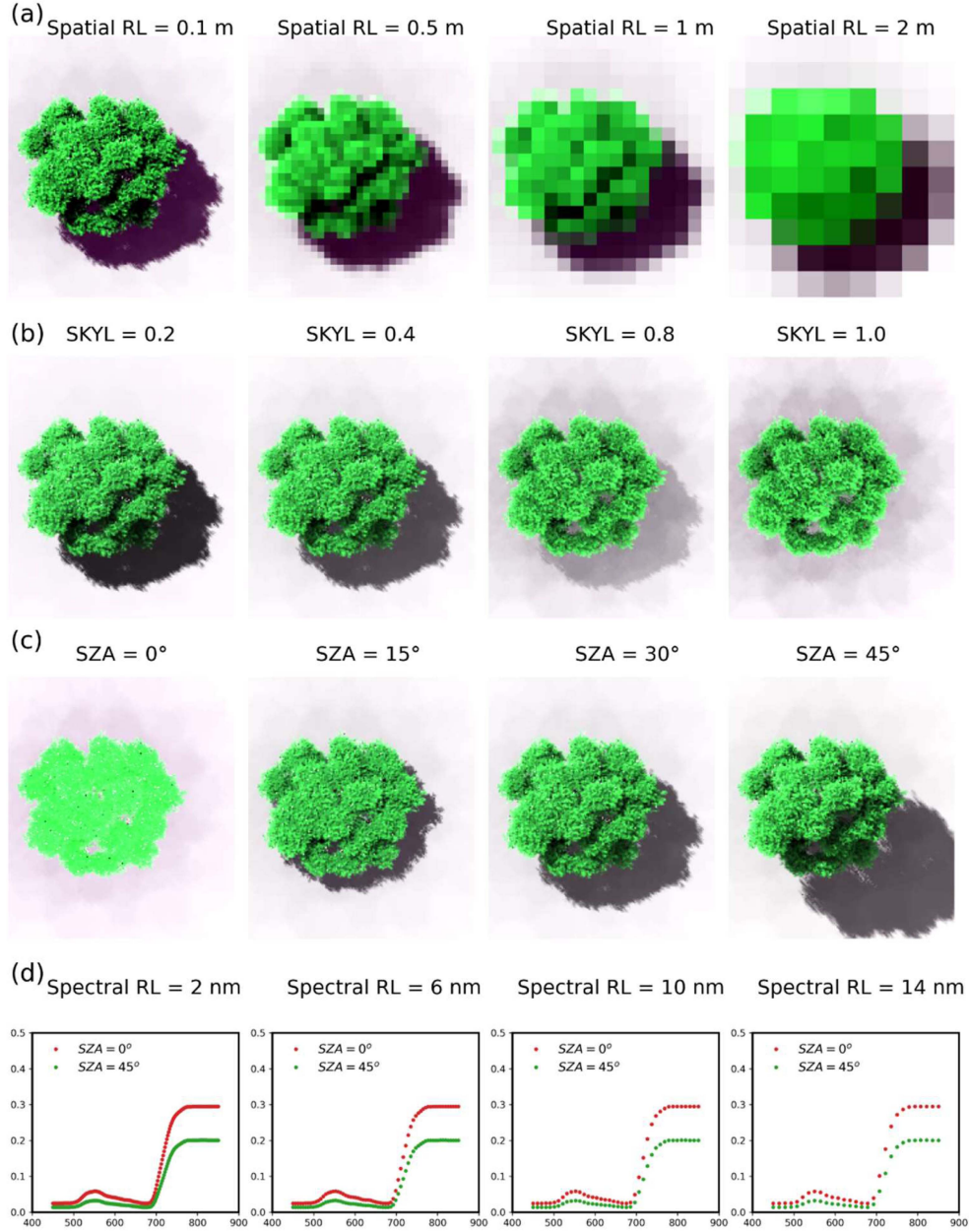


Fig. 1. Simulated hyperspectral images with varying (a) spatial resolutions (RL), (b) diffuse ratio of solar irradiance (SKYL), (c) solar zenith angles (SZAs), and (d) resultant scene reflectance spectra at different spectral resolutions.

(Fig. S1), using a Headwall Nano-Hyperspec push-broom imager mounted on a DJI Matrice 600 Pro quadcopter. Detailed on image acquisition and processing is provided in [36].

Similar to the simulated images, the performance of C_{ab} estimation was evaluated across varying spatial/spectral resolutions. The original 0.1-m spatial resolution was degraded to 0.5, 1, and 2 m by averaging over cells of $N \times N$ pixels, resulting in four sets of hyperspectral images with different spatial resolutions. Similarly, the original spectral resolution of 2 nm was degraded to 6, 10, and 14 nm by averaging in the spectral dimension.

C. C_{ab} Field Measurement

C_{ab} field measurements were conducted on 20 October 2020 and 8 March 2021. The C_{ab} of 60 leaves from each tree

crown was measured using an SPAD-502 chlorophyll meter. Detailed measurement procedures and the calibrated C_{ab} values ($\mu\text{g cm}^{-2}$) for each tree are provided in [36].

D. Sunlit/Shaded Pixels Classification

The tree crowns were manually delineated and used as crown masks from the simulated hyperspectral images. Subsequently, these delineated crown pixels underwent classification into five categories: sunlit, shaded, bright (specular reflection), dark (cavities within the leaves), and background, using an automated crown classification method [36]. Fig. 2 shows the example of simulated hyperspectral images of a tree crown (*Peltophorum pterocarpum*) with varying spatial resolutions, and the results of delineation and classification. The polygon of a delineated

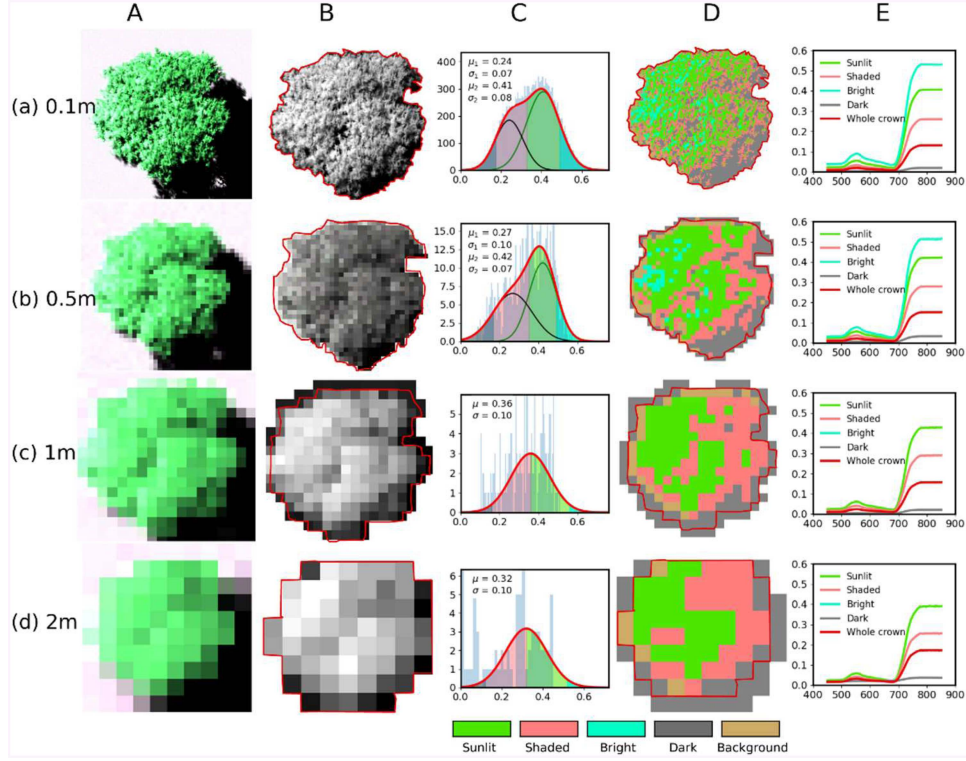


Fig. 2. Automatic classification of tree crown pixels using simulated images with different spatial resolutions: (A) delineated tree crown on the RGB composition (R: 660.0 nm, G: 551.0 nm, and B: 459.9 nm); (B) corresponding tree crown on the NIR band (851 nm); (C) NIR histogram curve and Gaussian fitting for classification; (D) tree crown classification results; and (E) average reflectance spectrum of different crown classes.

crown becomes simpler as the spatial resolution decreases from 0.1 to 2.0 m [Fig. 2(a) and (b)]. The histogram of the NIR band (851 nm) degrades from a bimodal to a monomodal Gaussian distribution as the resolution decreases [Fig. 2(c)]. As spatial resolutions become coarser, the pixels classified as sunlit and shaded begin to merge. At a 2-m resolution [Fig. 2(d)], more pixels at the edge of the crown are classified as shaded or background due to the mixing effect. A significant difference between sunlit and shaded reflectance can be observed at all spatial resolutions [Fig. 2(e)]. The same automatic sunlit/shaded classification method was applied to the UAV hyperspectral images at different spatial resolutions (Fig. 3).

E. Index Computation Formulations and Strategies

Although deep learning has demonstrated significant potential and effectiveness in vegetation monitoring [44], [45], index-based methods are more commonly used due to their ease of implementation in remote sensing applications. In this article, we focus on exploring the influence of UAV configuration on C_{ab} and LAI estimation by scanning across a range of NBIs method. The NBIs are commonly expressed as ratios of reflectance values in two or three spectral bands, using the following three formats:

- 1) Simple ratio (SR)

$$SR = \frac{\rho_{\lambda 1}}{\rho_{\lambda 2}}. \quad (1)$$

- 2) Normalized difference ratios (mND)

$$mND = \frac{(\rho_{ref} - \rho_{\lambda 1})}{(\rho_{ref} + \rho_{\lambda 2})}. \quad (2)$$

- 3) Structure-insensitive pigment index (SIPI)

$$SIPI = \frac{(\rho_{ref} - \rho_{\lambda 1})}{(\rho_{ref} - \rho_{\lambda 2})} \quad (3)$$

where λ_1 , λ_2 , and λ_{ref} denote the variable bands and the reference band, respectively. Previous evaluations have typically focused on a limited number of NBIs [46], [47]. This article evaluates all potential indices by varying λ_1 , λ_2 , and λ_{ref} from 450 to 851 nm, with an average bandwidth of 6.6 nm for simulation data and 2 nm for UAV hyperspectral data. Given that mND and SIPI have demonstrated better performance than SR in previous articles, this article focuses on the mND and SIPI formulations [36].

Two index calculation strategies for determining NBIs from crown pixels were evaluated for their impact on the C_{ab} and LAI estimation as follows:

- 1) computing NBIs from the average reflectance of all crown pixels (Ref_AVG), and
- 2) determining the average NBIs for each individual pixel within the crown (Index_AVG).

The correlations between these NBIs and both C_{ab} and LAI were investigated for their sensitivity to different crown sections, including sunlit, shaded, and the entire crown. Subsequently, the correlations between these NBIs and both C_{ab} and LAI were analyzed for their sensitivity to UAV sensor configurations (spatial and spectral resolutions) and environmental conditions (SZA and SKYL). The maximum Spearman's rank correlation coefficient between NBIs (calculated for all combinations of λ_1 and λ_2 over various λ_{ref}) and both C_{ab} and LAI across different

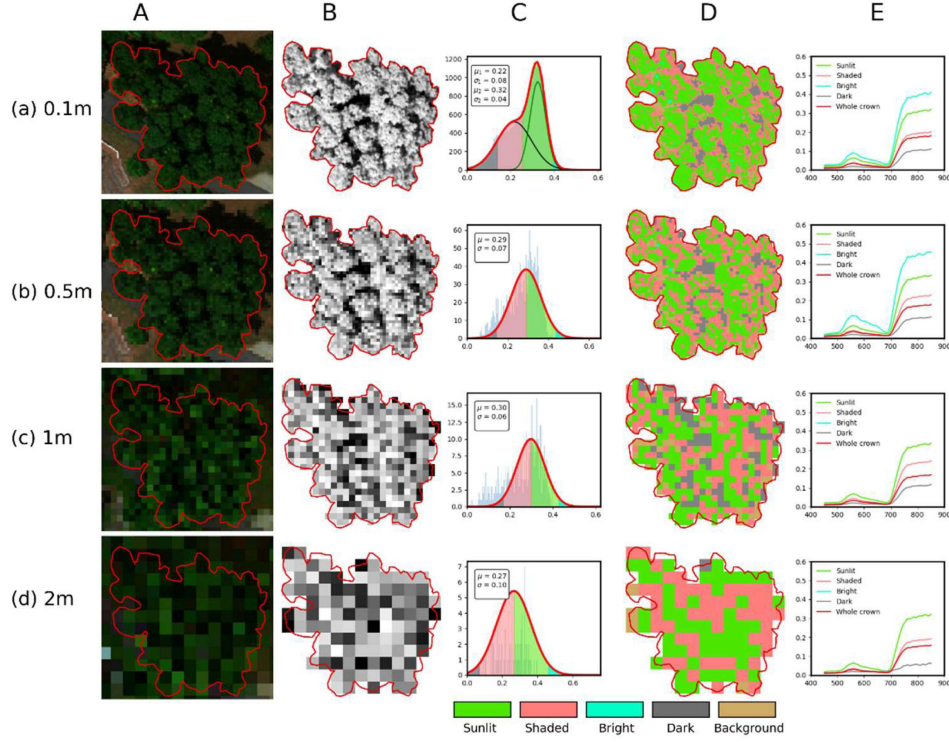


Fig. 3. Automated classification of tree crown pixels using UAV hyperspectral images at different spatial resolutions: (a) 0.1 m, (b) 0.5 m, (c) 1 m, and (d) 2 m.

spatial resolutions (0.1, 0.5, 1.0, and 2.0 m) were compared to assess the impact of spatial resolution on the estimation of C_{ab} and LAI. Similarly, various spectral resolutions, including 2, 6, 10, and 14 nm, were examined to assess their effect on the estimation of C_{ab} and LAI. In addition, we further evaluate the impacts of four selected SZAs ($SZA = 0^\circ, 15^\circ, 30^\circ$, and 45°); and three ranges of diffuse ratio: 1) $0 < SKYL < 0.2$ (direct dominant illumination); 2) $0.4 < SKYL < 0.6$ (partially cloudy illumination); and 3) $0.8 < SKYL < 1$ (diffuse dominant illumination) on the correlation between NBIs and both C_{ab} and LAI.

III. RESULTS

A. Pixel Selection and Index Calculation Strategy From Simulation Data

The pixel selection and index calculation strategy can strongly influence the estimation of C_{ab} and LAI, as demonstrated by the heatmap of correlation as a function of λ_1 and λ_2 wavebands with corresponding wavelengths bands (λ_{ref}) in the subplot, and the maximum correlation between NBIs and both C_{ab} and LAI across various reference wavelengths (λ_{ref}) in Fig. 4. For C_{ab} estimation, sunlit pixels exhibit a higher maximum correlation with NBIs compared to shaded and entire-crown pixels for both index calculation strategies (Index_AVG and Ref_AVG) [Fig. 4(a) and (b)]. Conversely, LAI estimation showed significant differences in crown pixel selection when using the two index calculation strategies [Fig. 4(c) and (d)]. Using the Ref_AVG strategy, the largest maximum correlation for LAI was achieved with $SIPI_{\lambda_{ref}}[\lambda_1, \lambda_2]$, where λ_{ref} is larger than 700 nm, utilizing sunlit or entire-crown pixels. With the Index_AVG strategy, the largest maximum correlation was obtained with

$SIPI_{\lambda_{ref}}[\lambda_1, \lambda_2]$ where λ_{ref} ranges from 450 to 500 nm using entire-crown pixels. Overall, the highest correlation between LAI and NBIs is attained using the entire-crown pixel for both index calculation strategies. Based on these findings, sunlit pixels were selected for C_{ab} analysis, while entire-crown pixels were used for LAI analysis in the subsequent sections.

B. Sensor Configuration From Simulation Data

The spatial resolution can influence the correlation between NBIs and both C_{ab} and LAI in various ways (Fig. 5). The correlation between NBIs and C_{ab} decreases slightly with spatial resolution dropping from 0.1 to 0.5 m and 1 m. However, at 2-m spatial resolution, the correlation between NBIs and C_{ab} decreases significantly compared to 1-m resolutions [Fig. 5(a) and (b)]. The influence of spatial resolution on the correlation between LAI and NBIs is more pronounced than for C_{ab} [Fig. 5(c) and (d)]. Finer spatial resolution exhibits a notably higher correlation than coarser spatial resolution for LAI estimation for both SIPI and mND and both index calculation strategies. Specifically, the 0.1-m resolution demonstrates clear superiority in correlation over the 0.5 m and the 0.5-m resolution consistently displays higher correlations than the 1.0-m resolution. Likewise, the 1.0-m resolution outperforms the 2.0-m resolution across all reference bands.

The spatial resolutions also impact the correlation distribution pattern between NBIs and C_{ab} , as well as LAI (Fig. 6), utilizing the optimal index format, reference band, and index calculation strategy determined from the evaluation results in Fig. 4. Specifically, $SIPI_{\lambda_{ref}}[\lambda_1, \lambda_2]$ with $\lambda_{ref} = 711$ nm was chosen for both index calculation strategies for C_{ab} estimation,

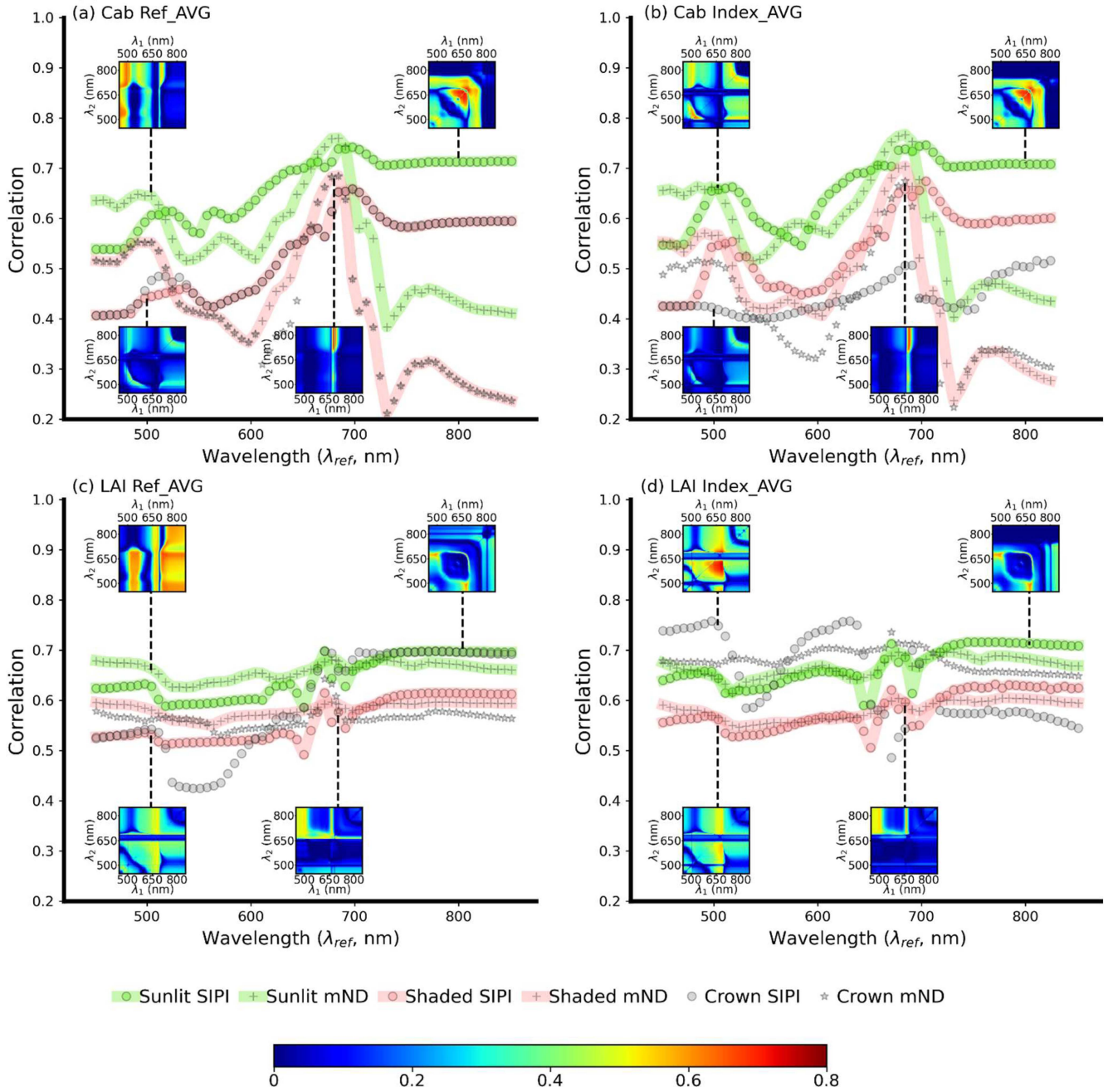


Fig. 4. Maximum Spearman's correlation coefficient values between NBIs and (a and b) C_{ab} and (c and d) LAI using various reference bands (λ_{ref}) in the $SIPI_{\lambda_{ref}}[\lambda_1, \lambda_2]$ and $mND_{\lambda_{ref}}[\lambda_1, \lambda_2]$ format from sunlit, shaded, and entire-crown pixels at 0.1-m spatial resolution. (a and c) Ref_AVG strategy. (b and d) Index_AVG strategy. The subfigure demonstrates the heat map of squared Spearman's correlation as a function of λ_1 and λ_2 wavebands with corresponding reference bands.

while $SIPI_{\lambda_{ref}}[\lambda_1, \lambda_2]$ with $\lambda_{ref} = 800$ nm for Ref_AVG strategy, with $\lambda_{ref} = 490$ nm for Index_AVG strategy for LAI estimation. The correlation distribution pattern between $SIPI_{\lambda_{711}}[\lambda_1, \lambda_2]$ and C_{ab} is not influenced by the index calculation strategy or spatial resolution [Figs. 6(a) and (b)]. High correlation regions are observed when λ_1 ranges from 700 to 850 nm and λ_2 ranges from 650 to 700 nm, along with another high correlation region encompassing both λ_1 and λ_2 from 600 to 650 nm, and a third high region with λ_1 and λ_2 from 650 to 700 nm. In contrast, the impact of spatial resolution on LAI estimation varies depending on the index calculation strategy and spatial resolution [Fig. 6(c)

and (d)]. With the Ref_AVG strategy, the highest correlation between $SIPI_{\lambda_{800}}$ and LAI is achieved by selecting both λ_1 and λ_2 from 650 to 700 nm. Conversely, using the Index_AVG strategy, the maximum correlation between $SIPI_{\lambda_{490}}$ and LAI is attained by choosing λ_1 from 650 to 700 nm and λ_2 from 650 to 800 nm. The correlation between LAI and NBIs decreases with coarser spatial resolutions, especially when utilizing entire-crown pixels for both index calculation strategies. Sunlit pixels are less affected by spatial resolution. Specifically, the effectiveness of entire-crown pixels over sunlit pixels diminishes with coarser spatial resolutions until sunlit pixels outperform

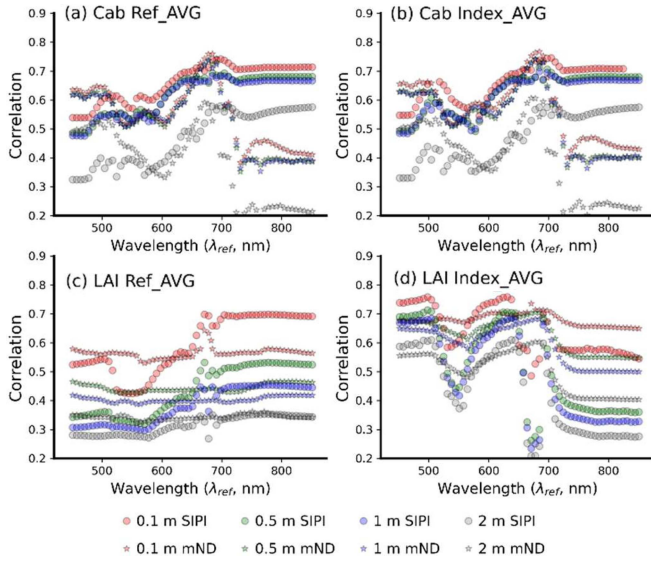


Fig. 5. Maximum Spearman's correlation coefficient values between NBIs and (a and b) C_{ab} and (c and d) LAI, utilizing various reference bands (λ_{ref}) in the $SIPI_{\lambda_{ref}} [\lambda_1, \lambda_2]$ and $mND_{\lambda_{ref}} [\lambda_1, \lambda_2]$ format, with different spatial resolutions (0.1, 0.5, 1, and 2 m). Panels (a and c) use Ref_AVG strategy, while panels (b and d) use the Index_AVG strategy. The spectral resolution employed is 2 nm.

using entire crown pixels when the spatial resolution deteriorates to 2 m.

1) *Spectral Resolution*: The influence of the spectral resolution on C_{ab} [Fig. 7(a) and (b)] estimation using NBIs is larger than that for LAI [Fig. 7(c) and (d)]. For C_{ab} , SIPI with a 2-nm spectral resolution shows significantly higher correlation than other coarser spectral resolutions for most of the reference bands (λ_{ref}). In contrast, the 6, 10, and 14 nm spectral resolutions exhibit similar correlations across all reference band. Conversely, mND is relatively insensitive to spectral resolution, showing little variation across all reference bands for different spectral resolutions. For LAI, the influence of spectral resolution on the correlation with NBIs depends on the index calculation strategy. For the Ref_AVG strategy [Fig. 7(c)], SIPI exhibits a noticeably higher correlation with LAI for finer spectral resolutions, while spectral resolution has minimal impact on mND. When using the Index_AVG strategy [Fig. 7(d)], spectral resolution has minimal impact on LAI estimation for both SIPI and mND format NBIs.

C. Illumination Configuration From Simulation Data

1) *Solar Zenith Angle (SZA)*: The SZA shows a significant influence on the maximum correlation between NBIs and both C_{ab} and LAI (Fig. 8). For C_{ab} , the correlation between C_{ab} and NBIs in the SIPI format increases with SZA, with the highest correlation observed at $SZA = 45^\circ$ and the lowest at $SZA = 0^\circ$, across almost all reference wavelength [Fig. 8(a) and (b)]. This suggests that C_{ab} estimation using SIPI is more accurate when using oblique SZAs. The SZA seems to have less influence on the correlation between C_{ab} and mND. In contrast, the correlation between LAI and NBIs decreases as SZA increases, with the highest correlation observed at $SZA = 0^\circ$ and the lowest at $SZA = 45^\circ$ for both SIPI and mND using both index calculation strategies [Fig. 8(c) and (d)]. This indicates that

LAI estimation based on NBIs performs better when the SZA is closer to the nadir angle. Comparing the two index calculation strategies, Index_AVG is more sensitive to SZA, with $SZA = 0^\circ$ providing a significant advantage over oblique SZAs (15° , 30° , and 45°).

2) *Diffuse Ratio of Solar Irradiance (SKYL)*: The SKYL shows a small influence on the correlation between NBIs and both C_{ab} and LAI (Fig. 9). Regarding C_{ab} , direct dominant illumination ($0 < SKYL < 0.2$) slightly outperforms other illuminations over the reference wavelength range between 650 and 750 nm. However, the influence of SKYL on C_{ab} becomes negligible when other reference bands are used in the NBIs [Fig. 9(a) and (b)]. The impact of SKYL on the correlation between NBIs and LAI is relatively larger and dependent on the chosen index calculation strategy [Fig. 9(c) and (d)]. Using the Ref_AVG calculation strategy, direct dominant illumination exhibits a slightly higher correlation than other illuminations across all reference bands for both SIPI and mND. On the other hand, under the Index_AVG calculation strategy, diffuse dominant illumination demonstrates a higher correlation compared to direct dominant illumination, particularly for the mND.

D. Pixel Selection and Index Calculation Strategy From UAV Hyperspectral Images

For the correlation between NBIs derived from UAV hyperspectral images and field C_{ab} , sunlit pixels show a higher maximum correlation with NBIs, compared to shaded and entire-crown pixels for both index calculation methods [Fig. 10(a) and (b)]. The $SIPI_{\lambda_{ref}} [\lambda_1, \lambda_2]$ and $mND_{\lambda_{ref}} [\lambda_1, \lambda_2]$ profiles across different reference bands are nearly identical for both strategies, indicating that the choice of calculation method does not impact C_{ab} estimation using NBIs, consistent with the simulation results (Fig. 4).

E. Sensor Configuration From UAV Hyperspectral Images

For NBIs derived from UAV hyperspectral images, the 0.1-m resolution consistently shows the strongest correlation with field-measured C_{ab} across all reference bands, outperforming the 0.5, 1, and 2 m resolutions for both NBI types ($SIPI_{\lambda_{ref}} [\lambda_1, \lambda_2]$ and $mND_{\lambda_{ref}} [\lambda_1, \lambda_2]$), using both calculation strategies (Ref_AVG and Index_AVG strategy) (Fig. 11). The correlation between NBIs and C_{ab} declines noticeably as spatial resolution decreases from 0.1 to 0.5, 1, and 2 m, which is consistent with simulation results (Fig. 5).

The substantial differences in the maximum correlation coefficient values between NBIs derived from UAV hyperspectral images and C_{ab} across various spectral resolutions (2, 6, 10, and 14 nm) indicate that spectral resolution significantly influences C_{ab} estimation (Fig. 12). Specifically, the SIPI with a 2-nm spectral resolution exhibits a markedly higher correlation than the coarser spectral resolutions for most reference bands (λ_{ref}). In contrast, the differences among the 6, 10, and 14 nm spectral resolutions are less pronounced than those observed with the 2-nm resolution, although the 6-nm resolution consistently outperforms both the 10 and 14 nm resolutions across all reference bands. This is consistent with the spectral resolution influence results using simulation data (Fig. 7).

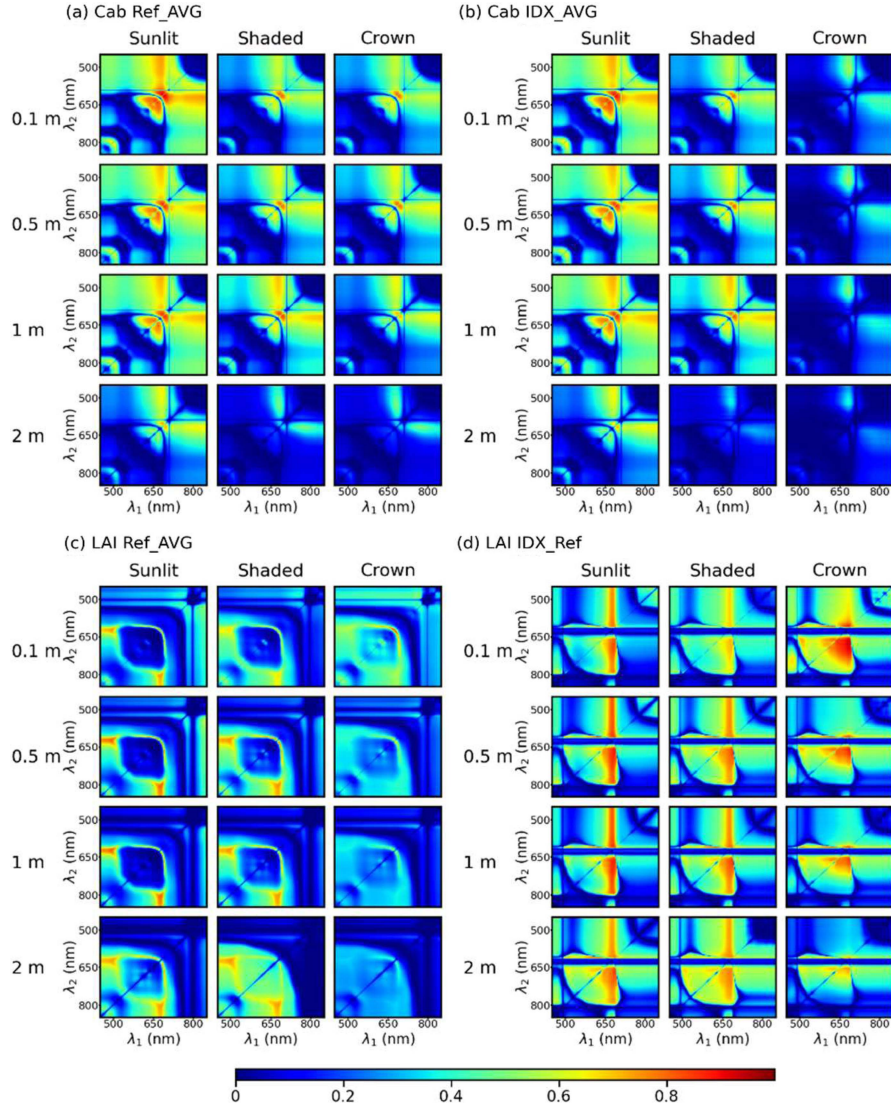


Fig. 6. Heatmap of squared Spearman's correlation: between $\text{SIPI}_{\lambda_{711}}[\lambda_1, \lambda_2]$ and C_{ab} using (a) Ref_AVG and (b) Index_AVG, and (c) between $\text{SIPI}_{\lambda_{800}}[\lambda_1, \lambda_2]$ and LAI using Ref_AVG, (d) between $\text{SIPI}_{\lambda_{490}}[\lambda_1, \lambda_2]$ and LAI using Index_AVG, as a function of λ_1 and λ_2 wavebands, with corresponding reference bands for sunlit, shaded, and crown.

IV. DISCUSSION

A. Pixel Selection and Index Calculation Strategy

One advantage of high spatial resolution images is the ability to select sensitive pixels for better C_{ab} and LAI estimation. Sunlit and shaded classification is commonly used for C_{ab} and LAI estimation using images with submeter resolutions. Coarser than this resolution, the differences between sunlit and shaded pixels are often ignored [34], [48], [49]. However, this article reveals substantial differences in reflectance between sunlit and shaded pixels even in images with 2-m spatial resolution [Fig. 2(d)]. In addition, the article demonstrates that the correlation between NBIs and C_{ab} exhibits significant differences between sunlit and shaded pixels for images with 1 and 2 m spatial resolutions. Inferior performance was demonstrated when using the entire crown without distinguishing between the sunlit and the shaded pixels for C_{ab} (Fig. 6). This underscores the importance of sunlit and shaded pixel classification, even in 2-m spatial resolution

imagery. This finding may seem contradictory to another urban tree study using 2-m spatial resolution hyperspectral images [11], which found that using sunlit pixels did not improve index correlation for C_{ab} . This discrepancy may be due to their usage of a threshold classification method, which may not be suitable for classifying sunlit and shaded areas of urban trees because of their heterogeneous and complex nature. To address this issue, a method based on statistical theory proposed in our prior research for urban tree sunlit and shaded pixel classification [36] has been adopted here. Previous articles excluded pixels intersecting with the tree crown border to mitigate contamination from background materials [11]. This aligns with our findings that pixels at the crown border are predominantly composed of mixed pixels at 2-m spatial resolution [Fig. 2(d)].

This article shows that sunlit pixels have a significant advantage over shaded pixels and entire-crown pixels for estimating C_{ab} (Fig. 4). This finding is consistent with previous research, as sunlit pixels can enhance the SNR and minimize background

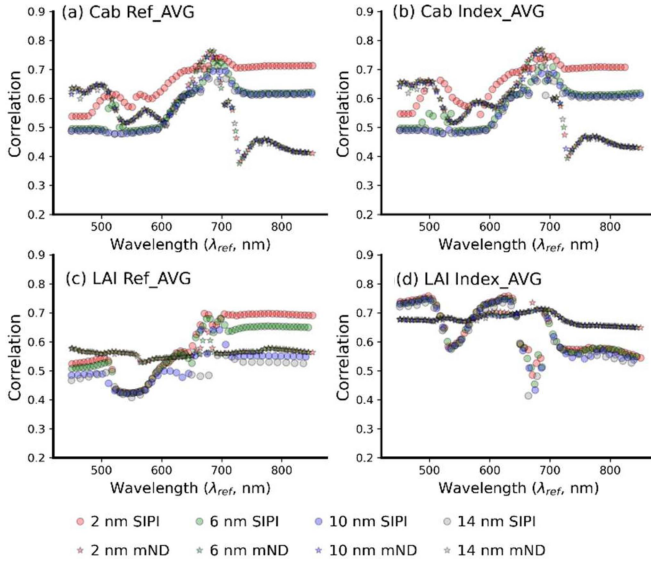


Fig. 7. Maximum Spearman's correlation coefficient values between NBIs and (a and b) C_{ab} , as well as (c and d) LAI, for different spectral resolutions (2, 6, 10, and 14 nm) using various reference bands (λ_{ref}) in the $SIPI_{\lambda_{ref}} [\lambda_1, \lambda_2]$ and $mND_{\lambda_{ref}} [\lambda_1, \lambda_2]$ format. In (a and c), the index calculation strategy is Ref_AVG. In (b and d), the index calculation strategy is Index_AVG. The spatial resolution utilized was 0.1 m.

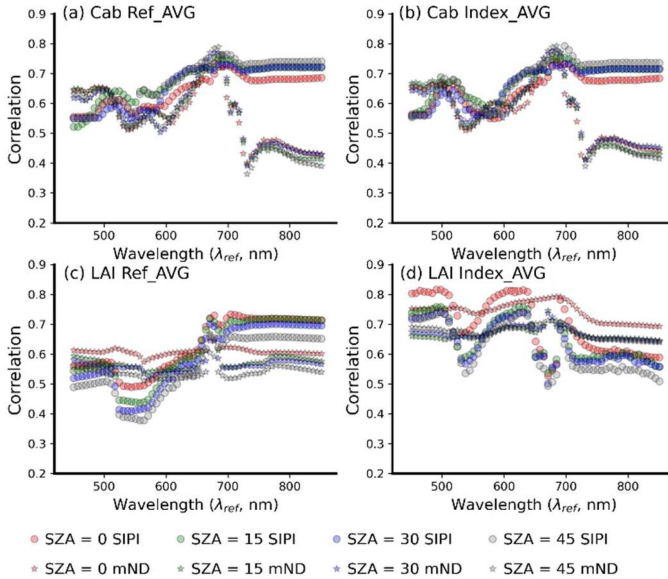


Fig. 8. Maximum Spearman's correlation coefficient values between NBIs and (a and b) C_{ab} , as well as (c and d) LAI, under different SZA (0° , 15° , 30° , and 45°) using various reference bands (λ_{ref}) in the $SIPI_{\lambda_{ref}} [\lambda_1, \lambda_2]$ and $mND_{\lambda_{ref}} [\lambda_1, \lambda_2]$ format. In (a and c), the index calculation strategy is Ref_AVG. In (b and d), the index calculation strategy is Index_AVG. These results were obtained at 0.1-m spatial resolution and 2-nm spectral resolution.

influence [34], [35], [36], [52], [53]. Previous articles have suggested using entire-crown pixels for LAI estimation, as it produces the lowest correlation with C_{ab} and the highest correlation with LAI [14], [36]. This is in line with the current study, which demonstrates that using crown pixels can achieve the highest correlation between LAI and NBIs across the reference wavelengths (Fig. 4). However, this article also reveals that pixel selection for LAI estimation is complex; it depends on

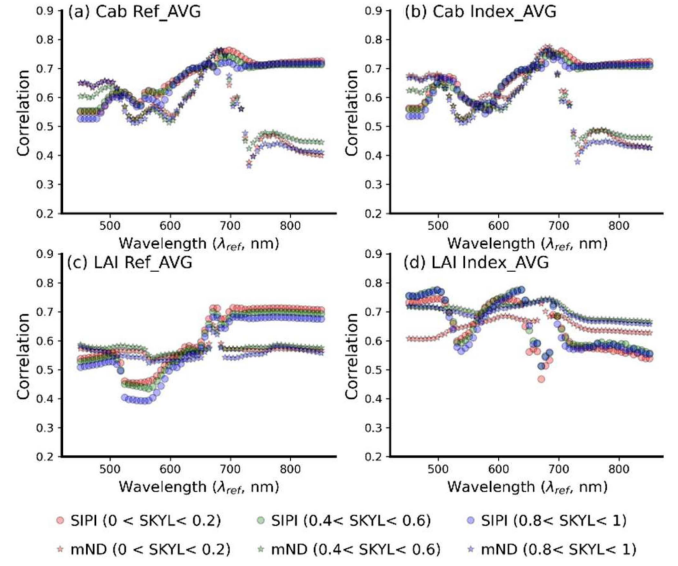


Fig. 9. Maximum Spearman's correlation coefficient values between NBIs and (a and b) C_{ab} , as well as (c and d) LAI, under different SKYL ($0 < SKYL < 0.2$, $0.4 < SKYL < 0.6$, $0.8 < SKYL < 1.0$) using various reference bands (λ_{ref}) in the $SIPI_{\lambda_{ref}} [\lambda_1, \lambda_2]$ and $mND_{\lambda_{ref}} [\lambda_1, \lambda_2]$ format. In (a and c), the index calculation strategy is Ref_AVG. In (b and d), the index calculation strategy is Index_AVG. The spatial resolution was 0.1 m and the spectral resolution was 2 nm.

the chosen reference wavelength, index calculation strategy, and spatial resolution of the images. The entire-crown pixels outperform others for reference wavelengths shorter than 700 nm using the Index_AVG strategy and longer than 700 nm using the Ref_AVG strategy (Fig. 4). The advantage of using the entire-crown for LAI estimation diminishes when using other reference wavelengths and index calculation strategies, and also decreases as spatial resolution decreases (Fig. 6).

This article demonstrates that the Ref_AVG and Index_AVG index calculation strategies yield similar correlations between NBIs and C_{ab} for spatial resolutions of 0.1, 0.5, 1, and 2 m (Fig. 5). This finding is consistent with a previous article, which indicated that these two strategies produce highly comparable results when the spatial resolution exceeds 10 cm [14]. Regarding LAI estimation, this article highlights the superiority of the Index_AVG strategy for reference bands below 650 nm, while both strategies demonstrate comparable performance for reference bands exceeding 700 nm (Fig. 4).

B. Spatial and Spectral Selection

Determining the optimal spatial resolution is crucial for enhancing parameter estimation accuracy without introducing noise and increasing computational burden. A previous article revealed that LAI estimation performances of hyperspectral images for sugar beet crops remained consistent for spatial resolutions finer than 4.4 cm but degraded with coarser resolutions [14]. Similarly, this article on urban trees demonstrates minimal difference in the estimate of C_{ab} for spatial resolutions finer than 1 m but a significant deterioration at 2-m resolution [Fig. 5(a) and (b)]. This indicates that a spatial resolution smaller than 2 m is optimal for C_{ab} estimation. For LAI estimation, 0.1-m resolution significantly outperforms coarser resolutions [0.5,

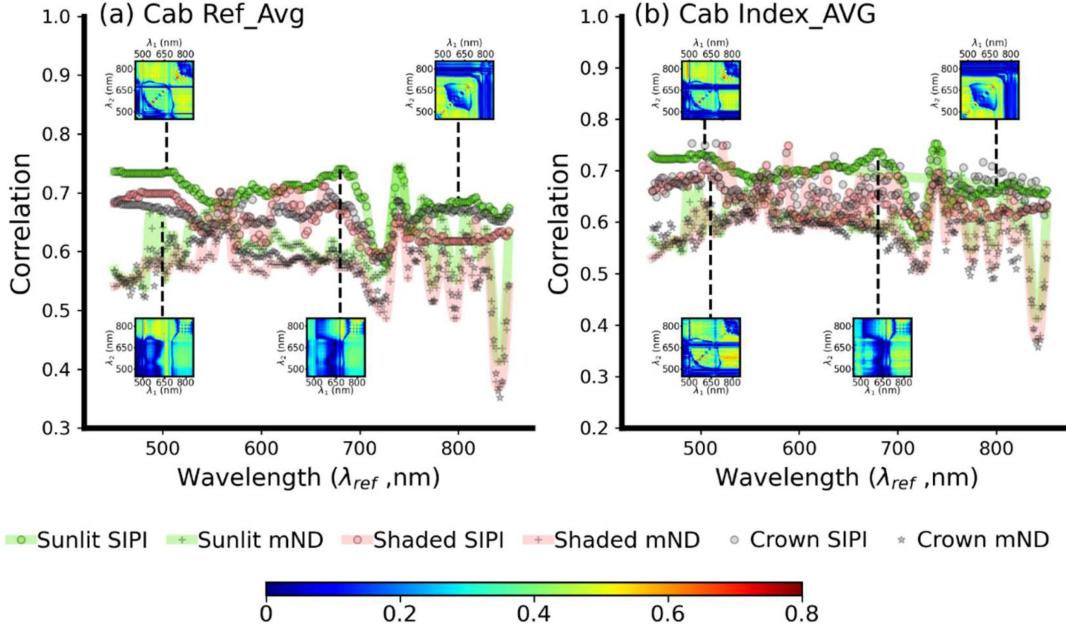


Fig. 10. Maximum Spearman's correlation coefficient values between NBIs derived from UAV hyperspectral images and C_{ab} using various reference bands (λ_{ref}) in the $SIPI_{\lambda_{ref}} [\lambda_1, \lambda_2]$, and $mND_{\lambda_{ref}} [\lambda_1, \lambda_2]$ format from sunlit, shaded, and entire crown pixels at 0.1-m spatial resolution. (a) Ref_AVG strategy. (b) Index_AVG strategy. The subfigure demonstrates the heat map of squared Spearman's correlation as a function of λ_1 and λ_2 wavebands with corresponding reference bands.

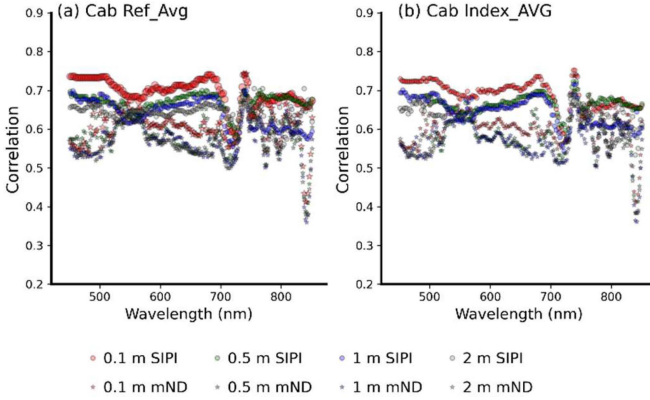


Fig. 11. Maximum Spearman's correlation coefficient values between NBIs derived from UAV hyperspectral images and C_{ab} , utilizing various reference bands (λ_{ref}) in the $SIPI_{\lambda_{ref}} [\lambda_1, \lambda_2]$ and $mND_{\lambda_{ref}} [\lambda_1, \lambda_2]$ format, with different spatial resolutions (0.1, 0.5, 1, and 2 m). Panels (a) use Ref_AVG strategy, while panels (b) use the Index_AVG strategy. The spectral resolution employed is 2 nm.

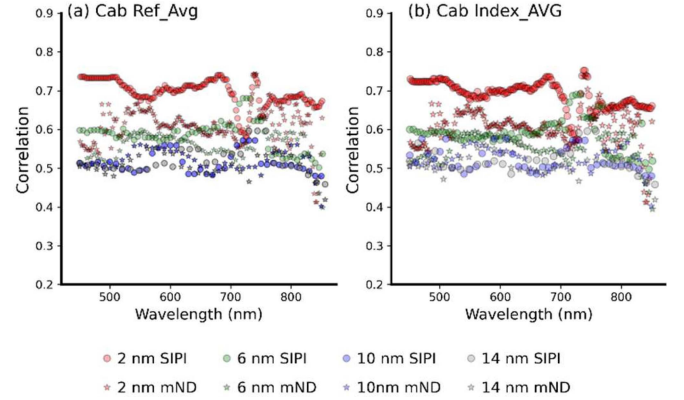


Fig. 12. Maximum Spearman's correlation coefficient values between NBIs derived from UAV hyperspectral images and C_{ab} for different spectral resolutions (2, 6, 10, and 14 nm), using various reference bands (λ_{ref}) in the $SIPI_{\lambda_{ref}} [\lambda_1, \lambda_2]$ and $mND_{\lambda_{ref}} [\lambda_1, \lambda_2]$ format. In (a), the reference band is Ref_AVG. In (b), the index calculation strategy is Index_AVG. The spatial resolution utilized was 0.1 m.

1, and 2 m; Fig. 5(c) and (d)], indicating that 0.1-m spatial resolution is optimal for LAI estimation. This suggests that current operational satellites, such as WorldView and Planet with resolutions of 2 and 3 m, respectively, may still be limited by their spatial resolution for LAI estimation. Thus, LAI estimates from UAVs could potentially serve as a reference for those derived from these satellite images. For accurate LAI estimation, UAVs must sacrifice flight efficiency by flying at lower altitudes and slower speeds to achieve higher spatial resolutions, ideally finer than 1 m for effective tree monitoring. In contrast, for C_{ab} estimation, UAVs can operate at higher altitudes and faster speeds, enhancing flight efficiency without significantly compromising the accuracy of C_{ab} measurements.

The 2-nm spectral resolution offers a significant advantage over coarser resolutions (6, 10, and 14 nm) for C_{ab} estimation for both index calculation strategies [Fig. 7(a) and (b)]. Even though previous articles show that LAI estimation from broadband indices can be influenced by illumination geometry, canopy architecture, leaf biochemistry, and background [51], this article shows that the impact of spectral resolution on LAI estimation is relatively minor, particularly when utilizing the Index_AVG strategy [Fig. (c) and (d)]. These findings could serve as a theoretical basis for sensor development aimed at C_{ab} and LAI estimation. For instance, cameras intended for tree C_{ab} estimation should prioritize higher spectral resolution, exceeding 2 nm, whereas for LAI estimation, the need for high spectral

resolution can be relaxed without significantly compromising accuracy, allowing for more cost-effective sensor options.

This article explores equal increments of spectral resolution for all wavelengths. However, some satellite missions increase the spectral resolution in certain spectral ranges. For example, several narrow waveband multispectral satellite sensors (e.g., RapidEye, Worldview-2, MERIS, and SumbandilaSAT) have been designed to include off-chlorophyll absorption center wavebands, which provide more sensitivity toward canopy biochemical constituents by including red-edge wavebands (i.e., 690–730 nm), while maintaining the characteristics (wider swaths, medium-to-high spatial resolutions, etc.) of multispectral sensors. The conclusions of this article also apply to such sensors when these specific wavelengths are used.

C. SZA and Illumination Selection

Previous article has demonstrated that oblique measurements are more sensitive to leaf properties compared to nadir measurements [48], [53], [54]. This increased sensitivity is attributed to a greater proportion of vegetation captured by the sensor and a reduced fraction of soil, resulting in a higher fraction of photons interacting with leaves before reaching the sensor. The current article supports these findings, revealing a stronger correlation between NBIs and C_{ab} at higher SZAs, implying that oblique SZAs are more effective for C_{ab} estimation [Fig. 8(a) and (b)]. In contrast, LAI, a structural characteristic of trees, exhibits a stronger correlation with NBIs when observed from a nadir view [Fig. 8(c) and (d)]. The variability in the correlation between NBIs and C_{ab} and LAI is partly due to the impact of anisotropic reflectance on spectral indices [55]. Notably, this article focuses exclusively on the influence of SZA, given the predominant nadir VZA of the UAV. Due to the Helmholtz reciprocity of the bidirectional reflectance distribution function, the effect of the VZA is expected to be similar to SZA in C_{ab} and LAI estimation. Consequently, our results align with those of previous articles indicating that nadir and oblique measurements are more sensitive to canopy structure and leaf biochemistry, respectively [48], [56].

Illumination also exhibits high variability and index-dependent effects on spectral indices. Therefore, careful consideration must be given to NBI selection to ensure that the interpretations are related to biophysical/biochemical phenomena rather than the effects of illumination [35]. Additionally, the impact of illumination on the correlation between NBIs and C_{ab} and LAI depends not only on the NBI format but also on the index calculation strategy (Fig. 9). Regarding the hypothesis that diffuse illumination conditions may have advantages in revealing spectral features in vegetation [35], this article shows the illumination barely influence C_{ab} estimation. However, for LAI estimation, the impact depends on the index calculation strategy used. Using Index_AVG calculation strategy, diffuse illumination benefits LAI estimation. Conversely, with the Ref_AVG calculation strategy, direct dominant illumination is more advantageous than diffuse illumination (Fig. 9). These findings indicate that the optimal image acquisition time for C_{ab} estimation is during early morning or late afternoon when the SZA is low, whereas for LAI estimation, local noon with a high SZA is more suitable. Weather conditions, such as clear or cloudy skies, do not significantly

affect C_{ab} estimation. However, index calculation strategies should be adjusted according to varying illumination conditions for LAI estimation.

D. Differences and Limitations of Simulation and Field Data

The largest discrepancies between the simulation data profiles (Figs. 4, 5, and 7–9) and field data profiles (Figs. 10–12) in terms of maximum correlation between NBIs and C_{ab} occur in the blue band (450–500 nm) and a small portion of the NIR band (750–760 nm). Both ranges exhibit higher correlations in the field data than in the simulated results. This discrepancy may be due to greater atmospheric variability in the simulation data compared to UAV hyperspectral imagery. The sensitivity of indices utilizing the blue band (450–500 nm) and the oxygen absorption band (around 760 nm) to illumination conditions likely reduces the correlation with C_{ab} . Aside from these two ranges, the profiles of maximum correlation between NBIs and C_{ab} are consistent between the field and simulated data, with correlations increasing from 550 nm to a peak around 700 nm, followed by a stable lower plateau in the NIR band (770–850 nm).

Unfortunately, LAI field data were not collected simultaneously with the hyperspectral image acquisition, making it impossible to evaluate the simulation-derived conclusions regarding LAI. Additionally, exploring the influence of SZA and illumination on C_{ab} and LAI estimation using field data is challenging, as acquiring UAV hyperspectral images under varying SZA and weather conditions is difficult due to airspace restrictions and the unpredictability of the weather. Fortunately, the key strengths of radiative transfer model simulations is their ability to reveal new insights or patterns when remote sensing imagery and field measurements are unavailable. For instance, simulated images have been generated prior to the launch of new satellites to explore the ability of the satellite images for parameter estimation [57], [58], [59], [60], [61], [62], [63] and radiative transfer model simulations have been used to evaluate field measurement methods when field data are lacking [43], [64]. In this article, the consistency between the simulation and field results for C_{ab} suggests that the model settings accurately represent urban environments, and the conclusions regarding LAI, SZA, and illumination drawn from the simulations are reliable.

Results derived from UAV hyperspectral images and field measurements (Figs. 4, 5, and 7–9) contain more outliers compared to the simulation data (Figs. 10–12). While field measurements are crucial for validating simulation settings, model simulations offer distinct advantages by providing controlled environments, avoiding confounding factors, such as camera noise, environmental noise during image acquisition (e.g., wind or atmospheric conditions), postprocessing inaccuracies (e.g., geolocation errors), and uncertainties in C_{ab} estimation during field measurements. Extracting meaningful information from the less noisy simulation data can be significantly more straightforward.

V. CONCLUSION

This article investigates the influence of observation configuration on the estimation of C_{ab} and LAI using NBIs derived from simulated hyperspectral images of trees generated by the 3-D

radiative transfer model, DART. The configurations considered include spatial resolution, spectral resolution, SZA, and SKYL. Additionally, this article examines the effectiveness of different index calculation strategies for C_{ab} and LAI estimation with sunlit, shaded, and entire-crown pixels. The findings reveal that, regardless of the index calculation strategy deployed, the sunlit pixels consistently outperform the shaded and entire-crown pixels for C_{ab} estimation across different spatial resolutions, including the 2-m spatial resolution. The strongest correlation is achieved when the reference band is around 700 nm. However, for LAI estimation, the highest correlation is observed when using entire-crown pixels with reference bands around 400–500 and 600–650 nm. The C_{ab} estimation is minimally affected by variations in spatial resolution, whereas LAI estimation is sensitive to spatial variations. A 0.1-m spatial resolution offers substantial advantages over coarser spatial resolutions for LAI estimation. Moreover, the advantages of using entire-crown pixels for LAI estimation diminish as spatial resolution decreases, while sunlit pixels exhibit stable correlations across different spatial resolutions. Higher spectral resolution (2 nm) significantly enhances C_{ab} estimation compared to coarser spectral resolutions (6, 10, and 14 nm), with smaller differences observed among these coarser spectral resolutions. LAI estimation appears less sensitive to changes in spectral resolution. In terms of SZA, an oblique SZA (45°) yields slightly higher correlations than a nadir SZA (0°) for C_{ab} estimation, whereas nadir SZA performs better for LAI estimation. The influence of the SKYL is minimal on C_{ab} estimation, but for LAI estimation, direct-dominant illumination performs slightly better with the Ref_AVG calculation strategy, while diffuse-dominant illumination performs slightly better with the Index_AVG calculation strategy. The exploration of the influence of spatial and spectral resolution on C_{ab} estimation using UAV hyperspectral images and field-measured C_{ab} demonstrates findings consistent with those derived from simulation data. This confirms the reliability of applying conclusions from the radiative transfer model to real-world scenarios, which is valuable for understanding the theory without direct measurements. This article provides valuable insights into the critical factors affecting hyperspectral image data for C_{ab} and LAI estimation. Such understanding is essential for enhancing vegetation monitoring using UAV data and guiding the development of future satellite missions.

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