

Numerical and Experimental Benchmark Solutions on Vibration and Sound Radiation of an Acoustic Black Hole Plate

Li Ma, Li Cheng*

Department of Mechanical Engineering, The Hong Kong Polytechnic University, Hong Kong

E-mail : li.cheng@polyu.edu.hk

1 **Abstract:** Acoustic Black Hole (ABH) has been attracting the ever-increasing attention from the
2 scientific community as a passive, effective and lightweight solution for vibration and noise
3 mitigations of vibrating structures. Most existing work, however, relies on numerical simulations
4 using Finite Element models, except a few cases where alternative methods are attempted. In
5 general, there is a lack of well-calibrated experimental benchmark solutions for model validations
6 and phenomena assertions, especially in 2D cases where precise fabrication of ABH indentations
7 with well-controlled thickness profile is a challenge. In this paper, a rectangular plate embodied
8 with a symmetric circular ABH indentation is meticulously manufactured and experimentally
9 tested in terms of eigen-frequencies, mode shapes, forced vibration response and radiated sound
10 power in a baffled half-space. These results offer useful benchmark solutions for future ABH
11 studies. In particular, experimental results show a high consistency with the ones predicted by the
12 previously developed 2D Daubechies wavelet (DW) model.

13
14 **Keywords:** Acoustic Black Hole (ABH); Daubechies wavelet (DW) model; Benchmark solutions;

15 Vibration and noise control.

16

17 **1. Introduction**

18 The mitigation of structural vibration and its noise radiation has been a long-lasting issue,
19 relevant to many applications. Vibration reductions via viscoelastic coating over the structural
20 surface [1] or reducing wave reflections from structural boundaries such as graded impedance
21 interface [2] are among a few popular options for achieving highly damped structures. However,
22 the need for lightweight structures poses new challenges to these conventional solutions. As an
23 alternative, structural design based on Acoustic Black Holes (ABHs) phenomena [3, 4] shows
24 promise for controlling flexural vibrations in thin-walled structures alongside a possible weight
25 reduction. Taking advantage of smoothly decreasing structural thickness, tailored according to a
26 power-law relationship, an ABH structure exhibits progressively reduced flexural wave phase
27 velocity towards the tapered/indentation area, giving rise to pronounced energy focalization and
28 reduced wave reflections with the use of a small amount of damping material [4, 5]. As a promising
29 passive and lightweight solution, interests in exploring ABH effects for various vibration and noise
30 control have been experiencing an exponential growth during the past decade [5-15].

31

32 As analytical solutions on realistic ABH structures are practically unavailable, most existing
33 work resorts to numerical simulations using Finite Element method [10, 11, 16, 17] or other
34 alternative techniques [18, 19]. In relation to these works, comparisons with experimental results,
35 in views of model validations, are scarce in the literature. Among a few existing examples, one
36 can cite O'Boy et al. [18] who investigated the damping and the mobility of a rectangular plate
37 containing a wedge of power-law profile using a bending plate model. However, positions of

38 resonant peaks showed significant differences with the results obtained from experiments.
39 Experimental investigations into vibration characteristics of ABH plates have also been carried out
40 in Refs. [7, 11, 19]. As opposed to vibration analyses [20-23], explorations into sound radiation
41 properties of ABH structures are scarce. Bowyer and Krylov [9] firstly experimentally investigated
42 the sound radiation properties of rectangular plates containing multiple circular indentations.
43 While demonstrating some typical ABH phenomena and their vibration and acoustic benefits, it is
44 observed that the experimental setup may cause some errors at low frequencies because of the
45 acoustic short circuiting resulting from the free edges of the plate due to the absence of the acoustic
46 baffle.

47
48 Simulation models are of vital importance for carrying out ABH design, analyses and
49 optimization. However, there is still a lack of well-calibrated experimental benchmark solutions
50 for their validations. This is probably due to the challenging task of manufacturing high-precision
51 ABH indentations. In fact, as demonstrated by Bowyer et al. [24], ABH effects show strong
52 dependence on geometrical details. Although effective damping of ABH structures can still be
53 obtained with the existence of imperfect geometrical and material parameters, such a variability
54 can be a serious issue from the viewpoint of model validations. Therefore, it is imperative to
55 establish a full set of well-controlled benchmark solutions, which motivates the present work.

56
57 In this paper, a rectangular plate embedded with a symmetric circular ABH indentation was
58 meticulously manufactured using Computer Numerical Control (CNC) milling. Structural
59 properties of the manufactured sample, such as eigen-frequencies, mode shapes, forced vibration
60 response and sound radiation into a baffled half-space were then experimentally measured and

61 compared with the predictions by a previously developed Daubechies wavelet (DW) model. The
62 objective of the paper is twofold: offering a useful set of experimental benchmark solutions for
63 future ABH studies; and validating the previously developed model along with the experimental
64 assertion of the revealed ABH-specific phenomena.

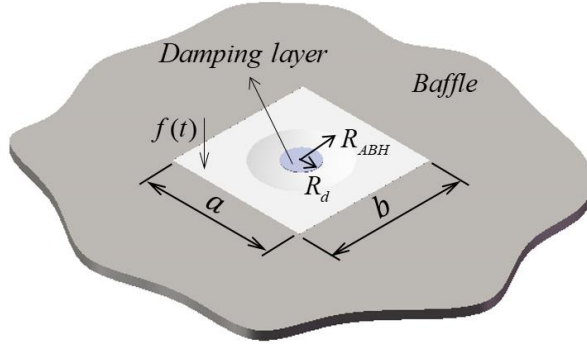
65
66 The rest of the paper is structured as follows. Section 2 briefly revisits the previously
67 developed DW model. Section 3 gives a description of the high-precision ABH manufacturing
68 process. In Section 4, experimental setup used for vibration and sound radiation tests are
69 introduced, followed by a brief description of the sound power measurement procedure.
70 Comparisons between the experimental results and DW model predictions are then conducted in
71 Section 5, in terms of eigen-frequencies of the first 120 modes, mode shapes, forced vibration
72 response and radiated sound power. Finally, conclusions are summarized in Section 6.

73

74 2. System description and benchmark semi-analytical model

75 For the completeness of the paper, this section gives a brief account of a previously developed
76 2D ABH plate model [13] surrounded by an infinite rigid baffle. As shown in Fig. 1, the plate (with
77 a lateral dimension of a, b) incorporates a symmetric circular ABH indentation whose thickness is
78 tailored according to $h(x, y) = \varepsilon r^\gamma + h_0$, where ε is a constant, γ the power law index, r the
79 distance from the observing point to the ABH center (x_c, y_c) , h_0 represents the minimum
80 thickness of the indentation. The radius of the circular indentation is denoted by R_{ABH} . The region
81 outside the ABH indentation of the plate has a uniform thickness h . The plate is supported by a set
82 of artificial springs, both translational and rotational, that are uniformly distributed along the edges.

83 The ABH indentation is partially coated with damping layers on both sides. The damping of the
 84 system is included using complex Young's modulus that incorporates the loss factor of material:
 85 $E_0^* = E_0(1 + i\eta_0)$ and $E_d^* = E_d(1 + i\eta_d)$ represent complex Young's moduli of the plate and the
 86 add-on damping layers, respectively; η_0 and η_d are the corresponding loss factors. The
 87 damping layers are integrated with the plate and are considered in a fully coupled manner in the
 88 model. The plate is subject to a harmonic mechanical point force $f(t)$ at the uniform portion of
 89 the plate.



90
 91 Fig. 1. Modelling of the ABH plate.

92 The solution to the established model is based on the Kirchhoff-Love thin plate theory under
 93 the framework of the Rayleigh-Ritz method, after decomposing the plate transverse displacement
 94 w as

$$95 \quad w = \sum_{i=1}^p \sum_{j=1}^q a_{ij}(t) \varphi_i(\xi) \varphi_j(\eta) \quad (1)$$

96 where $\xi = x/a$ and $\eta = y/b$ are the dimensionless coordinates, $\varphi_i(\xi)$ and $\varphi_j(\eta)$ are the
 97 Daubechies wavelet (DW) admissible functions. The discretized matrix form of the equation of

98 motion of the system writes [25]:

$$99 \quad (\mathbf{K} - \omega^2 \mathbf{M}) \mathbf{A} = \mathbf{F} \quad (2)$$

100 where vector \mathbf{A} contains the amplitudes of complex coefficients $a_{ij}(t)$; \mathbf{M} and \mathbf{K} respectively
101 stand for the global mass and stiffness matrices; ω is the circular frequency; \mathbf{F} is the vector of
102 the excitation force. Eq. (2) allows obtaining the eigen-frequencies and corresponding mode
103 shapes upon solving its eigenvalue problem or the forced vibration response. Subsequently, the
104 sound power radiated into a baffled half-space can be obtained as [25]:

$$105 \quad W_{rad} = \mathbf{V}^H \mathbf{R} \mathbf{V} \quad (3)$$

106 where \mathbf{V} is the vector of vibration velocity, \mathbf{R} the radiation resistance, and the superscript H
107 the complex conjugate. Results predicted by the DW model will be verified by experimental tests
108 on a manufactured test sample.

109

110 3. Manufacturing process of ABH test sample

111 The manufacturing procedure of an ABH plate sample and the parameters that control the
112 manufacturing process are reported as follows. To quantify the deviation of the manufactured
113 thickness profile from its predesigned one, the thickness at multiple points over the manufactured
114 profile is measured using a Coordinate Measuring Machine (CMM).

115

116 The designed geometrical parameters of the test sample are shown in Table 1. Material

117 parameters of ABH sample and those of the damping layer (3M™ VHB™ adhesive transfer tape
 118 F9473PC) are tabulated in Table 2. The damping material used in the tests are produced by 3M
 119 Company.

120 **Table 1** Geometrical parameters

$a=0.6$ m	$x_c=0.3$ m	$\varepsilon=0.24$ /m
$b=0.5$ m	$y_c=0.25$ m	$\gamma=2$
$h=6$ mm	$h_0=0.6$ mm	$R_{ABH}=0.15$ m

121

122 **Table 2** Material parameters

	Density	Elastic modulus	Loss factor	Poisson's ratio
ABH plate	$\rho_0=2800$ kg/m ³	$E_0=71$ GPa	$\eta_0=0.002$	$\mu_0=0.33$
F9473PC	$\rho_d=980$ kg/m ³	$E_d=30$ MPa	$\eta_d=0.9$	$\mu_d=0.499$

123

124 3.1. Manufacturing method

125 Manufacturing metallic structures with a thin thickness is technically challenging, especially
 126 for an ABH plate that incorporates an indentation with a power-lawed profile variation. The
 127 minimum thickness that can be reached in commonly used manufacturing techniques such as CNC
 128 milling and 3D printing is around 0.5 mm. In the present case, the targeted minimum thickness at
 129 the center of the indentation is chosen to be 0.6 mm. Meanwhile, the radius of the ABH indentation
 130 is relatively large, *i.e.*, 0.15 m. All in all, two main concerns arise. First, suffering from the
 131 mechanical stress from the milling cutter, the thin area of the ABH indentation is susceptible to

132 tearing. Second, the resulting high-temperature stress may deform the thin indentation area, thus
133 compromising the accuracy of the thickness profile. Therefore, materials of the test sample and
134 the milling cutter should be carefully selected. In the present case, top-grade aluminum 7075 which
135 is widely used in aerospace industry is chosen. Aluminum 7075 has good machinability with high
136 strength resistance to mechanical stress. Also, the sufficiently tough tungsten cutter with a ball end
137 is a preferable choice for milling. The parameters that determine the manufacturing process should
138 also be meticulously controlled. The rotation speed of the cutter is expected to be high, up to 10000
139 rpm. Also, the cutting volume and the cutting step of the milling cutter should be small, which are
140 0.5 mm and 0.15 mm, respectively.

141

142 The manufacturing procedure mainly consists of four steps. Firstly, a flat plate which has the
143 same size as the test sample was machined out from an aluminum block with the burs being
144 removed, while the flatness error of the surface on both sides is controlled within an acceptable
145 level, *e.g.* 0.05 mm for the present case. Secondly, the milling cutter produced the ABH indentation
146 following a circular path around the center of the indentation, from outside toward inside.
147 Meanwhile, cooling liquid was used to alleviate the induced high-temperature stress. Finally, after
148 completing the indentation on the top side of the plate, the sample was set aside for stress release
149 for several days. Prior to manufacturing the symmetric indentation on the other bottom side, the
150 finished indentation on the top side was fully filled with a plaster to alleviate possible flapping of
151 the cutter. Note the flapping effect frequently occurs when machining thin metals during CNC
152 milling, which can even lead to the tearing of the structure if not properly refrained. Meanwhile,
153 sufficient machining allowance should be considered in each manufacturing step. Following the

154 procedure described above, the symmetric indentation was successfully produced using a three-
155 axis CNC milling machine (type VSC-1470).

156

157 *3.2. Accuracy of the manufactured ABH profile*

158 The manufactured test sample contains inevitable geometrical imperfections because of
159 machining precision. Therefore, the deviation of the manufactured indentation from its
160 predesigned profile is checked through measurement.

161

162 For illustration purposes, the half thickness, defined as the distance from a point at the surface
163 of the indentation to the mid-plane of the test sample, is used to evaluate the error of the
164 manufactured profile. On the top side, 31 measurement points (including the ABH center point)
165 uniformly distribute along two perpendicular lines intersecting at the ABH center, as shown in [Fig.](#)
166 [2\(a\)](#). The thickness profile variations along these two perpendicular lines, for a total of four profile
167 trails (numbered 1[#], 2[#], 3[#], and 4[#]), were examined and deviations of them from the predesigned
168 profile were assessed. The projection of these profiles and the points onto the mid-plane is shown
169 in [Fig. 2\(a\)](#). The half thickness profile of these 31 points was measured using CMM. Similar
170 measurement was also carried out for the bottom side of the plate. The half thickness variations
171 obtained for both sides are respectively shown in [Figs. 2\(b\)](#) and [2\(c\)](#), in comparison with that of
172 the predesigned standard profile.

173

174 As can be seen from [Fig. 2\(b\)](#), for the top side, the half thickness for points over the four
175 measured profile trails are very similar. This similarity can also be observed for the bottom side.
176 Furthermore, the half thicknesses at four points located at the same circle are averaged, both for

177 the top side and bottom side, and compared with their predesigned counterpart in Fig. 2(d). It can
 178 be seen that, the half thickness on the top side shows a nice agreement with that of the predesigned
 179 profile, while a marginal deviation is observed for the bottom side, particularly at the central part
 180 (within a radius of 50 mm) of the indentation. However, this slight deviation is deemed to be
 181 acceptable, as will be further demonstrated by the agreement of vibration response between
 182 experimental tests and numerical simulations in Section 5.

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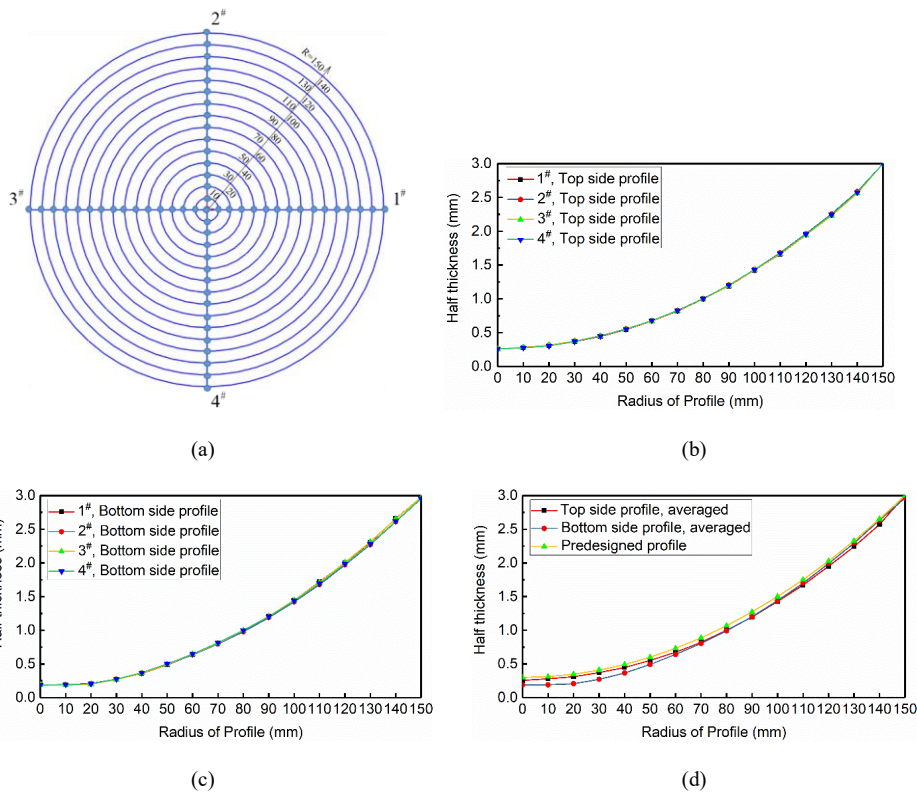


Fig. 2. Half thickness profile: (a) measuring points; (b) top side; (c) bottom side; (d) averaged manufactured profile and predesigned profile.

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191 **4. Experimental setup**

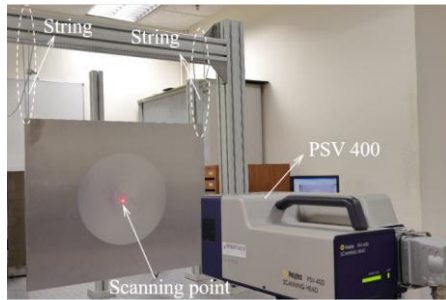
192 The vibrational properties of the manufactured sample and its radiated sound field were
193 measured, inside a test room and a fully anechoic room, respectively. This section reports the
194 experimental setup used for both tests.

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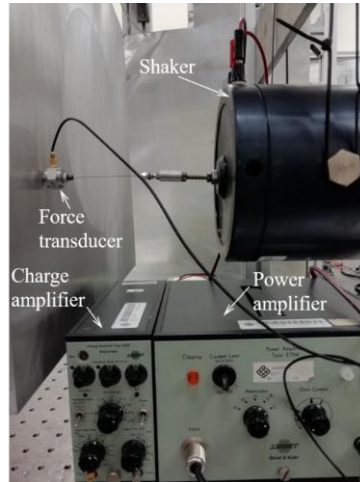
196 *4.1. Measurement of vibration characteristics*

197 The test sample was vertically suspended onto a rigid frame using two flexible strings that
198 introduce negligible damping, allowing for the vibration testing of the sample under free boundary
199 conditions. The two strings pass through small holes (with a diameter of 4 mm) near the corner of
200 the sample, as shown in Fig. 3(a). The strings maintain adequate strength to support the weight of
201 the sample plate (about 4.8 kilogram). The plate was excited by electromagnetic shaker (type 4809)
202 through a small thin rod/stinger to filter out possible moment excitation. A force transducer (B&K
203 8200) was installed to the end of the stinger to measure the input force. To reduce possible mass
204 loading effect, adhesive glue was used to connect the force transducer to the test sample, as shown
205 in Fig. 3(b). The electromagnetic shaker was fed by a power amplifier (B&K 2706) with the
206 periodic chirp signal. The input signal was converted to voltage signal via a charge amplifier (B&K
207 2635). A Polytec scanning laser vibrometer (PSV) 400 was used for signal generation and data
208 acquisition. The vibration response signals were averaged over ten measurements to guarantee
209 statistically representative results.

210



(a)



(b)

Fig. 3. Experimental setup: (a) ABH test sample; (b) excitation with electromagnetic shaker and force transducer.

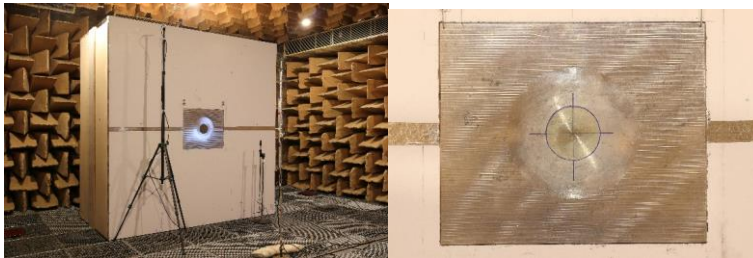
4.2. Measurement of the radiated sound power

The measurement of the radiated sound power was carried out in a fully anechoic chamber with an inner dimension of $6 \times 6 \times 3$ m. The cut-off frequency of the chamber is roughly 90 Hz. A B&K Pulse system was utilized for signal generation and data acquisition instead of PSV 400, while other equipment remaining the same as for the vibration test. Thick large wooden panels (8 long \times 8 ft wide \times 0.75 inch thick) were used to surround the test sample to form a rigid acoustic baffle. Four smaller wooden panels, 4 ft long \times 4 ft wide \times 0.75 inch thick, were annexed to the four edges of the baffle to constitute a folded wall (see Fig. 4(a)), which allows for a larger effective sound wave blockage area. The test plate, flush-mounted with the surface of the baffle, was installed in the middle of the baffle, as shown in Fig. 4(b). The gap between the wooden

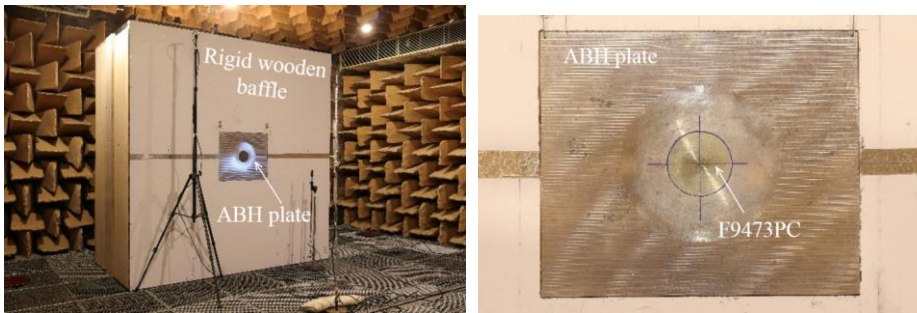
226 panel and the test sample was around 1 mm to avoid additional damping to the test sample caused
227 by friction. The electromagnetic shaker was sealed inside a thick-walled box made of Polymethyl
228 methacrylate to minimize its direct sound generation. The linearity of the system was ensured by
229 checking the sound power outputs while doubling the input force level. The schematic of the
230 experimental setup is shown in Fig. 5.

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232



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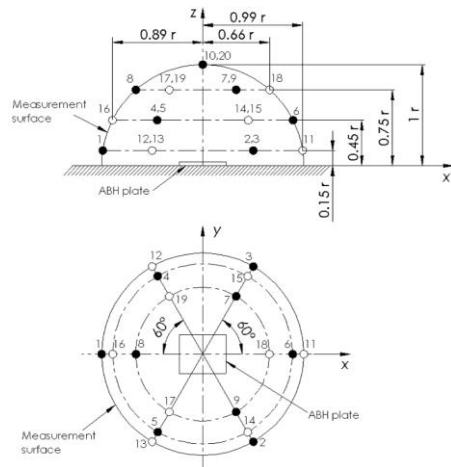
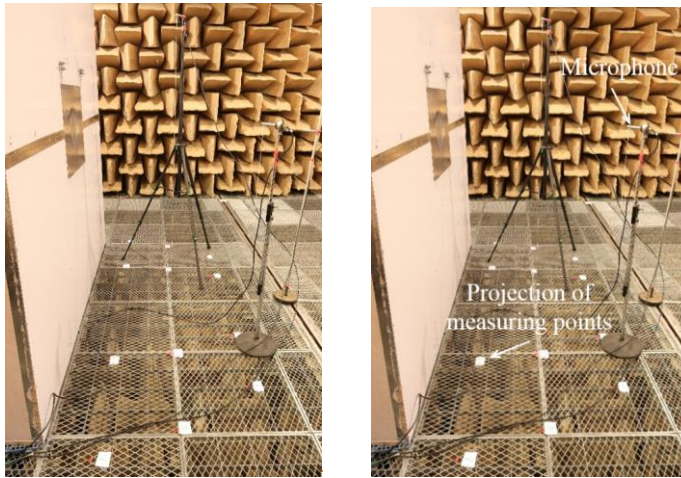


234

(a)

(b)

235



236

237

(c) --- (d)

238 Fig. 4. Anechoic chamber for radiated sound power tests: (a) position of the ABH test sample in relation to the
 239 rigid baffle; (b) coverage of the viscoelastic material F9473PC; (c) measuring points projected on the floor (red
 240 dot); (d) microphone positions over the hemispherical surface.

241

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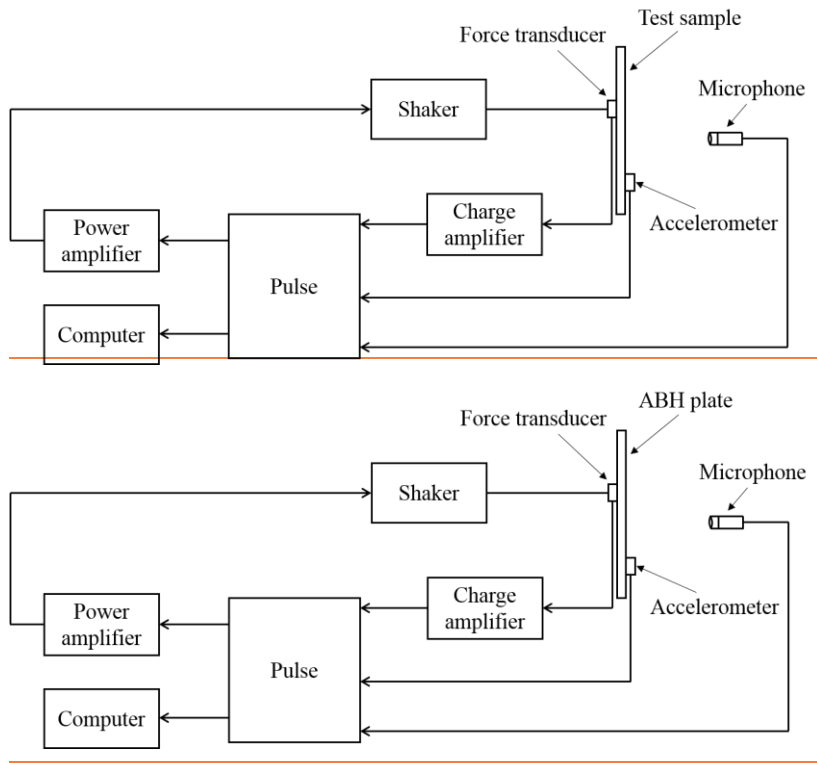


Fig. 5. Schematic of the sound radiation test

The sound power was obtained through sound pressure measurement in accordance with the international standard ISO 3744 [25]. Twenty microphones were installed over an assumed hemispherical surface enclosing the front panel, as shown in Fig. 4(d), with their projection on the floor of the chamber shown in Fig. 4(c). The radius of the hemispherical surface should be larger than twice the characteristic source dimension of the test sample (1.78 m for the current case). In the current case, microphones were positioned on a hemispherical surface with a radius of 1.3 m due to the restriction of the height of the chamber.

253 According to ISO 3744, the pressure determined sound power can be obtained by:

$$254 \quad L_w = \bar{L}_p + 10 \lg(S/S_0) \quad (4)$$

255 in which $S = 2\pi r^2$ is the area of hemispherical surface, $S_0 = 1 \text{ m}^2$, and \bar{L}_p is the surface time-
256 averaged sound pressure level which can be obtained by correcting the mean time-averaged sound
257 pressure level $\bar{L}_{p(ST)}$ from background noise,

$$258 \quad \bar{L}_p = \bar{L}_{p(ST)} - K_1 \quad (5)$$

259 where K_1 is the background noise correction. Assuming that the microphone positions are
260 allocated with equal segment of areas, the mean time-averaged sound pressure level from arrays
261 of microphones can be calculated as

$$262 \quad \bar{L}_{p(ST)} = 10 \lg 10 \left(\frac{1}{N} \sum_{i=1}^N 10^{0.1 L_{pi(ST)}} \right) \quad (6)$$

263 where $L_{pi(ST)}$ is the time-averaged sound pressure level at i th microphone position, and N the
264 number of microphone positions which is 20 in the present case.

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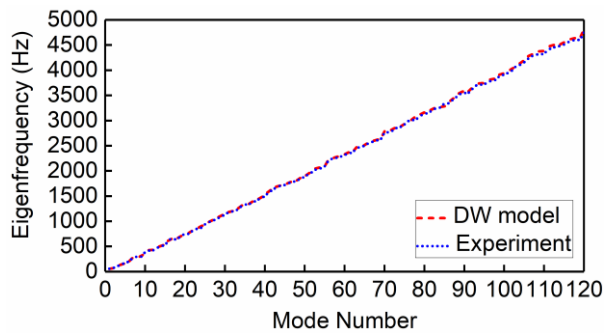
266 **5. Results and analyses**

267 The eigen-frequencies of the first 120 modes and their corresponding mode shapes were first
268 identified. Structural mobility and radiated sound power of the test sample subjected to a point
269 harmonic force were then measured, for plates with/without damping materials. These results are
270 compared against the numerically predicted ones. Additionally, reductions on structural vibration
271 and sound power level were also observed, as detailed later.

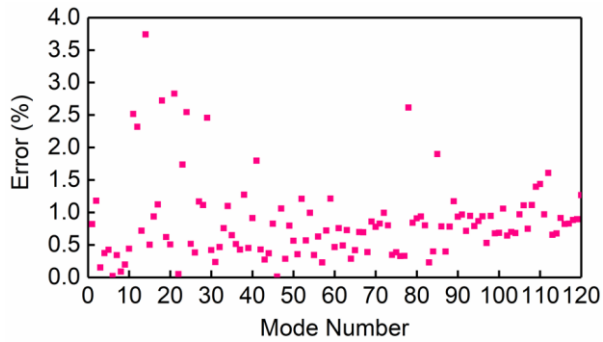
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273 5.1. Eigen-frequencies and mode shapes

274 Modal analyses of the manufactured ABH plate were first carried out experimentally. Eigen-
275 frequencies were identified based on the positions of resonant peaks observed from the frequency
276 response curves measured by the laser-vibrometer. The obtained eigen-frequencies of the first 120
277 modes are presented and compared with their numerically predicted counterparts from the DW
278 model in Fig. 65, showing a good agreement with each other. To quantify the agreement level, the
279 relative error, defined as $(f_{model} - f_{test})/f_{test} \times 100\%$, is present in Fig. 76, where f_{test} and f_{model}
280 represent the eigen-frequencies obtained from the experimental tests and the DW model,
281 respectively. It can be seen that experimental values are slightly smaller than the predicted ones
282 due to shearing effect of the plate which is neglected in the DW model. Nevertheless, most of the
283 errors are below 2% with the maximum one being 3.74%, which is deemed acceptable.



284
285 Fig. 65. Eigen-frequencies of the first 120 modes: DW model (short dash line); experiment (short dot line).

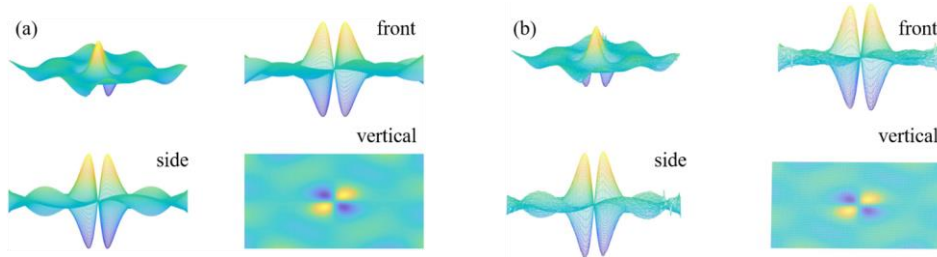


286
 287 Fig. 76. Relative errors of eigen-frequencies of the first 120 modes obtained from the DW model and experiments.
 288

289 Further comparisons are performed in terms of mode shapes. Four arbitrarily chosen mode
 290 shapes (30th, 50th, 83rd, 119th modes) are presented in Figs. 87-110. To ensure a detailed comparison,
 291 different views (front view, side view, and vertical view) of these mode shapes are shown. To
 292 capture the local details inside the ABH indentation, 75000 and 33233 points are respectively used
 293 to depict the mode shapes, obtained from numerical simulations and experiments. It is remarkable
 294 to see that experimentally measured mode shapes are in nearly perfect agreement with their
 295 numerically predicted counterparts, from low-order to high-order modes. Though signal to noise
 296 ratio is a bit low for high-order modes, details in deformation inside the ABH indentation are
 297 clearly observable.

298
 299 As previously mentioned, energy focalization is one of the unique features of the ABH. This
 300 can be clearly observed from the measured vibration patterns of the high-order modes, as shown
 301 in Figs. 109-110. The vibration amplitude inside the ABH indentation is obviously larger than that
 302 of the uniform part of the plate, more evident around the ABH center. Meanwhile, the highly

303 compressed waves inside the indentation area can also be clearly observed.



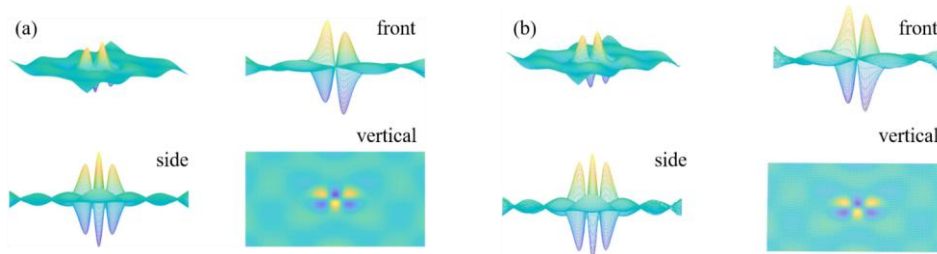
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305 Fig. 87. Comparison of 30th mode shape: (a) DW model (left), $f_n = 1025.8$ Hz ; (b) experiment (right),

306

$$f_n = 1014.0 \text{ Hz} .$$

307



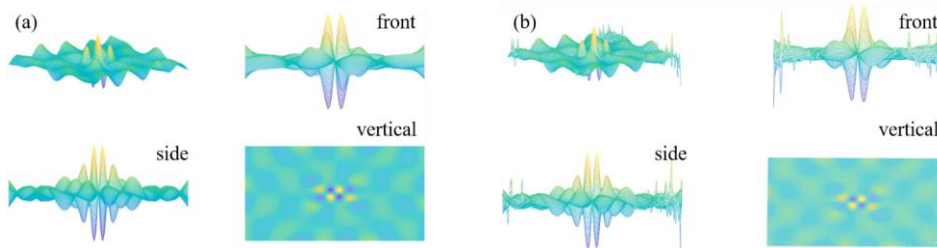
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309 Fig. 98. Comparison of 50th mode shape: (a) DW model (left), $f_n = 1801.4$ Hz ; (b) experiment (right),

310

$$f_n = 1782.5 \text{ Hz} .$$

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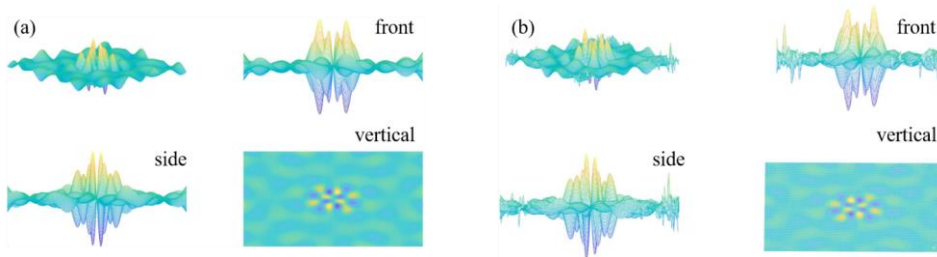
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313 Fig. 109. Comparison of 83rd mode shape: (a) DW model (left), $f_n = 3163.5$ Hz ; (b) experiment (right),

314 $f_n = 3135.0$ Hz .

315

316



317

318 Fig. 110. Comparison of 119th mode shape: (a) DW model (left), $f_n = 4593.7$ Hz ; (b) experiment (right),

319 $f_n = 4556.3$ Hz .

320

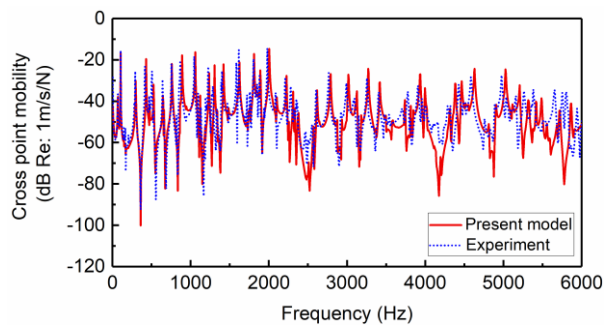
321 5.2. Cross point mobility

322 Forced vibration analyses were carried out on the test sample with a harmonic excitation
323 applied at (0.518, 0.165) m over the uniform portion. The amplitude of vibration displacement of
324 a number of measured points over the surface of the test sample was measured from 5 Hz to 6000
325 Hz with an increment of 5 Hz. Mobilities ($20\lg(v/F)$) at three representative points on the test
326 sample were extracted after 10 times averages. These three points include the ABH center (0.3,
327 0.25) m, a point (0.0375, 0.25) m on the uniform portion and the driving point (0.518, 0.165) m.

328 Figs. 124(a)-(c) illustrate the comparisons between the experimental results and numerical
329 simulations, which shows a good consistency in nearly the entire frequency range, especially
330 below 5500 Hz. Above 5500 Hz, differences begin to show; this presumably can be attributed to

331 the deviation of the manufactured ABH indentation from the predesigned profile, since the
332 response at high frequencies is supposed to be more sensitive to local details. Nevertheless, it can
333 be seen that the rich dynamics of the system, manifested by a large number of resonant peaks, can
334 be truthfully reproduced by the DW simulation model, testifying the accuracy of the model on one
335 hand, and the accuracy in manufacturing the test sample on the other hand.

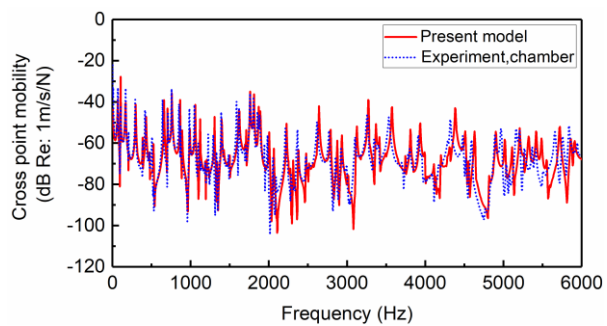
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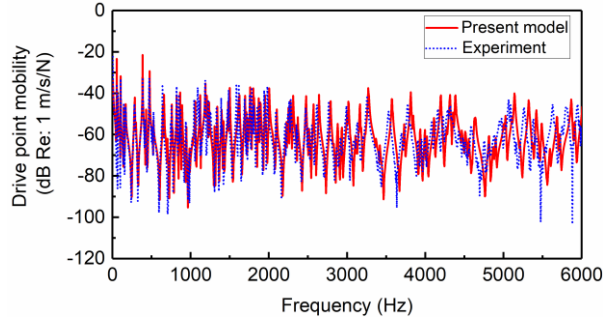
(a)



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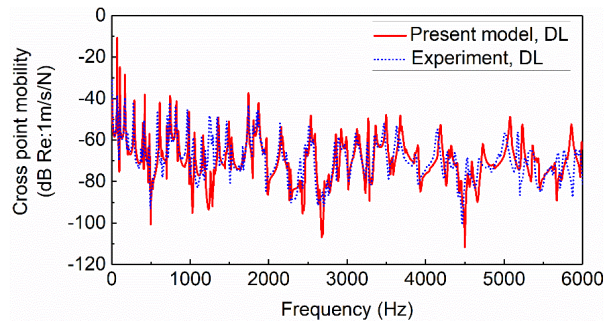
(b)



(c)

Fig. 124. Cross point mobility of the ABH plate: (a) ABH center (0.3,0.25) m; (b) an arbitrary point (0.0375, 0.25) m on the uniform portion; (c) drive point at (0.518, 0.165) m.

The deployment of damping layers inside the ABH indentation plays a crucial role in the realization of ABH effect. To illustrate this effect, the vibration response of the ABH test sample with its central ABH portion covered with 3MTM VHBTM adhesive transfer tape F9473PC was experimentally measured. The density ρ_d , elastic modulus E_d and loss factor η_d of this material were evaluated at 4000 Hz [26] and tabulated in Table 2. In the present case, the central area of ABH indentation within a radius of $R_d = 60$ mm was covered with transfer tape F9473PC of a constant thickness $h_d = 0.75$ mm. Fig. 132 shows the measured and predicted structural mobilities at (0.0375, 0.25) m, showing again a nice fit with each other. Compared with Fig. 124(b), the overall mobility level of the damped plate shows a general decreasing trend with frequencies alongside a general reduction in the peak levels, which can be attributed to the ABH-induced enhancement in the overall system damping.



357

358 Fig. 132. Comparison of cross point mobility at (0.0375, 0.25) m with damping layers: (a) present model
 359 (solid line); (b) experiment (dot line). DL denotes damping layer.

360

361 *5.3. Radiated sound power*

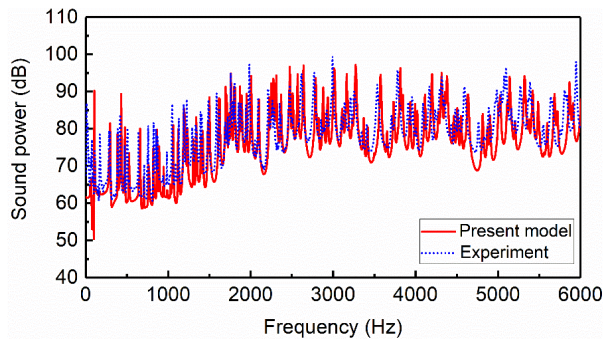
362 Following the procedure described in Section 4.2, the sound power radiated from the baffled
 363 ABH test ample was measured. Using the same excitation as in the vibration test, the sound power
 364 radiated from test sample with/without damping materials was measured. For the sake of
 365 comparison, again, the measured sound pressure at each microphone position was normalized by
 366 the input force. Subsequently, substitution of averaged sound pressure level into Eq. (4)(4) yields the
 367 total sound power as shown in Fig. 143. Comparing the experimentally obtained sound power with
 368 that of model simulations, an agreement can be noticed between these two sets of results, both
 369 with (Fig. 143(a)) and without (Fig. 143(b)) damping layers.

370

371 The results also show that the signal to noise ratio is variable in the frequency range of interest.
 372 Due to the low signal to noise ratio in the frequency range between 1000 Hz and 1500 Hz, the

373 observed sound power is larger than its numerical counterparts. Whereas for other frequency
374 ranges, both sets of results match well. Interference from the shaker should be responsible for the
375 discrepancy between 1000 Hz and 1500 Hz, as the noise from the shaker itself was detected and
376 was difficult to be completely eliminated. Nevertheless, the overall agreement between the model
377 and experiments is deemed satisfactory, especially for such a highly dynamic system exhibiting
378 complex dynamic behaviors.

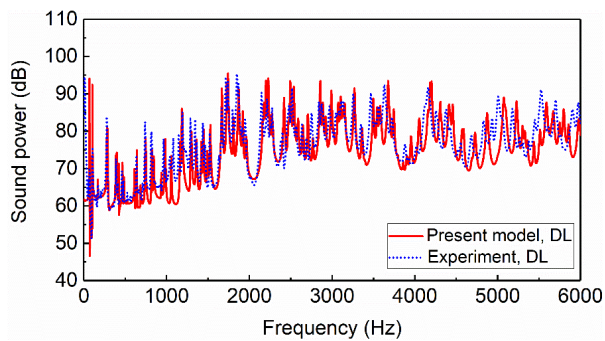
379



380

381

(a)



382

383

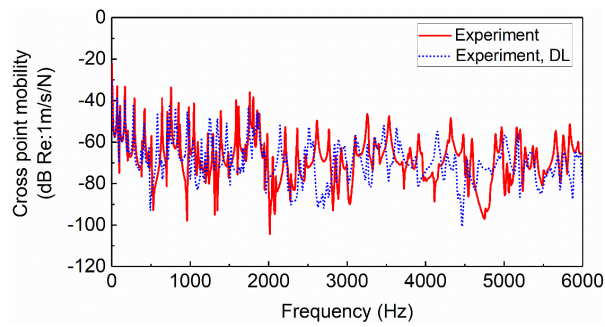
(b)

384 Fig. 143. Radiated sound power: (a) without damping layer; (b) with damping layer. DL denotes damping
385 layer.

386

387 5.4. Effect of damping layers on ABH performance

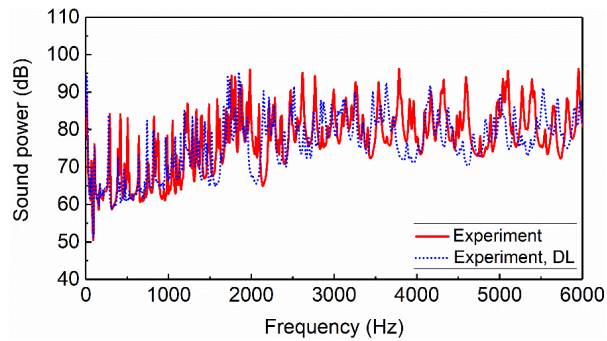
388 As aforementioned, damping layers coated around ABH center are indispensable for the
389 realization of ABH effects and are beneficial to energy dissipation and vibration attenuation. This
390 has been confirmed through experimental tests using the previous test sample. Note the mass of
391 the damping material only accounts for 0.66% of the entire plate. Cross mobility at point (0.0375,
392 0.25) m over the uniform portion was measured. It can be seen from Figs. 154-165 that damping
393 material enables significantly damped vibration peaks as compared with the bare ABH plate, more
394 obvious at high frequencies. Analogously, reduction in the sound power is also observed,
395 especially above the critical frequency of 1995 Hz, estimated using the thickness of the uniform
396 portion of the plate. Therefore, the utilization of realistic damping material deposited at the central
397 portion of the ABH test sample allows for a substantial attenuation of structural vibration response
398 and its radiated sound power, showing the great potential of ABH structures for vibration and noise
399 control applications. Note that in all test cases, due to the free boundaries of the plates, their sound
400 radiation efficiency at low frequencies are rather low, thus making them less efficient in radiating
401 sound despite their high vibration level in the low frequency range.



402

403 Fig. 154. Measured cross point mobility at (0.0375, 0.25) m on the uniform portion of the test samples:
 404 (a) without damping material (solid line); (b) with damping material FP9473 (dot line); (c) with damping
 405 material SD40PSA (dash line). DL denotes damping layer.

406



407

408 Fig. 165. Measured radiated sound power of test samples: (a) without damping material (solid line); (b)
 409 with damping material FP9473 (dot line); (c) with Damping material SD40PSA (dash line). DL denotes
 410 damping layer.

411

412 **6. Conclusions**

413 This paper reports a systematic experimental investigation on a rectangular plate embodied
414 with a symmetric circular ABH indentation. Upon a meticulous design and realization of the
415 manufacturing process, a high-precision ABH plate is manufactured and calibrated. Using the
416 manufactured sample, its structural properties, in terms of eigen-frequencies, mode shapes, forced
417 vibration response and radiated sound power, are experimental tested and compared with a
418 previously developed semi-analytical model. Meanwhile, with realistic damping materials
419 deposited at the central portion of the ABH indentation, ABH effects on reductions in vibration
420 response and sound power are experimentally verified.

421

422 The complete set of experimental results, in both vibration and sound radiation perspectives,
423 offer useful benchmark solutions for future ABH studies. As an illustrative example, experimental
424 data have been used to validate a previously proposed DW model. It has been shown that the model
425 provides remarkable accuracy in characterizing the vibration response and sound radiation of the
426 ABH plate which exhibits rich dynamics and complex dynamic behaviors. More specifically, most
427 of the relative errors on the eigen-frequencies of the first 120 modes of the plate are below 2%,
428 alongside a good match in the corresponding mode shapes. Cross point mobilities and the radiated
429 sound power predicted by the DW model also show a good agreement with experimental
430 measurement up to a high frequency range, both with and without deposition of damping materials.
431 Meanwhile, typical ABH phenomena such as wave compression, energy focalization and the
432 effects of viscoelastic damping layers are also clearly observed in experiments, also in agreement
433 with numerical predictions.

434

435 It is pertinent to stress that an important outcome of this work is the establishment of a feasible
436 manufacturing procedure of an ABH plate, as well as a full set of well-controlled experimental
437 benchmark solutions on some important vibrational and acoustic metrics. Considering the lack of
438 experimental data and the obvious deficiency in correlating simulations with experiments in the
439 literature, we believe this work would serve as an invaluable data source for future ABH studies.

440

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444

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