

**Evaluation of Penalty and Enforcement Strategies to Combat Speeding Offences among  
Professional Drivers: A Hong Kong Stated Preference Experiment**

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## **ABSTRACT**

Speeding has been a great concern around the world due to the occurrence and severity of road crashes. This paper presents an evaluation of the effectiveness of different penalty and camera-based enforcement strategies in curbing speeding offences by professional drivers in Hong Kong. A stated preference survey approach is employed to measure the association between penalty and enforcement strategies and drivers' speed choices. Data suggest that almost all drivers comply with speed limits when they reach a camera housing section of the road. For other road sections, a panel mixed logit model is estimated and applied to understand the effectiveness of penalties and enforcement strategies on driver's speeding behaviors. Driving-offence points (DOPs) are found to be more effective than monetary fines in deterring speeding offences, albeit there is significant heterogeneity in how drivers respond to these strategies. Warning drivers of an upcoming camera-based enforcement section increased speed compliance. Several demographic and employment characteristics, driving history and perception variables also influence drivers' choices of speed compliance. Finally, besides penalty and enforcement strategies, driver education and training programs aimed at addressing aggressiveness/risk-taking traits might help reduce repeated speeding offences among drivers.

**Keywords:** speeding, professional drivers, penalty, enforcement, stated preference survey, mixed multinomial logit

1 **1. INTRODUCTION**

2 Hong Kong is a city with high population density and limited road space. The ability of public  
3 transport to serve high density cities well, as well as the relatively high costs of private vehicle  
4 ownership and high operational costs (especially parking costs) resulting from the limited road  
5 space, has resulted, in Hong Kong, in the dominance of public transport as the primary mode  
6 for work-related as well as non-work travel. Of particular note is the relatively seamless  
7 integration of road-based and rail-based metro public transportation services in Hong Kong,  
8 with transfers between the two broad modes of public transportation commonplace. Overall,  
9 over 90% of commute trips as well as over 46 % of non-commute trips in the territory are  
10 undertaken by road-based and/or rail-based public transport (Transport and Housing Bureau,  
11 2017; Transport Department, 2014).

12 The road-based public transportation modes (PTMs) in Hong Kong primarily include a  
13 regular bus mode (operated either publicly or privately), a light bus mode (or mini-bus mode  
14 that typically carries up to 19 passengers, again operated publicly or privately), and taxis (while  
15 the taxi mode may not be traditionally viewed as a public transportation mode, it is not  
16 uncommon in Hong Kong for the use of taxis to access bus stations and rail stations, making it  
17 an integral component of public transportation use in the country). The substantial dependence  
18 on PTMs contribute to, on a per capita basis, a low vehicle miles of travel (VMT) in Hong Kong.  
19 This low exposure, along with low speeds (due to high vehicle densities) and the protective  
20 cushion offered by large buses, has resulted in a relatively low number of crashes in Hong Kong,  
21 especially those resulting in serious injuries/death. In particular, there were 108 fatalities and  
22 2214 individuals seriously injured in road traffic crashes in 2017 (Transport Department, 2017).  
23 Based on a population estimate of about 7.4 million in Hong Kong in 2017, this translates to a  
24 per capita fatality rate of 14.6 deaths per million population (relative to, for example, 28 road  
25 traffic fatalities per million population in the UK and 107 deaths per million population in the  
26 US).

27 Clearly, Hong Kong's traffic safety record, at least on a per capita basis, is superior  
28 relative to many other western nations. However, an issue of concern in Hong Kong is that,

1 unlike many western countries, a vast majority of the vehicles being driven on the roads are by  
2 professional drivers (interestingly, ride-hailing services have yet to be legalized in Hong Kong,  
3 and, as indicated earlier, taxi rides are a common way to access PTMs, in addition to walking;  
4 and taxi drivers are carefully regulated in terms of licensing requirements). Thus, it is of concern  
5 in Hong Kong that the crash involvement rate of public transport vehicles is seven times higher  
6 than that of the private car (Transport Department, 2017). It certainly brings into spotlight the  
7 safety performance of professional drivers and the licensing regulations in place for such drivers.  
8 While professional driver-related crashes and the organization/travel culture has been examined  
9 at some length in the west and the middle-east (for example, see Mallia et al., 2015; Newnam  
10 et al., 2018; Öz et al., 2010a, 2010b; Rosenbloom and Shahar, 2007), there has been relatively  
11 little research into the causes and considerations associated with professional driver-related  
12 crashes in the far-east. This is particularly surprising, given that professional drivers make up  
13 more of the pool of overall drivers in Hong Kong relative to the west and the middle east.

14 In this paper, we examine the factors that influence the crash-risk of professional drivers  
15 in Hong Kong. Earlier studies in other regions of the world, such as those referenced earlier,  
16 suggest that driver aggressiveness, caused by high work and time pressure and resulting in a  
17 trade-off deliberation between traffic offence-penalties and potential income gains from saved  
18 time in the face of congested travel conditions, contribute to the high crash risk of professional  
19 drivers (Öz et al., 2010a; Rosenbloom and Shahar, 2007). In particular, speeding has been  
20 identified as a common aggressive driving behavior exhibited by professional drivers, and  
21 speeding has also been identified in many earlier studies as being the single most important  
22 factor impacting the occurrence and severity of roadway traffic crashes (Fitzpatrick et al., 2017;  
23 Watson et al., 2015; WHO, 2018). In this context, in some OECD countries, the proportion of  
24 drivers who self-report being guilty of excessive speeding is as high as 80% (WHO, 2018). The  
25 same situation manifests itself in Hong Kong, with speeding being one of the most common  
26 recorded traffic offences among professional drivers and drivers at large. According to the  
27 number of prosecutions against traffic offences in 2017, speeding accounted for over 42%,  
28 while red light running and drunk driving accounted for 13% and 0.17% of the total number of

1 prosecutions in Hong Kong, respectively (Hong Kong Police Force, 2018). Admittedly, these  
2 statistics from Hong Kong do not necessarily reflect the relative prevalence of speeding  
3 compared to other illegal driving behaviors, because the statistics may simply be an indication  
4 of the type and intensity of resources dedicated to enforcing speed limits relative to other illegal  
5 driving behaviors. Even so, the very fact that more investment is made in preventing speeding  
6 relative to other behaviors is in and of itself an acknowledgment that countermeasures aimed at  
7 speed reduction are considered one of the most cost-effective ways to enhance traffic safety.

8 Monetary fine, driving disqualification and imprisonment are the common penalties to  
9 address and reduce speeding offence occurrences (as well as other driving offences; see  
10 Hössinger and Berger, 2012; Li et al., 2014). In Hong Kong, the Driving-offence Points (DOPs)  
11 system was introduced in 1984. Over 50 items of traffic offences carry DOPs in addition to a  
12 monetary penalty. As would be logical, more DOPs and higher monetary fines are issued as the  
13 level of speeding increases. Thus, a severe speeding offence (excess of speed limit by more  
14 than 30 km/h but less than or equal to 45 km/h) incurs five DOPs and HK\$ 600 penalty  
15 (Transport Department, 2018). Under this DOP system, persons who have incurred 15 points  
16 or more within two years are disqualified from driving.

17 Some previous studies have revealed a significant negative correlation between the  
18 monetary fine level imposed and penalty points, and the occurrence of traffic offences  
19 (Hössinger and Berger, 2012; Li et al., 2014; Wong et al., 2008). For example, an increase of  
20 fine by 10 Euros is associated with the reduction in speeding frequency by 5% among Austrian  
21 drivers (Hössinger and Berger, 2012). However, there are studies suggesting that monetary fine  
22 levels and penalty points alone have only a relatively minor deterrent effect on the speeding  
23 offence (Elvik and Christensen, 2007; Fleiter et al., 2010; Langlais, 2008; Ritchey and  
24 Nicholson-Crotty, 2011; Sagberg and Ingebrigtsen, 2018). Specifically, these studies raise the  
25 issue of not only the level of the penalty on speeding deterrence, but the risk of being subjected  
26 to that penalty (Kergoat et al., 2017; Li et al., 2014; Tay, 2009). That is, the propensity for  
27 speeding depends on both the level of penalty as well as the prevalence of speed enforcement  
28 operations, with some studies finding that the latter is much more effective in curbing speeding

1 offences than the former (see, for example, Gargoum and El-Basyouny, 2018; Lawpoolsri et  
2 al., 2007; Ryeng, 2012; Truelove et al., 2017). In other words, fines and DOPs penalty,  
3 according to these earlier studies, do not function very well when the level of speed enforcement  
4 is not adequate (and thus the risk of being subjected to the penalties is low). This finding also  
5 has backing in criminal justice-based deterrence theory (Gibbs, 1985), which stems from the  
6 notion that individuals effectively undertake a cost-benefit analysis of pursuing a “crime”, and  
7 the effectiveness of a dissuasive mechanism originates from the costs being perceived as higher  
8 than the benefits. The cost-benefit analysis itself is conducted within a frame of three criteria:  
9 the certainty, celerity (swiftness or rapidity of imposition), and the severity of a sanction. While  
10 the relative contributions of these three criteria may vary based on the crime under question,  
11 lower “crime” activities (at least as viewed traditionally by society, such as illegal driving  
12 behaviors) are typically dominated by the “certainty of being apprehended” criterion in the cost-  
13 benefit evaluation of individuals (Høye, 2014; Watson et al., 2015). In the context of speeding,  
14 this “certainty” criterion is directly related to the level of enforcement of speed limits.

15         The automated speed enforcement camera (ASEC) system is generally considered as a  
16 promising and cost-effective enforcement technique that increases the certainty of being  
17 apprehended if speeding (Carnis and Blais, 2013; De Pauw et al., 2014a; Tay, 2009). Once the  
18 cameras are installed, such systems obviate the need for more costly human police patrols along  
19 roadways. Of course, some studies suggest that human police patrols are still effective, when  
20 combined with ASEC systems, because many drivers feel embarrassed when confronted by a  
21 fellow human (that is, a police person) who is perceived as passing a judgment on one’s societal  
22 conduct. In addition, the fear of a verbal reprimand by the police also can add to the  
23 embarrassment factor, elevating the cumulative cost of being detained by a human police to be  
24 even higher than the fear of risking one’s life or that of others through speeding (Kergoat et al.,  
25 2017; Silcock et al., 2000). But drivers also understand that human agents, even if equipped  
26 with hand-held radar/laser speed guns that provide accurate and reliable readings, can get  
27 fatigued over long periods of time in terms of holding and directing the speed guns in  
28 appropriate directions, and cannot have a consistent level of vigilance over extended periods of

1 time, leading to speeding event “misses” (see Kergoat et al., 2017). On the other hand, properly  
2 functioning ASEC systems are more reliable in detecting speeding violations over extended  
3 stretches of time. Even so, there is the issue of driver ability to dodge the dangers posed by  
4 spatially fixed ASEC systems (that is, an ASEC with overtly announced camera locations, as  
5 opposed to covert or unpublicized camera locations). In particular, according to the integrative  
6 social-cognitive protection-motivation theory (PMT) (see Rogers, 1983), the effectiveness of a  
7 “threat” (that is, a speed enforcement mechanism in the context of roadway speeding) is based  
8 both on threat appraisal (by way of the certainty, celerity, and severity, as proposed by  
9 deterrence theory) as well as coping appraisal (that is, the ability to cope with and dodge the  
10 danger). As an individual’s self-efficacy (the ability to perform an action needed to dodge a  
11 threat) and the response efficacy (the efficacy of the response to actually dodge the danger)  
12 increase, there will be less incentive to not commit an offence based on a positive coping  
13 appraisal. In the context of a spatially fixed ASEC systems, drivers typically perceive more  
14 controllability and a positive coping appraisal (that is, a higher belief that they have the  
15 capability to effectively dodge the speeding enforcement threat) by simply reducing speeds in  
16 the immediate vicinity of the camera locations. This so-called “kangaroo effect” (abrupt  
17 reductions close to camera locations and abrupt speed jumps upstream and downstream of  
18 locations relatively removed from the camera range) has been well-identified in earlier studies  
19 (De Pauw et al., 2014a, 2014b; Elvik, 1997; Marciano et al., 2015). On the other hand, previous  
20 studies (see, for example, Cameron et al., 2003; Dowling and Holloman, 2008) have shown the  
21 higher effectiveness of covert (or unmarked and unpublicized) ASEC systems relative to fixed  
22 ASEC systems because of a lower coping appraisal and higher uncontrollability to dodge a  
23 threat on the part of drivers. However, such covert ASEC systems are not legally allowed in  
24 Hong Kong and many other countries, both due to privacy regulations as well as the notion that  
25 ASEC systems should be fundamentally aimed at preventing speeding rather than apprehending  
26 offenders (Høye, 2014).  
27

## 1 **1.1.The Current Paper**

2 In the current paper, we examine the effectiveness of a fixed ASEC system in Hong Kong to  
3 deter speeding. While Hong Kong employs a combination of human agent-based mobile speed  
4 enforcement mechanisms as well as a fixed ASEC system, the focus will be on a fixed ASEC  
5 system in this paper. In Hong Kong, the shares of speed enforcement prosecutions based on  
6 human agent-based mobile speed enforcement and a fixed ASEC system are about the same  
7 (Hong Kong Police Force, 2018). From time to time, strong public sentiment has been  
8 expressed to expand the ASEC system as a means not only to enhance the deterrent effect, but  
9 also to reduce the costs associated with police human resources. In this context, it become  
10 particularly imperative to evaluate the impacts of alternative designs for such an expanded  
11 ASEC system. While there may be benefits to supplementing an expanded automation-based  
12 ASEC speed enforcement mechanism with a much smaller base (relative to today) of human-  
13 based enforcement mechanisms, examining the possible optimal combination of investments in  
14 such fused mechanisms is not considered here. In any case, society has consistently moved  
15 closer to automation in traffic operations, and it is not inconceivable at all that there will be a  
16 time in the near future when no human-based resources (police personnel) will be invested on  
17 the task of field monitoring of speed for enforcement purposes.

18 Four main attributes associated with threat and coping appraisals related to an ASEC  
19 system are evaluated in the paper: DOP penalty, fine levels, camera-to-housing ratio (explained  
20 in detail later), and the placement of the warning sign. Among these four attributes, the first  
21 three may be considered to be associated with threat appraisal, while the last may be considered  
22 to be associated with coping appraisal (for instance, if a warning sign is placed farther away  
23 from the camera location, it may provide individuals with more time to absorb the information  
24 and act to adjust their speed to comply with the speed limit before arriving within the range of  
25 the camera detection zone). A stated preference experiment is conducted by developing  
26 scenarios that combine the attribute levels of the four attributes just identified. The scenarios  
27 are presented to professional drivers, who are asked to respond by choosing a speed level at  
28 which they would travel on a 50 km/h road at each of three sections of a roadway (corresponding



1 to a standard section with no enforcement and no warning, a warning section that starts from  
2 23 meters ahead of the placement of a warning sign, and the camera housing section itself in  
3 which a camera detects speeding violations).

4 Driver perceptions regarding speeding consequences and driving history (current level  
5 of DOP points, whether received a speeding ticket in the past 12 months, and exposure to ASEC  
6 systems when driving), as well as driver demographic characteristics and employment  
7 characteristics, are also collected in the survey. These variables are considered as direct  
8 influencers of travel speed as well as moderating the impact of the four main attributes of the  
9 SP experiment (to capture inter-individual differences in perceptions of threat appraisal and  
10 coping appraisal of speed enforcement, as well as overall intentions to speed or not and general  
11 attitudes toward the risks travel speeding poses to society). In doing so, we attempt to recognize  
12 the direct and moderating effects of driver characteristics on travel speed levels, and contribute  
13 further to the literature on the effectiveness of speeding enforcement mechanisms. Many earlier  
14 studies of enforcement mechanisms, on the other hand, have considered drivers as a single  
15 monolithic group or considered variations across drivers in a relatively limited manner. In  
16 addition, unlike many other earlier studies on professional driver speed decisions, we consider  
17 unobserved individual-specific heterogeneity to accommodate unobserved individual factors  
18 that are likely to influence speed choices. Such heterogeneity is important to consider in travel  
19 choice and safety studies to ensure consistent estimation of model parameters (see, for example,  
20 Mannering et al., 2016).

21 The remainder of this paper is structured as follows. Section 2 discusses the  
22 methodology used for data collection as well as for our analysis. Section 3 provides a  
23 description of the sample used in the analysis. Section 4 presents the results. Section 5  
24 concludes the paper with a summary of the findings, policy implications, and future research  
25 directions.

26

## 2. METHODOLOGY

The data used in the current analysis is drawn from a face-to-face survey conducted during the period from October 2018 to February 2019 (months inclusive). Our emphasis on a face-to-face survey is to avoid respondent biases that may accrue from less expensive web-based and other social media-based surveys. The professional driver participants were approached either at on-road parking areas (e.g. public bus, taxi, and public light bus stations) or outside the licensing offices of the Hong Kong Transport Department. The inclusion criteria were (1) having valid licences of bus, minibuss, taxi or goods (cargo) vehicles, and (2) driving for income, either full-time or part-time. Prior to the survey, the ethical approval from the Human Subjects Ethics Subcommittee (HSESC) of the Hong Kong Polytechnic University was obtained.

The questionnaire had three sections: (1) SP questions regarding speed choices, (2) Driving history and safety perceptions, and (3) Demographics and employment characteristics of professional drivers. The SP part is discussed in the next section. The second section collected information on the involvement with traffic offences and crashes, attitudes towards different speed enforcement measures, and actual experience with speed enforcement. The third section collected information on driver demographics (gender, age, education, marital status, and income) and employment characteristics (salary system, driving hours per day etc.)

### 2.1 SP design

In this study, drivers' perceptions and attitudes towards the deterrent effect of enforcement and penalty against speeding was gauged using their stated speed choices in an SP survey design. SP surveys have been widely applied to evaluate the effects of enforcement strategies and speeding penalties on the propensity for traffic offences by measuring the driver's response under hypothetically constructed conditions (Hössinger and Berger 2012; Li et al., 2016; Ryeng, 2012; Wong et al., 2008). The SP questions in the current paper are based on the scenario of driving on an urban road with a speed limit of 50km/h. For each question, three speed choices are presented to drivers for each of three location sections. The location sections are defined as follows: (1) a standard section, defined as one with neither ASEC-based speed enforcement and

1 nor warning signs of such enforcement, (2) a warning section, defined as the road section  
2 indicating the presence of speed camera housing unit ahead (this section starts 23 meters ahead  
3 of the warning sign and ends at the location of warning sign; the design of the section length is  
4 based on the vision standard for the driver licensing requirement in Hong Kong), and (3) a  
5 camera section, defined as being within the range of speed violation detection by the camera  
6 (this section starts 23 meters ahead of a camera housing unit and ends at the location of the  
7 housing; see **Figure 1**). The three speed choices (one to be selected) are: (1) comply with the  
8 prescribed speed limit; (2) exceed the prescribed speed limit by 15 km/h or less (traveling at  
9 51-65 kms./hour, corresponding to speeding range 1); and (3) exceed the prescribed speed limit  
10 by more than 15 km/h but less than or equal to 30 km/h (traveling at 66-80 kms./hour,  
11 corresponding to speeding range 2). Thus, for each SP question presented, the respondent makes  
12 a speed choice at each of the three location sections, providing three choices.

13 In each of the SP questions presented to respondents, four attributes are used to  
14 characterize the choice context: (1) Driving Offence Points (DOP) for different ranges of  
15 speeding infractions, (2) Monetary fines for different ranges of speeding infractions, (3)  
16 Camera-to-housing ratio, and (4) placement of the warning sign that determines the distance of  
17 the warning section. A screenshot of the content and format of a sample SP question is provided  
18 in **Figure 1**.

19 The levels of the first attribute - DOP – were set by pivoting off the current DOP for  
20 each of the two speed infraction ranges (of course, there are no DOPs for being within the speed  
21 limit). The current DOPs are zero for speeding range 1 and three for speeding range 2. We used  
22 these base DOPs and also introduced a higher DOP level of two for speeding range 1 and a  
23 DOP level of five for speeding range 2. Thus, for each speeding range, there are two possible  
24 DOP levels, and across the two speeding ranges, there are a total of four possible DOP levels.

25 The levels of the second attribute – monetary fine – were also set based on the current  
26 fine levels of 320 HKD (about US \$40) for speeding range 1 and 450 HKD (about US \$57) for  
27 speeding range 2. Again, we used these base fine levels, and also introduced increased levels

1 of 420 HKD (about US \$54) for speeding range 1 and 550 HKD (about US \$ 70) for speeding  
2 range 2. Across the two speeding ranges, there are a total of four possible fine levels.

3 In Hong Kong, not all the camera housings necessarily contain a speed camera, to save  
4 on costs (both installation and operating costs). Thus, while Hong Kong laws require that  
5 citizens be informed of any camera locations, it is not required that all the announced camera  
6 locations necessarily have an actual functional camera. Dummy camera housing boxes are  
7 allowed to be installed. However, the ratio of actual speed cameras to camera housings must be  
8 publicized. The current ratio of speed camera-to-housing is 1:6. In particular, there are 20 speed  
9 cameras and 120 housings across the entire territory of Hong Kong (Audit Commission of  
10 HKSAR, 2013). Four levels of the third attribute -- camera-to-housing ratio -- are set out by  
11 either increasing the number of housings or increasing the number of cameras: 20:240, 20:120  
12 (status quo), 40:120, and 60:120. An analysis of how Hong Kong professional drivers respond  
13 to different camera-to-housing levels can inform speed enforcement strategies considering the  
14 economic constraints of the transport authority.

15 Finally, four levels of the fourth attribute associated with the placement of the warning  
16 sign are considered: 50 meters, 100 meters, 150 meters, and 200 meters upstream of the speed  
17 camera housing (see **Figure 1**). Exploring the effect of the placement of the warning sign helps  
18 better understand alternative coping mechanisms, and can provide insights regarding the  
19 optimal placement of the warning sign that can minimize the “Kangaroo effect” associated with  
20 speed cameras.

21

22 <Figure 1>

23

24 All the levels for each of the attributes were tested extensively for reasonability in pilot  
25 surveys, and several changes were made before arriving at the final levels. In all, the SP  
26 experiments have four factors, each with four levels. If the full factorial design were considered,  
27 there would be 256 ( $4 \times 4 \times 4 \times 4$ ) combinations of factor attributes in total for the SP  
28 question. It is however not efficient and feasible to gauge the drivers’ perceptions and attitudes

1 if all the 256 combinations of scenarios are used. Therefore, an orthogonal fractional factorial  
2 design (Bhat and Sardesai, 2006; Hössinger and Berger, 2012; Lavieri and Bhat, 2019; Li et al.,  
3 2014) was adopted to reduce the number of combinations from 256 to 16. Further, our design  
4 enabled us to estimate models that are more general than the multinomial logit model by  
5 maintaining factor orthogonality within and between alternatives. Our design allowed for the  
6 estimation of main effects of attributes, as well as two-way interaction effects between attributes  
7 and respondent characteristics. Next, we developed a block design of four sets of four SP  
8 scenarios, because it would be too much burden to ask each respondent to answer 16 SP  
9 questions. Each participant was then presented with one of the four blocks of four SP scenarios  
10 in the survey. The entire survey instrument is available at <http://www.baige.me/v?i=RxE>.

11

## 12 **2.2. Econometric modeling framework**

13 In this paper, we formulate a panel mixed multinomial logit (or MMNL) model for the speed  
14 choice of professional drivers. The panel MMNL model formulation accommodates  
15 heterogeneity across individuals due to both observed and unobserved individual attributes,  
16 while also recognizing correlations among the different observations of a same individual. In  
17 the following discussion of the model structure, we will use the index  $q$  ( $q = 1, 2, \dots, Q$ ) for the  
18 decision-makers,  $i$  for the speed alternative ( $i = 1, 2, \dots, I$ ) and  $k$  for the choice occasion, *i.e.*  
19 SP choice occasions for a particular decision-maker, ( $k = 1, 2, \dots, K$ ). In the current study  $I = 3$   
20 (as indicated earlier, the choice alternatives are speed compliance, or speeding range 1, or  
21 speeding range 2) and  $K = 4 \times 3 = 12$  for all  $q$ . Within each of the four SP attribute scenarios  
22 presented, the respondents were asked to state their speed range choice in three different  
23 sections – standard, warning, and camera housing sections.

24 In the usual tradition of utility maximizing models of choice, we write the utility or  
25 valuation  $U_{qik}$  that an individual  $q$  associates with the alternative  $i$  (speed range) on choice  
26 occasion  $k$  as follows:

$$27 \quad U_{qik} = (\beta' + v'_q) x_{qik} + \varepsilon_{qik}, \quad (1)$$

1 where  $x_{qik}$  is a  $(M \times 1)$ -column vector affecting the valuation of individual  $q$  for alternative  $i$   
2 at the  $k^{th}$  choice occasion, and that includes the following: (1) choice-occasion specific  
3 attributes (that is, the four attributes varied in the SP experiments), (2) alternative-specific  
4 constants for speeding ranges 1 and 2 (with no speeding being the base category), (3) individual-  
5 specific attributes (driving history and perception, driver demographics and employment  
6 characteristics), and (4) interactions within each of the choice-specific and individual-specific  
7 variables, as well as across the two sets of variables.  $\beta$  is a corresponding  $(M \times 1)$ -column  
8 vector of the mean effects of the coefficients of  $x_{qik}$  on speeding range valuations, and  $v_q$  is  
9 another  $(M \times 1)$ -column vector with its  $m^{th}$  element representing unobserved factors specific to  
10 individual  $q$  that moderate the influence of the corresponding  $m^{th}$  element of the vector  $x_{qik}$ .  
11 A natural assumption is to consider the elements of the  $v_q$  vector to be independent  
12 realizations from a normal population distribution;  $v_{qm} \sim N(0, \sigma_m^2)$ .  $\varepsilon_{qik}$  represents a choice-  
13 occasion specific idiosyncratic random error term assumed to be identically and independently  
14 standard Gumbel distributed.  $\varepsilon_{qik}$  is assumed to be independent of  $x_{qik}$ .

15 For a given value of the vector  $v_q$ , the probability that individual  $q$  will choose speed  
16 range  $i$  at the  $k^{th}$  choice occasion can be written in the usual multinomial logit form (McFadden,  
17 1978):

$$18 \quad P_{qik} | v_q = \frac{e^{\beta'x_{qik} + v_q'x_{qik}}}{\sum_{j=1}^I e^{\beta'x_{qjk} + v_q'x_{qjk}}} \quad (2)$$

19 The unconditional probability can then be computed as:

$$20 \quad P_{qik} = \int_{v_q} (P_{qik} | v_q) dF(v_q | \sigma) \quad (3)$$

21 where  $F$  is the multivariate cumulative normal distribution and  $\sigma$  is a vector that stacks up the  
22  $\sigma_m$  elements across all  $m$ . The reader will note that the dimensionality in the integration above  
23 is dependent on the number of elements in the  $v_q$  vector.

1 The parameters to be estimated in the model of Equation (3) are the  $\beta$  and  $\sigma$  vectors.  
 2 To develop the likelihood function for parameter estimation, we need the probability of each  
 3 individual's sequence of observed SP choices. Conditional on  $v_q$ , the likelihood function for  
 4 individual  $q$ 's observed sequence of choices is:

$$5 \quad L_q(\beta | v_q) = \prod_{k=1}^K \left[ \prod_{i=1}^I \{P_{qik} | v_q\}^{\delta_{qik}} \right], \quad (4)$$

6 where  $\delta_{qik}$  is a dummy variable taking the value of 1 if the  $q^{\text{th}}$  individual chooses the  $i^{\text{th}}$   
 7 speed range in the  $k^{\text{th}}$  occasion, and 0 otherwise. The unconditional likelihood function for  
 8 individual  $q$ 's observed set of choices is:

$$9 \quad L_q(\beta, \sigma) = \int_{v_q} L_q(\beta | v_q) dF(v_q | \sigma) \quad (5)$$

10 The log-likelihood function is  $L(\beta, \sigma) = \sum_q \ln L_q(\beta, \sigma)$ . We apply quasi-Monte Carlo  
 11 simulation techniques to approximate the integrals in the likelihood function and maximize the  
 12 logarithm of the resulting simulated likelihood function across all individuals with respect to  
 13 the parameters  $\beta$  and  $\sigma$ . Under rather weak regularity conditions, the maximum (log) simulated  
 14 likelihood (MSL) estimator is consistent, asymptotically efficient, and asymptotically normal  
 15 (see Hajivassiliou and Ruud, 1994; Lee and Carter, 1992; McFadden and Train, 2000).

16 In the current paper, we use Halton sequences to draw realizations for  $v_q$  from its  
 17 assumed normal distribution. Details of the Halton sequence and the procedure to generate this  
 18 sequence are available in Bhat (2001, 2003).

19

### 20 **3. DATA AND SAMPLE USED**

21 A total of 401 professional drivers completed the questionnaire survey. Therefore, the dataset  
 22 has a total of  $401 \times 12 = 4,812$  SP choice occasions, with 1604 choice occasions at each of the  
 23 three location sections (standard, warning, and camera). The distribution of the dependent  
 24 variable was as follows within the 1604 choice occasions, as also shown in **Table 1**: (1)  
 25 Standard section – Not speeding (14.1%), Speeding Range 1 (71.2%), and Speeding Range 2

1 (14.7%), (2) Warning section – Not speeding (57.2%), Speeding Range 1 (40.0%), and  
2 Speeding Range 2 (2.8%), (3) Camera housing section – Not speeding (99.8%), Speeding  
3 Range 1 (0.2%), and Speeding Range 2 (0%). As can be observed from these descriptive  
4 statistics, drivers combine their threat and coping appraisals due to which a large proportion of  
5 them are generally willing to speed at the standard section (at least at speed range 1), but are  
6 more likely to adhere to the speed limit at the camera housing section. Indeed, there is literally  
7 no variation in adherence at the camera housing section regardless of the levels of DOP,  
8 monetary fine, camera-to-housing ratio, warning sign placement, as well as driver  
9 characteristics. Thus, we drop the 1604 choice occasion observations corresponding to the  
10 camera housing section in our analysis, because they do not contribute to understanding the  
11 effects of independent variables on speeding ranges. The final sample for analysis includes the  
12 3208 choice occasions at the standard and warning sections.

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<Table1>

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**Table 2** shows cross-tabulations of the four SP attributes with speed choice percentages at each of the standard and warning sections. As expected, increasing the DOP penalty by two points decreased the percentage of drivers choosing for speeding range 1 and speeding range 2 in the standard section. Further, increasing the DOP penalty by two points for both speeding levels led to a greater percentage of drivers complying with speed limit. The descriptive statistics do not show a clear trend of the speed choices with respect to increasing monetary fines. Interestingly, in the standard section, it seems that a greater proportion of drivers choose to speed when the fine is increased. More discussion on this will follow in the model results section. In the context of camera-to-housing ratio values, an increase in the ratio from status quo (20:120) to 40:120 shows a greater decrease in the percentage of drivers choosing speed ranges 1 or 2 than that from increasing the ratio further to 60:120. It appears that the bang per buck is greater for increasing the ratio from 20:120 to 40:120 than that to 60:120. As for the placement of warning sign, there is a monotonous trend of increasing percentage of speed



1 compliance choice with decreasing distance between the warning sign and the camera housing  
2 location.

3 Of course, the discussion above does not consider differential effects of the SP attributes  
4 based on observed and unobserved driver characteristics, which is the focus of the multivariate  
5 model results in Section 4.

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<Table 2>

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### 9 **3.2. Driver demographics and employment characteristics**

10 **Table 3** presents the demographic and other characteristics of the 401 participants, beginning  
11 with the demographic characteristics in the first set of rows. All participants of this study are  
12 male. This is consistent with the distribution of employed persons by occupation and gender in  
13 the population census dataset, which indicates that 97% of workers in the machine operation  
14 sector are male (Census and Statistic Department, 2018a). Although the information on the  
15 official registry of professional drivers in Hong Kong is not available, male drivers are believed  
16 to dominate the transport sector. The age distribution of our sample is close to that of the driving  
17 licensing record of general drivers in Hong Kong (Transport Department, 2017). In terms of  
18 educational background, 79% of the drivers in our sample have attained at least secondary  
19 education (the closest possible comparison at the Hong Kong-wide level is that 89% of male  
20 workers in Hong Kong have attained secondary education (Census and Statistic Department,  
21 2018b). In our sample, 73% of the drivers were married (the closest possible comparison is the  
22 most updated marital status statistics in Hong Kong, which indicates that 62% of the males are  
23 married (Census and Statistic Department, 2018c). Interestingly, almost all (395 of the 401)  
24 drivers provided their monthly income values. For the remaining six drivers who did not  
25 provide this information, we imputed the income values based on the procedure discussed in  
26 Bhat (1997). A little over 31% of the drivers have a monthly income below HK\$ 15,000 and a  
27 little over 21% of the sample earn over HK\$ 20,000.

1 Drivers' employment characteristics are presented in the next set of rows in the table.  
2 The salary system of professional drivers is stratified into three categories: (i) trip-based (34%  
3 of the sample), (ii) monthly-based (31%), and (iii) others (hourly or shift based, 35%). The trip-  
4 based drivers are self-employed, and their incomes vary greatly with the number and distance  
5 of trips made (e.g. taxi, red minibus and light van drivers). The drivers who are paid on a  
6 monthly basis are usually regular employees of a large corporation or transport operator, such  
7 as the franchised bus companies and logistic firms. The hourly or shift based drivers are usually  
8 (full-time or part-time) employees of small transport operators, such as the green minibus. Their  
9 salaries vary greatly with the daily working time. As for the daily driving hours, 8% of our  
10 sample drive for less than or equal to 7 hours per day while 42% of them drive for more than 9  
11 hours daily. The corresponding statistic from official reports is not accessible. The closest  
12 possible comparison is that 51% of bus drivers in Hong Kong drive for more than 9 hours daily  
13 (Legislative Council of HKSAR, 2018). In terms of weekly working hours, 46% of drivers in  
14 our sample work for 48 hours or less per week, which is comparable to the 50% of employees  
15 in the transport sector who work for less than or equal to 48 hours a week. However, only 9%  
16 of our sample work for more than or equal to 63 hours per week, while the corresponding  
17 percentage in the transport sector is close to 25% (Census and Statistic Department, 2018b).  
18 The commercial vehicles driven by our sample are categorized into four types – bus, green  
19 minibus, taxi and red minibus, and goods vehicles (accounting for 17%, 14%, 39%, and 30%  
20 of the sample respectively). The official distribution for the vehicle types of the commercial  
21 vehicle fleet in Hong Kong is not accessible.

22 Overall, the characteristics of drivers in the sample are reasonably close to general  
23 expectations for Hong Kong professional drivers, at least based on the latest statistics gleaned  
24 from the Census. Of course, one cannot be conclusive of the true representativeness of our  
25 sample because there is no official registry of professional drivers in Hong Kong, and the closest  
26 comparison we are able to make is with the population census demographics for people  
27 employed in the transport sector.

28

### 3.3. Driver history and safety perceptions

The last set of rows in **Table 3** report the descriptive statistics for driving history and safety perceptions of the 401 participants, which might influence how they would respond to the SP choice questions. As can be observed from these rows, 25% of the interviewed professional drivers have received at least one speeding ticket in the recent past. 70% of the drivers perceived speeding as a cause of injury while only 1.5% perceived a small effect of speeding on traffic injuries. As for the perception on effectiveness of cameras, 67% of drivers believed that speeding cameras are effective in catching offenders, while a smaller percentage (6%) perceived low effectiveness of this enforcement technique. The frequency of drivers sighting camera housings was also collected in terms of the number of times a driver would sight camera housings in 10 trips. It appears that a majority (62%) of the drivers do usually visually locate camera housings at a frequency of at least 7 times in 10 trips.

All the above driver history and perception variables are likely to influence drivers' responses to the SP choice questions. Also, while we make no claim of our sample being representative of the population of professional drivers, there is no reason to believe that the individual-level relationship we develop between speed range choices and SP attributes/driver characteristics would not be applicable for the general population of professional drivers.

## 4. RESULTS AND DISCUSSION

**Table 4** presents the results of a panel mixed multinomial logit model estimated on the aforementioned 3,208 observations – 1604 for the standard section and 1604 for the warning section<sup>1</sup> – with normal distributed random coefficients<sup>2</sup>. The dependent variable is speed choice (i.e.

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<sup>1</sup> Recall from the descriptive analysis of the SP choice data for the camera housing section that only a single alternative (speed compliance) was chosen 99.8% of the times. So, these data were not included in the model as the speed choice is deterministic in the camera housing section. This observation is consistent with the findings of previous studies that drivers would slow down when they notice or are warned of cameras (De Pauw et al., 2014a; De Pauw et al., 2014b; Elvik, 1997; Marciano and Norman, 2015).

<sup>2</sup> We also explored alternative distributional assumptions such as log-normal for the random coefficients, but the model with normal distribution provided the best fit. Besides, other distributions did not offer substantive interpretations that were very different from the model with normal distributions.

1 speed compliance, speeding range 1, or speeding range 2; with speed compliance considered as  
2 the base alternative). For each independent variable, a common coefficient was estimated for  
3 both standard and warning sections as well as a difference coefficient was introduced to account  
4 for the differential effect of that variable on the warning section compared to the standard  
5 section. In Table 4, the parameter estimates reported under the “Standard section” column are  
6 that of the common coefficients, which may also be interpreted as coefficients for the standard  
7 section. The parameter estimates under the “Difference between Warning and Standard section”  
8 column are the difference coefficients. For a given variable, a sum of its common coefficient  
9 and the difference coefficient would give its coefficient for the warning section. The parameter  
10 estimates are interpreted and discussed next in **Sections 4.1-4.4**. The coefficients on the  
11 constants indicate a general aversion to speeding, especially at level 2, at both the standard and  
12 warning sections. This aversion is typically higher in the warning section than in the standard  
13 section, though there is unobserved heterogeneity (captured by the significant standard  
14 deviation estimates on the constants) in these general trends (the panel nature of the data allows  
15 us to estimate the standard deviations on the constants in the table).

16 An important note is in order here. All results in this paper pertain to the influence of  
17 variables on the reported speed choices in our stated experiments, not actual speed choices in  
18 the real world. But, for presentation ease and tightness, we do not belabor over this distinction  
19 in the rest of this paper and use the general word “speeding”. However, all our statements should  
20 be viewed in the context of stated speed choices, not actual speed choices.

21

22

< Table 4 >

23

#### 24 **4.1 Effects of penalty level and enforcement strategy**

25 Among the SP attributes for penalty and enforcement, the DOP variable shows a statistically  
26 significant deterrence on speeding in both standard and warning sections, with higher  
27 deterrence in the warning section than in the standard section. Professional drivers are indeed,  
28 generically speaking, sensitive to the increase in DOPs since incurring DOPs may lead to

1 disqualification of driving license, which is the source of their livelihood (Wong et al., 2008).  
2 However, there is significant heterogeneity in the influence of the DOP variable both due to  
3 observed and unobserved factors. Specifically, drivers who were recently issued a ticket are  
4 more likely than their peers to be deterred by DOPs when traveling in the warning section.  
5 Considerable unobserved heterogeneity also exists in the influence of DOPs on drivers'  
6 speeding choices in both standard and warning sections. Interestingly, the standard deviation of  
7 the DOP coefficient in the warning section is higher than in the standard section, implying that  
8 the deterrent effect of an increased DOP penalty tends to be more diverse in the warning section  
9 despite its greater deterrent effect on average. This finding could be attributed to the  
10 heterogeneity in driver's threat and coping appraisals of the warning messages (Kergoat et al.,  
11 2017), as well as the effects of drivers' characteristics on the comprehension of traffic signs  
12 (Ng and Chan, 2008). For example, different drivers may perceive the self-efficacy of avoiding  
13 the speeding penalty differently when forewarned about camera enforcement. Thus, some  
14 drivers may actually initially increase their speeds as soon as they encounter the warning section  
15 (to compensate for the fact that they have to reduce speeds at the downstream camera section)  
16 because they feel confident in their ability (self-efficacy) to estimate where the camera section  
17 will begin and in their ability to decelerate at the right time to avoid speeding penalties in the  
18 camera section. Other drivers may immediately reduce their speed upon encountering the  
19 warning section because they feel less confident in their ability to take evasive speed reduction  
20 actions later downstream to avoid penalties in the camera section. Such variations in self-  
21 efficacy are likely to get magnified as the DOP penalty increases in the camera section, leading  
22 to the higher speed variance in the warning section as the DOP penalty increases.

23 Unlike the deterrent effect of DOPs, the monetary fines variable turned out to have a  
24 marginally positive coefficient in the standard section suggesting an increase in the propensity  
25 for speeding with an increase in fines. While this may be a coping mechanism to "make up"  
26 time in the standard section in anticipation of lost time due to adherence to speed limits in the  
27 warning section, we noted that this effect had a strong interaction with the length of the warning  
28 section. Thus, we chose to drop this variable and include the length of the warning section as

1 the primary determinant variable in our model (more on this warning section length effect later).  
2 In the warning section itself, monetary fines are associated with a negative coefficient for a  
3 majority of the sample (obtained from the mean and standard deviation of the corresponding  
4 random coefficient), suggesting a deterrent effect of monetary fine when it is combined with a  
5 warning of speed enforcement ahead for a majority of the drivers. Furthermore, there is  
6 heterogeneity in response to fines in the warning section based on driver characteristics.  
7 Specifically, in warning sections, monetary fines have a larger deterrent effect (in the context  
8 of speeding) for drivers who are paid on a per-trip basis and those with a recent speeding ticket  
9 relative to other drivers. These results are again an illustration of the interplay between drivers'  
10 threat and coping appraisal mechanisms, where drivers respond to the threat of a monetary fine  
11 when they are made aware of the cameras that will increase the likelihood of them being fined.  
12 And such interplay appears to vary across drivers based on both observed and unobserved  
13 factors.

14 In the context of camera-based enforcement strategy, reducing the camera-to-housing  
15 ratio from the status quo (i.e., from 20:120 to 20:240 camera-to-housing ratio) did not show a  
16 statistically significant effect on the drivers' stated speeding choices. However, drivers were  
17 less likely to opt for severe speeding (range 2) in both the standard and warning sections when  
18 the camera to housing ratio was increased from the status quo. This is presumably because an  
19 increase in the number of camera installations would result in an increased "threat" of being  
20 apprehended for speed limit violations. Interestingly, the standard deviation associated with the  
21 coefficient of a minor increase in camera-to-housing variable suggests that a small fraction (9%)  
22 of the drivers tend to choose speeding with an increase in camera-to-housing. This result may  
23 be attributed to the risk-taking behaviors of such individuals as well as heterogeneity in  
24 perceiving a threat of apprehension due to a minor increase in the number of cameras. However,  
25 with a major increase in the camera-to-housing ratio, this risk-taking behavior reduces, perhaps  
26 due to a greater perception of the threat of apprehension.

27 The placement of the warning sign – that is, the distance of the warning sign from the  
28 camera housing location – exhibits an influence on speeding in the warning section. Specifically,

1 reducing the distance between the warning sign and the housing unit leads to lower speeding  
2 tendencies (for both speeding ranges). This is intuitive as individuals may want to start slowing  
3 down (or at least not speed) to avoid sudden decelerations just before arriving at the camera  
4 housing. In fact, the presence of a warning sign (upstream of a fixed speed camera) has been  
5 found to be associated with reductions in mean driving speed and proportion of more severe  
6 speeding (Retting et al., 2008; Høye, 2014). Kergoat et al. (2017) postulated that the distance  
7 between warning sign and speed camera should be increased to weaken the “Kangaroo effect”.  
8 However, the parameter estimates for speeding range 2 suggest a heightened increase in the  
9 propensity to choose that speeding range when the warning sign is installed 150m or 200m  
10 upstream of a camera housing. That is, our results suggest that the deterrent effect of a warning  
11 sign could in fact be diminished when the distance between the warning sign and the housing  
12 unit increases excessively. That is, as drivers learn that the warning signs are placed farther  
13 away from the housing, they speed up because they know they have a larger cushion to  
14 decelerate and they also want to make up some time in anticipation of slowing down closer to  
15 the actual camera housing location. Basically, as warning signs are placed farther away from  
16 the camera housing, professional drivers start to view the early part of the warning section as a  
17 “standard” section. This indicates a need for optimal placement of warning sign that can  
18 tradeoff between the “Kangaroo effect” and effectiveness of the warning sign in deterring  
19 speeding behavior.

20

#### 21 **4.2 Effects of demographic characteristics of professional drivers**

22 Driver age does not have a strong association with speeding behavior in the standard section.  
23 This could be because all professional drivers, regardless of age, tend to be more aggressive  
24 when there is no speed enforcement and no warning (Öz et al., 2010a, Wong et al., 2008). In  
25 contrast, in the warning section, older drivers are less likely to speed up to range 1 and younger  
26 drivers are more likely to speed up to range 2. These results suggest that the likelihood of  
27 speeding offences decreases with driver age, perhaps because older drivers tend to be more  
28 cautious (Ram and Chand, 2016; Rosenbloom and Shahar, 2007) but younger people are more

1 likely to be sensation- and thrill-seeking (Delhomme et al., 2012; Fernandes et al., 2010; Tseng,  
2 2013). In the context of education background, individuals with up to primary level education  
3 are more likely to speed up to range 1 in both standard and warning sections. Previous studies  
4 also suggest that professional drivers with higher education attainment are less likely to commit  
5 traffic offences (Mallia et al., 2015; Mehdizadeh et al., 2018; Tronsmoen, 2010). Married  
6 drivers (relative to those who are single) are less likely to speed in both the standard and warning  
7 sections (see Mehdizadeh et al., 2018 and Wong et al., 2008 for similar findings), perhaps  
8 because married individuals, due to their familial responsibilities, tend to be more responsible  
9 in driving than single individuals.

10 Individuals with high monthly income (>20K), *ceteris paribus*, are more likely than  
11 others to choose to violate speed limits in warning sections. This is perhaps because they can  
12 afford to pay the fines. Also, recall from earlier discussion that the maximum fine of HK\$550  
13 for speeding range 2 is a rather small percentage of HK\$ 20K per month. In contrast, the  
14 maximum monetary fine for speeding can reach 50% of average monthly incomes of taxi  
15 drivers in the United States (United States Department of labor, 2018) and 35% in the United  
16 Kingdom (Sentencing Council, 2017), respectively. In road safety research, deterrence theory  
17 is widely used to investigate driver's perception of the sanctions (in terms of severity, certainty  
18 and celerity) for traffic offences (Kergoat et al., 2017; Li et al., 2014; Tay, 2005a, 2005b, 2005c,  
19 2009). It is based on the idea that people avoid committing a crime due to the threat and fear of  
20 being legally punished, which also involves an evaluation of the costs and benefits of the crime  
21 (Gibbs, 1985). In this sense, the ratio of the cost (monetary fine) to the benefits (possible income)  
22 of speeding offence is indeed quite low in Hong Kong.

23

#### 24 **4.3 Effects of operational characteristics of professional drivers**

25 As discussed earlier, drivers who earn on a per-trip basis (i.e., trip-based salary) are  
26 more likely to be deterred by monetary fines in the context of speeding in warning sections.  
27 Regardless of the level of monetary fines, the coefficients of the trip-based salary dummy  
28 variable suggest that such drivers are more likely than others to commit speeding offences in



1 both the standard and warning sections. Since their earnings depend on the number and distance  
2 of the trips made, trip-based salaried drivers have a higher incentive to speed up to arrive at the  
3 destination quickly. In Hong Kong, trip-based drivers (these are typically drivers of taxis, light  
4 vans, red minibuses etc.) are generally self-employed and are not well-regulated (Meng et al.,  
5 2017; Wong et al., 2008). In contrast, the monthly-salaried drivers are typically regular  
6 employees of large transport operators and logistics firms with good safety culture and driver  
7 management systems (Newnam et al., 2004; Öz et al., 2010b, 2013) including GPS-based  
8 tracking of vehicle speeds. These factors also have a bearing on the salary system-based  
9 differences in speeding choices.

10 Individuals who drive for more than nine hours per day have a lower inclination than  
11 others to violate speed limits. This could be attributed to the possible driver fatigue caused by  
12 a prolonged driving time. Drivers may adopt a compensation strategy by reducing their speed  
13 to lower their risk of fatigue-related crashes (Williamson et al., 2002). In contrast, individuals  
14 who drive for less than eight hours per day are associated with a greater likelihood (than others)  
15 of violating speed limits in the warning section. This finding will need further investigation to  
16 assess its robustness.

17 In the context of vehicle type, drivers of all types of vehicles other than buses have a  
18 higher tendency of speeding up in both standard and warning sections, albeit they are relatively  
19 less likely to speed up in warning sections than in standard sections. Indeed, minibus drivers  
20 and taxi drivers in Hong Kong have been recognized as problematic and risk-taking groups  
21 (Meng et al., 2017; Wong et al., 2008). On the other hand, goods vehicle drivers are paid to  
22 drive for the transport of goods while bus drivers are to drive for the transport of passengers. A  
23 greater sense of social responsibility on bus drivers might make them less aggressive (at least  
24 in a stated preference setting) than the drivers of other types of vehicles (Paleti et al., 2010).

25

#### 26 **4.4 Driver history and safety perceptions**

27 Driving history and safety perceptions have a substantial influence on the participants' stated  
28 speed choices. For instance, drivers who recently received a traffic ticket are associated with a

1 greater likelihood of speeding in both standard and warning sections (albeit the tendency for  
2 speeding range 2 is lower in warning sections than that in standard sections). Further, as  
3 discussed earlier in the context of interaction between this variable with the SP attributes,  
4 increasing fines or DOP appears to reduce the speeding tendency of these drivers in warning  
5 sections. However, even at the highest level of fine and DOP values presented in the SP  
6 experiment, these drivers show a higher tendency (than others without recent tickets) to violate  
7 speed limits. These results suggest that risk-taking behavior and aggressive driving styles of  
8 these drivers overshadow any deterrent effect from receiving a speeding ticket (Sagberg and  
9 Ingebrigtsen, 2018). It appears that simply imposing fines or DOPs might not suffice to reduce  
10 the aggressive driving traits of such drivers. This result suggests a need for additional  
11 investigations to assess the effectiveness of combining DOPs and fines with driver training  
12 programs aimed to reduce risk-taking and aggressive driving traits.

13 Individuals who perceive that speeding does not cause injuries have a higher tendency  
14 of opting for speed range 2 in both standard and warning sections. This aligns with the previous  
15 findings that drivers with lower risk perception tend to be associated with aggressive driving  
16 behaviors (Cestac et al., 2011; Rosenbloom, 2003). In addition, drivers who perceive that  
17 cameras are highly effective in catching offenders are associated with a lower tendency of  
18 speeding in speed range 2 in the warning section, while their disposition for speed range 1 is  
19 not statistically different from compliance. Individuals who sight speed enforcement camera  
20 housings more frequently (in at least 7 out of 10 trips) have a lower tendency of speeding in  
21 range 2 (in both standard and warning sections). This could be attributed to the perceived higher  
22 level of enforcement, which may contribute to the decrease in driver's speeding intention  
23 (Blincoe et al., 2006; Hössinger and Berger, 2012) at least in the high-speed range.

24

#### 25 **4.5 Marginal effects due to changes in SP attributes**

26 The model was applied to estimate marginal effects on market shares (of speed choice) in  
27 response to changes in the SP attributes. As shown in **Table 5**, the marginal effects were  
28 computed for both the standard and warning sections. According to these results, an increase in

1 the DOP by 1 point resulted in greater than 4% increase in compliance in both the sections. In  
2 the context of monetary fines, a 10% increase resulted in only a 1.73% increase in compliance.  
3 Such a low marginal effect is consistent with the discussion of model estimation results that  
4 monetary fines alone might not significantly deter professional drivers from speed violations.  
5 Note that the percentage reduction in the share of drivers who would opt for speeding range 2  
6 is high (13.02%). However, such a high percentage reduction is an artifact of a rather small  
7 proportion of drivers choosing this option in the base case.

8         Increasing camera-to-housing ratio from the status quo (20:120) to 40:120 shows a  
9 considerable (at least 29%) decrease in the share of drivers choosing speed range 2. However,  
10 the decrease is not substantial when the ratio is increased to 60:120. This suggests that the  
11 marginal benefit from increasing the camera-to-housing ratio beyond 40:120 might not be  
12 substantial. Furthermore, since the proportion of drivers choosing speed range 2 is itself very  
13 small (1%), even a 32% decrease in this share due to increasing the ratio to 60:120 does not  
14 appear to hold practical effectiveness.

15         In the context of the placement of warning sign, increase in the distance between the  
16 warning sign from 100m is associated with a substantial increase in the proportion of drivers  
17 choosing to speed in the warning section. Even if we neglect these increases for speed range 2  
18 (due to a rather small base market share for this alternative), the increases in the proportion of  
19 people choosing speed range 1 is substantial when the distance is increased. These results  
20 suggest the need for an optimal placement of warning sign that can tradeoff between the  
21 “Kangaroo effect” and effectiveness of the warning sign in deterring speeding behavior.

22

23

<Table5>

24

## 25 **5. CONCLUSION**

26 This study applied a stated preference survey and a panel mixed logit model to evaluate the  
27 deterrent effects of penalty and enforcement strategies – DOP penalty, monetary fines, and  
28 speed enforcement cameras along with a warning of such enforcement – on the propensity and

1 severity of speeding among professional drivers. In doing so, the study controlled for the effects  
2 of driver demographics and operational characteristics as well as driver history and safety  
3 perceptions. As importantly, observed and unobserved heterogeneity were incorporated in  
4 drivers' responses to penalty and enforcement strategies. A panel mixed logit model is estimated  
5 and applied to understand the effectiveness of penalties and enforcement strategies on driver's  
6 speeding behaviors.

7         The results indicate that an increase in DOP penalty is more effective as a deterrent  
8 against speeding than increasing monetary fines. This could be attributed to the higher  
9 sensitivity of professional drivers to the increase in DOPs since incurring more DOPs may lead  
10 to disqualification of the driving licence. Monetary fines were not found to be very effective,  
11 perhaps because the monetary fine levels were very low relative to the income levels of the  
12 drivers. It remains to be explored if increasing the quantity of fines combined with appropriate  
13 warning messages (such as "Check speed—fines up to \$1000") can help increase the  
14 effectiveness of monetary fines. Significant heterogeneity was found in the influence of the  
15 DOP variable both due to observed and unobserved factors. Specifically, while increasing DOP  
16 deters all drivers from speeding, doing so when combined with a warning (i.e., in the warning  
17 sections) appears to more strongly deter those who recently received a speeding ticket than  
18 others. However, the unobserved variation in the warning section is greater than that in the  
19 standard section, perhaps because of differences in drivers' threat and coping appraisals of the  
20 warning messages, as discussed in section 4.1.

21         In the context of camera-based enforcement strategy, increasing the ratio from status  
22 quo (20:120) to 40:120 showed a considerable effect (29%) on reducing the percentage of  
23 drivers opting for severe speeding, albeit it should be noted that the base percentage of drivers  
24 in this category is only 1%. Increasing it further to 60:120 did not show a substantial effect in  
25 the policy simulations we conducted. Further, reducing the ratio from the status quo (20:120)  
26 to 20:240 did not show a significant effect on the drivers' stated speeding choices.

27         The placement of the warning sign – that is, the distance of the warning sign from the  
28 camera housing location – exhibits an influence on speeding behaviors in the warning section.

1 Placing it close to the camera housing location decreases the likelihood of speeding but can  
2 potentially increase the “kangaroo” effect. And placing it too far from the camera location  
3 would substantially increase the percentage of speeding behaviors. These findings suggest a  
4 need for the optimal location of warning signs. Alternatively, information on the penalty level  
5 can be added to the warning signs to increase the threat appraisal of the driver for reducing  
6 speeding behaviors in warning sections.

7 The demographic characteristics of drivers such as age, education, income have an  
8 influence on how drivers respond to strategies aimed at increasing speed compliance. Similarly,  
9 the drivers’ operational characteristics, driving history and perceptions have a substantial  
10 bearing on the efficacy of speed compliance strategies. Therefore, targeted driver educational  
11 and training campaigns might help increase the speed compliance rates in the population. For  
12 example, drivers with a recent history of traffic tickets continue to demonstrate a greater  
13 tendency for speeding even for high levels of DOP and monetary fines. It appears that simply  
14 imposing fines or DOPs might not suffice to reduce the aggressive driving traits of such drivers.  
15 A combination of DOPs and fines with driver training programs aimed at addressing risk-taking  
16 and aggressive driving traits may be needed to increase safe driving tendencies among these  
17 drivers. Further, higher penalties may be considered for repeat offenders to enhance the  
18 deterrent effect of the penalties (Watson et al., 2015). Similar penalty strategies have been  
19 applied for repeat offenders of drink driving in Hong Kong (Li et al., 2014).

20 Speeding and other traffic offences may be attributed to drivers’ goals of travel time  
21 saving and revenue maximization (Cestac et al., 2011; Peer, 2010; Tarko, 2009), while safe  
22 driving performance and social responsibility may be lower in the hierarchy of professional  
23 drivers’ goals (Hatakka et al., 2002). Therefore, inclusion of positive motives and goals in the  
24 education/training and licensing of professional drivers may be beneficial. In addition,  
25 technology-based interventions, such as GPS-based automated speed surveillance and related  
26 automated speed enforcement mechanisms, may aid in reducing speeding behaviors.

27 The results from this study help enhance the current understanding and effectiveness of  
28 penalties and speed-enforcement strategies (i.e. penalties, warning signs, camera housings, etc.).

1 Yet, this study is limited to the assessment of a few demographics and operational  
2 characteristics of professional drivers. It would be worth exploring the possible effects of latent  
3 characteristics on speeding propensity and severity, when more comprehensive information on  
4 the physiological and psychological metrics of the participants is available. Moreover, results  
5 of this questionnaire survey are derived from a scenario of a typical city road with a speed limit  
6 of 50km/h. It would be interesting to explore the effect of other road environments, such as an  
7 expressway with a speed limit of 70 km/h or higher, on the speeding behavior of professional  
8 drivers. Further, it would be helpful to undertake a study that evaluates the effectiveness of  
9 combining speeding penalties with driver education/training campaigns in reducing risk-taking  
10 and aggressive driving. Also, the separation between the placement of a warning sign and the  
11 camera housing unit was expressed as a distance in the current study. Perhaps a time separation  
12 rather than a space separation would be a better approach to capture how individuals respond  
13 to warning signs before entering monitored roadway section. Yet another line of research would  
14 be to investigate whether fixed ASEC systems, when complemented with a small human police  
15 force, would have a higher impact in reducing speeding than a fixed ASEC system alone. And,  
16 if so, what may be the optimal combination of investment in human-based and machine-based  
17 enforcement mechanisms. Perhaps most importantly, all the results and recommendations in  
18 this paper are based on self-reported speed indications within stated experiments, which clearly  
19 can influence the reliability and accuracy of the relationships estimated. A study based on an  
20 actual field experimental design and field observations of speed at different sections would be  
21 more credible.

22

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8



1 **TABLES AND FIGURES**

2 Table 1 Distribution of speed choices by location type

Section	Speed choice					
	Speed compliance (<50 km/h)		Speeding range 1 (51-65 km/h)		Speeding range 2 (66-80 km/h)	
	Count	%	Count	%	Count	%
Standard	226	14.1	1142	71.2	236	14.7
Warning	918	57.2	641	40.0	45	2.8
Camera Housing	1600	99.8	4	0.2	0	0

3

4 Table 2. Crosstabulation of SP attributes with speed choices at plain and warning sections

Factor	SP attribute level for different speeds (<50kmph, 51-65kmph, 66-80kmph)			Speed choice %					
				Standard section			Warning section		
				Speed compliance	Speeding range 1	Speeding range 2	Speed compliance	Speeding range 1	Speeding range 2
	≤50	51-65	66-80 km/h						
DOPs	0	0	3	13.2%	69.6%	17.2%	54.6%	2.6%	2.8%
	<b>(status quo)</b>								
	0	0	5	12.0%	73.6%	14.4%	52.5%	3.8%	3.7%
	0	2	3	13.2%	68.6%	18.2%	53.7%	4.3%	2.0%
Monetary fine (HK\$)	0	2	5	15.5%	73.1%	11.4%	68.1%	9.2%	2.7%
	0	320	450	11.8%	73.3%	14.9%	54.8%	1.3%	3.9%
	0	320	550	15.2%	64.6%	20.2%	57.4%	9.9%	2.7%
	0	420	450	14.5%	78.6%	6.9%	59.9%	8.7%	1.4%
Camera-to-Housing ratio	0	420	550	15.0%	67.3%	17.7%	56.9%	0.1%	3.0%
		20:240		12.7%	71.8%	15.5%	57.9%	8.7%	3.4%
		20: 120		13.5%	67.3%	19.2%	55.6%	0.1%	4.3%
		<b>(status quo)</b>							
Placement of warning sign		40:120		13.7%	72.6%	13.7%	58.4%	8.7%	2.9%
		60:120		16.2%	72.1%	11.7%	56.1%	2.4%	1.5%
		50m upstream		--	--	--	77.8%	2.2%	0%
		100m upstream		--	--	--	65.3%	1.2%	3.5%
	150 m upstream		--	--	--	43.1%	3.9%	3%	
	200m upstream		--	--	--	42.6%	1.6%	5.8%	

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Table 3 Distribution of the sample

<b>Variable</b>	<b>Count</b>	<b>%</b>
<b><i>Demographics</i></b>		
Gender (Male)	401	100%
Age		
Older (>55 years old)	98	24.4
Younger (<45 years old)	151	37.7
Mid-aged (46-55 years old)	152	37.9
Education		
Primary or below	84	20.9
Secondary or above	317	79.1
Marital status		
Married	293	73.1
Unmarried	108	26.9
Monthly income		
less than 15K	127	31.7
Between 15K and 20K	183	45.6
More than 20K	85	21.2
<b><i>Operational characteristics</i></b>		
Salary system		
Trip-based	136	33.9
Monthly-based	126	31.4
Others (hourly or shift based)	139	34.7
Daily driving hours		
More than 9 hours	168	41.9
Less than 8 hours	39	9.7
8 to 9 hours (normal working hours)	194	48.4
Work time per week		
less than or equal to 48 hours	184	45.9
more than or equal to 63 hours	37	9.2
Others	179	44.9
Vehicle type		
Bus	67	16.7
Taxi and Red Minibus	157	39.2
Green minibus	56	14.0
Goods vehicle	121	30.2
<b><i>Driver history and safety perceptions</i></b>		
Received speeding ticket(s)		
Yes	99	24.7
No	302	75.3
Perceive speeding as a cause of injury		
High	281	70.1
Low	6	1.5
Neutral	114	28.4
Perceive speeding cameras are effective		
High	270	67.3
Low	24	6.0

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Neutral	107	26.7
Frequency of sighting cameras		
High (7-10 times in 10 trips)	250	62.3
Medium (4-6 times in 10 trips)	98	24.4
Low (0-3 times in 10 trips)	53	13.3

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