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# Analytical calculation of temperature-induced strain of supertall structures

Fei Gao<sup>1</sup>, Pan Chen<sup>2</sup>, Shun Weng<sup>3\*</sup>, Yong Xia<sup>4</sup>, Hongping Zhu<sup>5</sup>

**Abstract:** Estimating temperature-induced strain is of critical importance for structural safety assessment. Most previous studies estimated the temperature-induced strain by statistical analysis, resulting in the unexplainable physical meaning of the obtained model coefficients. In this paper, an analytical formula for the temperature-induced strain of supertall structures is derived based on the simulated temperature field. First, a supertall structure is simplified as a cantilever column and the theoretical relationship between the sectional two-dimensional temperature field and strain is derived. Afterwards, the structure is extended to a generalised cantilever column bounded by springs at the top end, and the theoretical relationship of temperature and strain is derived as well. The formula shows that the sectional strain is composed of the sectional average temperature-induced strain and the gradient temperature-induced strain along two horizontal directions. A finite element (FE) model is established to verify the derived strain formula. Finally, the formula is applied to a real supertall structure, the Wuhan Yangtze River Navigation Centre, on which a long-term structural health monitoring system has been installed. The temperature field of the whole structure is obtained by the FE heat transfer analysis, and the temperature-induced strain is calculated according to the derived formula. The average difference between the theoretically derived and the measured strain is less than 7  $\mu\epsilon$ . This study provides a simple theoretical formula for calculating the temperature-induced strain of supertall structures, avoiding the complicated FE structural analysis.

**Keywords:** supertall structures, temperature-induced strain, field monitoring, thermal action, theoretical formula

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## 1. Introduction

Structural health monitoring (SHM) has been widely deployed in large-scaled civil structures for evaluating their safety conditions [1–3]. The collected data from the SHM system not only measure the real structural response but also, more importantly, the static response caused by the environment [4, 5]. Variations in temperature-induced responses may mask the damage-induced response, which eventually results in erroneous evaluations. In recent years, a large number of supertall structures have installed SHM systems for performance evaluation [6–11]. The periodic fluctuation of temperature is the direct cause of changes in structural strain and displacement. However, research on estimating the temperature effect of supertall structures remains insufficient.

Early supertall SHM projects mostly focused on a single aspect of structural deformation, building top displacement and acceleration whereas rarely considered the temperature effect [12–14]. Recently, scholars have gradually realised that the temperature effect on structures cannot be ignored. Tamura et al. [15] unexpectedly found that thermal stress could cause a 4-cm top displacement when they measured the wind-induced response of a building by using RTK-GPS. Breuer et al. [16] studied the effects of solar radiation and temperature changes on the horizontal displacement of the top of the Stuttgart TV tower. The results showed that the daily movement trajectory of the tower top was related to the periodic changes in sunlight and atmospheric temperature. Xia et al. [17] derived the horizontal displacement and inclination of the 600 m tall Canton Tower by using multi-sectional strain data. They [18, 19] comprehensively studied the temperature distribution and the associated action of the Canton Tower. The movement of the tower top on a sunny day in winter was 15.7 cm in the east–west direction and 15.5 cm in the north–south. From summer to winter, the entire tower tilted toward northeast with the horizontal movement of 15 cm approximately at the tower top. Su et al. [20] also separated the typhoon- and temperature-induced quasi-static responses of the structure and found that the former was less than the latter.

Strain is an important static response parameter of a structure and closely related to its stress and displacement. The measured strain comes from various sources such as dead load, live load, winds, temperature, concrete shrinkage, concrete creep and other loads. Among these factors, concrete shrinkage and creep mainly occur at the initial stage of construction and gradually decrease with time. Temperature-induced strain exhibits a daily, seasonal and annual variation pattern. A number of studies have found that environment temperature-induced strain is more significant than other load-induced (Zhu et al. [21]). Moreover, the temperature field of a structure is generally non-uniform, causing the variations in the strain and temperature not synchronised (Yang et al. [22]). Therefore, the strain is

related to the overall temperature field of the entire structure, not a single temperature point, which leads to the complicated relation between the strain and temperature.

Obtaining the temperature field of the entire structure and calculating the temperature-induced response are two key steps for studying the temperature effect. FE heat transfer analysis has been developed for calculating the temperature field. Ni et al. [23] combined on-site monitoring data and FE heat transfer analysis to establish a temperature field model inside the concrete, which provided reliable input for the numerical simulation of temperature-induced deformation and internal forces. Su [24] calculated the temperature field of a single component of Canton Tower. By assuming the temperature field of the structure along the height is uniform, the temperature-induced deformation under several typical cases were calculated by manually inputting the temperature load. This divide-and-conquer approach is inefficient and cannot achieve real-time safety assessment. Gao et al. [25] proposed an efficient method for calculating the overall temperature field of a supertall structure. By establishing a virtual sun, the dynamic thermal boundary conditions under solar radiation were established and the dynamic temperature field of the whole structure was accurately simulated. In these heat transfer analyses, the steel bars were not modelled as the steel bars inside the concrete have negligible effects on the overall temperature field. However, in the structural FE analysis, the steel bars should be modelled as the contribution of steel bars to the sectional stiffness is larger. Including the steel bars will generate numerous elements, which is time-consuming for a large-scale supertall structure [25].

Statistical analysis is another method to estimate the relation between temperature and structural response. Hu et al. [26] have studied the quantitative relationship between displacement and multiple temperature of the Canton Tower in different seasons based on linear regression analysis. The results showed that a regularized linear regression model was able to describe the physical relationship between the temperature and displacement whereas an ordinary linear regression model could not. Bai et al. [27, 28] established the relationship between the strain and the temperature of a typical Tibetan timber building from 2-year monitoring data by combining singular spectrum analysis and polynomial regression. The disadvantages of the statistical analyses include the dependence on the accuracy of the measured data and the unexplainable physical meaning of model coefficients. Additionally, the statistical analysis predicts the structural response through the previous response data and relies on the authenticity of such data. This response–response mapping is prone to systematic deviations. For example, if the previous strain data includes structural damage, the established quantitative relationship between temperature and strain also includes structural damage and thus cannot reflect the original mechanical relationship between temperature and strain.

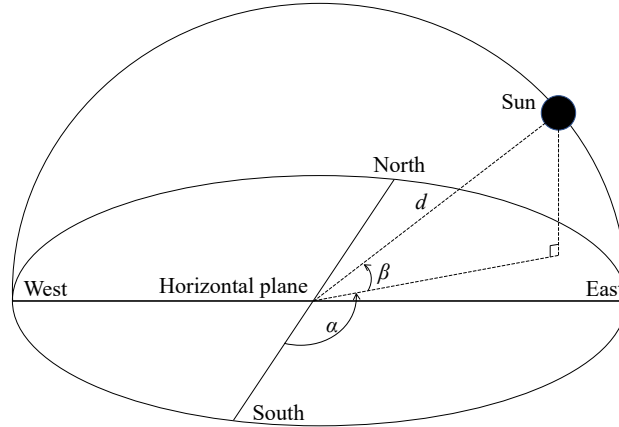
In a word, a simpler and more efficient method is needed to calculate the temperature-induced response, especially the temperature-induced strain. This paper derives the theoretical temperature-

strain formula for supertall structures and thus the complex mapping relationship between temperature and structural response is realized. The framework of this paper is as follows. Firstly, the virtual sun method for calculating time-varying temperature field is briefly described. Secondly, the theoretical temperature-strain formula of the cantilever and generalised cantilever columns is derived. Thirdly, an FE column model verifies the correctness of the formula. Finally, the temperature-strain formula is applied to calculate the temperature-induced strain of the 335 m tall Wuhan Yangtze River Navigation Centre.

## 2. Time-varying temperature field calculation by virtual sun method

### 2.1. Determination of the relative position of the sun

The relative position of the sun (Fig. 1) can be determined by solar altitude angle  $\beta$ , solar azimuth angle  $\alpha$  and the distance of the sun from the earth  $d$ . The distance  $d$  is treated as a constant given that its variation in one year is small. The solar altitude angle  $\beta$  and solar azimuth angle  $\alpha$  are derived in [25] and expressed as



**Fig. 1.** Relative position of the sun

$$\beta = \arcsin \left\{ \sin \varphi \sin \left[ 23.5 \sin \left( \frac{\tau}{365} \right) \right] + \cos \varphi \cos \left[ 23.5 \sin \left( \frac{\tau}{365} \right) \right] \cos \tau \right\}, \quad (1)$$

$$\alpha = \begin{cases} 360 - \arccos \left\{ \frac{\sin \beta \sin \varphi - \sin \left[ 23.5 \sin \left( \frac{\tau}{365} \right) \right]}{\cos \beta \cos \varphi} \right\}, & 360m < \tau \leq 360m + 180 \\ \arccos \left\{ \frac{\sin \beta \sin \varphi - \sin \left[ 23.5 \sin \left( \frac{\tau}{365} \right) \right]}{\cos \beta \cos \varphi} \right\}, & 360m + 180 < \tau \leq 360m + 360 \end{cases}, \quad (2)$$

where  $\varphi$  represents latitude, and  $\tau$  is the radiation calendar angle. In the radiation calendar system, March 21 (vernal equinox) 0:00:00 is set as the reference with  $\tau$  increasing by  $15^\circ$  per hour and changes from  $0^\circ$  to  $131400^\circ$ ;  $m = 0, 1, 2, \dots, 364$ .

## 2.2. Heat transfer equations and boundary conditions

According to the Fourier heat transfer theorem and the energy conservation theorem, the governing equation for heat transfer problems can be established as [29]

$$\rho c \frac{\partial T}{\partial t} = k_x \frac{\partial^2 T}{\partial x^2} + k_y \frac{\partial^2 T}{\partial y^2} + k_z \frac{\partial^2 T}{\partial z^2}, \quad (3)$$

where  $x, y$  and  $z$  are the Cartesian coordinates;  $\rho$  ( $\text{kg}/\text{m}^3$ ) is the density of the material;  $c$  ( $\text{J}/(\text{kg} \cdot ^\circ\text{C})$ ) represents the specific heat coefficient;  $T$  ( $^\circ\text{C}$ ) represents the temperature at coordinate point  $(x, y, z)$  and  $k_x, k_y$  and  $k_z$  ( $\text{W}/(\text{m} \cdot ^\circ\text{C})$ ) is the thermal conductivity coefficients of different directions.

The thermal initial and boundary conditions are required for solving Eq. (3). The thermal initial condition is the end-time temperature field in the previous analysis, which can be set as a uniform temperature field. The thermal boundary condition is determined by the following equations [30]

$$(h_c + h_r)(T_a + \frac{\alpha_s I}{h_c + h_r} - T) + k \frac{\partial T}{\partial n} = 0, \quad (4)$$

$$h_c + h_r = 9.8 + 3.8v, \quad (5)$$

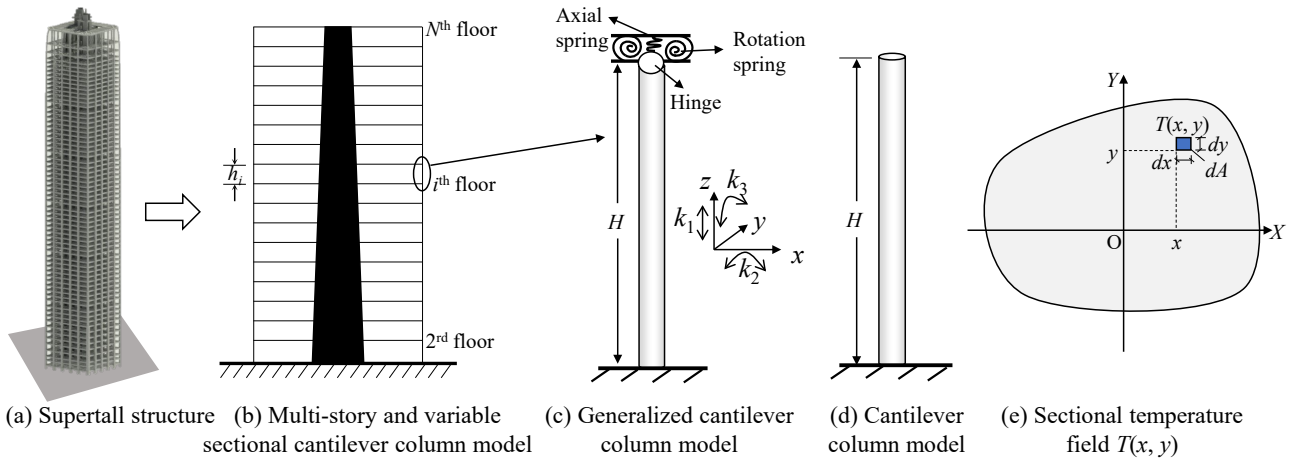
where  $h_c$  ( $\text{W}/(\text{m}^2 \cdot ^\circ\text{C})$ ) is the convective coefficient between the structural surface and the atmosphere;  $h_r$  ( $\text{W}/(\text{m}^2 \cdot ^\circ\text{C})$ ) is the radiant heat transfer coefficient;  $h_c$  and  $h_r$  are in correlation with average wind velocity  $v$ , which is simplified as Eq. (5);  $T_a$  ( $^\circ\text{C}$ ) represents the environmental temperature;  $\alpha_s$  ( $0 < \alpha_s < 1$ ) is the absorptivity coefficient of the surface;  $I$  ( $\text{W}/\text{m}^2$ ) is the intensity of the solar radiation projected onto the surface;  $k$  ( $\text{W}/(\text{m} \cdot ^\circ\text{C})$ ) represents the thermal conductivity coefficient and is assumed identical in three directions and  $n$  is the normal direction of the surface.

When applying the thermal boundary conditions, the irradiation elements receive solar radiation, whereas the shade elements receive none. The irradiation and shade elements are distinguished by the hemicube method [31]. A virtual sun, determined by Eq. (1) and (2) is established in the FE model. The sun is treated as a radiation source, while the structural elements are treated as absorbers. The angle coefficient between the radiation source and the absorbers are calculated. If the angle coefficient is not equal to zero, then the radiation source can ‘see’ the absorber, which is defined as the irradiation element. Otherwise, the radiation source cannot ‘see’ the absorption element and is referred to as the

shade element. The value of the angle coefficient is used to distinguish the shade and irradiation elements automatically [25].

### 3. Derivation of temperature-strain formulas for supertall structures

After obtaining the whole temperature field of the structure, a structural FE model is generally established for calculating the temperature-induced response. Because the steel bars contribute a lot to the sectional stiffness, the structural FE model needs to build a large number of steel bar elements, which results in long calculation time and low calculation accuracy. In order to avoid this disadvantage, this paper will develop another method that can calculate the structural response without establishing a structural FE model. Considering that the deformation profile of the whole structure caused by solar radiation is the first bending mode [17], the supertall structure is equivalent to a multi-story and variable sectional cantilever column model (Fig. 2 (b)). In the model: the bottom is fully constrained; the core tube and the columns are connected by beams and slabs; the cross section of the core tube decreases linearly from the bottom to top. Under the effect of ambient temperature, the non-uniform temperature of the outer columns change significantly, resulting in greater strain variations than the core tube. Therefore, we will focus on the temperature-induced strain of the outer columns. For a column on each floor, its temperature-induced strain is independent of the strain of the upper and lower columns. It can be equivalent to a generalised cantilever column (Fig. 2 (c)), which is fully constrained at the bottom and constrained with axial and rotation springs at the top. The temperature-induced strain of a column is only related to the sectional temperature field. Firstly, the analytical calculation of the temperature-induced strain for the cantilever column is derived, and then extended to the generalised cantilever column. This paper extends the traditional single-point temperature-strain formula (i.e.,  $\Delta\varepsilon = \alpha\Delta T$ ) to the sectional temperature field-strain formula for calculating the temperature-induced strain. Consequently, establishing a structural FE model is avoided.



**Fig. 2. Theoretical model**

### 3.1. Cantilever column model

As shown in Fig. 2 (d), the cantilever column has a height of  $H$ , and the bottom is fully constrained. Assume that the sectional temperature field at the initial time is constant 0, and at a certain time is  $T(x, y)$ . Firstly, we completely constrain the top of the column so that the column does not deform. The stress at any point  $(x, y)$  in the section due to the temperature change is  $\sigma(x, y) = E\alpha T(x, y)$ , where  $E$  represents the elastic modulus and  $\alpha$  is thermal expansion coefficient. At this time, the axial force to be applied at the top can be expressed as  $F_N = \int \sigma(x, y) dA = \int E\alpha T(x, y) dA$ . In addition to the axial force, the non-uniform distributed stress in the cross section also generates bending moments. The bending moments along the x- and y-axis are  $M_x = \int E\alpha T(x, y) y dA$ ,  $M_y = \int E\alpha T(x, y) x dA$ .

Next the constraints at the top are released. We need to apply external forces of  $F'_N$ ,  $M'_x$  and  $M'_y$  to make the cantilever column the same as the initial state. Assuming that the deformation of the section meets the plane section assumption, the strain caused by the axial force and bending moment at any point  $(x_0, y_0)$  are respectively:  $\varepsilon'_0 = \frac{F_N}{EA} = \frac{\alpha \int T(x, y) dA}{A}$ ,  $\varepsilon'_m = \frac{M_x}{EI_x} y_0 + \frac{M_y}{EI_y} x_0$ , where  $\varepsilon'_0$  and  $\varepsilon'_m$  refer to the z-direction strains,  $I_x$  and  $I_y$  are moments of inertia with respect to the x- and y-axis, respectively. The total strain at any coordinate  $(x_0, y_0)$  is summed as

$$\varepsilon' = \varepsilon'_0 + \varepsilon'_m = \frac{\alpha \int T(x, y) dA}{A} + \frac{\alpha \int T(x, y) y dA}{I_x} y_0 + \frac{\alpha \int T(x, y) x dA}{I_y} x_0. \quad (6)$$

If take  $T'_A = \frac{\int T(x, y) dA}{A}$ ,  $T'_{ex} = \frac{\int T(x, y) y dA}{I_x}$ ,  $T'_{ey} = \frac{\int T(x, y) x dA}{I_y}$ , then,

$$\varepsilon'(x_0, y_0) = \alpha(T'_A + T'_{ex} \cdot y_0 + T'_{ey} \cdot x_0). \quad (7)$$

The above formula shows the relationship between the strain and the sectional temperature field at arbitrary coordinates.  $T'_A$  can be regarded as the sectional average temperature, and  $T'_{ex}$ ,  $T'_{ey}$  can be regarded as the gradient temperature along the x-axis and y-axis directions, respectively. When the temperature remains constant along the y direction, then  $T'_{ex} = 0$ . So does  $T'_{ey}$ . At any time, when the sectional temperature field is known,  $T'_A$ ,  $T'_{ex}$  and  $T'_{ey}$  are all available. The strain of any point can then be calculated from the coordinates and the sectional temperature field.

### 3.2. Generalised cantilever column model

The generalised cantilever column model is shown in Fig. 2 (c). The constraints of beams and slabs on the column are equivalent with axial and rotation springs at the top. The top axial spring stiffness,  $x$ - and  $y$ -rotation spring stiffness are  $k_1$ ,  $k_2$ , and  $k_3$ , respectively. A similar process is used to derive the temperature-strain formula under the temperature field  $T(x, y)$ .

The axial displacement at the column top is defined as generalised displacements  $u_0$ . The  $x$ - and  $y$ -rotation angles at the top are defined as generalised rotation angles  $\theta_x$  and  $\theta_y$ , respectively. When the top is unconstrained, the equivalent force caused by the temperature field  $T(x, y)$  is calculated as  $F_N = \int E\alpha T(x, y)dA$ ,  $M_x = \int E\alpha T(x, y)y dA$ , and  $M_y = \int E\alpha T(x, y)x dA$ . The top springs will constrain the top displacement. The constrained displacement will produce internal forces. The equilibrium equation between the internal and external forces requires that,  $F_N - k_1 u_0 = \frac{u_0}{H} EA$ ,  $M_x - k_2 \theta_x = EI_x \delta_x''$ ,  $M_y - k_3 \theta_y = EI_y \delta_y''$ , where  $\delta_x$  and  $\delta_y$  represent the lateral displacement at the top along the  $x$ - and  $y$ -directions, respectively.

Consider the relationship between the top lateral displacement and the rotation. The expressions of  $M_x$  and  $M_y$  show that the bending moments  $M_x$  and  $M_y$  are directly caused by the temperature field  $T(x, y)$ . Thus,  $M_x$  and  $M_y$  remain constant along the height direction. As the first derivative of the lateral displacement is the rotation and the first derivative of the rotation is proportional to the bending moment, the rotation is a linear function of height and the lateral displacement is a quadratic function of height. Moreover, the  $x$ -direction rotation angles at the bottom and top are 0 and  $\theta_x$ , respectively.

Then, the rotation equation at an arbitrary height  $z$  is expressed by  $\delta_x'(z) = 0 + \frac{\theta_x - 0}{H} z = \frac{\theta_x}{H} z$ .

According to  $\delta_x'(z)$ , we get  $\delta_x''(z) = \frac{\theta_x}{H}$ .  $\delta_x''(z)$  shows that the  $\delta_x''(z)$  remains constant in the

height direction. When substitute  $\delta_x''(z)$  into  $M_x - k_2 \theta_x = EI_x \delta_x''$  and then have  $k_2 = \frac{M_x}{\theta_x} - \frac{EI_x}{H}$ .  $k_3$

can be calculated in a similar manner. Therefore,  $k_1$ ,  $k_2$  and  $k_3$  are expressed as

$$k_1 = \frac{F_N}{u_0} - \frac{EA}{H}, \quad (8)$$

$$k_2 = \frac{M_x}{\theta_x} - \frac{EI_x}{H}, \quad (9)$$

$$k_3 = \frac{M_y}{\theta_y} - \frac{EI_y}{H}. \quad (10)$$



209  $k_1$ ,  $k_2$  and  $k_3$  are stiffness and can be regarded as constants. The relationship between the  
 210 generalised displacement and temperature can be derived from Eqs. (8) to (10):  $u_0 = \frac{F_N}{k_1 + \frac{EA}{H}}$ ,

211  $\theta_x = \frac{M_x}{k_2 + \frac{EI_x}{H}}$ ,  $\theta_y = \frac{M_y}{k_3 + \frac{EI_y}{H}}$ . According to the plane section assumption, the strain in the section is

212 linearly distributed,  $\varepsilon = \frac{u_0}{H} + \frac{\theta_x}{H}y + \frac{\theta_y}{H}x$ . Take the obtained  $u_0$ ,  $\theta_x$  and  $\theta_y$  into  $\varepsilon = \frac{u_0}{H} + \frac{\theta_x}{H}y + \frac{\theta_y}{H}x$ , we

213 get  $\varepsilon = \frac{F_N}{k_1H + EA} + \frac{M_x}{k_2H + EI_x}y + \frac{M_y}{k_3H + EI_y}x$ . Since  $F_N$ ,  $M_x$  and  $M_y$  are functions of the temperature

214 field  $T(x, y)$ , the strain at any point  $(x_0, y_0)$  can be obtained as

$$215 \quad \varepsilon = \alpha \left( \frac{\int T(x, y) dA}{\frac{k_1H}{E} + A} + \frac{\int T(x, y) y dA}{\frac{k_2H}{E} + I_x} y_0 + \frac{\int T(x, y) x dA}{\frac{k_3H}{E} + I_y} x_0 \right). \quad (11)$$

216 Let

$$217 \quad T_A = \frac{\int T(x, y) dA}{\frac{k_1H}{E} + A}, \quad T_{ex} = \frac{\int T(x, y) y dA}{\frac{k_2H}{E} + I_x}, \quad T_{ey} = \frac{\int T(x, y) x dA}{\frac{k_3H}{E} + I_y}, \quad (12)$$

218 then,

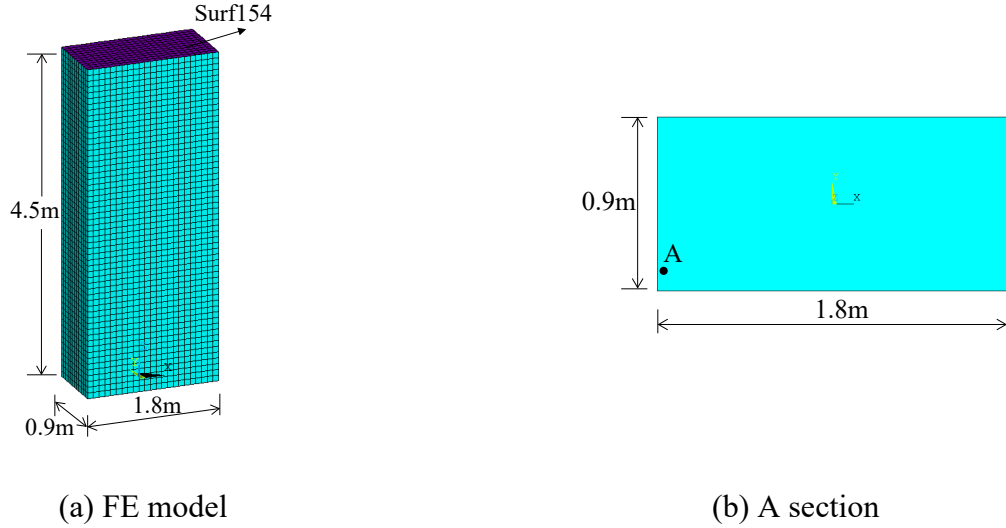
$$219 \quad \varepsilon(x_0, y_0) = \alpha(T_A + T_{ex} \cdot y_0 + T_{ey} \cdot x_0). \quad (13)$$

220 It is noteworthy that Eq. (11) and (6) are similar and Eq. (11) degenerates into Eq. (6) as  $k_1 = k_2 =$   
 221  $k_3 = 0$ . Therefore Eq. (11) is more general.

222 Eq. (13) shows that the strain occurs within a three-dimensional plane and consists of three  
 223 components: the sectional axial deformation caused by  $T_A$ ,  $y$ -direction deviation deformation by  $T_{ex}$   
 224 and  $x$ -direction deviation deformation by  $T_{ey}$ .

#### 225 4. Formula verification by an FE model

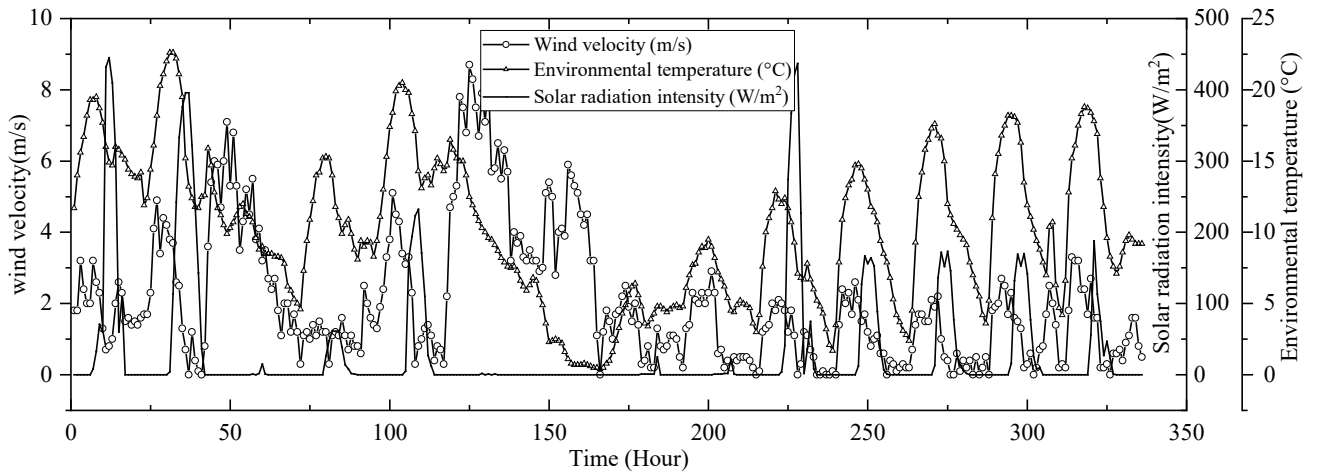
226 In this section, a generalised cantilever column model subjected only to temperature loads will be  
 227 established. Based on the simulated temperature field, the temperature-induced strain is calculated from  
 228 Eq. (11) and then compared with the strain calculated by the FE thermal-structure coupling analysis.



**Fig. 3.** Generalized cantilever column model

**Table 1.** Material parameters used in generalized cantilever column FE model

Density /(kg/m <sup>3</sup> )	Elastic modulus /(N/m <sup>2</sup> )	Poisson's ratio	Thermal expansion coefficient /°C <sup>-1</sup>	Thermal conductivity /W/(m·°C)	Specific heat coefficient /(J/(kg·°C))
2635	$3.7 \times 10^{10}$	0.28	$10 \times 10^{-6}$	2.33	921

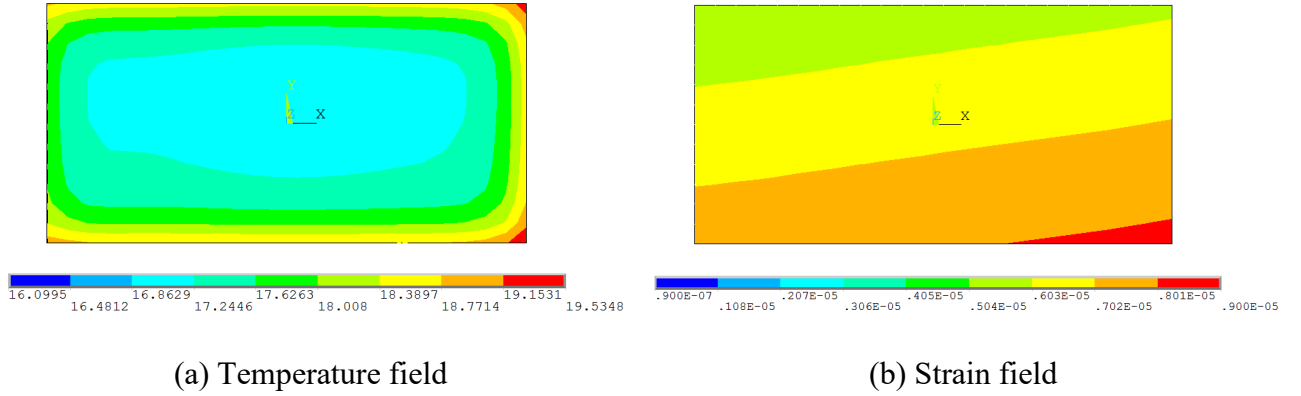


**Fig. 4.** Meteorological data

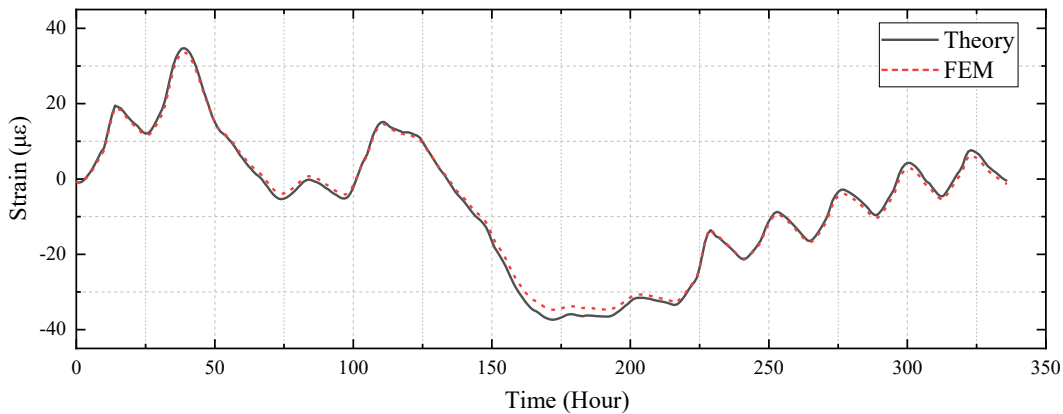
As shown in Fig. 3, the generalised cantilever model is in a rectangular cross section with the dimensions of 0.9 m × 1.8 m × 4.5 m. The column is constrained by axial and rotation springs at the top and fully constrained at the bottom. These springs are added by applying surface effect elements SURF154 in ANSYS. The surface effect elements are attached to the top surface of the model for

simulating the axial and rotation springs. The stiffness of the axial and rotation springs are time-independent, which are calculated according to Eqs. (8) to (10).  $k_1$ ,  $k_2$  and  $k_3$  are  $1.33 \times 10^{10}$  N/m,  $8.92 \times 10^8$  N·m and  $3.58 \times 10^9$  N·m, respectively. The element mesh size is set as 80 mm. The material parameters of this model are shown in Table 1. Meteorological data from weather station (Fig. 4) is transferred into the third thermal boundary conditions and then applied on the outer surface of the model. A 336-hour heat transfer analysis is conducted for obtaining the time-varying temperature field. Point A ( $-0.85, -0.35$ ) near the outer surface is selected to calculate the strain.

Fig. 5 (a) shows the sectional temperature field at the 10th hour.  $T_A$ ,  $T_{ex}$  and  $T_{ey}$  at any time are calculated according to Eq. (12). The temperature-induced strain of Point A is calculated according to Eq. (13). For comparison, the thermal-induced strain of the FE model is also calculated through the structural analysis and the strain field at the 10th hour is illustrated in Fig. 5 (b). The strain is linearly distributed in the section, which also verifies the plane section assumption.



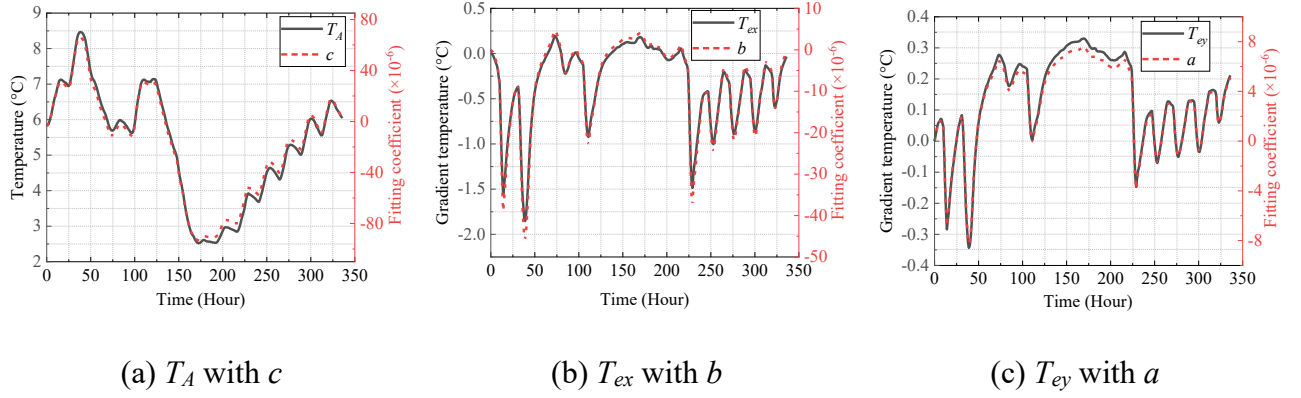
**Fig. 5.** Temperature and strain fields of the column at 10th hours



**Fig. 6.** Comparison between the theoretical and FE numerical strains of point A

The strain time history at Point A calculated from the present theoretical formula and the FE model are compared in Fig. 6. The two curves are very close. Furthermore, the strain field calculated by the

FE model at a certain time is fitted to a plane equation,  $\varepsilon = \alpha(c + by + ax)$ , where  $\varepsilon$  represents strain,  $\alpha=10 \times 10^{-6}/^{\circ}\text{C}$  is the thermal expansion coefficient, and  $a$ ,  $b$  and  $c$  are the fitting coefficients of the plane equation, which are corresponding to  $T_{ey}$ ,  $T_{ex}$  and  $T_A$  in Eq. (12). These three pairs of coefficients ( $c$  and  $T_A$ ,  $b$  and  $T_{ex}$ , and  $a$  and  $T_{ey}$ ) are compared in Fig. 7 and the results are consistent. This verifies that the average surface temperature  $T_A$ , the gradient temperature  $T_{ex}$  and  $T_{ey}$  cause axial strain,  $y$ -direction and  $x$ -direction gradient strain, respectively.



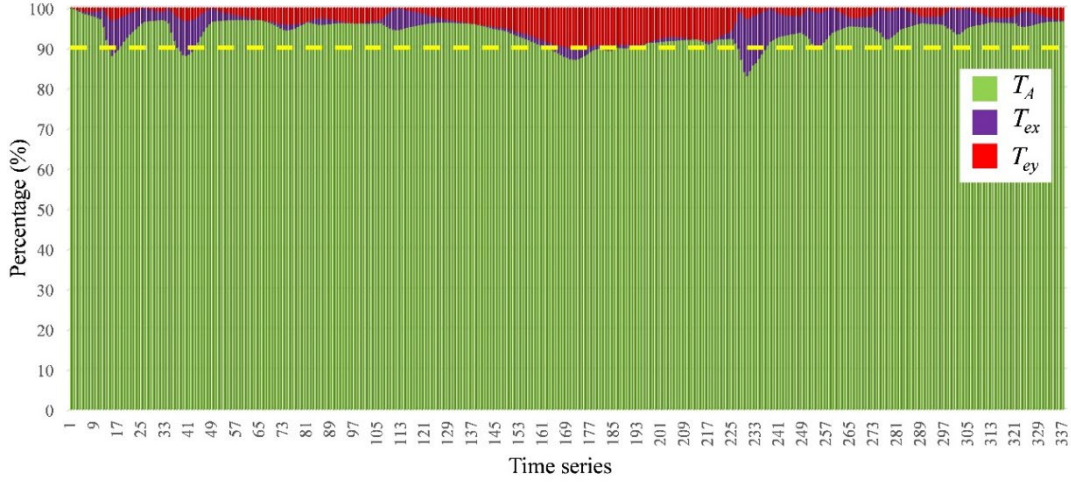
**Fig. 7.** Relationship between temperature components and strain fitting coefficients

**Table 2.** Maximum theoretical contribution ratio of three temperature components

	$T_A = \bar{T}$ ( $^{\circ}\text{C}$ )	$T_{ex} = 1/2 \Delta T_x$ ( $^{\circ}\text{C}$ )	$T_{ey} = 1/2 \Delta T_y$ ( $^{\circ}\text{C}$ )	Contribution ratio of $T_A$	Contribution ratio of $T_{ex}$	Contribution ratio of $T_{ey}$
In Spring	10	6	6	45.46%	27.27%	27.27%
In Summer	27	5	5	72.98%	13.51%	13.51%
In Autumn	25	6	6	67.56%	16.22%	16.22%
In Winter	8	5	5	44.44%	27.78%	27.78%

Further, the contribution of  $T_A$ ,  $T_{ex}$ ,  $T_{ey}$  to the total strain is different. In general,  $T_A$  contributes most to the strain. Consider the simplest possible situation:  $k_1 = k_2 = k_3 = 0$  and the temperature field is linearly distributed along the two sectional directions, which are  $\Delta T_x$  and  $\Delta T_y$ , respectively. The temperature-induced strain formula is simplified to:  $\varepsilon(x_0, y_0) = \alpha(T_A + \frac{x}{b_x} \Delta T_x + \frac{y}{b_y} \Delta T_y)$ , which  $b_x$  and  $b_y$  are the sectional heights along the  $x$  and  $y$  directions, respectively. Table 2 shows the average temperature  $\bar{T}$  and maximum temperature difference  $\Delta T$  in Wuhan in one year. When the strain contribution ratio of  $T_{ex}$  and  $T_{ey}$  is the largest,  $x/b_x = y/b_y = 1/2$ . The contribution of three temperature

components to the strain is shown in Table 2. It can be found that in four different seasons, the minimum contribution of  $T_A$  to strain fluctuates between 44.44% and 72.98%, accounting for the largest proportion; the maximum contribution of  $T_{ex}$  and  $T_{ey}$  to strain fluctuates between 13.51% and 27.78%, accounting for the smaller proportion; When the average temperature decreases or the temperature difference increases, the contribution of  $T_{ex}$  and  $T_{ey}$  increases; conversely, the contribution of  $T_A$  increases. In this FE example, Fig. 8 illustrates the three components during the 336 hours period.  $T_A$  contributes more than 90% to the strain. The ratio change in Fig.8 meets the above rules.



**Fig. 8.** Contribution of  $T_A$ ,  $T_{ex}$ ,  $T_{ey}$  to the total strain

## 5. Case study: a supertall structure

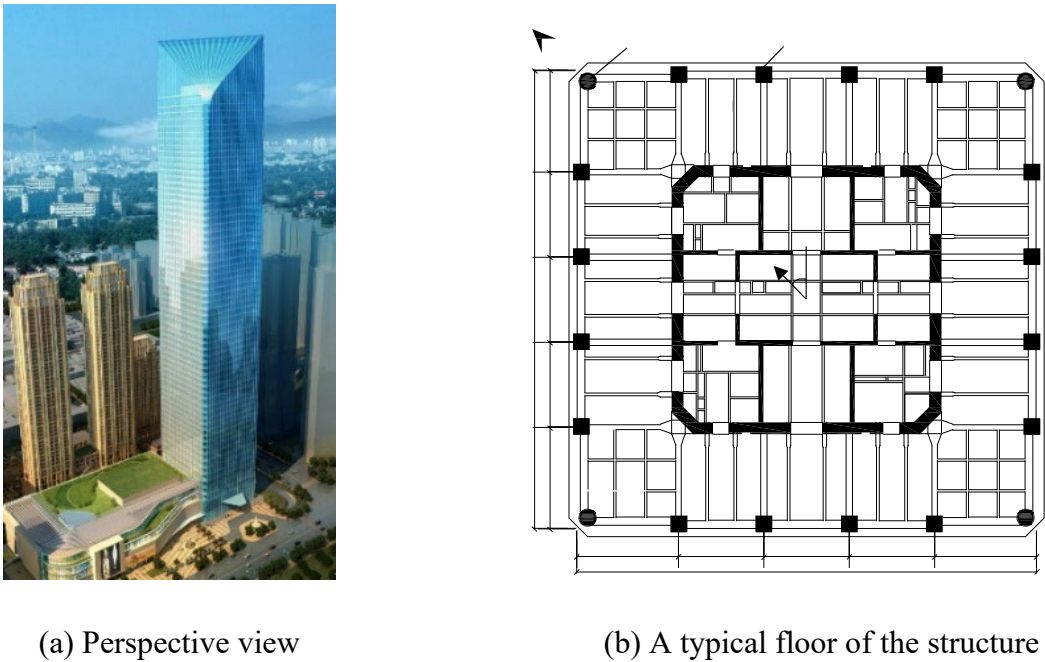
### 5.1. Wuhan Yangtze River Navigation Centre and its SHM system

The proposed strain calculation is applied to the newly completed Wuhan Yangtze River Navigation Centre, a supertall frame-tube structure with a total height of 335 m as illustrated in Fig. 9(a). This building consists of a 66-floor square main body and a triangular steel roof. During the construction stage, the outer frames and inner core tube were constructed simultaneously.

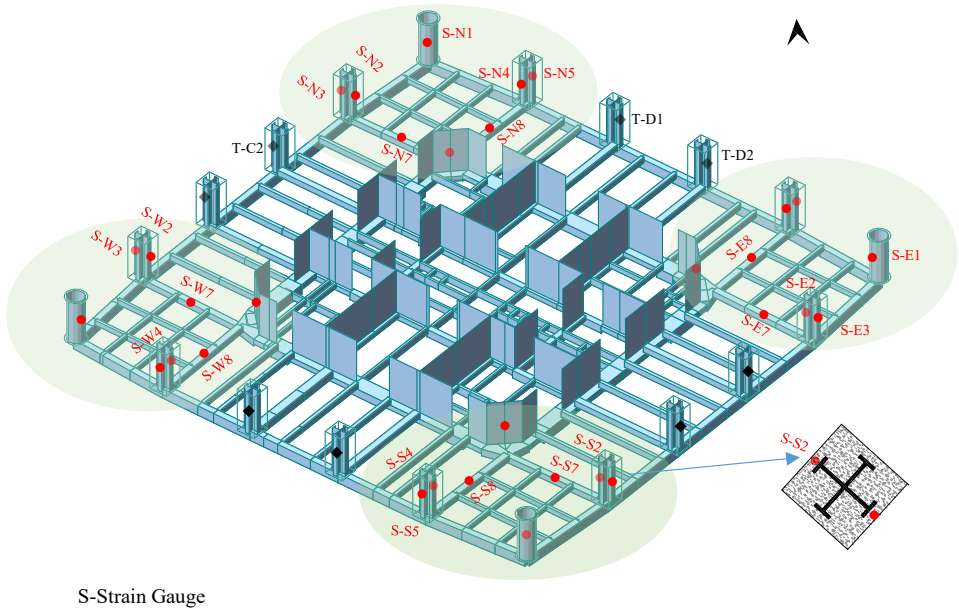
Fig. 9 (b) shows the typical floor of this skyscraper. The floor section has a constant size of 50.6 m  $\times$  50.6 m, surrounded by 20 columns consisting of 4 concrete-filled tube (CFT) columns at the corners and 16 square steel-reinforced concrete (SRC) columns in the middle of each facade. The inner core tube is a square with the dimensions of 30.0 m  $\times$  30.0 m. The core tube and the columns are connected through concrete beams.

A long-term SHM system has been installed on the structure to monitor the structural performance during both construction and service stages. Six monitoring sections have been selected along the height for temperature and strain monitoring. These monitoring sections are located on the 10th, 18th, 28th, 38th, 48th and 58th storeys, which correspond to the heights of 47.05, 83.05, 129.55, 176.05,

290 222.55 and 265.05 m, respectively. A weather station was deployed near the skyscraper to record the  
 291 surrounding meteorological parameters, such as environmental temperature, wind speed, solar  
 292 radiation, etc.



**Fig. 9.** Wuhan Yangtze River Navigation Centre

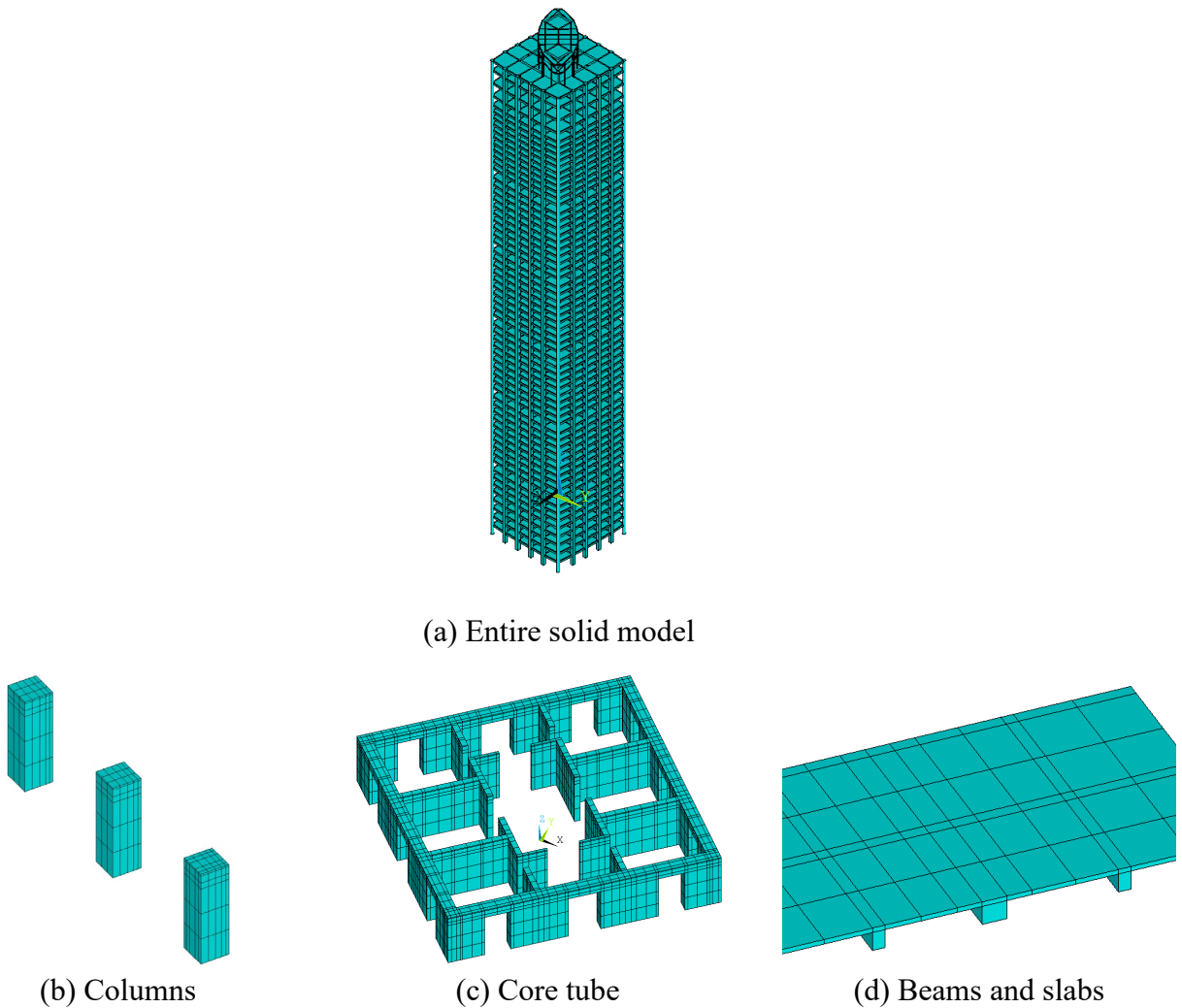


**Fig. 10.** Sensor layout of a typical monitoring section

293 All six monitoring sections have the same sensor layout. As shown in Fig. 10, a typical monitoring  
 294 sections consists of 32 vibrating wire strain gauges and eight temperature sensors. The strain gauges  
 295 are distributed in the east, south, west and north zones. For example, in the east zone, one strain gauge  
 296  
 297

is installed in the CFT column, named S-E1 ('S' represents 'strain', and 'E' is for 'east'), four in the SRC columns (named S-E2 to S-E5), one in the core tube (S-E6) and two in the beams (named S-E7 and S-E8). The vibrating wire strain gauges can measure the strain and temperature of one point simultaneously. The temperature sensors are installed in the eight middle SRC columns, denoted as T-A1 and T-A2 to T-D1 and T-D2. All strain gauges and temperature sensors are embedded in the concrete 60 mm from the surface. The sampling rate of the strain gauges and temperature sensors is one reading per 10 min.

## 5.2. The FE model



**Fig. 11.** The FE model of Wuhan Yangtze River Navigation Centre

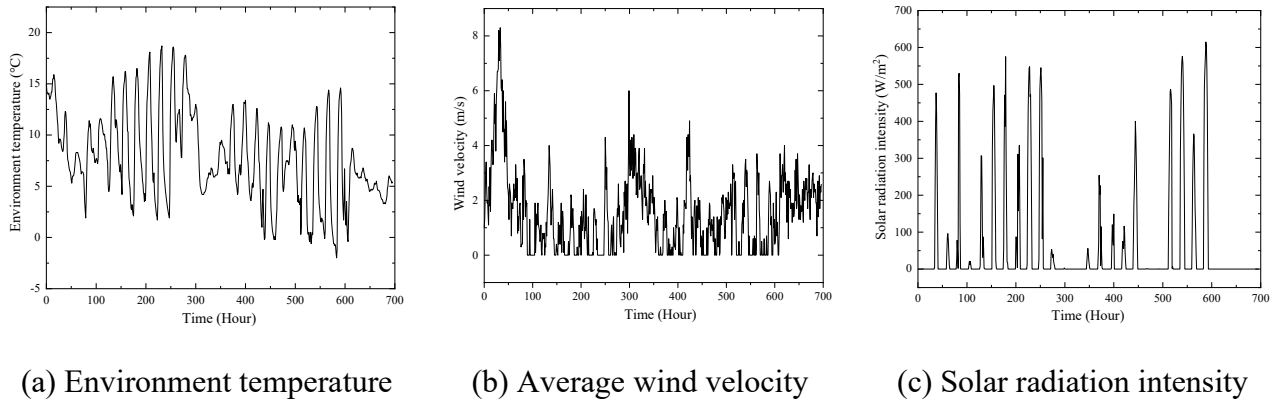
An FE model is established according to the actual geometry of the structure on the ANSYS platform, as shown in Fig. 11. Given that the steel bars are embedded in the concrete and their cross-sectional area is only approximately a tenth of the total section, the effect of the steel bars on the concrete temperature field can be neglected. Therefore, only concrete is included in the FE model. The



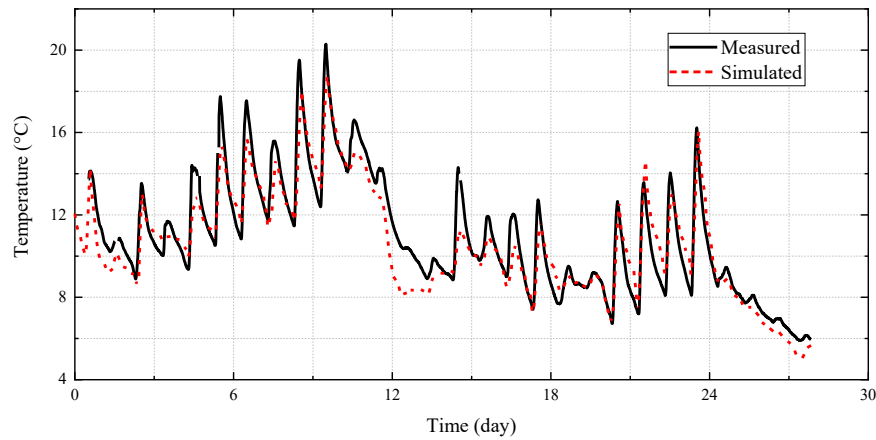
element type Solid90 is used for all elements, each consisting of 20 nodes with one thermal DOF at each node. The element mesh sizes of the columns, core tube, beams and slabs are approximately 0.12, 0.20, 0.48 and 0.6 m, respectively. The mass density of the material is 2635 kg/m<sup>3</sup>. The equivalent elastic modulus of columns, core tube, beams and slabs are  $3.7 \times 10^{10}$ ,  $4.44 \times 10^{10}$ ,  $3.33 \times 10^{10}$  and  $3.07 \times 10^{10}$  N/m<sup>2</sup>, respectively. The thermal expansion coefficient is  $10 \times 10^{-6}/^{\circ}\text{C}$ . Only temperature load is considered in the FE model.

### 5.3. Simulation of time-varying temperature field

The monitoring data from November 18 to December 16, 2017 were selected for the heat transfer analysis. During this period, the structure was constructed on the 28th floor. The FE model at this construction stage is released from the entire model. The meteorological data recorded from the weather station are shown in Fig. 12. The virtual sun method is conducted to obtain the time-varying temperature field during this period. Points T18-E3, T18-S4, T18-W3 and T18-N4 at four different directions are selected for comparison, as shown in Fig. 13.

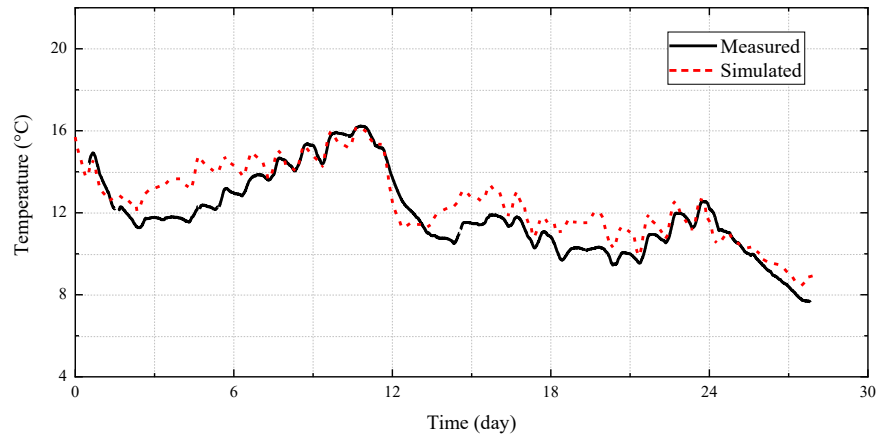


**Fig. 12.** Meteorological data from November 18, 2017 to December 16, 2017

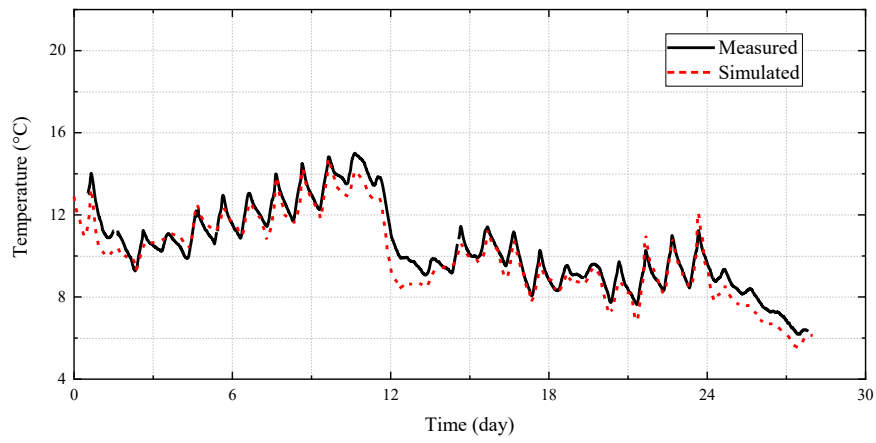


(a) East point T18-E3

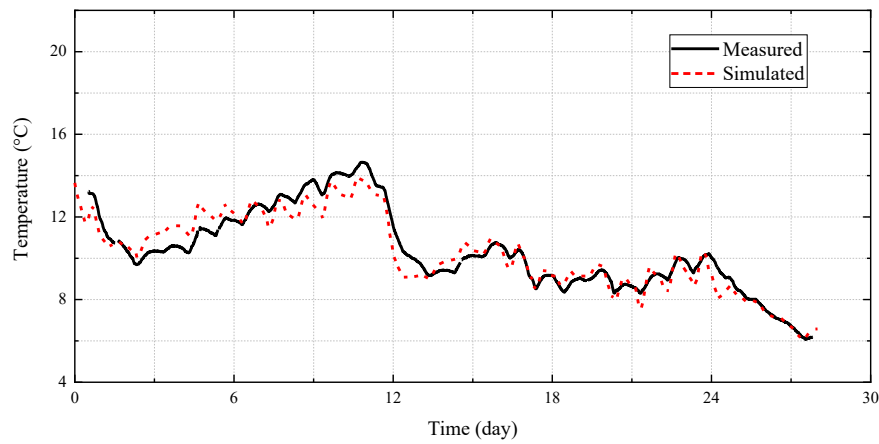




(b) South point T18-S4



(c) West point T18-W3



(d) North point T18-N4

**Fig. 13.** Verification of the simulated temperature field

The root mean square difference (*RMSD*) between the simulated and measured temperature are calculated by

$$RMSD = \sqrt{\frac{1}{n} \sum_{i=1}^n (T_s - T_m)^2}, \quad (14)$$

where  $n$  represents the number of measured points;  $T_s$  and  $T_m$  denote the simulated temperature and measured temperature, respectively. The relative root mean square difference (*RRMSD*) between the simulated and measured temperature are calculated by

$$RRMSD = \frac{RMSD}{T_{\max} - T_{\min}}, \quad (15)$$

where  $T_{\max}$  and  $T_{\min}$  represents the maximum temperature and minimum temperature in the measured temperature, respectively; *RRMSD* indicates the relative difference between simulated and calculated temperatures.

The *RMSD* and *RRMSD* of these four points are listed in Table 3. The maximum *RMSD* and *RRMSD* in these four points are 1.03 °C and 11.63%, respectively. The average *RMSD* and *RRMSD* in these four points are only 0.81 °C and 8.18%, respectively. The simulated temperature field agrees well with the calculated temperatures, which will be used for the calculation of the temperature-induced strain.

**Table 3.** The *RMSD* and *RRMSD* between the simulated and measured temperature

Point	T18-E3	T18-S4	T18-W3	T18-N4	Average
<i>RMSD</i> /°C	1.03	1.00	0.62	0.59	0.81
<i>RRMSD</i>	7.16%	11.63%	7.03%	6.89%	8.18%

#### 5.4. Theoretical estimation of temperature-induced strain

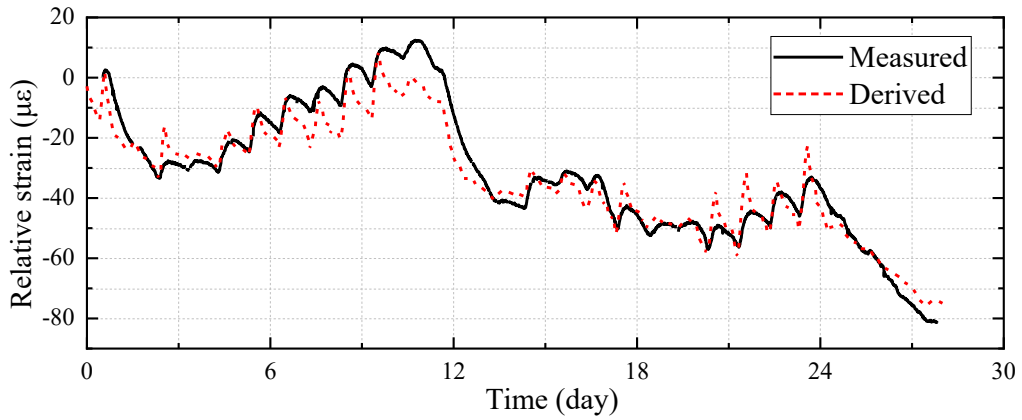
The structural temperature field at any time can be obtained through the FE simulation. The temperature-induced strain of the structural component is then calculated by using Eqs. (11) to (13).

For example, for the column where the measuring point S18-E3 is located, the parameters in Eq. (11) are determined as follows:  $\int T(x, y) dA$ ,  $\int T(x, y) y dA$  and  $\int T(x, y) x dA$  are calculated by the simulated temperature field;  $H$  is the storey height;  $A = 3.24 \text{ m}^2$  is the area of the column section;  $E = 3.7 \times 10^{10} \text{ N/m}^2$ ;  $I_x = I_y = 0.87 \text{ m}^4$  are the  $x$ -direction and  $y$ -direction moments of inertia;  $k_1$ ,  $k_2$  and  $k_3$  represent axial spring stiffness,  $x$ - and  $y$ -direction rotation stiffness and are caused by the surrounding beams and

slabs. In a real structure,  $k_1$ ,  $k_2$  and  $k_3$  are difficult to calculate. As Fig. 10 demonstrates,  $T_A$  contribute most to the strain. Therefore, Eq. (11) is simplified as

$$\varepsilon \approx \alpha \frac{\int T(x, y) dA}{\frac{k_1 H}{E} + A} = C \int T(x, y) dA, \quad (16)$$

where  $C = \alpha/(k_1 H/E + A)$  is a constant. The above formula reveals that the strain is approximately proportional to  $\int T(x, y) dA$ , which are available from the FE heat transfer analysis. Eq. (16) can be used to estimate the temperature-induced strain in a real structure. The calculated time-history strain the structure is compared with the measured one in Fig. 14.



**Fig. 14.** The derived and measured strain

Fig. 14 shows that the derived strain reflects the fluctuation and trend of the strain successfully. The *RMSD* and *RRMSD* between the derived and measured strain are  $6.18 \mu\epsilon$  and  $6.6\%$ , respectively. The difference between the two curves is mainly caused by three reasons: First, the simulated temperature field has errors with the actual temperature field. Second, the measured strain includes not only temperature strain but also those due to the construction load, concrete shrinkage, concrete creep and wind load. Third, the temperature-induced strain caused by gradient temperature is reduced in Eq. (16). Nevertheless, the small difference indicates that the temperature-induced strain dominates the total strain of the structure in practice.

The method proposed in this paper provides a new method for estimating the temperature-induced strain in field monitoring without the FE structural analysis. The mechanism between temperature and strain is detailed described. The structural response due to other loads can be subsequently obtained by subtracting the pure temperature-induced strain from the measured total strain.

## 6. Conclusions

In this paper, the temperature-strain formula is derived through the mapping relationship between the temperature field and strain. A generalised cantilever column FE model verifies the correctness of the temperature-strain formula. Taking the Wuhan Yangtze River Navigation Centre as the test bed, the temperature-induced strain was successfully estimated by a combination of FE heat transfer analysis and temperature-strain formula. The following conclusions are drawn.

(1) Simplifying the bending-mode supertall structure into a generalised cantilever column is feasible when deriving the temperature-induced strain.

(2) The temperature-induced strain for the columns or the core tube of a supertall structure is composed of three parts: the sectional average temperature-induced strain, the  $x$ -direction gradient temperature-induced strain and the  $y$ -direction gradient temperature-induced strain. The sectional average temperature contributes most to the strain.

(3) The measured strain fluctuates every day, which is mainly caused by temperature variations. Combining the FE heat transfer analysis and the temperature-strain formula derived in this paper, we can estimate the temperature-induced strain. The RMSE of the derived and measured strain is within 7  $\mu\epsilon$ .

## Acknowledgements

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