

Constitutive Modeling for Two Sands under High Pressure

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Abstract: Particle breakage is a typical characteristic of crushable granular soil under high pressure, which has great effects on its stress-strain behaviors. The phenomenon of critical state line (CSL) shifting downwards in the compression plane caused by particle breakage was depicted by a breakage-dependent critical state plane (BCSP). Particle breakage was incorporated into a void-ratio-pressure state parameter to modify Rowe's stress-dilatancy equation, and then the state parameter was incorporated into the bounding stress ratio and plastic modulus. Due to the impact of high pressure on particle breakage, the pressure-dependent plastic modulus parameters were introduced. A breakage-dependent bounding surface plasticity model was proposed to capture the influence of particle breakage on the state-dependent stress-strain behaviors for silica and coral sands and the transition of complex breakage-dependent critical states resulted from the competition between the contraction due to particle breakage and the dilatancy due to particle rearrangement.

Keywords: plasticity; constitutive model; particle breakage; critical state; state parameter; dilatancy

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33 Introduction

34 Crushable granular materials are easily prone to fracturing when they are subjected to high pressure
35 (Hagerty et al. 1993; Lade et al. 1996; Yamamuro et al. 1996; Nakata et al. 2001; Hyodo et al. 2016; Zheng
36 and Tannant 2016; Man and Chik-Kwong Wong 2017; Mun and McCartney 2017; Yu 2017b; Mao et al.
37 2018; Yu 2019; Mao et al. 2020; Wu et al. 2020), large displacement (Luzzani and Coop 2002; Coop et al.
38 2004; Wafid Agung et al. 2004; Fukuoka et al. 2006; Hiroshi et al. 2006; Sadrekarimi and Olson 2010,
39 2011b; Miao and Airey 2013; Zhang and Baudet 2013; Wei et al. 2018), high strain rate (Omidvar et al.
40 2012; Huang et al. 2014; Suescun-Florez et al. 2015; Huang et al. 2017; Parab et al. 2017; Xiao et al. 2019b),
41 high frequency (Sun et al. 2015; Indraratna et al. 2020), complex loading conditions (Liu et al. 2020; Ning
42 et al. 2020; Pan et al. 2020), and a series of drying-wetting cycles or flooding (Ovalle et al. 2015; Alonso
43 et al. 2016; Mun and McCartney 2017; Chen et al. 2020; Tong et al. 2020), especially in the pile installation,
44 and high rockfill dam, etc. Particle breakage has great influences on the deformation and strength of sands,
45 which leads to an increase in volume strain and a decrease in peak strength (Hagerty et al. 1993; Nakata et
46 al. 1999; Luzzani and Coop 2002; Coop et al. 2004; Russell and Khalili 2004; Tarantino and Hyde 2005;
47 Lobo-Guerrero and Vallejo 2006; Valdes and Koprulu 2007; Kuwajima et al. 2009; Lade et al. 2009;
48 Bandini and Coop 2011; Wang et al. 2011; Zhang and Baudet 2013; Yu 2017b, 2019). The extent of particle
49 breakage would be determined by the coordinate numbers and internal flows of particles (McDowell et al.
50 1996; McDowell and Bolton 1998; Ueng and Chen 2000; Liu et al. 2019). In addition, particle breakage
51 intensifies with increases in particle size and angularity and decreases in mineral strength, uniformity
52 coefficient, density and biobonding (Hardin 1985; Yamamuro et al. 1996; Nakata et al. 1999; McDowell
53 and Amon 2000; Hyodo et al. 2016; Xiao et al. 2019a; Xiao et al. 2020).

54 It is great challenging to precisely predict the deformation and strength of granular soils under high
55 pressure using a set of unique model parameters. Ueng and Chen (2000) studied the effect of particle
56 breakage on the shear strength of sands by considering the energy consumption correlated to the rate of
57 increment in particle surface area per unit volume of sand, which has also been extended to other crushable
58 soils (Indraratna and Salim 2002; Salim and Indraratna 2004; Tarantino and Hyde 2005). Varadarajan et al.
59 (2006) applied the framework of disturbed state concept (Desai 2000) to establish an elastoplastic model
60 by introducing a degradation function (Varadarajan et al. 2003) to consider the effect of particle breakage
61 on the stress-strain relationship of rockfill materials. Russell and Khalili (2004) proposed a model within
62 the critical state framework based on a critical state line (CSL) consisting of three linear segments (a
63 complex function) to account for the influence of particle breakage. In addition, the breakage theory
64 proposed by Einav (2007) was effectively used to establish a breakage-dependent elastoplastic constitutive
65 model in the thermodynamic framework to capture the effects of particle breakage evolution on the stress-
66 strain relation (Tengattini et al. 2016; Zhang et al. 2016; Chang et al. 2019; Cil et al. 2020). A notion of
67 dynamic CSL due to particle breakage (Daouadji et al. 2001; Muir Wood and Maeda 2008) has been widely
68 accepted to establish breakage-dependent models, e.g., elastoplastic models with different yielding
69 mechanisms (Daouadji and Hicher 2010; Hu et al. 2011; Yin et al. 2017), elastoplastic models in the
70 framework of bounding surface plasticity (Kan and Taiebat 2014; Indraratna et al. 2015; Chen et al. 2016;
71 Xiao and Liu 2017), elastoplastic models in the framework of generalized plasticity (Liu and Zou 2013;
72 Liu and Gao 2017).

73 State-dependent behaviors of granular soils (Bolton 1986; Been et al. 1991; Yu 1998; Salgado et al.
74 2000; Chu and Leong 2002; Xiao et al. 2014; Lashkari 2016) are significant when analyzing the

75 deformation and stability of slopes, embankments, dams, coastal engineering, etc. The state indices
76 referring to CSL are effective parameters to unify strength and dilatancy (Been and Jefferies 1985; Yang
77 and Li 2004; Chiu and Fu 2008; Chu and Wanatowski 2008, 2009; Rabbi et al. 2019) and also to establish
78 a unified state-dependent constitutive model (Jefferies 1993; Muir Wood et al. 1994; Gajo and Muir Wood
79 1999; Li and Dafalias 2000; Yao et al. 2004; Ling and Yang 2006; Lashkari and Yaghtin 2018; Sun et al.
80 2019; Wei and Yang 2019; Yang et al. 2019; Sun et al. 2020). The dilatancy equation proposed by Rowe
81 (1962) is widely applied in constitutive models to simulate the state-dependent dilatancy behavior by
82 incorporating a state parameter (Wan and Guo 1998; Xu and Song 2009; Xiao et al. 2017). Xiao and Liu
83 (2017) proposed a void-ratio-pressure state parameter by combining a void-ratio state parameter (Wan and
84 Guo 1998) and a pressure state parameter (Wang et al. 2002), which is appropriate for crushable soils with
85 a wide range of confining pressures and void ratios. However, the state parameter and state-dependent
86 dilatancy considering the evolution of particle breakage for sands under high pressure have not been fully
87 understood and thereby need to be further investigated.

88 The main objective of this paper is to establish a breakage-dependent plasticity model for sands using
89 the revised Rowe's stress-dilatancy equation by incorporating a void-ratio-pressure state parameter in the
90 framework of the extended breakage-dependent critical state theory.

91 **Constitutive Model**

92 The bounding surface plasticity model (Dafalias and Popov 1976) can capture the volumetric expansion
93 and strain softening of granular soils (Bardet 1986; Li and Dafalias 2000; Russell and Khalili 2004; Kan
94 Mojtaba et al. 2014). The framework proposed by Li and Dafalias (2000) was adopted to establish the
95 constitutive equations. However, it is noted that the mechanical behaviors of granular materials are always

96 affected by particle breakage (Ueng and Chen 2000; Coop et al. 2004; Russell and Khalili 2004; Zhang and
 97 Baudet 2013; Hyodo et al. 2016; Yu 2017b; Mao et al. 2019; Ovalle and Hicher 2019; Ganju et al. 2020),
 98 which reduces the dilatancy and peak strength, and enhances the hardening and contraction behaviors of
 99 sands (Indraratna and Salim 2002; Hasanlourad et al. 2008; Sadrekarimi and Olson 2011a; Zhang et al.
 100 2013; Liu et al. 2016; Yu 2017b; Ciantia and O’Sullivan 2020; Wang et al. 2020; Zhang and Luo 2020).
 101 Thereby, the influences of particle breakage on the critical state and the state-dependent behaviors of sands
 102 must be considered. The breakage-dependent critical state plane (BCSP) and the corresponding state
 103 parameter will be defined in the following Sections.

104 ***Breakage-Dependent Critical State Plane***

105 Particle breakage leads to the upward-shifting of grading curves and the dynamic change of material
 106 structure as the large-size particles break into small-size particles, which fill the void among the remnant
 107 larger ones (Hardin 1985; McDowell and Bolton 1998; Daouadji et al. 2001). Lade et al. (1996) used a
 108 hyperbolic model to establish the relationship between relative breakage and total input energy per unit
 109 volume. Yu (2017a) and Jia et al. (2017) employed the plastic work per unit volume W_p instead of the
 110 total input energy (Lade et al. 1996), and found the relationship between B_r and W_p can also be
 111 expressed as a hyperbolic function:

$$112 \quad B_r = \frac{W_p}{\chi_w + k_w W_p} \quad (1)$$

113 where B_r is the particle breakage index defined by Hardin (1985); χ_w and k_w are material parameters.
 114 $\chi_w = 7.847 \text{ MJ/m}^3$ and $k_w = 1.686$ for silica sands NO.5 (Yu 2017a) while $\chi_w = 4.820 \text{ MJ/m}^3$ and k_w
 115 $= 3.228$ for coral sands NO.3 (Yu 2018). The plastic work W_p can be calculated by:

$$W_p = \int dW_p = \int (p' d\varepsilon_v^p + q d\varepsilon_s^p) \quad (2)$$

where $d\varepsilon_v^p$ is the plastic volumetric strain increment; $d\varepsilon_s^p$ is the plastic shear strain increment; p' is the mean effective stress; and q is the deviatoric stress.

Based on the phenomenon that the CSL shifts downwards in the compression plane (i.e., void ratio e versus logarithm of mean effective stress $\ln p'$) due to particle breakage (Muir Wood and Maeda 2008; Kikumoto et al. 2010; Bandini and Coop 2011; Ghafghazi et al. 2014; Indraratna et al. 2015; Heitor et al. 2016; Altuhafi et al. 2018; Ciantia et al. 2019), the data of silica sands NO.5 (Yu 2017a) in **Figs. 1(a)-1(b)** and coral sands NO.3 (Yu 2018) in **Figs. 1(c)-1(d)** are presented to illustrate the dynamic transition of breakage-dependent critical state line (BCSL) due to grain crushing. According to previous work (Yu 2019), the slope of BCSL in the compression plane with a neglectable grain crushing was approximated as 0.1. **Figs. 1(a)-1(b)** show the transition of BCSL of silica sand with the same void ratio of 0.798 under different confining pressures while **Figs. 1(c)-1(d)** present the transition of BCSL of coral sand with different initial void ratios under the same confining pressure of 3 MPa. The red line in **Fig. 1** is the BCSL with $B_r = 0$, and the blue lines are a series of BCSLs with different B_r values for the corresponding critical state points (CSPs). The evolution of BCSL is shown in **Figs. 1(b)** and **1(d)** with a normal coordinate and in **Figs. 1(a)** and **1(c)** with a semi-logarithmic coordinate.

Following the concept of BCSP in the $B_r - e - p'$ space proposed by Xiao and Liu (2017), the BCSP for silica sand in **Figs. 2(a)-2(b)** and coral sand in **Fig. 2(c)** can be defined as:

$$e_{cs} = e_{cs0} - \lambda \ln p'_{cs} \quad (3)$$

$$e_{cs} = e_{cs0} - \lambda \ln p'_{cs} = e_{cs0} (B_r) - \lambda \ln p'_{cs} \quad (4)$$

where e_{cs} is the critical-state void ratio; p'_{cs} is the critical-state mean effective stress; e_{cs0} is the initial

critical-state void ratio; λ is the slope of the BCSL. According to the finding by Xiao and Liu (2017), the relationship between e_{cs0} and B_r can be expressed as an exponential function:

$$e_{cs0} = e_{B0} - k_B \exp(\chi_B B_r) \quad (5)$$

where e_{B0} , k_B and χ_B are the breakage-dependent critical-state parameters. Substituting **Eq. (5)** into **Eq. (4)**, the BCSP can be given as:

$$e_{cs} = e_{B0} - k_B \exp(\chi_B B_r) - \lambda \ln p'_{cs} \quad (6)$$

Equation (6) suggests that an increase in B_r leads to a downward movement of the BCSL, which is in agreement with the test observations (Kikumoto et al. 2010; Bandini and Coop 2011; Ghafghazi et al. 2014; Indraratna et al. 2015; Heitor et al. 2016; Altuhafi et al. 2018). Combination of **Eqs. (1)** and **(6)** gives:

$$e_{cs} = e_{B0} - \lambda \ln p'_{cs} - k_B \exp\left(\chi_B \frac{W_p}{\chi_w + k_w W_p}\right) \quad (7)$$

Equation (7) indicates that the location of CSL during grains crushing is determined by the plastic work W_p , as shown in **Figs. 3(a)-3(b)** for silica sand and **Fig. 3(c)** for coral sand, which is in line with the findings by Liu and Zou (2013).

State Parameter

A void-ratio-pressure state parameter suggested by Xiao and Liu (2017) that combines the void-ratio state parameter defined by Wan and Guo (1998) and the pressure state parameter proposed by Wang et al. (2002), as shown in **Fig. 1**, is adopted in this study:

$$I_{ep} = \frac{e}{e_{cs}} \frac{p'}{p'_{cs}} \quad (8)$$

As shown in **Fig. 1**, **Eq. (6)** can be further rewritten by substituting p'_{cs} with p' :

$$e_{cs} = e_{B0} - k_B \exp(\chi_B B_r) - \lambda \ln p' \quad (9)$$

Similarly, substituting e_{cs} with e into **Eq. (6)** gives:

$$p'_{cs} = \exp \left\{ (1/\lambda) [e_{B0} - k_B \exp(\chi_B B_r) - e] \right\} \quad (10)$$

Substituting **Eqs. (9) and (10)** into **Eq. (8)** yields

$$I_{ep} = \frac{\frac{ep'}{e_{B0} - k_B \exp(\chi_B B_r) - \lambda \ln p'}}{\exp \left[\frac{e_{B0} - k_B \exp(\chi_B B_r) - e}{\lambda} \right]} \quad (11)$$

The values of void-ratio-pressure state parameter I_{ep} from the initial state point (ISP) to the critical state point (CSP) during the shearing process are calculated and labelled in **Figs. 2-3**. A specimen is defined as loose if the initial state parameter $I_{ep}^0 > 1$, indicating that ISPs are above BCSP, while a specimen is dense when $I_{ep}^0 < 1$, indicating that ISPs are below BCSP. The void-ratio-pressure state parameter I_{ep} approaches one as the specimen is sheared to critical state, where CSPs are on BCSP. Therefore, the void-ratio-pressure state parameter could describe the evolution of state-dependent behavior for crushable sands during the shearing process.

Friction Angle and Stress Ratio

The mobilized friction angle ϕ_m is an important mechanical parameter for granular soils, which can be defined under triaxial compression condition as follows:

$$\sin \phi_m = \frac{3\eta}{6 + \eta} \quad (12)$$

where the stress ratio η , the deviatoric stress q , and the mean effective stress p' under the triaxial condition can be expressed as:

$$\eta = \frac{q}{p'} \quad (13a)$$

$$q = \sigma'_1 - \sigma'_3 \quad (13b)$$

$$p' = (\sigma'_1 + 2\sigma'_3) / 3 \quad (13c)$$

The stress ratio η becomes the critical-state stress ratio M_{cs} when specimen is sheared to critical state.

Yielding Surface and Loading Unit Vector

The yielding surface of modified Cam-Clay (MCC) model proposed by Roscoe and Burland (1968) is adopted in this study:

$$f(p', q, p_0) = p'(1 + \frac{\eta^2}{M_{cs}^2}) - p_0 = 0 \quad (14)$$

where p_0 is the initial confining pressure.

The compression-related component (n_v^f) and shearing-related component (n_s^f) of the loading unit vector, which are normal to the MCC yielding surface, can be expressed as follows:

$$\begin{aligned} n_v^f &= \frac{\frac{\partial f}{\partial p'}}{\sqrt{\left(\frac{\partial f}{\partial p'}\right)^2 + \left(\frac{\partial f}{\partial q}\right)^2}} \\ &= \frac{(M_{cs}^2 - \eta^2)}{\sqrt{(M_{cs}^2 - \eta^2)^2 + 4\eta^2}} \end{aligned} \quad (15a)$$

$$\begin{aligned} n_s^f &= \frac{\frac{\partial f}{\partial q}}{\sqrt{\left(\frac{\partial f}{\partial p'}\right)^2 + \left(\frac{\partial f}{\partial q}\right)^2}} \\ &= \frac{2\eta}{\sqrt{(M_{cs}^2 - \eta^2)^2 + 4\eta^2}} \end{aligned} \quad (15b)$$

Dilatancy and Plastic Flow Rule

Rowe (1962) proposed a stress-dilatancy relation for the uniform rods according to the minimum energy theory:

$$\sin \psi_m = \frac{\sin \phi_m - \sin \phi_{cs}}{1 - \sin \phi_m \sin \phi_{cs}} \quad (16)$$

where ϕ_{cs} is the critical-state friction angle and ψ_m is the mobilized dilatation angle. A modified Rowe stress-dilatancy equation was proposed by Xu and Song (2009) due to the difference in deformation mechanism and particle characteristics of actual soils as compared to the uniform rods, which is given as:

$$\sin \psi_m = d_0 \frac{\sin \phi_m - \sin \phi_{cs}}{1 - \sin \phi_m \sin \phi_{cs}} \quad (17)$$

where d_0 is a dilatancy parameter. In addition, Wan and Guo (1998) incorporated the void-ratio state parameter into the Rowe's stress-dilatancy equation to account for the state-dependent dilatancy behavior, which is expressed as:

$$\sin \psi_m = \frac{\sin \phi_m - (e/e_{cs})^\alpha \sin \phi_{cs}}{1 - (e/e_{cs})^\alpha \sin \phi_m \sin \phi_{cs}} \quad (18)$$

where α is a dilatancy parameter. Furthermore, Xiao et al. (2017) suggested a logically modified Rowe's stress-dilatancy equation by incorporating the void-ratio-pressure state parameter into the above two modifications, which can be given as:

$$\sin \psi_m = d_0 \frac{\sin \phi_m - \exp[\mathcal{G}_d (I_{ep} - 1)] \sin \phi_{cs}}{1 - \exp[\mathcal{G}_d (I_{ep} - 1)] \sin \phi_m \sin \phi_{cs}} \quad (19)$$

where \mathcal{G}_d is a dilatancy parameter.

A coefficient of dilatancy ratio S_d is defined as:

$$S_d = I_{ep}^{k_d} \quad (20)$$

where k_d is a dilatancy ratio parameter. It is noted that S_d meets the following requirement at critical

208 state:

$$209 \quad S_d \big|_{\eta=M_{cs}, e=e_{cs}} = I_{ep}^{k_d} = 1^{k_d} = 1 \quad (21)$$

210 A new modification of Rowe's stress-dilatancy equation in this paper is defined as:

$$\begin{aligned} 211 \quad \sin \psi_m &= d_0 \frac{\sin \phi_m - S_d \sin \phi_{cs}}{1 - S_d \sin \phi_m \sin \phi_{cs}} \\ &= d_0 \frac{\sin \phi_m - I_{ep}^{k_d} \sin \phi_{cs}}{1 - I_{ep}^{k_d} \sin \phi_m \sin \phi_{cs}} \end{aligned} \quad (22)$$

212 The dilatancy d (by neglecting elastic strains) and the dilatation angle ψ_m at triaxial conditions are
213 defined as:

$$214 \quad d = -\frac{d\varepsilon_v^p}{d\varepsilon_s^p} = -\frac{3d\varepsilon_v/d\varepsilon_a}{3 - d\varepsilon_v/d\varepsilon_a} \quad (23a)$$

$$215 \quad \sin \psi_m = -\frac{d\varepsilon_v/d\varepsilon_a}{2 - d\varepsilon_v/d\varepsilon_a} \quad (23b)$$

216 where $d\varepsilon_a$ and $d\varepsilon_v$ are axial and volumetric strain increments, respectively. Combination of **Eqs. (23a)**
217 and **(23b)** gives:

$$218 \quad d = \frac{6 \sin \psi_m}{3 - \sin \psi_m} \quad (24)$$

219 Substituting **Eq. (22)** into **Eq. (24)** yields:

$$220 \quad d = \frac{6d_0 \sin \phi_m - 6d_0 \sin \phi_{cs} I_{ep}^{k_d}}{3 - d_0 \sin \phi_m - \sin \phi_{cs} (3 \sin \phi_m - d_0) I_{ep}^{k_d}} \quad (25)$$

221 The compression-related component (n_v^g) and shearing-related component (n_s^g) of the plastic flow unit
222 vector can be defined as:

$$223 \quad n_v^g = \frac{-d}{\sqrt{1+d^2}} \quad (26a)$$

$$n_s^g = \frac{1}{\sqrt{1+d^2}} \quad (26b)$$

Substitution of **Eq. (25)** into **Eq. (26)** yields:

$$n_v^g = \frac{-\frac{6d_0 \sin \phi_m - 6d_0 \sin \phi_{cs} I_{ep}^{k_d}}{3 - d_0 \sin \phi_m - \sin \phi_{cs} (3 \sin \phi_m - d_0) I_{ep}^{k_d}}}{\sqrt{1 + \left[\frac{6d_0 \sin \phi_m - 6d_0 \sin \phi_{cs} I_{ep}^{k_d}}{3 - d_0 \sin \phi_m - \sin \phi_{cs} (3 \sin \phi_m - d_0) I_{ep}^{k_d}} \right]^2}} \quad (27a)$$

$$n_s^g = \frac{1}{\sqrt{1 + \left[\frac{6d_0 \sin \phi_m - 6d_0 \sin \phi_{cs} I_{ep}^{k_d}}{3 - d_0 \sin \phi_m - \sin \phi_{cs} (3 \sin \phi_m - d_0) I_{ep}^{k_d}} \right]^2}} \quad (27b)$$

Bounding Stress Ratio and Plastic Modulus

A coefficient of bounding stress ratio S_b is defined as:

$$S_b = I_{ep}^{-k_b} \quad (28)$$

where k_b is a bounding stress-ratio parameter. It is noted that S_b meets the following requirement at critical state:

$$S_b \big|_{\eta=M_{cs}, e=e_{cs}} = I_{ep}^{-k_b} = 1^{-k_b} = 1 \quad (29)$$

Therefore, the bounding stress ratio M_b satisfies the following condition at critical state:

$$\begin{aligned} M_b \big|_{\eta=M_{cs}, e=e_{cs}} &= M_{cs} S_b = M_{cs} I_{ep}^{-k_b} \\ &= M_{cs} 1^{-k_b} = M_{cs} \end{aligned} \quad (30)$$

Based on **Eqs. (11)** and **(30)**, the state-dependent bounding stress ratio M_b considering the effect of particle breakage is given as:

$$M_b = M_{cs} \left\{ \frac{\frac{ep'}{e_{B0} - k_B \exp(\chi_B B_r) - \lambda \ln p'}}{\exp \left\{ \frac{1}{\lambda} [e_{B0} - k_B \exp(\chi_B B_r) - e] \right\}} \right\}^{-k_b} \quad (31)$$

Equation (31) indicates that M_b is correlated to grain crushing. A breakage-state-dependent plastic modulus H_p can be expressed as a function of G_e , η and M_b :

$$\begin{aligned} H_p &= h_0 G_e (M_b - \eta) / (1 + \eta)^4 \\ &= h_0 G_e (M_{cs} I_{ep}^{-k_b} - \eta) / (1 + \eta)^4 \end{aligned} \quad (32)$$

where h_0 depends on confining pressure according to the tests on silica and coral sands and can be expressed as:

$$h_0 = \chi_h \left(\frac{P_0}{P_a} \right)^{-k_h} \quad (33)$$

where χ_h and k_h are pressure-dependent plastic modulus parameters.

Strain-Stress Relationships

Strain increments produced by stress increments can be expressed as the sum of elastic and plastic strain increments:

$$d\varepsilon_v = d\varepsilon_v^e + d\varepsilon_v^p \quad (34a)$$

$$d\varepsilon_s = d\varepsilon_s^e + d\varepsilon_s^p \quad (34b)$$

where $d\varepsilon_s$ is the total shear strain increment; $d\varepsilon_v^e$ is the elastic volumetric strain increment; $d\varepsilon_s^e$ is the elastic shear strain increment; and other strain increments have already been defined in previous Sections.

In addition, the axial strain increment $d\varepsilon_a$ under the triaxial condition can be expressed as:

$$d\varepsilon_a = d\varepsilon_v / 3 + d\varepsilon_s \quad (35)$$

For simplicity, the elastic volumetric and shear strain increments can be expressed as:

$$d\varepsilon_v^e = dp' / K_e \quad (36a)$$

$$d\varepsilon_s^e = dq / (3G_e) \quad (36b)$$

where dp' and dq are the mean effective stress and deviatoric stress increments, respectively; K_e and

259 G_e are the elastic bulk modulus and elastic shear modulus, respectively. Hardin and Richart (1963) pointed
 260 out that G_e can be expressed as a function of the mean effective stress p' and void ratio e at the current
 261 state:

$$262 \quad G_e = G_0 \frac{(2.97 - e)^2}{1 + e} \sqrt{p' p_a} \quad (37)$$

263 where p_a is the atmospheric pressure of 0.1 MPa; and G_0 is the elastic shearing modulus parameter. The
 264 elastic bulk modulus is usually expressed as a function of the elastic shear modulus G_e and Poisson's ratio
 265 ν :

$$266 \quad \begin{aligned} K_e &= G_e \frac{2(1 + \nu)}{3(1 - 2\nu)} \\ &= G_0 \sqrt{p' p_a} \frac{(2.97 - e)^2}{1 + e} \frac{2(1 + \nu)}{3(1 - 2\nu)} \end{aligned} \quad (38)$$

267 Based on a non-associated flow rule, the plastic strain increments ($d\varepsilon_v^p$ and $d\varepsilon_s^p$) is given as:

$$268 \quad d\varepsilon_v^p = \frac{1}{H_p} (n_v^f dp' + n_s^f dq) n_v^g \quad (39a)$$

$$269 \quad d\varepsilon_s^p = \frac{1}{H_p} (n_v^f dp' + n_s^f dq) n_s^g \quad (39b)$$

270 Substituting **Eqs. (31), (33) and (37)** into **Eq. (32)** gives:

$$271 \quad \begin{aligned} H_p &= h_1 \left(\frac{p_0}{p_a} \right)^{k_h} G_0 \frac{(2.97 - e)^2}{1 + e} \frac{\sqrt{p' p_a}}{(1 + \eta)^4} \times \\ &\quad \left\{ M_{cs} \left\{ \frac{ep'}{e_{B0} - k_B \exp(\chi_B B_r) - \lambda \ln p'} \right\}^{-k_b} \right\} - \eta \end{aligned} \quad (40)$$

272 **Equation (40)** indicates that the particle breakage can affect the plastic modulus. In addition, the plastic
 273 modulus H_p can also be used to capture the particle breakage-induced plastic strain under the isotropic

274 compression condition.

275 **Determinations of Model Parameters**

276 The new model for crushable sand has fourteen material parameters, as listed in **Tables 1** and **2**,
277 including two elastic parameters (G_0 and ν), five breakage-dependent critical state parameters (M_{cs} , λ ,
278 e_{B0} , k_B and χ_B), two breakage-energy parameters (χ_w and k_w), two dilatancy parameters (d_0 and
279 k_d), one bounding stress-ratio parameter (k_b), and two plastic modulus parameters (χ_h and k_h). The
280 values of breakage-energy parameters determined by Yu (2017a) and Yu (2018) are adopted in this study.
281 The determinations of other model parameters are based on the methods used in previous studies (Li and
282 Dafalias 2000; Xiao and Liu 2017). The values of two plastic modulus parameters can be determined by
283 the plastic modulus calibrated from a series of triaxial tests under different confining pressures. **Table 1**
284 lists values of initial state and model parameters and their changed values within a certain range to study
285 their effects on the stress-strain relationships and evolution of particle breakage. **Table 2** lists the calibrated
286 values of the model parameters from the test data by Yu (2017a) and Yu (2018).

287 **Model Performances and Predictions**

288 Variations of the initial state and model parameters listed in **Table 1** are applied to assess the model
289 capability to simulate the evolution of stress, deformation, and particle breakage. **Figs. 4a-4d** show the
290 effect of initial confining pressure p_0 on model predictions. The model can predict strain softening and
291 volumetric expansion at a low confining pressure of 0.6 MPa, and strain hardening and volumetric
292 contraction behavior at a high confining pressure of 1.2 MPa. An increase in confining pressure results in
293 a significant increase in particle breakage, as shown in **Figs. 4c-4d**. Similarly, as shown in **Figs. 5a-5b**,
294 the transition from strain softening and volumetric expansion to strain hardening and volumetric contraction

can be predicted with an increase in void ratio from 0.7 to 0.9. **Figs. 5c~5d** show that the influence of void ratio on particle breakage is less than that of confining pressure in **Figs. 4c-4d**. Meanwhile, an increase in initial elastic shearing modulus G_0 in **Figs. 6a-6d** can lead to an increase in strain softening, dilatancy and particle breakage. **Figs. 7a-7d** show that an increase in the parameter λ results in a great decrease in peak-state strength, a great increase in volumetric strain, and a neglectable change in particle breakage. The dilatancy parameter d_0 in **Figs. 8a-8d** mainly affects the maximum dilatancy and volumetric strain while the dilatancy parameter k_d in **Figs. 9a~9d** mainly influences the maximum dilatancy. **Figs. 10a-10d** show that an increase in bounding stress-ratio parameter k_b leads to a great increase in peak-state strength and maximum dilatancy, a great decrease in volumetric strain, and a slightly increase in particle breakage. The plastic modulus parameter h_0 in **Figs. 11a~11d** plays a similar role on peak-state strength, maximum dilatancy, volumetric strain, and particle breakage as the bounding stress-ratio parameter k_b .

Figures 12-19 describe the comparisons between model predictions and test data for silica sand from Yu (2017a) and coral sand from Yu (2018) with different values of initial state parameter I_{ep}^0 . Model predictions and test data on the evolutions of stress ratio, volumetric strain, particle breakage and plastic work are shown in **Figs. 12-13** for silica sand at $p_0 = 1$ MPa with $e_0 = 0.798$ and 0.825, respectively. The difference in model predictions on the $\eta - \varepsilon_a$ relationship with and without particle breakage is marginal whereas the prediction on the volumetric strain for the proposed model with particle breakage is larger than that without particle breakage. The proposed model prediction for test data with particle breakage is overall better than that without particle breakage, especially for a low void ratio of 0.798. For a high confining pressure, as shown in **Figs. 14-16**, the volumetric contraction is underestimated by the model without particle breakage at $\varepsilon_a > 8\%$ but well predicted by the proposed model with particle breakage. In addition,

the evolution of particle breakage with respect to the axial strain or plastic work are well predicted by the proposed model with particle breakage.

As expected, coral sand with $e_0 = 0.798$ at $p_0 = 3$ MPa in **Fig. 17** exhibits more particle breakage than silica sand under the same condition in **Fig. 16**. In addition, the underestimation of volumetric strain predicted by the model without particle breakage becomes more obvious for coral sand in **Figs. 17-19**, whereas the proposed model with particle breakage can well capture the evolution of the stress ratio, volumetric strain and particle breakage, which would be attributed to the application of the BCSP, the corresponding void-ratio-pressure state parameter, and the breakage-state-dependent dilatancy and plastic modulus in the proposed model. Consequently, the proposed model can well capture the stress-strain relationship of crushable soils by the coupled influences of the contraction caused by particle breakage and dilatancy caused by particle rearrangement.

Discussion

In the triaxial test, the critical state of sand with particle breakage in the compression plane is a competition between the shrinkage due to particle crushing and the expansion due to particle rearrangement (Luzzani and Coop 2002; Hasanlourad et al. 2008). The developed model introduced the breakage-dependent void-ratio-pressure state parameter I_{ep} into dilatancy ratio and bounding stress ratio, which can reflect the state-dependent behaviors of crushable sand. As shown in **Figs. 20-21**, the state parameter I_{ep} is represented by a breakage-dependent state vertical wall (BSVW) that is formed by the projection of the predicted breakage-dependent deformation path to the BCSP. For the initial state parameter I_{ep}^0 smaller than one, as shown in **Fig. 20(a)**, the height of the BSVW approaches zero below the BCSP as the final critical state is gradually reached. For the initial state parameter I_{ep}^0 larger than one, as shown in **Fig. 20(b)**,

the height of the BSVW approaches zero above the BCSP as the final critical state is gradually reached. For coral sand, as shown in **Figs. 21(b)-21(c)**, critical state is not reached at the axial strain of 0.2, as the height of the BSVW is not zero. **Figs. 18(b) and 19(b)** also illustrate that the volumetric strain increment is still considerable, as the particle breakage continuously increases for coral sand at this condition.

Figures 22-23 present the evolutions of yielding surfaces, loading unit vector and plastic flow unit vector with particle breakage. The loading unit vector is always perpendicular to the yielding surface, whereas the plastic flow unit vector is not always perpendicular to the yielding surface. **Figs. 22(a)-22(b)** show that the plastic flow unit vector is approximately perpendicular to the yielding surface at its top point and close to the loading unit vector at the end of shearing process, which yields that the plastic volumetric strain increment is comparatively small. In contrast, **Figs. 23(a)-23(c)** show that the plastic flow unit vector is not perpendicular to the yielding surface at its top point, which illustrates that the plastic volumetric strain induced by particle breakage still increases at a considerable rate. These findings are in line with the model predictions as mentioned before.

It is significant for engineering applications to consider particle breakage and improve the predictions of the deformation and strength of geomaterials, especially for the infrastructures sustained high stress and/or large displacement, e.g. pile-driven engineering, high rockfill dam, etc. The framework in this study can provide a theoretical basis to analyze the stability of infrastructure engineering involving particle breakage when this model is implemented into finite element method or material point method, which will be investigated in future.

Conclusions

A constitutive model was proposed for sands under high pressure by considering the effect of grain

358 crushing on strength and deformation. The major conclusions of this research are summarized below:

- 359 (1) Based on the concept of the breakage-dependent critical state surface (BCSP), the void-ratio-pressure
360 state parameter is adopted to reflect the effect of particle breakage. The evolution of the current state
361 point with the BCSP during shearing process demonstrates the capability of the proposed state
362 parameter in reflecting the effects of particle breakage on state-dependent behaviors of sands under
363 high pressure.
- 364 (2) The breakage-dependent void-ratio-pressure state parameter is incorporated into Rowe's stress
365 dilatancy equation, bounding stress ratio and plastic modulus to reflect the influence of particle
366 breakage on the state-dependent characteristics. Based on the bounding surface plasticity framework
367 and the non-associated flow rule, a constitutive model considering the state-dependent and particle
368 breakage is established for silica and coral sands under high pressure.
- 369 (3) Effects of model parameters on the stress-strain relationship and evolution of particle breakage are
370 also investigated. Based on the comparisons between model predictions and test results, the proposed
371 model can better capture the evolution of particle breakage and its effects on the stress-strain
372 relationship, which is mainly attributed to the use of BCSP and breakage-dependent void-ratio-
373 pressure state parameter.

374 **Data Availability**

375 All data, models, and code generated or used during the study appear in the submitted article.

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Notations

The following symbols are used in this paper:

I_{ep} = Void-ratio-pressure state parameter;

I_{ep}^0 = Initial void-ratio-pressure state parameter;

p_0 = Initial confining pressure (unit: MPa);

p' = Mean effective stress (unit: MPa);

q = Deviatoric stress (unit: MPa);

p'_{cs} = Critical-state mean effective stress (unit: MPa);

p_a = Atmospheric pressure (unit: MPa);

σ'_1 and σ'_3 = Maximum and minimum principle stress, respectively (unit: MPa);

dp' and dq = Mean effective stress increment and deviatoric stress increment, respectively (unit: MPa);

$d\varepsilon_a$ = Axial strain increment (unit: %);

$d\varepsilon_v$ and $d\varepsilon_s$ = Volumetric strain and shear strain increments, respectively (unit: %);

$d\varepsilon_v^e$ and $d\varepsilon_s^e$ = Elastic volumetric and shear strain increments, respectively (unit: %);

$d\varepsilon_v^p$ and $d\varepsilon_s^p$ = Plastic volumetric and shear strain increments, respectively (unit: %);

n_v^f and n_s^f = Compression-related and shearing-related components of the loading unit vector, respectively;

n_v^g and n_s^g = Compression-related and shearing-related components of the plastic-flow unit vector,

respectively;

η = Stress ratio;

ϕ_{cs} = Critical state friction angle (unit: degree);

400 ϕ_m and ψ_m =Mobilized friction angle and dilatation angle, respectively (unit: degree);

401 e =Current void ratio;

402 e_0 =Initial void ratio;

403 e_{cs} =Critical state void ratio;

404 e_{cs0} =Initial critical state void ratio;

405 λ , e_{B0} , k_B and χ_B =Breakage-dependent critical-state parameters;

406 M_{cs} =Critical state stress ratio;

407 M_b =Bounding stress ratio;

408 S_b =Coefficients of bounding stress ratio;

409 k_b = Bounding stress-ratio parameter;

410 B_r =Relative breakage index (unit: %);

411 d =Dilatancy;

412 S_d =Coefficient of dilatancy ratio;

413 d_0 , α , \mathcal{G}_d , and k_d =Dilatancy parameters;

414 W_p =Plastic work (unit: MJ/m³);

415 χ_w =Breakage-energy parameter (unit: MJ/m³);

416 k_w =Breakage-energy parameter;

417 K_e and G_e =Elastic bulk modulus and elastic shear modulus, respectively;

418 G_0 =Elastic shear modulus parameter;

419 ν =Poisson's ratio;

420 H_p =Plastic modulus;

421 h_0 = Pressure-dependent plastic modulus parameter; and

422 χ_h and k_h = Plastic modulus parameters.

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691

Table 1. Values of initial state and model parameters for model presentations

Initial and material parameters	Basic values	Changed values
p_0 (MPa)	0.8	0.6, 1.2
e_0	0.8	0.7, 0.9
G_0	80	40, 160
ν	0.25	-
χ_w	7.847	-
k_w	1.686	-
λ	0.1	0.09, 0.11
e_{cs0}	1.598	-
k_B	0.046	-
χ_B	5.698	-
d_0	1.2	0.6, 2.4
k_d	0.2	0.1, 0.4
k_b	0.4	0.2, 0.8
h_0	10	5, 20

Table 2. Values of model parameters of silica sand and coral sand for model simulations

Material parameters	Silica sand	Coral sand
G_0	86.4	87.2
ν	0.25	0.25
M_{cs}	1.36	1.32
χ_w	7.847	4.820
k_w	1.686	3.228
λ	0.10	0.10
e_{B0}	1.598	1.850
k_B	0.046	0.302
χ_B	5.698	2.0408
d_0	1.52	1.20
k_d	0.13	0.25
k_b	0.15	0.12
χ_h	904.0	613.6
k_h	1.45	1.16

Figure Caption List:

Fig. 1. (Color) BCSL and state parameter in the compression plane: (a and b) silica sand; and (c and d) coral sand

Fig. 2. (Color) BCSL and state parameter in three-dimensional $e - B_r - p'$ space: (a and b) silica sand; and (c) coral sand.

Fig. 3. (Color) BCSL and state parameter in three-dimensional $e - W_p - p'$ space: (a and b) silica sand; and (c) coral sand.

Fig. 4. (Color) Influence of p_0 on model performance: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - \varepsilon_v$ planes, respectively.

Fig. 5. (Color) Influence of e_0 on model performance: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - \varepsilon_v$ planes, respectively.

Fig. 6. (Color) Influence of G_0 on model performance: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - \varepsilon_v$ planes, respectively.

Fig. 7. (Color) Influence of λ on model performance: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - \varepsilon_v$ planes, respectively.

Fig. 8. (Color) Influence of d_0 on model performance: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - \varepsilon_v$ planes, respectively.

Fig. 9. (Color) Influence of k_d on model performance: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - \varepsilon_v$ planes, respectively.

Fig. 10. (Color) Influence of k_b on model performance: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - \varepsilon_v$ planes, respectively.

Fig. 11. (Color) Influence of h_0 on model performance: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - \varepsilon_v$ planes, respectively.

Fig. 12. (Color) Predictions for silica sand at $I_{ep}^0 = 0.55$: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - W_p$ planes, respectively.

Fig. 13. (Color) Predictions for silica sand at $I_{ep}^0 = 0.67$: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - W_p$ planes, respectively.

Fig. 14. (Color) Predictions for silica sand at $I_{ep}^0 = 1.08$: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - W_p$ planes, respectively.

Fig. 15. (Color) Predictions for silica sand at $I_{ep}^0 = 1.25$: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - W_p$ planes, respectively.

Fig. 16. (Color) Predictions for silica sand at $I_{ep}^0 = 1.72$: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - W_p$ planes, respectively.

Fig. 17. (Color) Predictions for coral sand at $I_{ep}^0 = 1.92$: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - W_p$ planes, respectively.

Fig. 18. (Color) Predictions for coral sand at $I_{ep}^0 = 4.29$: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - W_p$ planes, respectively.

Fig. 19. (Color) Predictions for coral sand at $I_{ep}^0 = 7.8$: (a-d) $\eta - \varepsilon_a$, $\varepsilon_v - \varepsilon_a$, $B_r - \varepsilon_a$ and $B_r - W_p$ planes, respectively.

Fig. 20. (Color) Evolution of state vertical wall for silica sand: (a-c) $p_0 = 1, 2$ and 3 MPa, respectively.

Fig. 21. (Color) Evolution of state vertical wall for coral sand: (a-c) $e_0 = 0.798, 0.870$ and 0.924 , respectively.

Fig. 22. (Color) Evolution of loading and plastic flow unit vectors: (a-c) $p_0 = 1, 2$ and 3 MPa, respectively.

Fig. 23. (Color) Evolution of loading and plastic flow unit vectors: (a-c) $e_0 = 0.798, 0.870$ and 0.924 , respectively.













































