

1 Direct-write Nanocomposite Sensor Array 2 for Ultrasonic Imaging of Composites

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28 **Abstract**

29 To improve the ultrasonic imaging of composites, an all-printed nanocomposite sensor array
30 (APNSA) is developed using a direct-write approach. Individual sensing elements of
31 APNSA are inkjet printed by directly writing graphene/poly (amic acid) (PAA)-based
32 nanocomposite ink on Kapton film substrates, with an ultra-thin thickness of $\sim 1 \mu\text{m}$ only.
33 APNSA is morphologically tuned at a nano scale to be sensitive to acousto-ultrasonic waves
34 of a broad band regime. Each sensing element features a homogenous and consolidated
35 nanostructure, with which transient change of tunneling resistance between adjacent
36 graphene nanoplatelets in the polyimide (PI) matrix can be triggered when the element is
37 loaded with acousto-ultrasonic waves. The triggered quantum tunneling effect endows
38 APNSA with capability to perceive dynamic strains in a broadband regime with high fidelity
39 and accuracy. Compared with a conventional ultrasonic phased array which is of a low
40 degree of compatibility with composites, APNSA can be fully integrated with the inspected
41 composites. In conjunction with the use of the additively manufactured APNSA, ultrasonic
42 imaging of composites can be implemented, spotlighting a nature of full integration of
43 APNSA with composites for *in situ* structural health monitoring and anomaly detection, yet
44 without degrading the original integrity of the composites.

45

46 **Keywords:** Nanocomposite sensor array; Additive manufacturing; Ultrasonic imaging;
47 Composites structural health monitoring

48 **1. Introduction**

49 With the ability of directional scanning and high-precision signal acquisition, phased array
50 technique has secured its popularity in radar searching [1], sonar positioning [2], seismology
51 study [3], telecommunication [4], and biomedical imaging [5], as well as non-destructive
52 testing (NDT) [6, 7]. Particularly for NDT, with multiple, synchronized sensing elements, a
53 phased array features merits including wave focusing, steerable inspection and enhanced
54 signal-to-noise ratio, through which a broad region can be scanned, and rich information on
55 material defect or structural anomaly can be obtained.

56

57 Despite proven effectiveness when used for ultrasonic imaging of composite structure [8],
58 conventional ultrasonic phased arrays are encountering problematic issues. With a bulky and
59 unwieldy nature, phased arrays are of a low degree of coupling compatibility with inspected
60 structure [9], limited adaptation to curved or geometrically complex structural surfaces [10],
61 possible blind zones [11], and low inspection efficiency due to the need of manipulating
62 arrays back and forth along the inspected surface. In particular, the impossibility of
63 integrating an array with the inspected structure precludes the phased array-based inspection
64 from being extended from offline NDT to *in situ*, real-time ultrasonic imaging of composite
65 structure.

66

67 In the past decade, additive manufacturing has paved a promising way to develop innovative
68 electronics and devices [12-14], including sensing devices [15], transistors [16], flexible
69 radio frequency identification (RFID) [17] and battery electrodes [18], to name a few.
70 Amongst appealing additive manufacturing techniques, direct-write inkjet printing, by
71 directly depositing functional inks onto various substrates, has gained prominence towards
72 electronic device fabrication in a large-scale and cost-effective manner. With its high

73 automaticity and controllability, direct-write inkjet printing warrants ultrahigh fabrication
74 precision, and in the meantime allows the electronics to be tailor-made with specific patterns
75 and functionalities [19].

76

77 In the authors' previous attempts [20-23], nanocomposite-based ultrasonic sensors have been
78 developed, and proven to be applicable to various structures, with advantages including high
79 flexibility, ultralight weight, broadband responsivity (up to frequency of 1.6 MHz), and good
80 sensitivity to ultrasound signals that feature ultra-weak magnitudes (in the order of
81 microstrain or even smaller), along with significantly reduced producing cost. The sensors
82 leverage quantum tunneling effect formed in a nanoparticle-formed percolated network in
83 the sensor [24]. The tunneling effect is triggered when an acousto-ultrasonic wave traverses
84 the sensors, inducing dynamic alteration of tunneling resistance between adjacent electrical-
85 conductive nanofillers and leading to subtle changes in piezoresistivity of the sensors. Thus-
86 produced sensors manifest ultrafast sensing response and excellent sensing accuracy to
87 broadband acousto-ultrasonic waves.

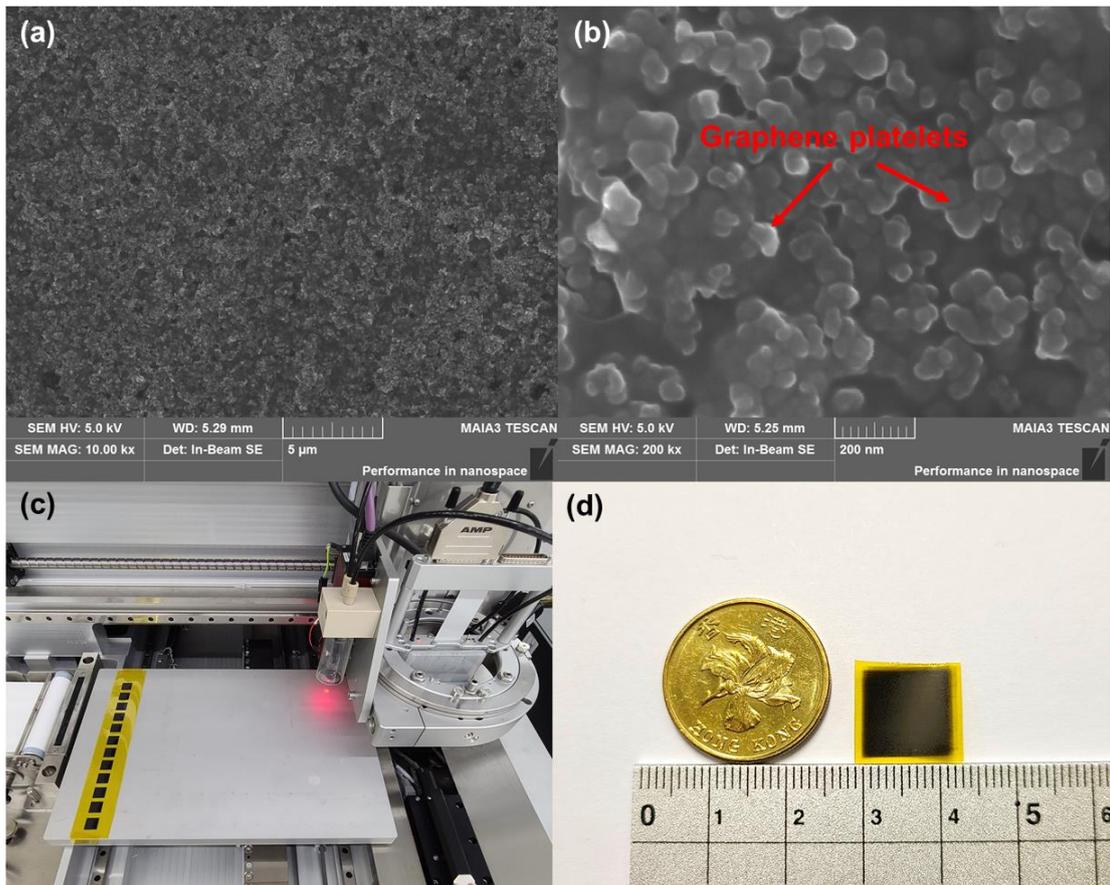
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89 Recognizing the deficiencies that conventional phased arrays are facing, and extending the
90 authors' continued endeavours in developing nanocomposite-inspired sensors, we develop
91 all-printed nanocomposite sensor array (APNSA) using a direct-write approach. APNSA is
92 fabricated via drop-on-demand inkjet printing, by directly writing graphene/PAA-based
93 nanocomposite ink on Kapton film substrates. With novel graphene/polyimide (PI) sensors
94 as individual sensing elements and by virtue of the quantum tunneling effect, APNSA is
95 functionalized to substitute conventional ultrasonic phased array which is of a low degree of
96 integrity with composites, for acquiring acousto-ultrasonic waves and implementing *in situ*
97 ultrasonic imaging of composites.

99 **2. Results and Discussion**

100 Individual sensing elements of APNSA are inkjet printed by directly writing graphene/poly
101 (amic acid) (PAA)-based nanocomposite sensing ink on a Kapton film substrate. Details of
102 graphene/PAA sensing ink and APNSA fabrication, morphological characterization, and
103 acousto-ultrasonic wave responsivity calibration are elaborated in the Supplementary
104 Material. The graphene/PI sensing elements of APNSA show a homogenous and
105 consolidated nanostructure (**Figures 1(a) and (b)**) and feature an ultra-thin thickness of ~ 1
106 μm only (**Fig. S1**). Benefiting from this, the charge carriers of neighbouring graphene
107 nanoplatelets are able to pass through the potential barrier, when the sensing element is
108 loaded with an acousto-ultrasonic wave even with an ultra-low magnitude. This triggers the
109 quantum tunneling effect that further alters the tunneling resistance between neighbouring
110 graphene nanoplatelets, in pace with the acousto-ultrasonic wave. Such a transient variation
111 of tunneling condition in the percolation network leads to the consequent change in
112 piezoresistivity of each sensing element of APNSA, endowing the sensing elements with
113 prominent capability for acquisition of broadband acousto-ultrasonic wave signals (**Figs. S3,**
114 **S4 and S5**). The number of sensing elements in an APNSA depends on specific applications,
115 and a paradigm of an APNSA with 12 sensing elements deployed on Kapton film is pictured
116 in **Fig. 1(c)**.

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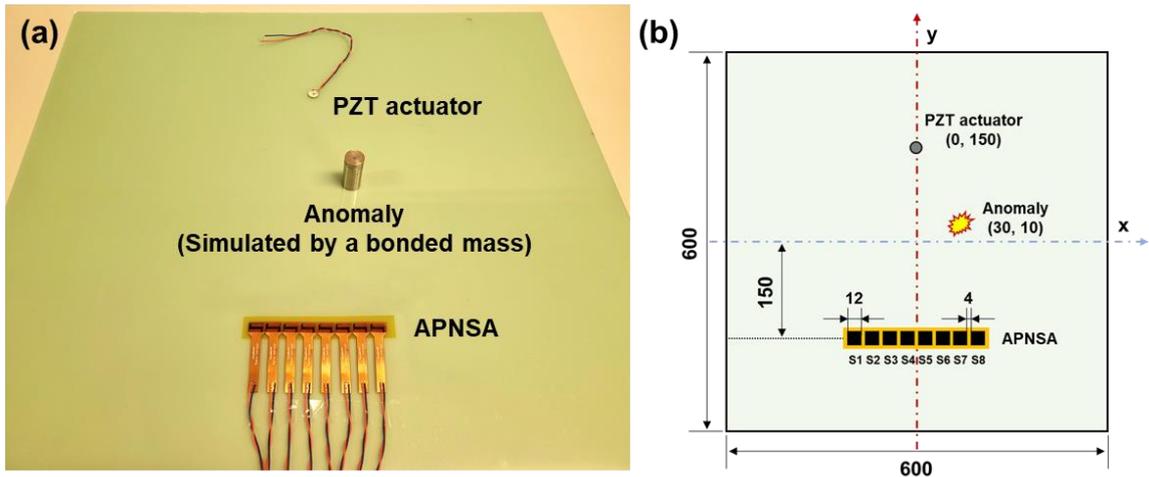
119 **Fig. 1.** Field emission scanning electron microscope (FESEM) image of graphene/PI
 120 sensing element of APNSA: (a) 10.00 k \times magnification; and (b) 200 k \times magnification; (c)
 121 APNSA on a Kapton film substrate, printed on a desktop inkjet printing platform; and (d) a
 122 typical graphene/PI sensing element of an APNSA.

123

124 With proven responsivity and sensing precision in responding to broadband acousto-
 125 ultrasonic wave signals, the fabricated APNSA is applied to implement *in situ* ultrasonic
 126 imaging for a glass fibre/epoxy composite laminate plate, pictured in **Fig. 2(a)**, as a proof-
 127 of-concept validation. An APNSA consisting of eight graphene/PI sensing elements (labelled
 128 as S1, S2, ..., S8) is surface-mounted on the plate, and a piezoelectric lead zirconate titanate
 129 (PZT) wafer (\varnothing 12 mm, 1 mm thick) is mounted on the plate surface as a wave actuator. The
 130 locations of the APNSA and PZT wafer on the plate are indicated in **Fig. 2(b)**. A steel
 131 cylinder (\varnothing 20 mm, 200 g weight) is bonded on the plate as a mock-up anomaly, at the

132 location of (30 mm, 10 mm), in **Fig. 2(b)**. The experimental system and measurement
 133 procedures remain the same as the responsivity calibration experiment. A five-cycle
 134 Hanning-windowed sinusoidal tone-burst at a central frequency of 100 kHz is applied to
 135 drive the PZT actuator, to generate a probing wave with wavelength (λ) of 37.2 mm in the
 136 laminate. For the APNSA, the shape effect of the sensing element on the sensing responsivity
 137 can be considered negligible. The element pitch (*i.e.*, distance between the centres of
 138 neighbouring sensing elements, denoted by l herein-after) has been pre-set as 16 mm during
 139 inkjet printing, which is smaller than the half wavelength (*i.e.*, 18.6 mm) of the generated
 140 probing wave, and this will ensure the detection resolution and avoid false results caused by
 141 spatial aliasing [25].

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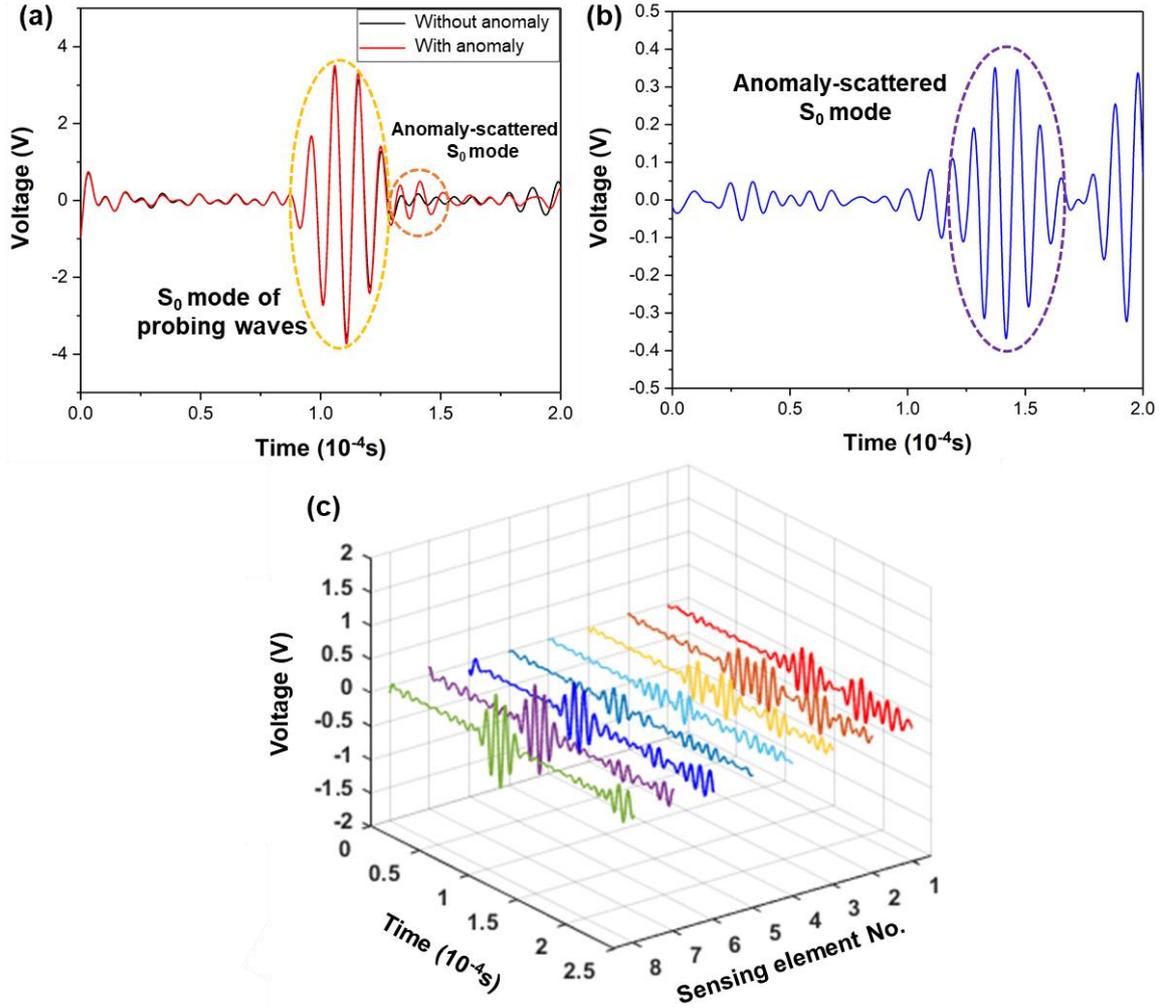
144 **Fig. 2.** (a) Photograph and (b) schematic of the glass fibre/epoxy composite laminate plate
 145 with APNSA and a mock-up anomaly (unit: mm).

146

147 **Figure 3(a)** presents representative signals captured by sensing element S1 of APNSA,
 148 before and after that the mock-up anomaly is introduced to the laminate plate. The S_0 (the
 149 zeroth-order symmetric plate wave mode guided by the laminate) wave mode of the probing
 150 wave can be perceived clearly in both cases. After introducing the mock-up anomaly, an

151 additional wave packet, following the original S_0 mode, is prominent which is classified as
 152 the anomaly-induced wave component in the sensing element-captured signal [26, 27]. For
 153 anomaly imaging, this additional wave component is extracted, **Fig. 3(b)**, and named the
 154 anomaly-scattered S_0 mode (S_0^{Anomaly}).

155



156

157

158 **Fig. 3.** (a) Wave signals captured by S1 of APNSA, before and after the mock-up anomaly
 159 introduced; (b) S_0^{Anomaly} in the signal captured by S1; and (c) S_0^{Anomaly} in signals captured by
 160 all the sensing elements of APNSA.

161

162 Analogously, the S_0^{Anomaly} is in turn extracted from the signal captured by each sensing
 163 element of APNSA, as shown in **Fig. 3(c)**. The *multiple signal classification* (MUSIC) – an
 164 array signal processing method for ultrasonic imaging [28, 29], is applied (**Fig. 4**). As
 165 indicated in **Fig. 4**, the actuator is placed at position (x_0, y_0) , and the m^{th} sensing element of
 166 APNSA ($S_m, m = 1, 2, \dots, 8$) is located at (x_m, y_m) . All extracted S_0^{Anomaly} are written as a
 167 matrix form [30], as

$$\mathbf{R}^{S_0^{\text{Anomaly}}}(t) = [r_1(t), \dots, r_m(t), \dots, r_8(t)]^T, \quad (1)$$

168 where $\mathbf{R}^{S_0^{\text{Anomaly}}}(t)$ denotes the matrix of S_0^{Anomaly} acquired by all elements of APNSA, and
 169 $r_m(t)$ signifies S_0^{Anomaly} captured via the m^{th} sensing element. Assuming that a scanning
 170 position in the inspection region is at (x, y) , the APNSA steering vector $\mathbf{A}(x, y)$ at this position
 171 can be defined as

$$\mathbf{A}(x, y) = [a_1(x, y), \dots, a_m(x, y), \dots, a_8(x, y)], \quad (2)$$

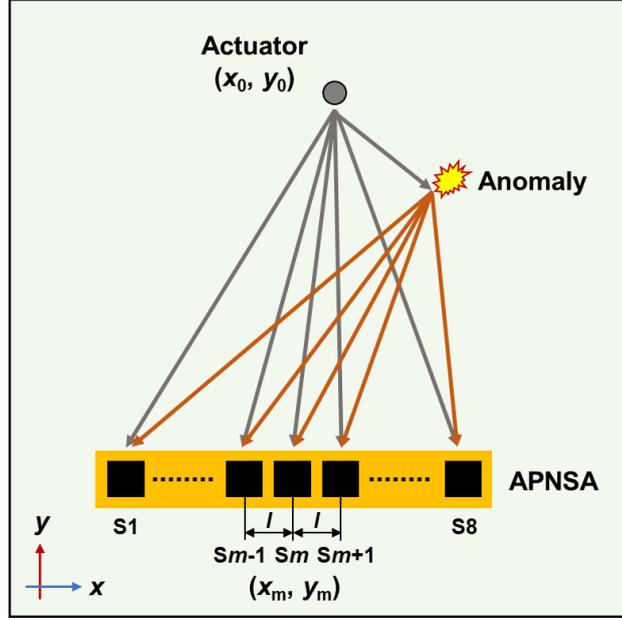
172 where

$$a_m(x, y) = e^{j\omega_0\tau_m}, \quad (3)$$

$$\tau_m = \frac{d_1 - d_m}{c}, \quad (m = 1, 2, \dots, 8) \quad (4)$$

$$d_m = \sqrt{(x_0 - x)^2 + (y_0 - y)^2} + \sqrt{(x - x_m)^2 + (y - y_m)^2}. \quad (5)$$

173 In Eqs. (3)-(5), $a_m(x, y)$ is the steering vector of sensing element S_m , and τ_m is the difference
 174 in propagation time between two signals captured by sensing element S1 and element S_m .
 175 d_m signifies the wave propagation distance from the actuator to the scanning position, and
 176 then to S_m . c is the propagation velocity of the probing waves with central frequency of ω_0 .
 177



178
179 **Fig. 4.** Use of MUSIC algorithm and APNSA for anomaly imaging.
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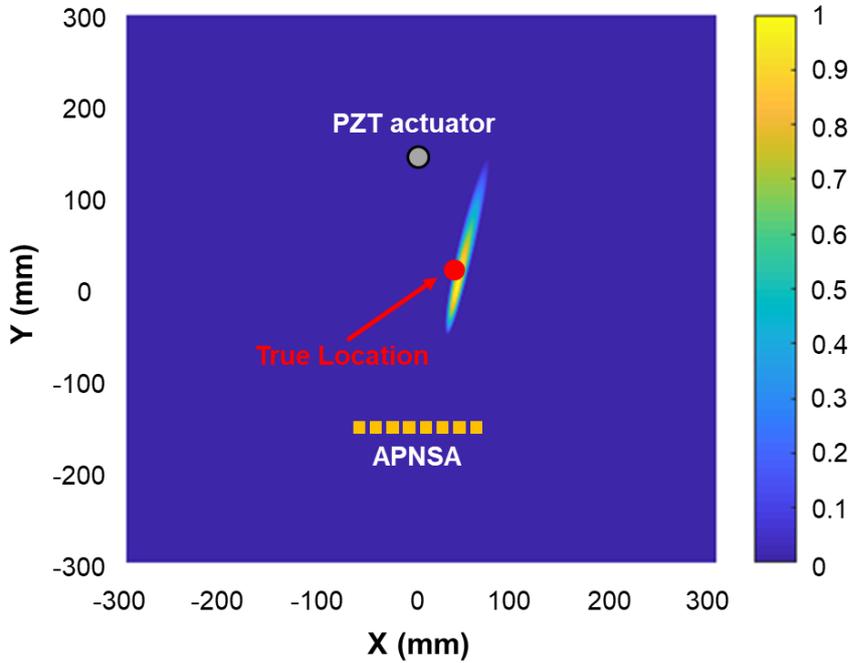
181 The covariance matrix of the array signals $\mathbf{R}^{S_0^{\text{Anomaly}}}(t)$ can be decomposed into
182 signal subspace \mathbf{U}_S and noise subspace \mathbf{U}_N via an eigenvalue decomposition. Based on the
183 orthogonality between these two subspaces, the pixel value of the spatial spectrum at (x, y) ,
184 $P_{\text{MUSIC}}(x, y)$, is formulated as

$$P_{\text{MUSIC}}(x, y) = \frac{1}{\mathbf{A}^H(x, y)(\mathbf{U}_N \mathbf{U}_N^H) \mathbf{A}(x, y)}. \quad (6)$$

185 Superscript H represents the complex conjugate transpose. By varying the scanning position
186 (x, y) , the spatial spectrum of the entire inspection region of the laminate is obtained. When
187 the scanning position matches the anomaly location, the steering vector $\mathbf{A}(x, y)$ is orthogonal
188 with regard to the noise subspace \mathbf{U}_N , and thus the denominator of Eq. (6) approaches 0,
189 resulting in a peak in the spatial spectrum that corresponds to the anomaly location. The
190 anomaly imaging result is shown in **Fig. 5**: the area with highest field value suggests the
191 location of the mock-up anomaly, which shows high coincidence with the true location,

192 demonstrating the great application potential of the developed APNSA towards *in situ*
193 composite structural health monitoring.

194



195

196 **Fig. 5.** Anomaly image obtained via MUSIC algorithm and APNSA.

197

198 **3. Conclusions**

199 The nanocomposite-based APNSA is developed, and fabricated via a direct-write additive
200 manufacturing approach. Leveraging graphene/PAA-based nanocomposite sensing ink,
201 novel graphene/PI sensors, as individual sensing elements of APNSA, are inkjet printed on
202 Kapton film substrates, with an ultra-thin thickness of $\sim 1 \mu\text{m}$ only and a homogenous and
203 consolidated nanostructure. When acousto-ultrasonic waves traverse APNSA, transient
204 change of tunneling resistance between adjacent graphene nanoplatelets in the PI polymeric
205 matrix is triggered, endowing APNSA with ultra-sensitive responsivity to dynamic strains in
206 a broadband regime. APNSA can be fully integrated with the inspected composite structure,
207 without degrading its original structural integrity – a task that is challenging to be fulfilled

208 using conventional ultrasonic phased arrays. With a high degree of compatibility with the
209 host structure, the APNSA manifests proven effectiveness in performing anomaly imaging
210 of composite laminates, in lieu of conventional ultrasonic phased arrays with insufficient
211 structural compatibility, limited surface adaptation, and low inspection efficiency,
212 highlighting its alluring application prospects towards *in situ* structural health monitoring of
213 composites.

214

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