

Short-term Prediction of Wind Power and Its Ramp Events based on Semi-supervised Generative Adversarial Network

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Abstract: Short-term predictions of wind power and its ramp events play a critical role in economic operation and risk management of smart grid. This paper proposes a hybrid forecasting model based on semi-supervised generative adversarial network (GAN) to solve the short-term wind power outputs and ramp event forecasting problems. In the proposed model, the original time series of wind energy data can be decomposed into several sub-series characterized by intrinsic mode functions (IMFs) with different frequencies, and the semi-supervised regression with label learning is employed for data augmentation to extract non-linear and dynamic behaviors from each IMF. Then, the GAN generative model is used to obtain unlabeled virtual samples for capturing data distribution characteristics of wind power outputs, while the discriminative model is redesigned with a semi-supervised regression layer to perform the point prediction of wind power. These two GAN models form a min-max game so as to improve the sample generation quality and reduce forecasting errors. Moreover, a self-tuning forecasting strategy with multi-label classifier is proposed to facilitate the forecasting of wind power ramp events. Finally, the real data of a wind farm from Belgium is collected in the case study to demonstrate the superior performance of the proposed approach compared with other forecasting algorithms.

Highlights

Wind power prediction problem is formulated as a min-max game based on GAN.

Semi-supervised regression is used for the point prediction of wind power.

A double objective model is designed for data augmentation and feature extraction.

A self-tuning strategy is proposed for forecasting of wind power ramp events.

Keywords: Generative adversarial network; semi-supervised regression; wind power forecasting; wind power ramp event; renewable energy.

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1 Introduction

2 1.1 Motivation

3 As a clean, green and environmentally friendly renewable energy resource, wind energy has
4 developed rapidly in recent years [1]. The penetration of wind energy poses significant challenges to the
5 economic operation, reliability and real-time control of electrical power and energy system [2]. Statistics
6 in [3] reported that global installation capacity of wind power has reached 597GW in 2018, with an
7 increase of 9.1% over last year. Nevertheless, because of high volatility and intermittency of wind energy,
8 especially for large and sudden ramp events, various energy storage systems and fast hydropower plants
9 should be utilized as power reserves to mitigate the fluctuating wind generation outputs for real-time
10 electricity supply demand balance [4]. Hence, developing accurate and reliable wind energy prediction
11 techniques has become a common priority for the energy scheduling of dispatchable power sources to
12 accommodate large-scale wind farms in power grids, thereby increasing wind energy's contribution to
13 global electrical power supply [5]-[6].

14 Wind power ramp prediction is a challenging problem and has received great attentions in recent
15 years, as large forecasting deviations of wind power or misidentification of ramp events would exacerbate
16 the smart grid reliability and operations. The wind power ramp event is referred as a suddenly-increasing
17 or decreasing fluctuation of wind power within a short-time period, and these events usually come from
18 extreme atmospheric phenomena, such as thunderstorms, cyclones, wind gusts or low-level jets [7]. Wind
19 power ramps can be divided into different types and characterized by their ramping direction, duration,
20 and intensity. The basic types include ramp up and ramp down events. Pitch angle control of wind turbines
21 or energy storage technology can be used to avoid the imbalance between power generation and load
22 when a ramp up event occurs, thereby reducing wind energy curtailment. To address a ramp down event,
23 system operators can regulate the power outputs of dispatchable generators and energy storage systems
24 to compensate the power shortage caused by sudden wind power reductions [8]. Integrating high-
25 penetration wind energy into smart grid urgently requires accurate wind energy prediction and ramp event
26 identification [8]. Therefore, this paper aims to address the short-term prediction of wind power and its
27 ramp events based on the advanced generative adversarial network.

28 1.2 Relevant Background

29 The researches on point prediction of wind power can be classified into three categories: physical
30 methods, mathematical statistical methods, and machine learning algorithms [5]. Physical methods focus
31 on establishing a mathematical relationship between meteorological, environmental and geographical

1 information and wind power outputs. The meteorological, environmental and geographical information
2 are usually collected from numerical weather prediction (NWP) systems, including atmospheric pressure,
3 temperature, wind direction, wind farm location and terrain [9]. A hybrid model combining NWP and
4 Gaussian processes was proposed in [10] for short-term forecasting of wind energy, and the forecasting
5 results of the hybrid approach was comprehensively tested. As NWP models often require a large amount
6 of meteorological information and computing resources, physical methods are generally not applicable
7 to short-term wind energy forecasting [4]. Statistical methods are developed to formulate a mathematical
8 relationship between the historical wind power time-series and future forecasting values. Typical
9 statistical methods include autoregressive integrated moving average model (ARIMA) [11],
10 autoregressive model [12], Kalman filter (KF) [13]-[14], Bayesian learning [15], Gaussian process [10].
11 Fei *et al.* in [16] proposed a forecasting model combining empirical mode decomposition (EMD) and
12 ARIMA, and the prediction performance in several simulation examples was tested. In [17], an adaptive
13 hybrid model based on variational mode decomposition (VMD), ARIMA and deep neural network for
14 wind speed forecasting was designed. ARIMA model was built to predict regular component decomposed
15 by VMD. However, most of statistical methods are often modeled as simplified linear functions, so the
16 prediction performance of statistical models may be largely limited.

17 Recently, various machine learning algorithms have been developed for wind energy forecasting. In
18 order to address the classification, feature extraction and nonlinear regression problems in wind energy
19 prediction, lots of machine learning techniques are presented [18]-[30]. Typical machine learning
20 algorithms include support vector machine (SVM) [18], artificial neural network (ANN) [19]-[20],
21 neuron-fuzzy network [21], extreme learning machine (ELM) [22]-[23], random vector functional link
22 network (RVFLN) [24], recurrent neural network (RNN) [25], long short term memory network (LSTM)
23 [26] and convolutional neural network (CNN) [27]. The study in [27] and [28] designed two structures
24 based on the deep CNN and deep belief network (DBN) to achieve the accurate forecasting of solar
25 photovoltaic and wind power outputs, respectively. Extensive studies in [19]-[26] have demonstrated that
26 the prediction models based on traditional backward propagation mechanism have several problems, such
27 as over-fitting and be prone to local minimum. In order to solve these problems, heuristic optimization
28 algorithms have been used, such as genetic algorithm and particle swarm optimizer [29]. In general, these
29 machine learning-based models typically have better forecasting results than the physical and statistical
30 methods due to their powerful feature learning capabilities [28]. **Moreover, various signal decomposition**
31 **techniques, such as wavelet transformation (WT) [27], wavelet packet decomposition (WPD) [26], EMD**
32 **[16], ensemble empirical mode decomposition (EEMD), and VMD [20], have been used along with ANN,**
33 **CNN, LSTM or other machine learning algorithms to cope with the wind power time series a variety of**

1 irregularities [30].

2 Due to the intrinsic fluctuation and volatility of wind speed, the grid-connected wind power poses a
3 great threat to the economic and secure operation of smart grid, especially when the wind speed undergoes
4 a large ramp event. So far, wind power ramp forecasting methods can fall into two categories: indirect
5 forecasting and direct forecasting methods [7]. In the direct methods, one or several parameters related
6 to wind power ramp events, such as the ramp rate and duration, can be forecasted directly on the basis of
7 historical ramp events. In [31], a data mining approach was proposed for the direct ramp event forecasting
8 (REF), and a feature selection model based on mutual information was employed to optimize the SVM
9 classifier inputs. In [32], a probabilistic model was proposed to provide a suitable uncertainty estimation
10 associated with the forecasting of a ramp event based on the NWP information. Nevertheless, these direct
11 methods may lead to a large prediction bias when historical ramp events are incomplete [8].

12 For the indirect methods, the deterministic point forecasting model of wind power is performed and
13 then its ramp events can be extracted latterly [33]-[35]. An ANN network was established in [33] for the
14 short-term wind power prediction under different operational scenarios, so as to extract wind power ramp
15 statistics on the ramp swing, ramp start time and ramp duration. A feature mining technique was presented
16 in [34] to predict wind power ramp events, and the competitive and robust performance within hourly
17 forecasting horizon were validated with existing benchmarking methods. A hybrid indirect REF model
18 based on support vector regression was discussed and assessed using various absolute error metrics in
19 [35]. Besides, an optimized swing door algorithm based on dynamic programming was developed in [36]
20 to improve the REF capability of wind power and reduce the missing rate of ramp events. Because of its
21 superior forecasting accuracy and applicability [8], the indirect REF method is adopted with a self-tuning
22 forecasting strategy in this study to solve the forecasting problem of wind power ramp events.

23 *1.3 Contribution and Organization of this Paper*

24 In this paper, a hybrid forecasting model is proposed based on generative adversarial network (GAN)
25 and semi-supervised regression for the short-term forecasting of wind power and its ramp events. GAN
26 algorithm has been highly concerned and extensively applied in the technical fields of image processing,
27 scenario generation, and speech synthesis [37]. The GAN exhibits a strong generalization capability to
28 generate virtual samples similar to real samples. In the proposed method, the semi-supervised regression
29 with label learning is integrated into the GAN framework for data augmentation to extract intrinsic non-
30 linear and dynamic behaviors from wind power time series, and the improved performance for point
31 prediction of wind power can be obtained. The main contributions of this paper can be summarized as
32 follows:

1 (1) The problem of wind power forecasting (WPF) is formulated as a min-max game based on the
2 GAN framework. This formulation is utilized to extract the potential statistical distribution and features
3 in the wind power time series from labeled samples and unlabeled virtual samples. Hence, the under-
4 fitting problem in the traditional GAN training process can be solved.

5 (2) A hybrid point forecasting method based on the GAN and semi-supervised regression is proposed
6 to address the WPF and REF problems. The improved GAN uses the generative model to expand the
7 training samples, while the discriminative model with a semi-supervised regression layer is redesigned
8 to minimize the dual-objective GAN function, thereby improving the prediction accuracy of wind power.

9 (3) A self-tuning forecasting strategy with rolling horizon procedures is proposed to adjust the REF
10 results of wind power ramp events in the future horizons based on the updated real-time information. A
11 multi-label classifier is further employed to analyze wind power ramp characteristics and assign multiple
12 labels to different types of ramp events based on ramp rate and given thresholds. The self-tuning strategy
13 with multi-label ramp event features can facilitate the semi-supervised GAN to improve the forecasting
14 accuracy of wind power ramp events.

15 The feasibility and effectiveness of the proposed forecasting method are verified in real wind power
16 from a wind farm in Belgium. The rest of this paper is organized as follows: Section 2 introduces the
17 algorithm framework and models of the classic GAN. Sections 3 and 4 propose GAN-based WPF and
18 self-tuning REF frameworks, respectively. Section 5 describes the overall implementation steps for GAN-
19 based WPF and self-tuning REF approaches. Then, the overall indices for evaluating the forecasting
20 performance are introduced in Section 6. Section 7 provides case studies and comparative analysis, and
21 the conclusions is given in Section 8.

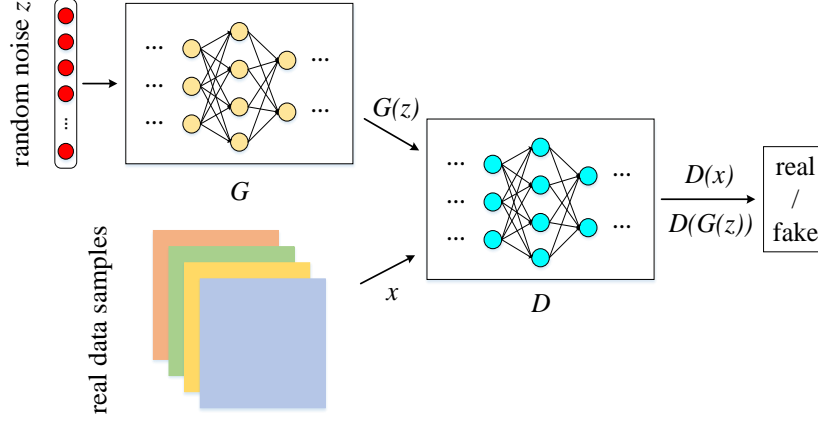
22 **2 Generative Adversarial Network**

23 As a typical unsupervised deep learning method, the GAN algorithm has been extensively used to
24 solve the problems of image processing, feature extraction and model recognition [37]-[38]. In the GAN
25 framework, the generative model and the discriminative model compete with each other to produce
26 optimal forecasting results. This Section mainly presents the detailed structure of GAN algorithm and its
27 calculation processes.

28 *2.1 Algorithm Framework of GAN*

29 Inspired by the zero-sum game, Goodfellow first proposed a GAN structure including a generative
30 model and a discriminative model in 2014 [37]. The generative model is used to extract the potential
31 complex distribution in real data samples and generate virtual samples, and the discriminative model is

1 used to identify whether the input comes from a real sample or a virtual sample. Generative model and
 2 discriminative model are continually optimized through min-max games to increase their ability to
 3 generate or discriminate. The basic architecture of the GAN is presented in Fig. 1. In this figure, G and
 4 D correspond to the generative model and discriminative model in the GAN, respectively.



5
 6 **Fig. 1** Basic algorithm structure of GAN

7 As shown in Fig. 1, both the real sample x and the virtual sample $G(z)$ generated by the generative
 8 model can be used as the input to the discriminative model. If the input is $G(z)$, the output of the
 9 discriminative model is marked as "0". If the input is the real sample x , the output of the discriminative
 10 model is marked as "1". It can be seen that the discriminative model is essentially a binary classifier. The
 11 main objective of generative model is to mimic the complex distribution of real sample data so as to
 12 achieve the purpose of deceiving the discriminative model. Thus, G and D are actually a dynamic game.
 13 In the most ideal state, G can generate a virtual sample $G(z)$, and it is hard for D to decide whether the
 14 virtual sample generated by G is true or not [38].

15 2.2 Min-Max Game of GAN Models

16 The objective function of the discriminative model is easy to define because its objective is relatively
 17 simple, that is, the output of discriminative model corresponds to 1 and 0 when the input is x and $G(z)$,
 18 respectively. In general, the training process of discriminative model minimizes the following objective
 19 function based on the cross entropy [38], as follows:

$$20 \quad L_D = -\frac{1}{2} \mathbb{E} \cdot \log[D(x)] - \frac{1}{2} \mathbb{E} \cdot \log[1 - D(G(z))] \quad (1)$$

21 where x and z represent real sample and random noise, respectively; \mathbb{E} stands for an expectation.

22 The goal of the generative model is to mimic the complex distribution in real data by minimizing
 23 the objective function in Eq. (2), so as to achieve the purpose of making $D(G(z))$ close to 1:

$$24 \quad L_G = \frac{1}{2} \mathbb{E} \cdot \log[1 - D(G(z))] \quad (2)$$

1 It can be seen from Eq. (1)-(2) that L_D and L_G can constitute a dynamic min-max optimization
 2 game [39], as follows:

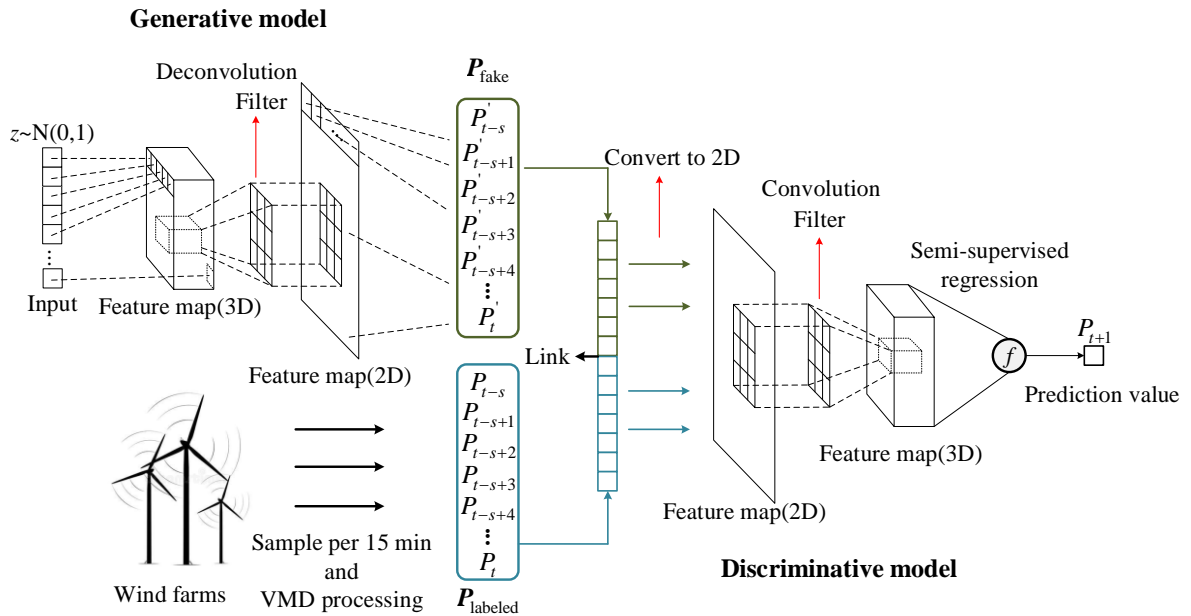
$$3 \min_G \max_D V(D, G) = E \cdot \log[D(x)] + E \cdot \log[1 - D(G(z))] \quad (3)$$

4 In general, the generative model and discriminative model in the GAN are alternately optimized so
 5 that they can reach the stable state of Nash equilibrium [37].

6 3 GAN Based Wind Power Forecasting Approach

7 3.1 GAN Prediction Structure

8 The proposed prediction structure hybridizes different techniques for signal decomposition, sample
 9 generation, feature extraction and alternative training, as shown in Fig. 2. Firstly, the VMD is employed
 10 to decompose raw wind power time series into several intrinsic mode functions (IMFs). Then, the GAN
 11 generative model is used with linear layers, up-pooling layers and deconvolution layers to generate virtual
 12 wind power time series $P_{\text{fake}} = \{P'_{t-s+1}, P'_{t-s+2}, \dots, P'_t\}$ for capturing data distribution characteristics of wind
 13 power. Furthermore, the GAN discriminative model utilizes convolution and pooling operations to
 14 extract nonlinear features hidden in the wind power time series, and the semi-supervised regression
 15 is employed to forecast the wind power in the following horizons. Finally, an alternative training process is
 16 used to update parameters of GAN towards their optimal states for minimizing forecasting errors.



17 **Fig. 2** The proposed semi-supervised regression GAN structure

19 3.2 Variational Mode Decomposition

20 Original wind power time series collected from real wind farms always exhibit strong nonlinearity

1 and irregular fluctuations. These features will degrade the accuracy of WPF and REF results. In this study,
2 a VMD technique is adopted to decompose the original wind power time series into different variational
3 modes u_k with limited bandwidth [17]. The VMD is an effective technique for the frequency domain
4 decomposition of signals, especially for processing nonlinear and non-steady signals [17]. Different from
5 the cyclic screening stripping used by EMD [16], the VMD can shift the signal decomposition process
6 into variational modes so as to achieve the adaptive decomposition of wind power time series based on
7 frequency domain characteristics of the decomposed signals, which is beneficial to reduce the impacts of
8 data noise and outliers. Generally, these decomposed modes form a set $\{\mathbf{u}_k\} = \{u_1, u_2, \dots, u_k\}$ and each
9 mode in the set can be defined as follows:

$$10 \quad u_k(t) = A_k(t) \cos(\phi_k(t)) \quad (4)$$

11 where, $A_k(t)$ represents the instantaneous amplitude; $\phi_k(t)$ represents the instantaneous phase; k is
12 the number of modes.

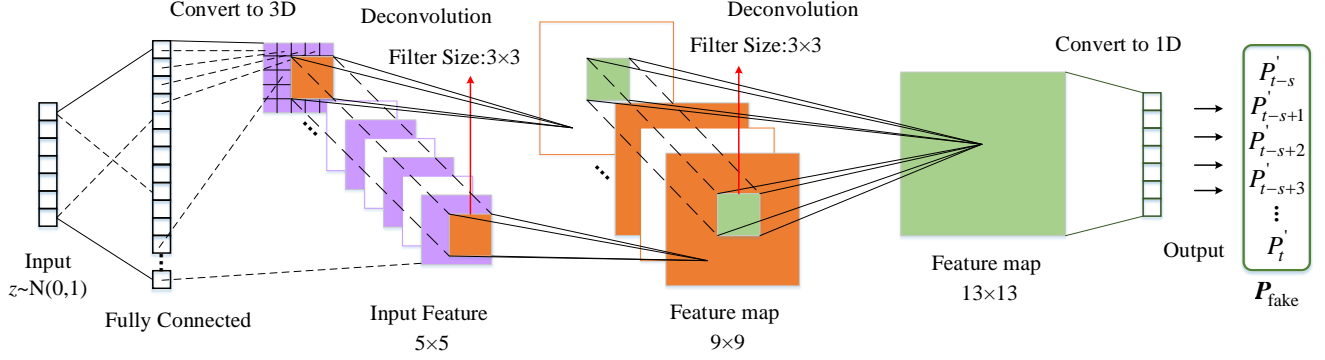
13 There is a right number k of mode function corresponding to different original signals. In this study,
14 the number of modes is set to 3 according to setting rules in [20]. Consequently, the original wind power
15 series can be adaptively processed and decomposed into multiple sub-series with lower uncertainties
16 based on the VMD. In the following, an independent GAN model for each sub-series will be developed
17 to extract the inherent features of time series.

18 *3.3 Sample Generation with Generative Model*

19 Deep learning usually has a deep ANN structure with many model parameters, and massive training
20 samples are required to make the algorithm converge. Nevertheless, collecting massive samples is very
21 time consuming and expensive [30]. On the other hand, traditional sample generation techniques usually
22 use uniform sampling, which is essentially the same as the original sample [38]. Therefore, a new sample
23 generation technique is required to expand the training samples for enhancing the generalization ability
24 of deep learning algorithms.

25 CNN algorithm is adopted in the generative model to obtain virtual samples, as the CNN has better
26 feature extraction capability and less model parameters with the weight sharing technique. However, the
27 CNN cannot be directly used for signal processing on the time series of wind power data and noise data
28 because these time series data is usually one-dimensional. To this end, a data dimension conversion
29 technique is adopted in this paper to solve this problem. In this way, the basic structure of GAN generative
30 model can be described as follows: 1) Converting one-dimensional data samples into two-dimensional
31 image samples, and taking the samples as the inputs to the convolution layer; 2) Mapping multiple low-
32 dimensional images using several transposed convolution layers to the high-dimensional data space in

1 order to mimic the complex distribution of real samples; 3) Converting these two-dimensional image
 2 features into one-dimensional data to match the input dimension of the discriminative model; (4) Sending
 3 the virtual samples \mathbf{P}_{fake} and real samples $\mathbf{P}_{\text{labeled}}$ to the GAN discriminative model. The multi-layer
 4 architecture of the generative model in the GAN is displayed in Fig. 3.



5
 6 **Fig. 3** Generative model architecture in the GAN

7 The primary objective of generative model is to mimic the complex distribution of real samples in
 8 an unsupervised manner. Therefore, the GAN generative model can generate a deceptive virtual sample
 9 according to the random noise [37]. The objective function of the unsupervised learning is expressed as:

$$L_G = \| E \cdot f(\mathbf{P}_{\text{fake}}) - E \cdot f(\mathbf{P}_{\text{labeled}}) \|^2 \quad (5)$$

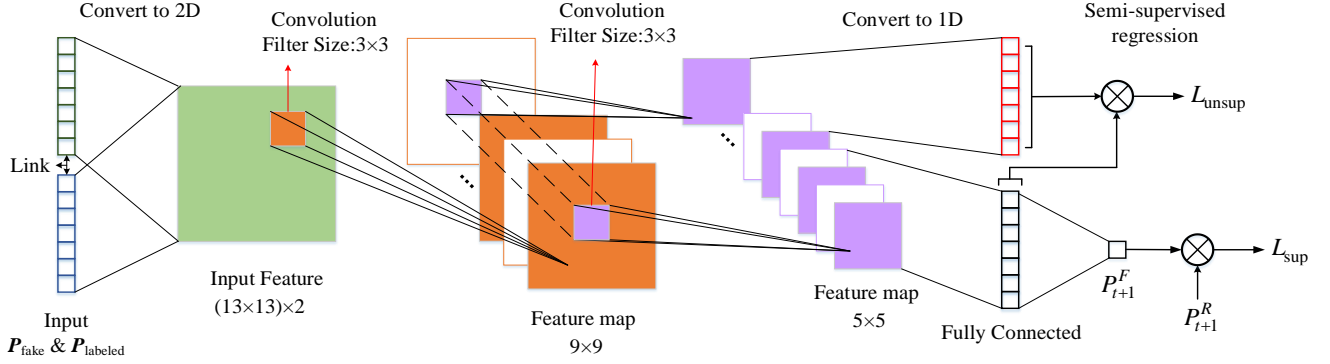
11 where $f(\mathbf{P}_{\text{fake}})$ and $f(\mathbf{P}_{\text{labeled}})$ denote the output of an intermediate layer of the discriminative model;
 12 \mathbf{P}_{fake} and $\mathbf{P}_{\text{labeled}}$ represent virtual wind power series and labeled wind power series, respectively.

13 By iteratively minimizing L_G in Eq. (5), the statistical features of the virtual samples and original
 14 samples tend to be more and more similar. These generated virtual samples can be viewed as an extension
 15 of the real samples, which can be utilized again to train the GAN model structure and parameters. Thus,
 16 the problem in wind power prediction scenarios, i.e., the training samples are limited, can be handled.

17 3.4 Feature Extraction with Discriminative Model

18 Furthermore, a modified discriminative model with semi-supervised regression [39] is proposed to
 19 form the nonlinear mathematical relationship functions between the historical time-series data and future
 20 prediction values of wind power. The modified discriminative model is illustrated in Fig. 4 and can be
 21 explained as: 1) Taking the virtual samples and the real wind power samples of wind power data as the
 22 inputs to the discriminative model; 2) Converting the inputs samples into a feature map; 3) Performing
 23 the convolution and pooling operations to obtain a high-dimensional characteristic representation of the
 24 input samples; 4) Finally, the regression layer is connected to the fully connected layer at the end of
 25 discriminative model to achieve nonlinear regression of the wind power data to obtain WPF results. It is
 26 worth noting that the outputs of the discriminative model is the prediction results of wind power, instead

1 of binary classification results in the basic GAN discriminative model.



2
3 **Fig. 4** Discriminative model architecture in the GAN

4 The proposed discriminative model includes a feature extraction layer and a regression layer. The
5 feature extraction layer uses an unsupervised learning technique while the regression layer performs
6 with a supervised learning mechanism [5]. In order to enhance the regression capability of the developed
7 discriminative model, a dual-objective optimization model is implemented with alternative training, and
8 it can be expressed as follows,

9
$$L_D = L_{\text{unsup}} + L_{\text{sup}} \quad (6)$$

10
$$L_{\text{unsup}} = -\|E \cdot f(P_{\text{fake}}) - E \cdot f(P_{\text{labeled}})\|^2 \quad (7)$$

11
$$L_{\text{sup}} = E \cdot (P_{t+1}^F - P_{t+1}^R)^2 \quad (8)$$

12 where P_{t+1}^F and P_{t+1}^R represent the wind power prediction results and the real value at next time instant;
13 P_{labeled} and P_{fake} indicate labeled wind power series and virtual wind power series, respectively.

14 It can be found that Eq. (7) is an unsupervised loss function to make the statistical distribution of
15 virtual samples and real samples as dissimilar as possible. Eq. (8) is the supervised loss function, which
16 is devoted to quantitatively assess the statistical deviations of the real wind power data as well as its
17 predicted values. In other words, the regression minimization of loss function in (8) is the realization of
18 the short-time prediction of wind power. It can be observed from Eq. (5) and Eq. (6) that the objective
19 functions of GAN generative and discriminative models are competing to form a min-max game [39].
20 With the aid of virtual samples in the GAN generative model, the discriminative model can more readily
21 to find the potential features in the original wind power samples, making the GAN predictions closer to
22 their true values. Up to date, the alternative training process is generally used for well-training of the
23 GAN, as detailed in the next Section.

24 **3.5 Alternative Training Process**

25 The GAN usually uses an alternative training method [37] to form a min-max game between GAN
26 generative and discriminative models, thereby iteratively updating the model parameters of the GAN. In

1 this paper, an alternative training with adaptive moment estimation optimizer is applied to train the whole
 2 network of GAN. The training steps are given as follows:

3 Step 1: A set of noise vectors is generated and used as the input to the generative model, thereby
 4 obtaining a set of generated virtual samples;

5 Step 2: The virtual samples and their corresponding real samples of wind power are sent to the GAN
 6 discriminative model, and then the wind power prediction results can be obtained with semi-supervised
 7 regression;

8 Step 3: The errors of each layer in the discriminative model can be obtained using Eq. (6)-(8), and
 9 the parameters of discriminative model are updated with the following formula:

$$10 \quad \mathbf{w}_i = \mathbf{w}_{i-1} - \alpha_i \mathbf{m}_i / (\sqrt{\mathbf{v}_i} + \varepsilon) \quad (9)$$

$$11 \quad \mathbf{b}_i = \mathbf{b}_{i-1} - \alpha_i \mathbf{m}_i / (\sqrt{\mathbf{v}_i} + \varepsilon) \quad (10)$$

12 where, subscript i indicates the number of iterations; \mathbf{w}_i and \mathbf{b}_i represent the weight vector and bias
 13 vector, respectively; \mathbf{m}_i and \mathbf{v}_i represent first-order and second-order moment estimation vectors; α_i
 14 is the learning rate and ε is a parameter used to prevent denominator from being equal to zero. In each
 15 iteration, \mathbf{m}_i , \mathbf{v}_i and α_i can be updated as follows:

$$16 \quad \mathbf{m}_i = \beta_1 \mathbf{m}_{i-1} + (1 - \beta_1) \cdot \partial L_i / \partial \mathbf{w}_i \quad (11)$$

$$17 \quad \mathbf{v}_i = \beta_2 \mathbf{v}_{i-1} + (1 - \beta_2) \cdot (\partial L_i / \partial \mathbf{w}_i)^2 \quad (12)$$

$$18 \quad \alpha_i = \alpha_0 \cdot \sqrt{1 - (\beta_2)^i} / [1 - (\beta_1)^i] \quad (13)$$

19 where β_1 and β_2 represent two parameters of exponential decay rate and their values are respectively
 20 set to 0.9 and 0.999; The initial learning rate α_0 is set to 10^{-3} , and then the parameter α_i can be online
 21 adjusted with the increased number of iterations;

22 Step 4: Given a GAN discriminative model, the regression errors are estimated and back-propagated
 23 to the generative model so that the parameters of generative model can be updated once;

24 Step 5: Collect the next batch of training samples and repeat Steps 1-4 until all raw training samples
 25 of wind power are traversed once;

26 Step 6: If the number of iterations reaches the preset value or the prediction errors is less than a
 27 certain threshold, the alternative training process should be ended at once. Otherwise, repeat Steps 1-5
 28 once again to update the model parameters of GAN.

29 It can be found from algorithm analysis that the distribution of virtual samples from the generative
 30 model is closer to the statistical distribution of real wind power samples, which helps the discriminative
 31 model to find its global optimal state. Meanwhile, the regression errors evaluated from the discriminative

1 model can reversely update the algorithm parameters of the generative model. The GAN generative and
2 discriminative models are alternatively optimized to achieve a Nash equilibrium in a semi-supervised
3 manner. Consequently, the point prediction results of short-term wind power based on the GAN can be
4 obtained.

5 **4 Multi-Step Self-Tuning Strategy for Wind Power Ramp Event Forecasting**

6 Wind power ramp events are generally characterized by rapid and sharp fluctuations in wind power.
7 Due to the high and sudden rate of power change within a short period of time, the REF problem of wind
8 power is a substantially challenging issue [8]. Here, the wind power ramp rate can be defined as follows:

$$9 \quad S_r = \frac{P_{t_{\text{end}}} - P_{t_0}}{t_{\text{end}} - t_0} \quad (14)$$

10 where $t_{\text{end}} - t_0$ represents a given time interval and is set to 60 min in this study; P_{t_0} and $P_{t_{\text{end}}}$ denote
11 the wind power outputs at time t_0 and t_{end} ; S_r is the ramp rate in a time interval, and is considered to
12 be a ramp event when it is larger than a given threshold. The wind power ramp forecasting plays an
13 important role in the energy management and dispatch of modern power systems with high wind energy
14 penetration. In this paper, based on the proposed semi-supervised learning driven GAN algorithm for
15 wind power forecasting in Section 3, a multi-label classifier is designed for different types of wind power
16 ramp events to facilitate the REF performance of wind power.

17 *4.1 Self-Tuning Forecasting Strategy with Rolling Horizon Procedures*

18 Traditional multi-step forecasting strategies utilize the forecasted results at the prior time, instead of
19 actual wind power values, to implement a point prediction at the future time. These strategies would lead
20 to accumulative forecasting errors and the deteriorated performance with the forward horizons [22],[28].
21 In this paper, a self-tuning REF strategy with rolling horizon procedures is proposed to utilize the updated
22 real-time data of wind power for tuning the ramp rate of the predicted ramp events in a rolling horizon
23 mode. This strategy can effectively improve the REF prediction accuracy without missing any ramp event
24 spanning two adjacent time intervals. The proposed method can be described as follows:

25 Step 1: Implement the GAN-based WPF approach recursively to forecast wind power outputs every
26 Δt over a forecasting horizon $[t_0, t_{\text{end}}]$ based on historical data;

27 Step 2: Calculate the initial wind power ramp rate S_r with Eq. (14). If the initial ramp rate is close
28 to the pre-defined thresholds, the rolling horizon strategy is activated to tune and modify the REF results
29 in each rolling step and set $t = t_0$;

30 Step 3: Input the updated real-time data of wind power at current time t for the self-tuning REF

1 model;

2 Step 4: Based on the updated real-time wind power outputs, perform the semi-supervised GAN to
3 tune and forecast the wind power from the next time $t+\Delta t$ to the end of the rolling horizon by multi-step
4 recursive prediction processes;

5 Step 5: Calculate and update the ramp power rate according to the forecasted wind power with Eq.
6 (14) in the rolling horizon;

7 Step 6: Set $t = t + \Delta t$; If t is equal to t_{end} , then output the wind power ramp rate during this time
8 interval for further REF classification; otherwise return to Step 3.

9 In each rolling step, the forecasted wind power and the corresponding ramp rate can be tuned and
10 updated based on the real-time wind power observation and its variation trend. Thus, the proposed self-
11 tuning forecasting strategy can track the fluctuation of wind power in real time and adaptively tune the
12 REF forecasting results. The flowchart of the proposed self-tuning strategy is shown in Fig. 5.

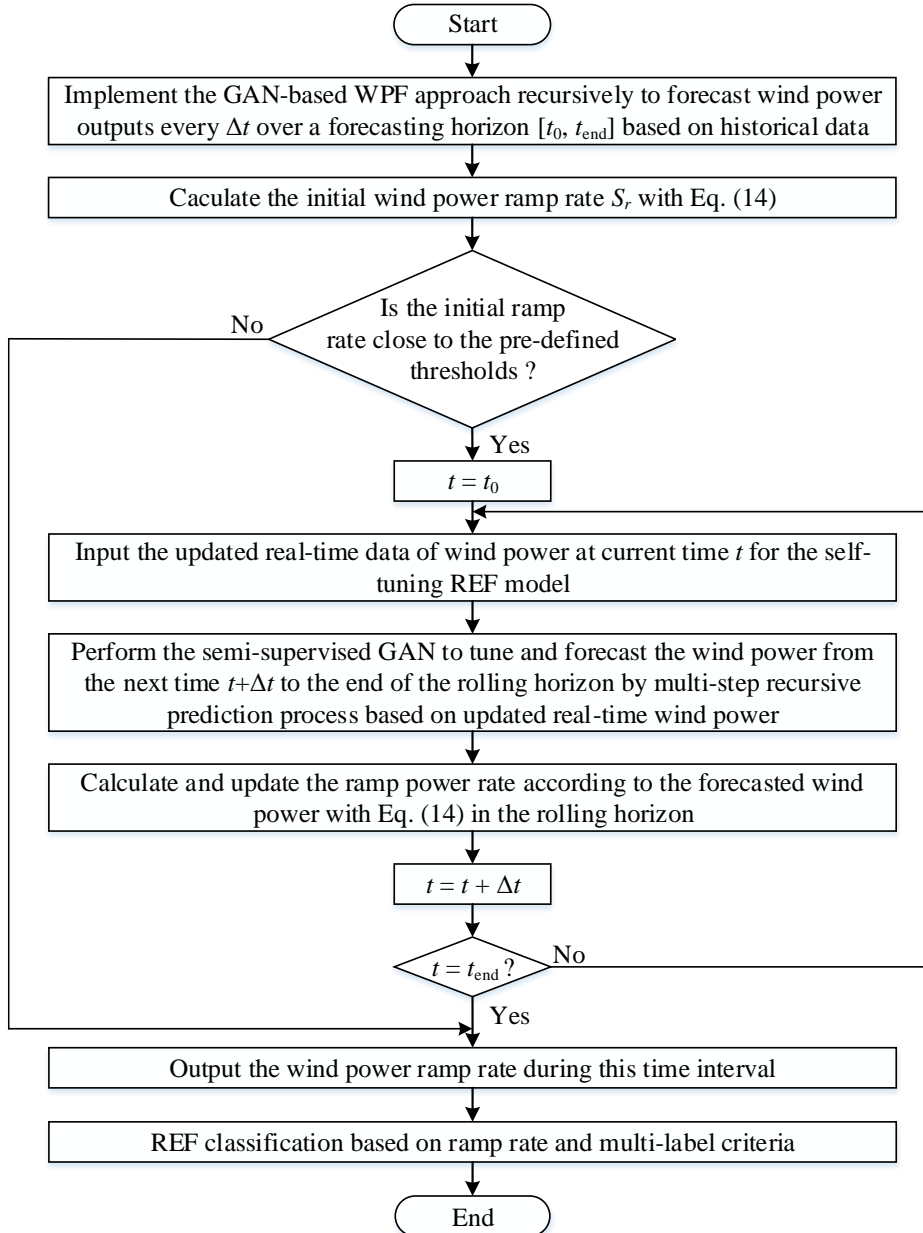


Fig. 5 The flowchart of the proposed with self-tuning REF method

4.2 Multi-Label Classifier for Ramp Events

Different types of wind power ramp events, such as ramp-up and ramp-down events with different ramp rates, have different impacts on the stability and economic operation of the smart grid [31]. In general, wind power ramp event prediction can be formulated as a multi-label classification problem. In this paper, the wind power ramp events are divided into five categories for semi-supervised learning, including large ramp up events, small ramp up events, large ramp down events, small ramp down events and no ramp events. The multi-label criteria of REF classification are listed in Table 1. Here, R_1 and R_2 are the thresholds of power ramp rates, and their values depend on the maximum installed capacity of the wind farm [33].

Table 1 Multi-label criteria of REF classification

Label of wind power ramp events	Classification criteria
Large ramp up events	$S_r > R_2$
Small ramp up events	$R_1 < S_r < R_2$
No ramp events	$-R_1 < S_r < R_1$
Small ramp down events	$-R_2 < S_r < -R_1$
Large ramp down events	$S_r < -R_2$

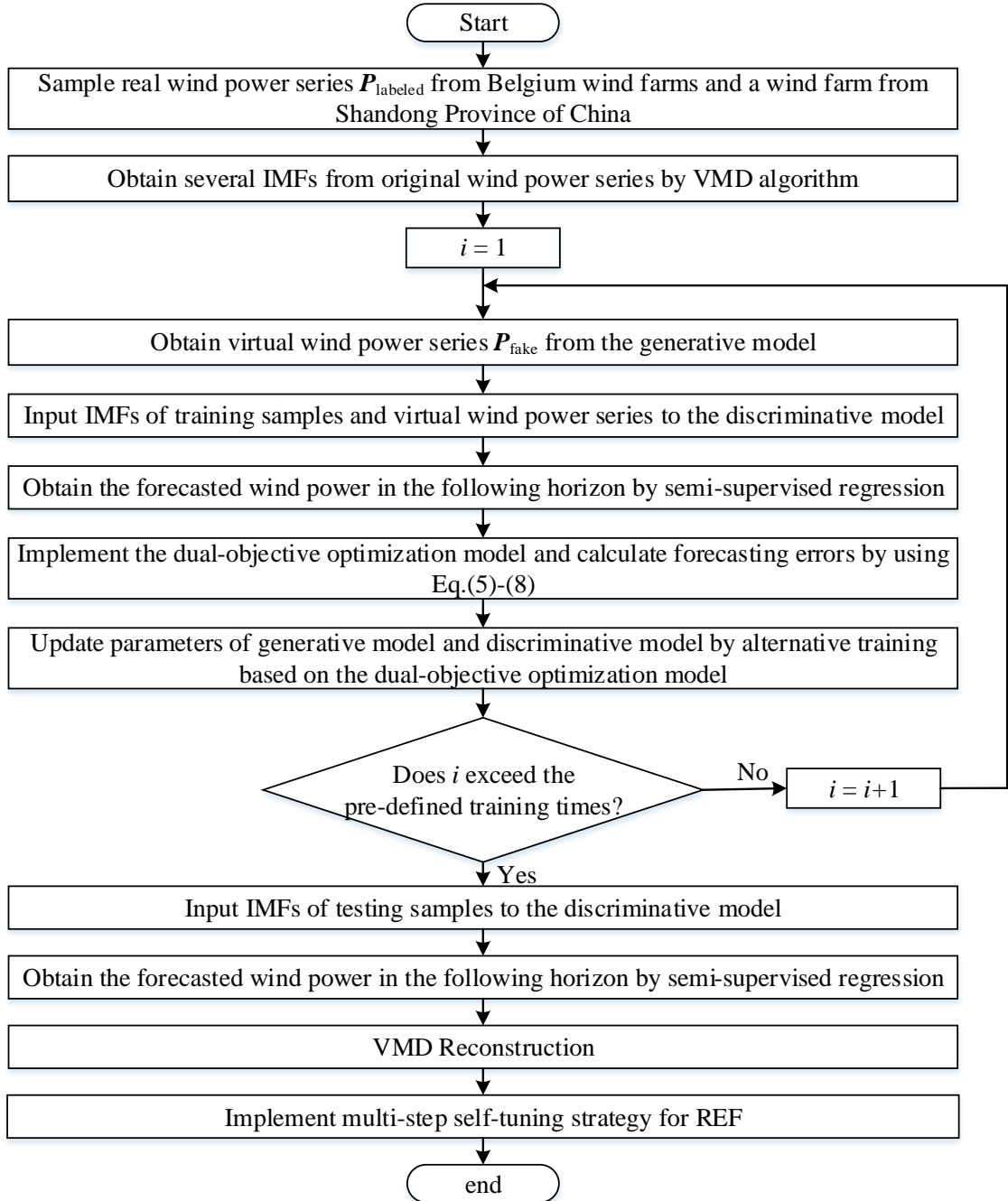
5 Implementation of Proposed Forecasting Method

In this paper, a hybrid prediction model based on semi-supervised regression, CNN and GAN is proposed for the forecasting of wind power and its ramp events. The proposed method combines various techniques such as data augmentation, feature extraction, and alternative training. In summary, the overall forecasting framework of the proposed prediction method is illustrated in Fig. 6.

Firstly, the VMD is applied to decompose the original time series of wind power into multiple IMF signals and one residual sub-series. Then, a random noise vector is generated and also converted into a virtual sample by the GAN generative model. This virtual sample increases the diversity for training GAN discriminative model. Subsequently, the virtual samples and IMF sub-series are taken as the inputs into the discriminative model with three convolution layers and one regression layer. Thus, the WPF results of each sub-series and its prediction errors can be obtained. Furthermore, the prediction errors are fed back to the GAN generative model to update the generative parameters, and each IMF sub-series with the residual signal correspond to an independent discriminative model. The entire WPF prediction model is trained using the alternative training process as illustrated in Section 3.4. After the GAN training

1 process is completed, the prediction performance for the forecasting of wind power and its ramp events
 2 can be evaluated by statistical indices.

3 Compared with the previous WPF and REF models, the proposed semi-supervised learning driven
 4 GAN method possesses the following advantages: (1) The GAN used in the proposed prediction method
 5 is essentially a general framework and can be combined with other time-series forecasting model with
 6 strong compatibility; (2) The proposed prediction method uses the GAN generative model to generate
 7 virtual samples for extending the set of training samples, and it can improve the prediction robustness
 8 against random noise; (3) The CNN adopted in the discriminative model has better capability for
 9 extracting time series features. Hence, these advantages can effectively improve the prediction stability,
 10 robustness and forecasting accuracy of the proposed GAN-based WPF method.



1 **Fig. 6** Implementation framework of the proposed method

2 **6 Evaluation Criteria**

3 *6.1 Wind Power Forecasting Metrics*

4 In this paper, three metrics, including mean absolute error (MAE), mean absolute percentage error
5 (MAPE) and root mean square error (RMSE), are used for evaluating the WPF performance [4]. MAE
6 and RMSE is to assess the forecasting capacity and accuracy of the proposed prediction method, while
7 MAPE is used to evaluate the relative deviation of point forecasting results from real wind power outputs,
8 as follows,

9
$$\text{MAE} = \frac{1}{N} \sum_{i=1}^N |P_i^F - P_i^R| \quad (15)$$

10
$$\text{MAPE} = \frac{1}{N} \sum_{i=1}^N \frac{|P_i^F - P_i^R|}{P_i^R} \times 100\% \quad (16)$$

11
$$\text{RMSE} = \sqrt{\frac{1}{N} \sum_{i=1}^N (P_i^F - P_i^R)^2} \quad (17)$$

12 where P_i^F and P_i^R represent the WPF results and the real data of wind power at the time step t_i ; N
13 denotes the total number of samples.

14 *6.2 Ramp Event forecasting Metrics*

15 Here, the forecast accuracy (FA) and ramp capture (RC) are chosen as evaluation indices for REF
16 performance evaluation [7]. FA is applied to evaluate the forecasting accuracy of the proposed method,
17 and RC is to measure the forecasting recall of the proposed method, as follows,

18
$$\text{FA} = \frac{\text{TF}}{\text{TF} + \text{FF}} \times 100\% \quad (18)$$

19
$$\text{RC} = \frac{\text{TF}}{\text{TF} + \text{MR}} \times 100\% \quad (19)$$

20 where, True Forecast (TF) represents the observed ramp events that have been predicted; False Forecast
21 (FF) represents the unobserved ramp events that have been predicted by REF methods; Missed Ramp
22 (MR) represents the observed ramp events ignored by REF methods.

23 **7 Case Studies**

24 In this case study, the proposed method has been comprehensively tested on wind power datasets
25 from three wind farms. The real measurement from Belgium wind farms (15 min) and a wind farm from

1 Shandong Province of China (60 min) in 2018 are adopted to demonstrate the superiority of the proposed
2 method on WPF and REF problems. Cases 1 and 2 adopt the real power from Wallonia and Vlaanderen
3 wind farms for one-step ahead WPF and REF with a data resolution of 15 minutes [27], while Case 3
4 uses the real power from a wind farm of Shandong Province of China for multi-step ahead WPF with a
5 data resolution of 60 minutes [5]. The wind power at the next time is forecasted based on 9 consecutive
6 historical values of these time series, and the ratio of the number of training samples to test samples is
7 set to 4:1 [28]. WPF and REF performance of the proposed forecasting method is compared with various
8 algorithms including ARIMA [11], SVM [18], shallow ANN [19], CNN [27], RNN [25], ELM [22]-[23],
9 RVFLN [24], DBN [28] and hybrid method DBN+WT.

10 *7.1 Wind Power Forecasting*

11 (1) Case 1

12 Two small datasets are adopted to test the forecasting results of the proposed prediction method. The
13 first wind power dataset was from the Wallonia wind farm in Belgium, which has a maximum wind power
14 output of 700.2 MW in February and 806.11 MW in August [5]. The dataset contains 1000 samples, of
15 which 800 are training samples and 200 are testing samples. The forecasting results with the proposed
16 method and other algorithms are shown in Fig. 7, and the statistical indices of these 200 test samples are
17 shown in Fig. 8.

18 It can be found from Fig. 7 that the prediction results of the GAN-based method have very similar
19 variation trends to the real wind power data, and the proposed forecasting method has good adaptability
20 and flexibility. It can be clearly seen from Fig. 8 that the MAE, MAPE, and RMSE results of the proposed
21 method are 2.9474 MW, 1.02%, and 4.0502 MW, respectively, with the best forecasting performance
22 among all the comparative algorithms. In addition, the MAE, MAPE and RMSE of the statistical ARIMA
23 method are 29.3359 MW, 10.28% and 34.1086MW, respectively. It can also be observed that ARIMA is
24 not good at handling wind power data with high randomness, while RNN has relatively good performance
25 due to its strong time-series processing capability. **The improvements of MAPE results with the proposed
26 method are 62.91% and 65.31% compared to ELM and RVFLN, respectively.** Furthermore, the MAE,
27 MAPE, and RMSE of DBN are 15.4123 MW, 5.34%, and 19.1470 MW, respectively. Obviously, the
28 prediction performance of DBN is not as good as the results of the proposed method. This is because the
29 size of this dataset is too small for the DBN to learn the intrinsic characteristics of wind power time series,
30 even if WT is used. Undoubtedly, the GAN-based prediction method greatly outperforms other existing
31 methods in all three evaluation metrics.

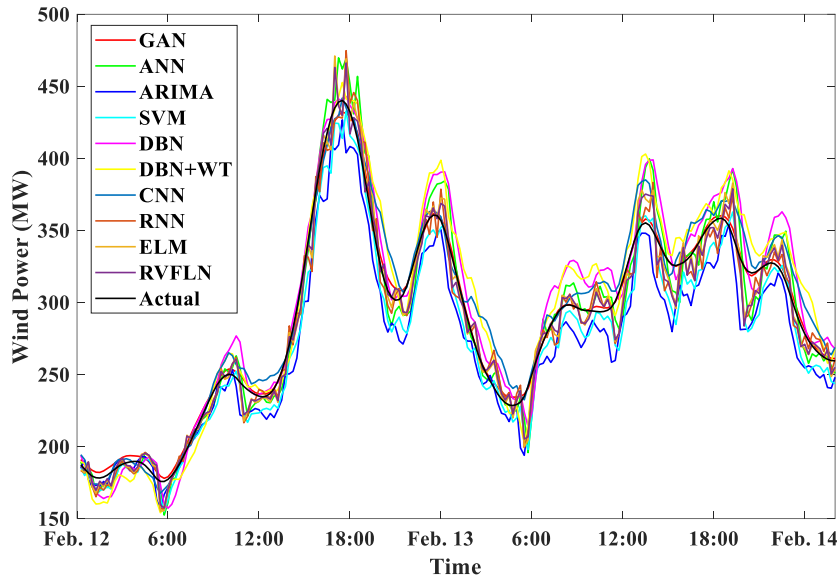


Fig. 7 WPF results on February 12-14, 2018 at Wallonia

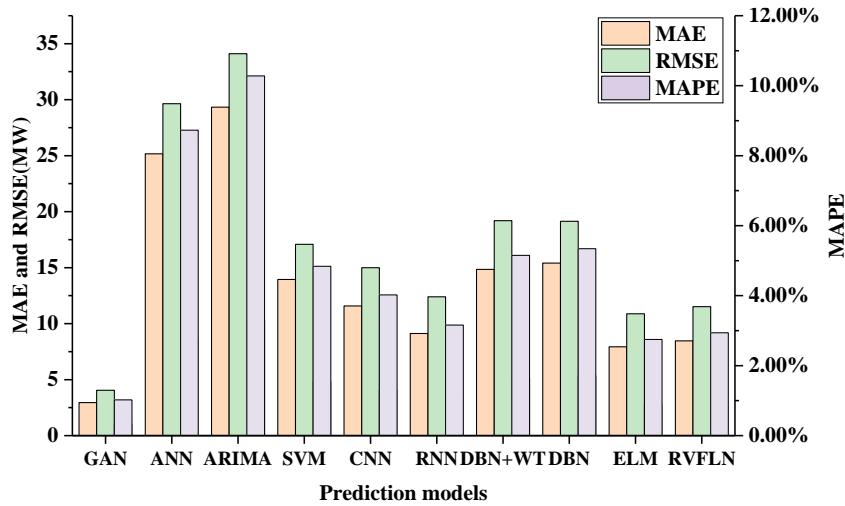


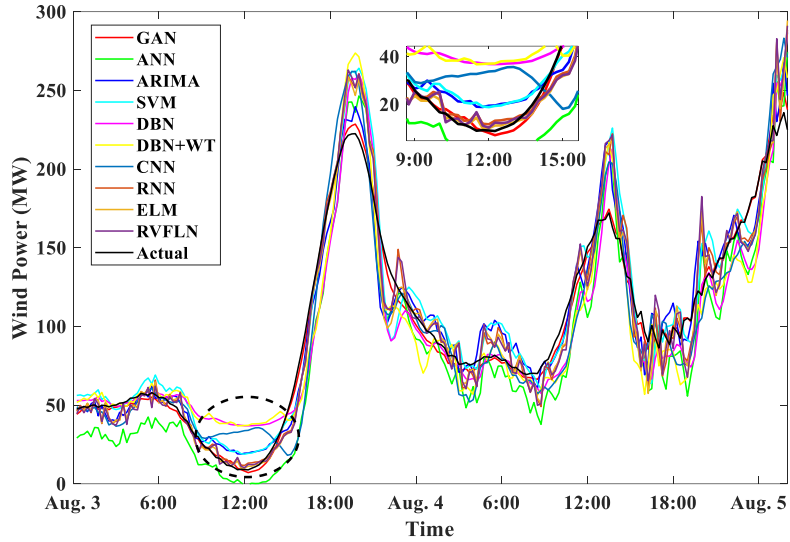
Fig. 8 WPF indices on February 12-14, 2018 at Wallonia

1
2

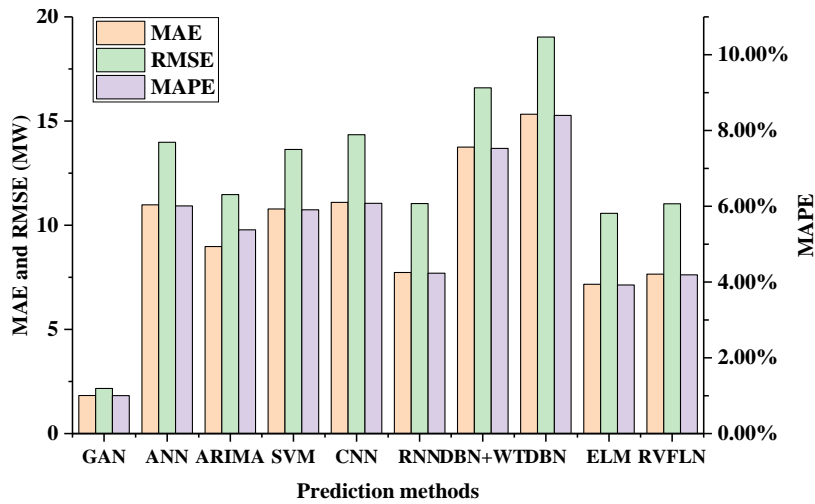
3
4

5 The second dataset is also collected from the Wallonia wind farm in Belgium. It covers the wind
6 power data from August 3, 2018 to August 13, 2018. Similarly, the dataset contains 1000 samples, of
7 which 200 are testing samples and the rest are training samples. The final forecasting results are shown
8 in Fig. 9, and the statistical performance indices are given in Fig. 10. As seen from Figs. 9-10, the results
9 of MAE, MAPE and RMSE using the GAN-based method are 1.8257 MW, 1.82%, and 2.1646 MW,
10 respectively. The reductions on MAPE are 74.47% and 76.11% compared to ELM and RVFLN, and range
11 from 76.36% to 88.08% compared to other methods. During the period from 10:00 to 14:00 on Aug. 3,
12 the performance of other methods is worse than that of the proposed method. It is worth mentioning that
13 the DBN performs the worst with the MAE, MAPE and RMSE of 15.3304 MW, 15.27% and 19.0301
14 MW, respectively. This is mainly because the sample size is too small so that its feature extraction
15 capability is hugely limited. Also, the number of deep learning layers is large, which tends to cause over-
16 fitting problem. The additional experimental performance in spring and autumn are presented in Table 2

1 to further validate the forecasting ability of proposed method. It can be found from Table 2 that, compared
 2 with other methods, the improvements of MAPE range from 51.82% to 78.35% with an average of 65.08%
 3 in spring, and range from 61.48% to 84.53% with an average of 73.18% in autumn. The results can be
 4 explained that wind power time-series in autumn is more irregular and unpredictable and other methods
 5 cannot extract the inherent features in wind power. Obviously, the proposed GAN is suitable for wind
 6 power forecasting with small/big sample size.



7 **Fig. 9** WPF results on August 3-5, 2018 at Wallonia



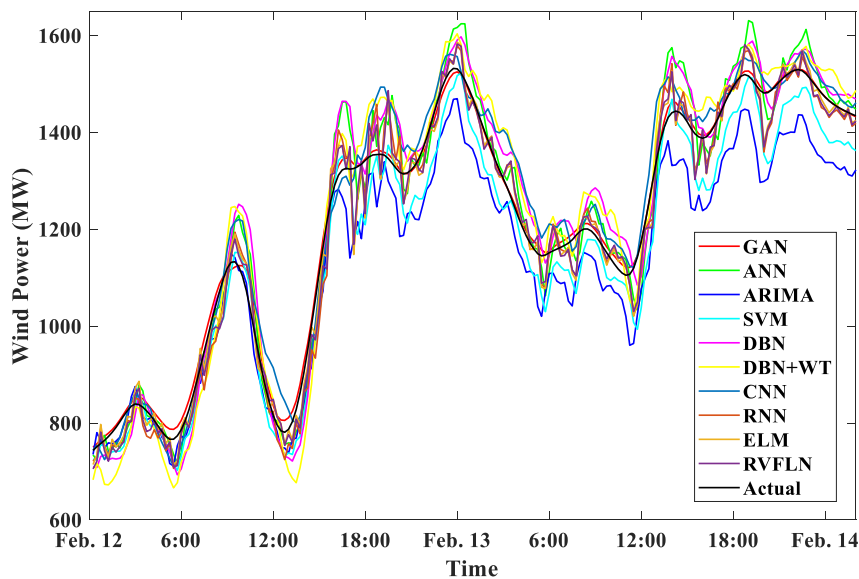
8 **Fig. 10** WPF indices on August 3-5, 2018 at Wallonia

9 **Table 2** WPF indices in spring and autumn of 2018 at Wallonia

Season	Index	GAN	ANN	ARIMA	SVM	CNN	RNN	DBN+WT	DBN	ELM	RVFLN
Spring	MAE	3.8395	16.5011	22.3638	8.0432	12.7801	7.9516	15.3667	18.7539	7.7709	8.0094
	RMSE	4.8748	20.3967	25.9973	13.2325	16.6721	12.5526	19.7234	20.8841	11.0880	13.3955
	MAPE	1.67%	6.38%	9.10%	4.14%	6.58%	4.09%	6.54%	7.98%	4.00%	4.52%
Autumn	MAE	2.2173	8.3021	6.2576	5.5050	12.7145	5.7166	9.4011	13.7104	5.5230	6.3722
	RMSE	3.1574	11.8202	10.1917	9.4693	16.8322	9.9971	13.5263	18.1034	9.5609	10.8962
	MAPE	1.93%	8.42%	6.75%	5.79%	13.37%	6.01%	9.88%	14.42%	5.81%	6.70%

1 (2) Case 2

2 This case adopts the wind power dataset from Vlaanderen in Belgium, which has a maximum wind
3 power output of 2621.924 MW in February and 3003.185 MW in August [5], to further verify the
4 effectiveness of the proposed forecasting method. Similar to Case 1, the dataset contains 1000 samples
5 and covers the time period of February 12-22, 2018 and the time period of August 4 to 14, 2018. The
6 ratio of the testing samples to the training samples is set to 1/4. The forecasting results of the GAN-based
7 forecasting method are graphically presented in Figs.11-12. It is clear that the wind power dataset from
8 Vlaanderen is more chaotic, with more spikes and fluctuations. While, the forecasting curve of the
9 proposed method and the real wind power data are almost overlapped. Fig. 12 shows that, in terms of
10 MAPE, the improvements of the proposed method range from 68.41% to 85.17% compared to other
11 methods. During the period from 17:00 to 23:00 on Aug. 4, the proposed GAN method has small errors
12 and low fluctuations. The 12 monthly forecasting performance in 2018 at Vlaanderen is presented in
13 Table 3. Apparently, the MAPE of GAN varies from 0.72% to 2.74% with an average of 1.73%, which
14 shows larger differences and stronger stability compared to other methods. From Fig. 12, it can be found
15 that the proposed method has a slightly worse fitting degree in August than that in February. This is
16 because wind power dataset in August is more stochastic than that in February.



17 **Fig. 11** WPF results on February 12-14, 2018 at Vlaanderen
18

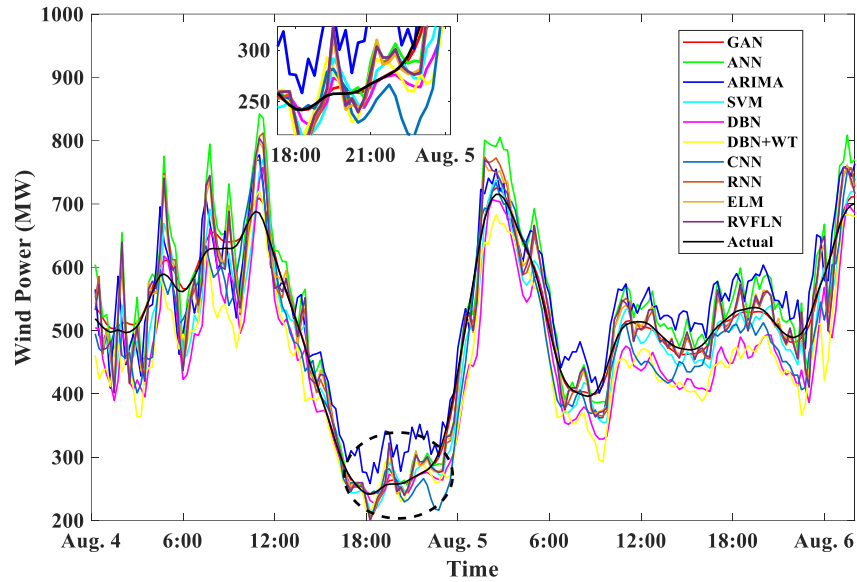


Fig. 12 WPF results on August 4-6, 2018 at Vlaanderen

Table 3 Comparative WPF indices in 2018 at Vlaanderen

Month	Index	GAN	ANN	ARIMA	SVM	CNN	RNN	DBN+WT	DBN	ELM	RVFLN
Jan.	MAE	3.4521	11.4752	11.1070	10.9442	16.2625	11.4545	18.0258	24.1351	11.0810	12.4857
	RMSE	5.2478	16.5239	12.6189	15.9942	24.7028	20.2510	23.2287	29.5567	16.0831	16.8384
	MAPE	1.22%	4.05%	3.92%	3.86%	5.74%	4.05%	6.36%	8.51%	3.91%	4.40%
Feb.	MAE	5.0006	27.6192	90.1810	22.8374	39.0018	23.7065	37.4699	40.2722	22.7746	28.2572
	RMSE	6.4073	39.8695	174.6899	33.9657	56.3376	42.8871	45.4122	52.7891	34.1481	41.2477
	MAPE	0.72%	3.18%	10.74%	2.63%	4.49%	2.74%	4.16%	4.64%	2.61%	3.25%
Mar.	MAE	3.4054	11.5878	38.7240	10.7080	15.9549	11.2778	8.7934	20.3967	10.9200	12.7575
	RMSE	4.0058	16.2114	49.6524	15.5112	20.4144	19.3257	10.0325	25.8894	15.8014	16.7993
	MAPE	1.41%	4.79%	14.28%	4.43%	6.60%	4.64%	3.64%	8.43%	4.52%	5.28%
Apr.	MAE	3.1803	10.9700	20.0691	9.6044	16.6270	9.7173	15.3754	21.1516	9.6368	12.9410
	RMSE	3.9895	15.7949	24.1794	14.9844	21.385	15.0032	17.3855	26.2702	15.0005	17.3472
	MAPE	1.96%	6.77%	12.89%	5.93%	10.26%	5.96%	9.89%	13.05%	5.95%	7.98%
May.	MAE	2.7632	8.3994	16.6116	7.1848	13.4779	7.6984	12.1948	18.5197	7.2062	8.5605
	RMSE	3.2416	12.0798	21.5450	11.3426	17.4205	19.0724	16.0490	23.3816	11.3553	12.3126
	MAPE	2.04%	6.21%	10.25%	5.31%	9.97%	5.66%	8.61%	13.70%	5.33%	6.33%
Jun.	MAE	1.7654	7.2302	19.0616	5.9461	12.1849	6.2680	13.0272	15.9288	6.0291	8.2463
	RMSE	2.4162	9.9705	20.4323	9.0357	15.9454	9.2167	15.7521	20.1558	9.0885	10.7411
	MAPE	1.29%	5.30%	13.97%	4.36%	8.93%	4.59%	9.55%	11.67%	4.42%	6.04%
Jul.	MAE	1.3639	7.3552	14.9137	5.6382	11.9737	5.9759	8.5062	15.5843	5.7813	8.3589
	RMSE	1.8084	9.9744	18.3835	9.0717	15.2494	10.8305	11.3459	19.7724	9.1003	10.8683
	MAPE	1.16%	6.25%	12.78%	4.79%	10.17%	5.04%	7.66%	13.24%	4.91%	7.10%
Aug.	MAE	7.7139	27.0173	85.8003	23.5467	39.9314	23.5441	21.9100	44.2481	22.3807	28.9852
	RMSE	20.7972	46.2334	96.9450	41.5225	63.6969	41.2537	30.1810	66.5978	36.0501	48.5520
	MAPE	1.44%	5.02%	15.96%	4.38%	7.43%	4.39%	4.07%	8.23%	4.15%	5.39%
Sept.	MAE	4.7658	9.7171	26.9542	7.8288	14.0106	7.9354	11.5627	22.1869	7.9368	7.9066
	RMSE	5.6984	14.1535	33.4521	12.9691	19.4105	13.1058	13.9201	29.7170	13.1495	13.0896
	MAPE	2.74%	5.59%	15.67%	4.50%	8.06%	4.55%	6.65%	12.76%	4.57%	4.55%
Oct.	MAE	3.5025	9.8866	16.5179	8.2902	14.0612	8.4080	12.4085	23.3892	8.1528	9.4537
	RMSE	4.1277	13.5258	21.3361	12.5897	18.4658	12.7464	16.9578	29.2207	12.1510	12.9309
	MAPE	2.09%	5.90%	9.51%	4.94%	8.39%	5.00%	7.69%	13.95%	4.82%	5.64%

	MAE	3.5297	11.2897	13.4987	9.8082	15.1153	9.9691	10.7995	25.7856	9.8285	9.9583
Nov.	RMSE	4.5279	15.6792	18.8425	14.6805	19.6832	15.1437	13.4643	32.3875	14.7513	14.8678
	MAPE	1.77%	5.68%	6.79%	4.93%	7.60%	5.01%	5.43%	12.96%	4.94%	5.01%
	MAE	4.1139	12.5960	30.1345	11.0630	16.3319	11.4216	15.2927	29.1251	13.1970	13.5654
Dec.	RMSE	4.9410	17.1936	36.6183	16.2606	21.2684	17.6006	19.3318	35.5000	17.4049	17.5322
	MAPE	1.43%	4.39%	10.50%	3.85%	5.69%	3.98%	5.33%	10.15%	4.90%	4.73%

(3) Case 3

This case adopts the real data of a wind farm from Shandong Province of China to verify the overall forecasting performance of the proposed method on one-step prediction and multi-step prediction tasks. The multi-step forecasting is an iterative point prediction process and performed in a rolling mode with high forecasting accuracy [30]. In each iteration, the one-step prediction results in the prior time steps are used as the inputs of multi-step forecasting for a certain time point. The forecasting structure and parameter settings are the same as that in the previous Cases 1-2. The one-step prediction and the multi-step prediction results are illustrated in Figs. 13-14, respectively. The corresponding statistical indices of benchmarking algorithms are given in Tables 4-5. In Table 4, the MAE, MAPE and RMSE indices of the proposed method are 0.3154 MW, 2.55% and 0.4326 MW, respectively. In Table 5, the MAE, MAPE, and RMSE of the proposed method are 0.5944 MW, 4.80%, and 0.8349 MW, respectively. The prediction results from Figs. 13-14 and Tables 4-5 show that the GAN-based prediction method can be used in the multi-step wind power prediction tasks.

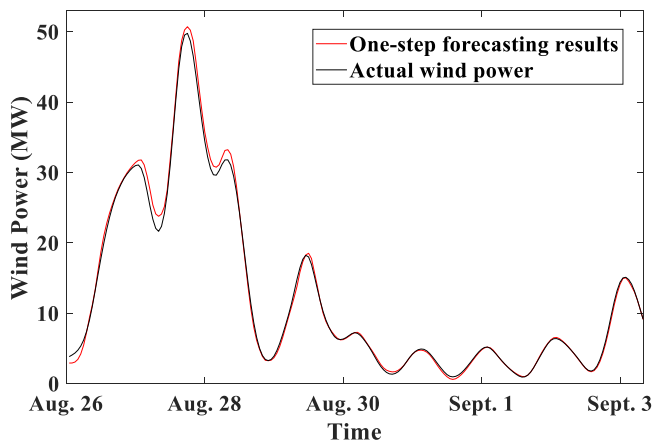


Fig. 13 One-step WPF results of the proposed approach

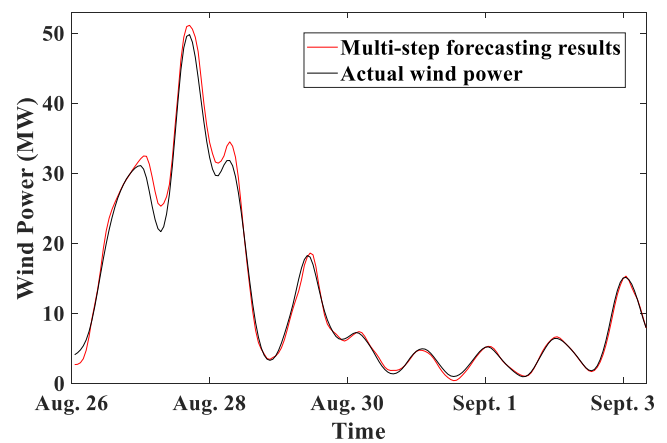


Fig. 14 Multi-step WPF results of the proposed approach

Table 4 One-step WPF indices with different forecasting methods

Index	GAN	ANN	ARIMA	SVM	CNN	RNN	DBN+WT	DBN	ELM	RVLFN
MAE	0.3154	1.0914	2.2214	1.3016	1.1451	0.9557	1.6569	1.7766	1.1167	1.0435
RMSE	0.4326	1.7085	3.3249	2.0817	1.8677	1.3084	2.2684	2.5587	1.7794	1.6505
MAPE	2.55%	9.61%	19.56%	11.46%	10.08%	8.41%	14.59%	16.94%	9.78%	9.19%

Table 5 Multi-step WPF indices with different forecasting methods

Index	GAN	ANN	ARIMA	SVM	CNN	RNN	DBN+WT	DBN	ELM	RVFLN
MAE	0.5944	2.0999	2.5458	2.2935	1.6997	1.5696	1.8653	2.3543	2.2236	2.1674
RMSE	0.8349	3.1431	3.9001	3.4389	2.7043	2.3450	2.8867	3.5232	3.3483	3.2750
MAPE	4.80%	18.46%	22.37%	20.16%	16.30%	14.04%	17.68%	20.74%	19.47%	18.14%

1 A comparison of the calculation time with all the forecasting methods is presented in Table 6. All
2 the methods are implemented in MATLAB R2018b and carried out on a personal computer with 2.60GHz
3 Intel CPU and 8 GB of RAM. The dataset contains 800 training samples and 200 testing samples. From
4 Table 6, it can be seen that the proposed GAN takes more time for forecasting than ARIMA, SVM, RNN,
5 shallow ANN, CNN, ELM, and RVFLN. That is because the proposed method employs the VMD for
6 signal decomposition, and both generative and discriminative models need to be trained. In addition, the
7 calculation time of the GAN-based prediction algorithm is shorter than that of DBN-based forecasting
8 algorithm. This can be explained by the fact that the DBN has a complicated training process including
9 layer-wise training and fine-tuning. Consequently, it can be seen that the proposed prediction algorithm
10 based on GAN is attractive from the aspects of prediction performance and efficiency.

11 **Table 6** Computational time of ten prediction method

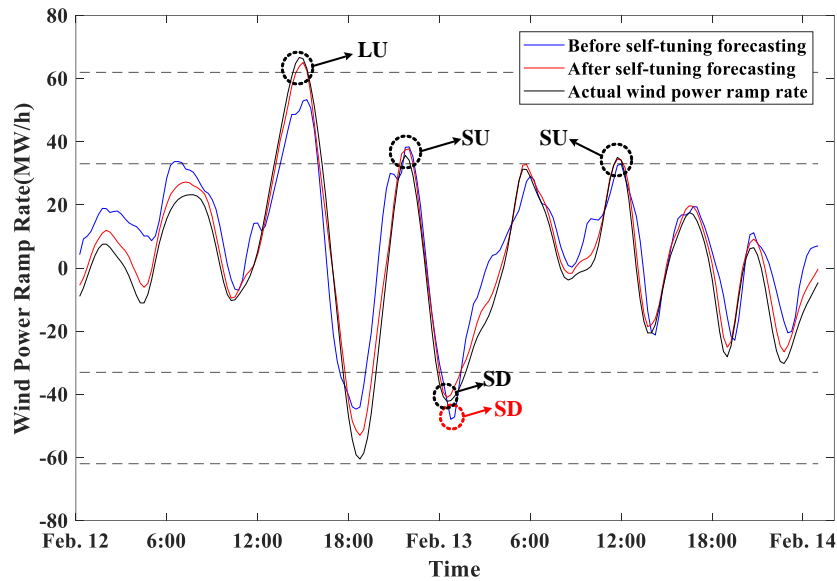
	GAN	ANN	ARIMA	SVM	CNN	RNN	DBN+WT	DBN	ELM	RVFLN
Runtime/s	17.9208	12.3658	5.6708	4.5185	10.9633	5.9640	32.2438	21.3253	11.5306	13.7885

12 7.2 Ramp Event Forecasting of Wind Power

13 This section aims to test the overall performance of the self-tuning GAN-based method for the REF
14 problem of wind power. The multi-label classifier is used to identify different types of power ramp events
15 including LU (large ramp up), SU (small ramp up), NO (no ramp), SD (small ramp down) and LD (large
16 ramp down). The threshold values of ramp rate R_1 and R_2 correspond to 5% and 10% of the installed
17 wind power capacity, and the leading time is set to 60 min. The ramp rate curves obtained from pure REF
18 and self-tuning REF are shown in Figs. 15-16. It can be seen that the proposed self-tuning REF method
19 can successfully predict most of observed events. For example, in Fig. 15, a LU is predicted by self-
20 tuning REF. While, this LU is not detected by pure REF at 15:00 on Feb. 12. The undetected ramp event
21 using pure REF method also happens at 22:00 on Feb. 12. They are marked with black circles. At 1:00
22 AM on Feb. 13, the SD with a red circle is predicted by pure REF, but the prediction result lags behind
23 actual ramp event, which is useless for real-time scheduling. In Fig. 16, a similar situation can also be
24 found at 21:00 on Aug. 3.

25 The statistical forecasting performance are presented in Tables 7-8, respectively. The TF and FF
26 indices can indicate the number of observed/unobserved ramp events of wind power predicted by
27 different algorithms. In general, the larger values of FA and RC denote the better algorithm performance.

1 From Table 7, the proposed GAN successfully captures 1 large ramp up event, 7 small ramp up events, 6
 2 small ramp down events and 1 large ramp down events, and thus the index TF is equal to 15
 3 (1+7+6+1=15), while the FF is equal to 0. The FA calculated by Eq. (18) is equal to 100%. On the other
 4 hand, there is 1 small ramp down event which is not captured by the proposed method, and the MR is 0.
 5 Thus the RC is equal to 93.75%. Comparatively, for the hybrid method DBN+WT, 4 large ramp up events
 6 have been predicted, but only 1 events is actually observed. Thus, the TF is equal to 14 (1+6+7+0=14),
 7 and the FF and MR are 6 and 2, respectively. Also, although the CNN algorithm exhibits the highest FF
 8 index, there are still 2 small ramp up events and 1 large ramp down event which are not predicted by the
 9 CNN. Compared to other algorithms in Table 7, the FA from the proposed method is 100.00% with the
 10 improvement of 33.33%. The RC from the proposed method is 93.75% with the improvement of 33.33%.
 11 It can be found from Table 8 that the proposed method have successfully captured 10 small ramp up
 12 events and 2 large ramp down events, but there is 1 small ramp down event to be wrongly predicted.
 13 Compared to other algorithms in Table 8, the FA of the proposed method is 93.33% with the improvement
 14 of 34.06%. The RC of the proposed method is 100.00% with the improvement of 42.86%. It can be
 15 concluded from these results that the proposed GAN-based forecasting method can provide the superior
 16 REF performance than the existing prediction algorithms.



17 **Fig. 15** REF results on February 12-14, 2018 at Wallonia

18 **Table 7** REF indices in February 2018 at Wallonia (Total 16 ramp events)

Index	Real	GAN	ANN	ARIMA	SVM	CNN	RNN	DBN+WT	DBN	ELM	RVFLN
LU	1	1	1	0	1	1	2	4	4	1	0
SU	7	7	8	7	6	5	4	6	4	6	5
NO	33	34	32	34	34	36	36	29	34	35	34
SD	7	6	5	6	5	7	4	10	4	6	8
LD	1	1	3	2	3	0	3	0	3	1	2

FA	\	100.00%	82.35%	93.33%	86.67%	100.00%	76.92%	70.00%	66.67%	100%	86.67%
RC	\	93.75%	87.50%	87.50%	81.25%	81.25%	62.50%	87.50%	62.50%	87.50%	81.25%

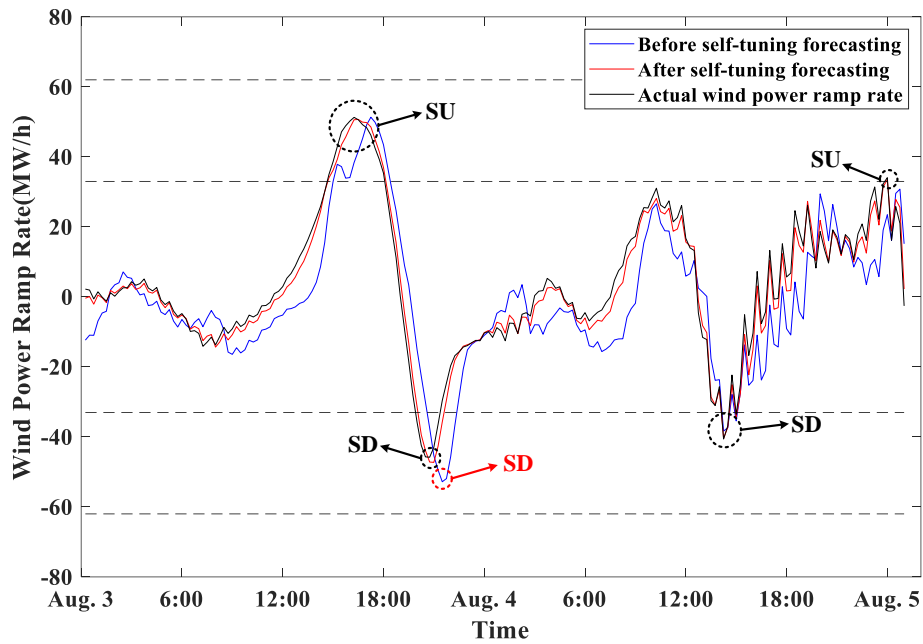


Fig. 16 REF results on August 3-5, 2018 at Wallonia

Table 8 REF indices in August 2018 at Wallonia (Total 14 ramp events)

Index	Real	GAN	ANN	ARIMA	SVM	CNN	RNN	DBN+WT	DBN	ELM	RVFLN
LU	0	0	2	1	4	3	4	4	3	0	1
SU	10	10	8	8	5	7	7	4	6	9	12
NO	35	34	33	36	36	35	33	37	36	33	32
SD	2	3	5	2	1	2	2	2	2	5	3
LD	2	2	1	2	3	2	3	2	2	2	1
FA	\	93.33%	68.75%	92.31%	61.54%	78.57%	68.75%	66.67%	76.92%	81.25%	76.47%
RC	\	100.00%	78.57%	85.71%	57.14%	78.57%	78.57%	57.14%	71.43%	92.85%	92.85%

7.3 Performance Analysis

It can be found that, compared with other benchmarking methods, the proposed method can exhibit a superior performance in term of different lengths of wind power data and prediction horizons. The highlights can be explained as follows: 1) The proposed method uses the VMD to decompose the original time-series data of wind power into IMF sub-series with smooth outer contours, and each IMF is used as the inputs to discriminative model for semi-supervised regression with label learning, thereby improving the predictability of the WPF and REF models; 2) The GAN generative model can generate extra training samples, enhancing the generalization capability of the proposed method, while traditional deep learning algorithms, like the DBN algorithm, are not suitable for the WPF problem with small size of dataset. 3) The proposed self-tuning REF strategy can dynamically adjust and modify the multi-step ramp event

1 parameters based on real-time information. Additionally, the ramp events can be classed by multi-label
2 criterion, allowing dispatchers to prepare for future unknown ramp events.

3 Regarding the calculation time, the proposed method is not the most efficient compared with other
4 methods. The reason can be explained that, a signal decomposition technique is employed and three
5 independent GAN models need to be trained separately. Also, the GAN contains two deep learning
6 networks, which double the time consumption for updating network parameters. In the near future, the
7 on-going investigations will focus on how to improve the calculation efficiency, making the proposed
8 method suitable for practical applications in different renewable energy forecasting problems.

9 **8 Conclusions**

10 In this paper, in order to alleviate the negative impact of wind power uncertainties on the forecasting
11 accuracy, a hybrid prediction model combining multi-step self-tuning strategy and semi-supervised GAN
12 with generative and discriminative models is developed for the WPF and REF problems. The proposed
13 method has been comprehensively tested and compared with statistical method, classical neural networks
14 and deep learning algorithms, using wind power time series collected from real wind farms. From these
15 obtained forecasting results, it is observed that the proposed method can outperform all the benchmarking
16 algorithms in terms of various evaluation metrics. Statistically, compared to other methods at Wallonia
17 wind farm, the highest improvements of MAE, RMSE and MAPE are 89.95%, 88.64%, and 88.08%,
18 respectively. Also, the highest improvements of MAE, RMSE, and MAPE are 87.58%, 87.86%, and
19 84.48% at Vlaanderen wind farm, respectively. Moreover, it has been proved in Case 3 that the proposed
20 multi-step self-tuning REF strategy is efficient and effective to improve the wind power ramp event
21 prediction accuracy on the start time of ramp, duration and ramp rate. These statistical results demonstrate
22 the superior performance of the proposed method, showing that it has a great potential for future
23 applications in smart grid.

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