

1 **Construction Activity Recognition and Ergonomic Risk Assessment Using a Wearable Insole**

2 **Pressure System**

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4 Maxwell Fordjour Antwi-Afari<sup>1</sup>, Heng Li<sup>2</sup>, Waleed Umer<sup>3</sup>, Yantao Yu<sup>4\*</sup>, Xuejiao Xing<sup>5</sup>

5  
6 <sup>1</sup>Postdoctoral Research Fellow, Department of Building and Real Estate, Faculty of Construction and  
7 Environment, Hong Kong Polytechnic University, Hung Hom, Kowloon, Hong Kong Special Administrative  
8 Region, Room No. ZN1002, E-mail: [maxwell.antwifari@connect.polyu.hk](mailto:maxwell.antwifari@connect.polyu.hk)

9  
10 <sup>2</sup>Chair Professor, Department of Building and Real Estate, Faculty of Construction and Environment, Hong  
11 Kong Polytechnic University, Hung Hom, Kowloon, Hong Kong Special Administrative Region, Room No.  
12 ZS734, E-mail: [heng.li@polyu.edu.hk](mailto:heng.li@polyu.edu.hk)

13  
14 <sup>3</sup>Postdoctoral Research Fellow, Department of Building and Real Estate, Faculty of Construction and  
15 Environment, Hong Kong Polytechnic University, Hung Hom, Kowloon, Hong Kong Special Administrative  
16 Region, Room No. ZN1002, E-mail: [waleed.umer@connect.polyu.hk](mailto:waleed.umer@connect.polyu.hk)

17  
18 <sup>4</sup>Ph.D. Candidate, Department of Building and Real Estate, Faculty of Construction and Environment, Hong  
19 Kong Polytechnic University, Hung Hom, Kowloon, Hong Kong Special Administrative Region, Room No.  
20 ZN1002, E-mail: [yt.yu@connect.polyu.hk](mailto:yt.yu@connect.polyu.hk)

21  
22 <sup>5</sup>Ph.D. Candidate, Department of Building and Real Estate, Faculty of Construction and Environment, Hong  
23 Kong Polytechnic University, Hung Hom, Kowloon, Hong Kong Special Administrative Region, Room No.  
24 ZN1002, E-mail: [xue.xu.xing@polyu.edu.hk](mailto:xue.xu.xing@polyu.edu.hk)

25  
26 **\*Corresponding author:**  
27 Miss Yantao Yu  
28 E-mail: [yt.yu@connect.polyu.hk](mailto:yt.yu@connect.polyu.hk)

29

30 **Abstract**

31 Overexertion-related construction activities are identified as a leading cause of work-related musculoskeletal  
32 disorders (WMSDs) among construction workers. However, few studies have focused on automated  
33 recognition of overexertion-related construction workers' activities as well as assessing ergonomic risk levels  
34 which may help to minimize WMSDs. Therefore, this study examined the feasibility of using acceleration  
35 and foot plantar pressure distribution data captured by a wearable insole pressure system for automated  
36 recognition of overexertion-related construction workers' activities and for assessing ergonomic risk levels.  
37 The proposed approach was tested by simulating overexertion-related construction activities in a laboratory  
38 setting. The classification accuracy of five types of supervised machine learning classifiers was evaluated  
39 with different window sizes to investigate classification performance and further estimate physical intensity,  
40 activity duration and frequency information. Cross-validation results showed that the Random Forest  
41 classifier with a 2.56s window size achieved the best classification accuracy of 98.3% and a sensitivity of  
42 more than 95.8% for each category of activities using the best features of combined data set. Furthermore,  
43 the estimation of corresponding ergonomic risk levels was within the same level of risk. The findings may  
44 help to develop a non-invasive wearable insole pressure system for continuous monitoring and automated  
45 activity recognition—which could assist researchers and safety managers in identifying and assessing  
46 overexertion-related construction activities for minimizing the development of WMSDs' risks among  
47 construction workers.

48 **Keywords:** Activity recognition; Construction workers; Overexertion risk; Supervised machine learning  
49 classifiers; Wearable insole pressure system; Work-related musculoskeletal disorders.

50 **Introduction**

51 The construction industry is regarded as one of the most hazardous occupations and labor-intensive industries  
52 (Wang et al. 2015a). Although significant efforts have been demonstrated to reduce occupational injuries and  
53 fatalities in the construction industry (Valero et al. 2016; Antwi-Afari and Li 2018g; Kong et al. 2018),  
54 statistics show that it is still regarded as one of the most dangerous occupations (Center to Protect Workers’  
55 Right (CPWR) 2018). These health and safety issues in the construction industry are mostly attributed to  
56 ergonomic risk factors such as awkward working postures, repetitive lifting, and excessive force or  
57 overexertions (Wang et al. 2015a; Umer et al. 2017b; Antwi-Afari et al. 2017a). Ergonomic risk factors  
58 associated with workplace activities may lead to construction workers developing work-related  
59 musculoskeletal disorders (WMSDs).

60 Compared to different industry sectors, construction workers are faced with the highest risk of developing  
61 WMSDs (OSHA 2017). Examples of WMSDs include low back pain, shoulder pain, tendonitis, and carpal  
62 tunnel syndrome (Umer et al. 2017a; Antwi-Afari et al. 2018a). According to the Bureau of Labor Statistics  
63 (BLS) in the United States, WMSDs accounted for a median of 12 days of work absenteeism in 2015 (BLS  
64 2016). In Germany, WMSDs constitute a major cause of occupational disabilities among construction  
65 workers (Arndt et al. 2005). The high prevalence rate of WMSDs among construction workers not only  
66 causes work absenteeism, schedule delays and increased the cost of insurance premium but also lead to loss  
67 of productivity and early retirement (Umer et al. 2017a). Given above, there is a critical need to assess  
68 ergonomic risks which may lead to WMSDs among construction workers.

69 To minimize WMSDs among construction workers, there is a crucial need to identify potential risk factors  
70 associated with workers’ activities. Overexertion has been identified as the leading risk factor for developing  
71 WMSDs among construction workers (BLS 2016). Notably, existing methods or approaches for identifying  
72 potential risk factors of developing WMSDs include self-reports (e.g., questionnaires), observational-based  
73 methods (e.g., strain index), vision-based methods (e.g., Kinect<sup>TM</sup>), and direct measurement methods (e.g.,  
74 inertial measurement units (IMUs)). Despite their advantages, these approaches are characterized as time-  
75 consuming, relatively imprecise, require expert’s subjective judgment, intrusive and a direct line of sight is  
76 required to register workers’ movement (David 2005). Consequently, it is difficult to identify and evaluate

77 the potential ergonomic risks using the existing approaches. Despite the high prevalence rate of WMSDs  
78 among construction workers and the possible approaches to mitigate WMSDs, less attention has been given  
79 to the use of a wearable sensing system—which can serve as a non-invasive tool for recognizing workers’  
80 activities and mitigating the risk of developing WMSDs.

81 To address these issues, the authors proposed a non-invasive wearable insole pressure system for recognizing  
82 overexertion-related workers’ activities and to assess ergonomic risk levels. To this end, it was hypothesized  
83 that each overexertion-related workers’ activity creates unique patterns of acceleration and foot plantar  
84 pressure distribution data, which can enable the detection and classification of different categories of  
85 activities. Overall, the proposed approach could provide a relatively accurate and objective assessment of  
86 ergonomic risk level—which could help other researchers and safety managers to understand the level of  
87 exposure of workers’ risk and provide effective interventions to mitigate WMSDs’ risks in construction.

88

## 89 **Research Background**

### 90 *Ergonomic Risk Assessment Methods for Identifying Potential Risk Factors of WMSDs*

91 There are four ergonomic risk assessment methods for identifying potential risk factors for developing  
92 WMSDs. These methods are 1) self-reported methods; 2) observational-based methods; 3) vision-based  
93 methods; and 4) direct measurement methods.

94 In the self-reported methods, data is collected on both physical and psychosocial factors through interviews  
95 or questionnaires (Li and Yu, 2011; Reme et al. 2012). These methods have the advantages of being  
96 straightforward to use, applicable to a wide range of working situations and require low initial cost (David  
97 2005). However, a major problem with these methods is the inter-rater difference in workers’ perception of  
98 exposure levels (Wang et al. 2015a). Many observational-based methods have been developed to evaluate  
99 workers’ exposure factors on the job site (McAtamney and Corlett, 1993; Buchholz et al. 1996). Despite  
100 being inexpensive and practical for a wide range of work situations, these methods are time-consuming,  
101 disruptive in nature, and are subjected to intra- and inter-observer variability (David 2005). Vision-based  
102 methods use either depth sensors or stereo camera systems to capture human motion data to extract a three-  
103 dimensional (3D) skeleton models (Han et al. 2013; Han and Lee 2013). These methods provide accurate,

104 non-invasive and automated human motion data for analyzing unsafe actions in construction (Han et al. 2013).  
105 However, they are limited because they: (1) are occasionally ineffective with moving backgrounds; and (2)  
106 require a direct line of sight to register the movements in a construction environment (Han and Lee 2013).  
107 Direct measurement methods use wearable sensor-based systems which are attached to workers' bodies to  
108 collect human motion-related output data (Akhavian and Behzadan 2016; Valero et al. 2016; Antwi-Afari et  
109 al. 2017b; Nath et al. 2017). Previous studies have reported that direct measurement methods provide accurate  
110 and reliable data for identifying WMSDs risk factors as compared to other methods (David 2005; Umer et al.  
111 2017b). However, these methods: (1) require sensors to be attached to the workers' skin which may cause  
112 discomfort; (2) cannot acquire the ground reaction force data; and (3) require additional attachments such as  
113 straps, belts to prevent detachment of sensors from the body when performing tasks.  
114 To overcome these limitations, the current study proposed a wearable insole pressure system for identifying  
115 a potential risk factor of developing WMSDs among construction workers. In the realm of construction,  
116 recent studies have demonstrated the feasibility of using the proposed approach for automated detection and  
117 classification of workers' loss of balance events (Antwi-Afari et al. 2018e) and awkward working postures  
118 (Antwi-Afari et al. 2018f). While these previous studies mainly focused on awkward working postures and  
119 loss of balance events, no research study has been conducted by using a wearable insole pressure system for  
120 recognizing overexertion-related construction workers' activities and assessing ergonomic risk levels.

121

122 ***Wearable Sensing Technologies for Automated Activity Recognition in Construction—the Feasibility of***  
123 ***Using a Wearable Insole Pressure System***

124 Wearable IMU-based systems are the commonest wearable sensing technologies used for activity recognition  
125 and fall risk assessment in construction (Kim et al. 2016; Valero et al. 2016; Yang et al. 2016; Yang et al.  
126 2017; Jahanbanifar and Akhavian 2018; Antwi-Afari et al. 2019). For example, Valero et al. (2016)  
127 developed a system to detect unsafe postures of construction workers (e.g., stooping and squatting with back  
128 bending). To expand the applications of wearable IMU-based systems, smartphones are now embedded with  
129 sensors to collect human motion-related data in the construction field for activity recognition (Akhavian and  
130 Behzadan 2016; Nath et al. 2018; Ryu et al. 2018). Akhavian and Behzadan (2016) used a smartphone with

131 embedded accelerometer and gyroscope sensors to capture body movement data to classify different  
132 categories of construction activities. Nath et al. (2018) collected time-stamped motion data from body-  
133 mounted smartphones with embedded accelerometer and gyroscope sensors to recognize workers' activities.  
134 They also estimated activity duration and frequency information through a classification framework to  
135 evaluate the ergonomic risk levels of the activities caused by overexertion. Ryu et al. (2018) examined the  
136 feasibility of the wrist-worn accelerometer-embedded activity tracker for automated action recognition of  
137 four different subtasks of masonry works. Albeit wearable IMU-based systems have demonstrated reliable  
138 and accurate classification of various construction activities, wearing these sensors at different body parts  
139 make workers' feel uncomfortable, and they also have high hardware costs—limiting their applications on  
140 construction sites (Zhang et al. 2018). In addition, they can only monitor body motions based on velocity,  
141 acceleration, and orientation output data without considering ground reaction force data.

142 To address the above limitations, a wearable insole pressure system offers the following advantages as  
143 compared to wearable IMUs-based systems. First, it can measure the vertical force component of the ground  
144 reaction force data to estimate the physical intensity and subsequently assess corresponding ergonomic risk  
145 levels. Second, it can be easily inserted or detached from workers' safety boots, which minimizes restraint in  
146 body movement and discomfort (Antwi-Afari and Li 2018g). Third, multiple footsteps of workers can be  
147 continuously monitored on construction sites. Ultimately, it offers higher portability, ease of use, and great  
148 potentials in complex and dynamic applications without being invasive. Wearable insole pressure system has  
149 been demonstrated as a useful and reliable tool in several areas of applications such as gait, posture and  
150 activity recognition (Sazonov et al. 2011; Tang and Sazonov 2014), sport biomechanics (Queen et al. 2007),  
151 and improving balance in the elderly (Mickle et al. 2011). In particular, these previous studies used a wearable  
152 insole pressure system to recognize activities of daily living such as sitting, standing, walking, running, stair  
153 ascent or descent and cycling (Sazonov et al. 2011; Tang and Sazonov 2014). In the realm of construction,  
154 workers' activities are more physically demanding and dynamic. The feasibility of using a wearable insole  
155 pressure system for recognizing overexertion-related construction workers' activities has not been explored.  
156 In addition, no study has been conducted by using the proposed approach for estimating the physical intensity,  
157 activity duration and frequency information for assessing corresponding ergonomic risk levels.

## 158 **Research Objective and Contributions**

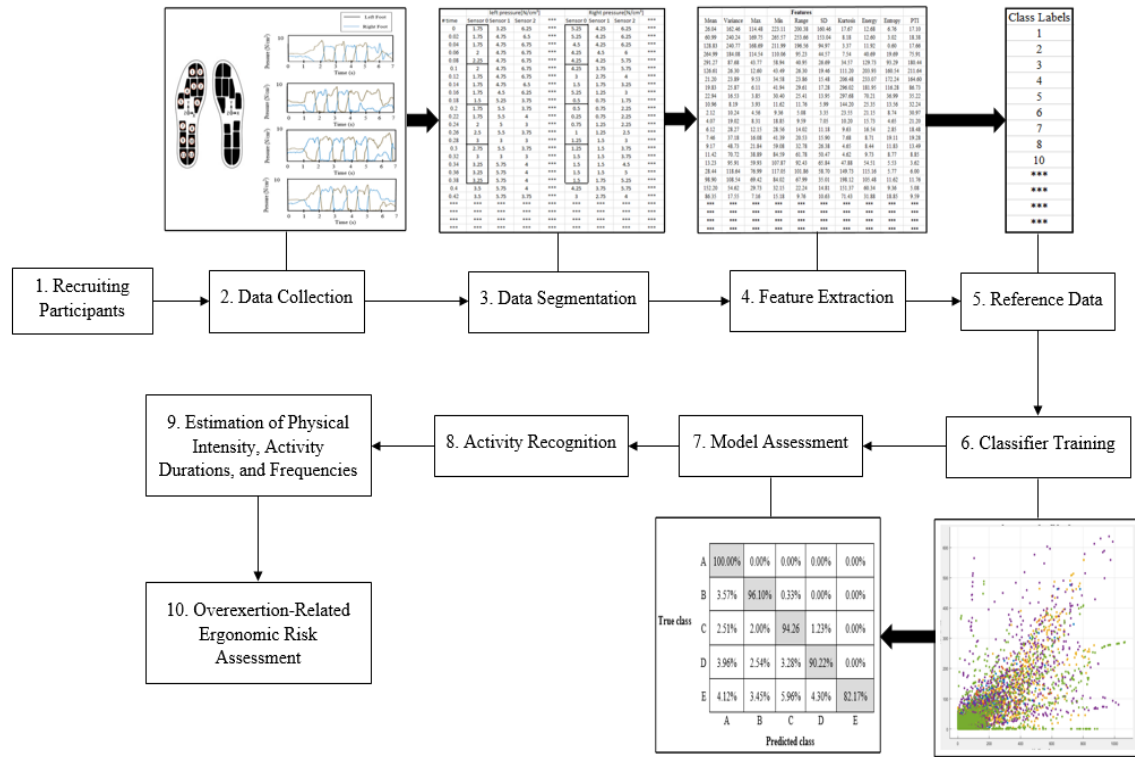
159 The objective of this research was to automatically recognize overexertion-related construction workers'  
160 activities and assess the corresponding ergonomic risk levels by using acceleration and foot plantar pressure  
161 distribution data measured by a wearable insole pressure system. The main contributions of this research  
162 were to: (1) propose a non-invasive wearable insole pressure system for continuous monitoring and  
163 automated recognition of overexertion-related construction workers' activities based on acceleration and foot  
164 plantar pressure distribution data; and (2) estimate the physical intensity, activity duration, and frequency  
165 information for assessing the ergonomic risk levels of overexertion-related construction workers' activities.

166

## 167 **Research Methods**

168 Fig. 1 shows the framework for overexertion-related ergonomic risk assessment. The first step involves  
169 recruiting participants to participate in the proposed approach. Next, acceleration and foot plantar pressure  
170 distribution data were collected in a laboratory setting using a wearable insole pressure system. The two  
171 streams of sensor data were collected to examine which extracted features contribute more to the  
172 classification performance. Following data collection, the sliding window technique was adopted to divide  
173 sensor streams into smaller window size segments. This data segmentation technique has been widely used  
174 due to its simplicity and classification performance in handling both acceleration and foot plantar pressure  
175 distribution data (Akhavian and Behzadan 2016; Antwi-Afari et al. 2018b; Nath et al. 2018; Ryu et al. 2018).  
176 In this study, four window size segments were evaluated to select the optimum window size segment. Three  
177 groups of features (i.e., time-domain, frequency-domain, and spatiotemporal) were extracted as input  
178 variables for supervised machine learning classifiers to test the classifier models. Also, the hybrid feature  
179 selection method was adopted in this research to identify the most distinctive or best features. Reference data  
180 in activity recognition provides the ground truth to evaluate the classification performance. Afterwards, a  
181 classifier model is built and the performance of the model was assessed in terms of the sensitivity and  
182 accuracy metrics. This study examined five types of supervised machine learning classifiers to select the best  
183 classifier with the highest classification performance. Based on the trained models and classification  
184 performance, the various categories of activities are detected and classified. Overall, the goal to find the

185 optimum window size segment, select the best features, and use different types of classifiers was to identify  
 186 and built a classifier model that provides the highest classification performance for activity recognition.  
 187 Finally, the physical intensity, activity duration and frequency information are estimated from the activity  
 188 recognition and then used to determine the ergonomic risk levels associated with each category of activities  
 189 performed by the participants. In the following sections, the detailed procedure of each method is discussed.  
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191

192 **Fig. 1.** Framework for overexertion-related ergonomic risk assessment

193

194 **Participants**

195 Two healthy male participants volunteered to participate in this study. Each participant was a student who  
 196 had basic construction engineering knowledge and experience in working at construction sites. The  
 197 participants mean age, weight, and height were  $27 \pm 4.24$  years,  $66 \pm 5.66$  kg, and  $1.65 \pm 0.21$  m, respectively.  
 198 Both participants had no history of mechanical pain/injury of upper extremities, back, or lower extremities.



199 The participants provided their informed consent forms in accordance with the procedure approved by the  
200 Human Subject Ethics Subcommittee of the Hong Kong Polytechnic University (reference number:  
201 HSEARS20170605001).

202

### 203 ***Data Collection***

#### 204 **Data Acquisition Using a Wearable Insole Pressure System**

205 The current study proposed an OpenGo system (Moticon GmbH, Munich, Germany), which is a wearable  
206 insole pressure system for measuring both triaxial acceleration and spatiotemporal foot plantar pressure  
207 distribution data (Antwi-Afari and Li 2018g). It consists of two sensor insoles (containing 13 capacitive  
208 sensors each) that measure the foot plantar pressure distribution. Each wearable insole sensor electronically  
209 incorporates 3D micro-electro-mechanical systems (MEMS) accelerometer (Bosh Sensortech BMA 150),  
210 which is located at the center with respect to gravity. In the current study, foot plantar pressure patterns and  
211 acceleration signals were sampled at 50 Hz.

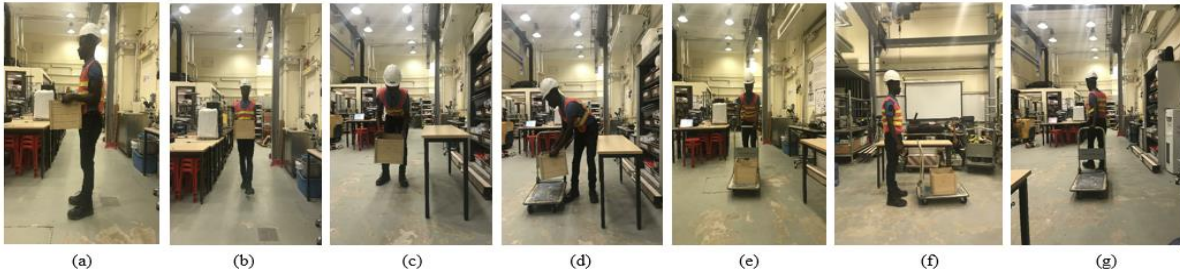
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#### 213 **Experimental Design and Procedure**

214 The current study adopted a cross-sectional study design in a single visit. The experimental procedure was  
215 explained to the participants. In order to simulate overexertion-related construction workers' activities to  
216 mimic those conducted by a worker on construction sites (i.e., real-world conditions), the following criteria  
217 were set in the experimental protocol. First, each participant was asked to wear a pair of safety boots and a  
218 hard hat during the testing sessions. Second, each participant was shown representative videos of  
219 overexertion-related construction workers' activities—which are performed by workers in real-world  
220 conditions. These activities were basically related to manual material handling tasks involving excessive  
221 force exertions. They included upright holding, carrying, lifting, lowering, pushing and pulling.

222 In this research, each participant performed 20 cycles of each of the following overexertion-related  
223 construction workers' activities: (1) load a wooden box—measuring 30 × 30 × 25 cm with dumbbell weights  
224 and hold it in an upright standing position to receive further instruction from the experimenter (Fig. 2a); (2)  
225 walk while carrying the weighted box along a set path to a particular destination on the floor (Fig. 2b); (3)

226 lift the weighted box from the floor level onto a table at waist level for inspection (Fig. 2c); (4) lower the  
227 weighted box from the table at waist level onto a four-wheeled dolly (Fig. 2d); (5) walk while pushing the  
228 dolly on a set path to another destination (Fig. 2e); (6) wait while the experimenter offload the dumbbell  
229 weights from the wooden box (Fig. 2f); and (7) walk while pulling the dolly to a specific location in the  
230 laboratory (Fig. 2g). The entire experiment was recorded using a video camcorder and both acceleration and  
231 foot plantar pressure distribution data were synchronized. After data collection, the activities were manually  
232 annotated based on inspecting the recorded video and the collected data. Consequently, these activities were  
233 grouped into four different categories of activities, namely (1) category-1-activities: grip force; (2) category-  
234 2-activities: lift/lower/carry; (3) category-3-activities: push/pull; and (4) category-4-activities: any other non-  
235 risk activity. The categories of activities mostly require overexertion such as forces involved in grip force,  
236 forces involved in lifting, lowering, or carrying, and forces involved in pushing or pulling (Jaffar et al. 2011).  
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246 **Fig. 2.** Laboratory experimental setup (images by authors): (a) upright holding; (b) carrying;  
 247 (c) lifting; (d) lowering; (e) pushing (f) upright standing (g) pulling

248

249 ***Data Segmentation***

250 The sliding window technique was adopted to divide the raw sensor signals into smaller window size  
 251 segments. This technique is well-suited for real-time applications since it does not require any pre-processing  
 252 of raw sensor data (Preece et al. 2009). Also, overlapping adjacent windows reduces the error caused by  
 253 transition state noise (Su et al. 2014). Similar to previous studies (Antwi-Afari et al. 2018b; Nath et al. 2018),  
 254 a 50% overlap of the adjacent windows was adopted for this study. In order to find an optimum window size,  
 255 four window size segments were examined in this research. These are 0.32s, 0.64s, 1.28s and 2.56s which  
 256 corresponds to 16 ( $2^4$ ), 32 ( $2^5$ ), 64 ( $2^6$ ), and 128 ( $2^7$ ) data samples, respectively. They are selected because of  
 257 the conversion of time-domain to frequency-domain using fast Fourier transform (FFT) in MATLAB 9.2  
 258 software (Matlab, The MathWorks Inc., MA, USA) requires the window size of a power of two (Akhavian  
 259 and Behzadan 2016).

260

261 ***Feature Extraction***

262 One of the most essential procedures in activity recognition and classification studies is feature extraction.  
 263 This procedure involves extracting relevant informative features from raw sensor data of each window size  
 264 to be used as input variables for model development and classification. The collected data by the wearable  
 265 insole pressure system was a set of discrete points of acceleration and foot plantar pressure patterns. The  
 266 three-axis acceleration and 13 plantar pressure distribution data of each foot depict the human motion

267 acceleration and foot plantar pressure distribution when the participants conducted the overexertion-related  
268 activities. Consequently, the two forms of collected data could reflect unique patterns of different categories  
269 of activities, implying that a single data point could not be able to represent the activities. As a result, this  
270 research study extracted different groups of features from acceleration and foot plantar pressure patterns for  
271 classification performance. Three groups of common features mostly used by previous studies (Akhavian  
272 and Behzadan 2016; Antwi-Afari et al. 2018f; Nath et al. 2018; Ryu et al. 2018) for activity recognition were  
273 selected in this study and extracted from acceleration and foot plantar pressure data. They are (1) time-domain  
274 features, (2) frequency-domain features, and (3) spatiotemporal features. Table 1 presents a summary of the  
275 features. As shown in Table 1, twelve time-domain features were extracted from each window size. These  
276 features are also known as signal statistical features. They are relatively simple to calculate and, as such  
277 reduce computational time. Notably, the last three features (Table 1) were extracted from only acceleration  
278 data. Moreover, we extracted two frequency-domain features (Table 1) by converting signal streams in time-  
279 domain to frequency-domain by using the FFT function (Attal et al. 2015; Akhavian and Behzadan 2016).  
280 Furthermore, three spatiotemporal features (Table 1) were extracted from only foot plantar pressure  
281 distribution data. Considering data collection in 3 axes of acceleration data and 13 axes of foot plantar  
282 pressure distribution data of each foot and 17 independent features extracted (see Table 1), a total of 436  
283 features were extracted.

284

**Table 1.** Summary of Features

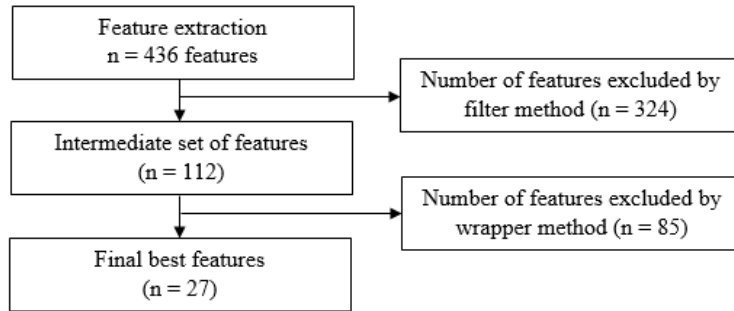
Item	Time-domain	Item	Frequency-domain	Item	Spatiotemporal
1.	Mean	1.	Spectral energy	1.	Pressure-time integral
2.	Variance	2.	Entropy spectrum	2.	Anterior/Posterior centre of pressure (A/P COP)
3.	Maximum			3.	Medial/Lateral centre of pressure (M/L COP)
4.	Minimum				
5.	Range				
6.	Standard deviation				
7.	Root mean square				
8.	Kurtosis				
9.	Skewness				
10.	Standard deviation magnitude				
11.	Sum vector magnitude				
12.	Signal magnitude area				

285

## 286 Feature Selection

287 Fig. 3 presents a flowchart depicting the hybrid feature selection method. As presented in Fig. 3, a total of  
 288 436 features were initially extracted from acceleration and foot plantar pressure distribution data for the  
 289 purpose of classification performance. Since numerous extracted features may lead to overfitting of data set,  
 290 choosing an appropriate dimensionality reduction is a crucial feature selection step which helps to select an  
 291 optimal set of features (i.e., best features), and also limit the complexity of the classifier model (Cates et al.  
 292 2018). This research adopted the hybrid feature selection method (Barkalla et al. 2017) as depicted in Fig. 3.  
 293 This method comprises the successive application of both the filter and wrapper methods. To do this, the  
 294 authors used two commonly filter methods, namely: (1) analyses of variance (ANOVA) and (2) Pearson  
 295 correlation coefficient to evaluate the performance of each feature for discriminating between the categories  
 296 of activities. Based on the average values, all the extracted features were ranked and the highest ranked  
 297 features (i.e., 112 features) are selected for the wrapper method (Fig. 3). Next, the wrapper method was used  
 298 to select the best features (i.e., 27 features) by using a Random Forest classifier to evaluate the performance  
 299 accuracy of each feature (Fig. 3).

300



301

302 **Fig. 3.** A flowchart depicting the hybrid feature selection method

303

### 304 *Reference Data*

305 Following data preparation and feature extraction, a class label of each category of activity was assigned to  
 306 each window size with the assistance of the video data. Table 2 shows the class labels and the number of  
 307 collected data samples in each activity of category. This step in human activity recognition serves as the  
 308 ground truth to evaluate the performance of the classifiers (Akhavian and Behzadan 2016; Antwi-Afari et al.  
 309 2018f).

310 **Table 2.** Class Label and Collected Data Samples in Each Category of Activity

Class label/activity category	Category of activity	Number of data samples
1	Grip force	98,896
2	Lift/Lower/Carry	487,274
3	Pull/Push	284,528
4	Any other non-risk activity	187,852

311

### 312 *Classifier Training*

313 In this research, supervised machine learning classifiers were adopted for training and classification. The  
 314 goal was to generate a model by learning acceleration and foot plantar pressure distribution data by using the  
 315 extracted features as input variables to match the class labels of the different categories of activities. The  
 316 performance of the classifiers was assessed by evaluating the accuracy in predicting unseen class labels (i.e.,  
 317 output variables). These classifiers have achieved satisfactory results in the field of human activity  
 318 recognition and fall risk events (Akhavian and Behzadan 2016; Antwi-Afari et al. 2018c; Ryu et al. 2018).  
 319 In order to select the best classifier, five different types of supervised machine learning classifiers, namely 1)

320 Artificial Neural Network (ANN), 2) Decision Tree (DT), 3) Random Forest (RF), 4) K-Nearest Neighbor  
321 (KNN), and 5) Support Vector Machine (SVM) were examined. All data processing including the statistical  
322 computation of features and training, testing, and validation of the classifiers were performed using Toolbox  
323 in MATLAB 9.2 software (Matlab, The MathWorks Inc., MA, USA).

324 ANN has advantages of not only using a trained model to recognize previously unseen dataset but also having  
325 a potentially high tolerance for noisy data (Haykin 2009). As a result, this research used an ANN-based on a  
326 multilayer perceptron feed-forward neural network (Haykin 2009). DT is a schematic, tree-like classifier  
327 constructed to divide the training dataset into partitions according to a given set of splitting rules for each  
328 node, which is repeated iteratively until a leaf node is reached (Preece et al. 2009). The classification and  
329 regression tree (CART) algorithm was used to construct the best splitting rule for each node (Akhavian and  
330 Behzadan 2016; Zhang et al. 2018). RF classifier is a supervised ensemble classification method that makes  
331 use of multiple randomized decision trees to subdivide the feature space. Each decision tree in the RF is  
332 learned from a bootstrap aggregating sample (i.e., bagging) and a random subset of features (Breiman 1984).  
333 KNN is a non-parametric method for a classification based on the  $k$ -nearest training data set and vectors in  
334 the feature space (Ke et al. 2013). In this research, the distance of the neighbors over the feature space is  
335 calculated by using the Euclidean distance (Akhavian and Behzadan 2016). SVM is a non-probabilistic binary  
336 linear classifier (i.e., distinguish between two classes) in its standard soft margin, which attempts to find the  
337 best hyperplane that separates one class of dataset from the other class (Cortes and Vapnik 1995). In this  
338 study, the kernel function used for non-linear classification is the Gaussian radial basis function (RBF)  
339 (Akhavian and Behzadan 2016).

340

#### 341 ***Model Assessment***

342 Model assessment is the final step in human activity recognition in which the accuracy of the classifiers was  
343 assessed. The 10-fold cross-validation was used to assess the accuracy and validity of the classifier models  
344 (Barkalla et al. 2017). The accuracy and sensitivity indicators were used to evaluate the performance of the  
345 classifiers (Attal et al. 2015).

346

347 ***Activity Recognition***

348 Once the model is trained, and its parameters are finalized, it can be used for recognizing activities for which  
349 it has been trained. While data is being collected to determine the activities according to a trained classifier,  
350 such data can be stored in a dataset repository and be added to the existing training data, so that the model is  
351 further trained with a richer training dataset.

352

353 ***Estimation of Physical Intensity, Activity Duration and Frequency***

354 One of the great potentials of using a wearable insole pressure system is that it can provide the total ground  
355 reaction force data while performing a given activity. As such, it was assumed that the total ground reaction  
356 force is equal to the physical intensity (i.e., the amount of physical effort required to perform a given task)  
357 and self-weight of each participant. Consequently, the physical intensity was calculated by subtracting the  
358 participant's self-weight from the total ground reaction force (Yu et al. 2018). Next, the activity duration was  
359 calculated from the corresponding windows. The duration of each instance was calculated by counting the  
360 number of windows in that category and multiplying the result by half of the window size (i.e., 50% overlap  
361 of adjacent windows) (Nath et al. 2018). The total duration of a category was evaluated by summing the  
362 durations of all instances of that category. Lastly, the frequency (i.e., how many times a category of activity  
363 was performed) was determined by counting all the instances of that category (Simoneau et al. 1996).

364

365 ***Overexertion-Related Ergonomic Risk Assessment***

366 Table 3 presents the ergonomic risk levels (low, moderate, and high) that can be used to estimate the physical  
367 intensity, activity duration and frequency information of each category of activity (OSHA 2012). In order to  
368 estimate for the corresponding ergonomic risk levels, physical intensity, activity duration and frequency were  
369 expressed as weight of the object (kg), percentages of the work shift, and frequency per minute of the shift,  
370 respectively. In this study, a shift is the total duration of the experiment.

371

372

373



374

**Table 3.** Ergonomic Risk Levels of Categories of Activities

Activity category	Risk factor parameter	Low risk	Moderate risk	High risk
1	Grip effort	Hold object weighing 5 kg or low worker effort	Hold object weighing 5 kg or Medium worker effort	Hold object weighing 5 kg or high worker effort
	Duration/shift	Up to 25%	26 – 50%	51 – 100%
	Frequency	Gripping < 5 s at once	Gripping 5 – 30s at once	Gripping > 30 s at once
2	Weight of object	< 8 kg	8 – 23 kg	> 23 kg
	Duration/shift	Up to 25%	26 – 50%	51 – 100%
3	Frequency per minute	< 1	1 – 5	> 5
	Force required	< 9 kg	9 – 23 kg	> 23 kg
	Duration/shift	Up to 25%	26 – 50%	51 – 100%
4	Frequency per minute	< 1/480	1/480 – 10	> 10
	N/A	N/A	N/A	N/A

375

## 376 **Results and Discussion**

377 This is the first study to automatically recognize overexertion-related workers' activities and assess  
378 corresponding ergonomic risk levels using acceleration and foot plantar pressure distribution data measured  
379 by a wearable insole pressure system. The results of the present study evaluated the classification  
380 performance of the proposed approach in two main ways. First, the combined data set from both participants  
381 were used for activity recognition to determine the best classifier, optimal selected features and window sizes.  
382 Second, an individualized participant evaluation was conducted to evaluate the performance of the proposed  
383 approach.

384

### 385 *Classification Performance for Combined Data Set from both Participants*

386 This section presents the results and discussion of the classification performance according to the types of  
387 classifiers, selected features and optimal window size using combined data set from both participants based  
388 on 10-fold cross-validation. Before determining the data optimization, the hybrid feature selection was used  
389 to select the best features for recognizing overexertion-related workers' activities. Table 4 shows the best  
390 features for each participant using the hybrid feature selection. As shown in Table 4, only 23 features were  
391 selected as the best features for classification performance using the combined data set. This is because these  
392 features are considered to be common optimal best features among the two participants.

393 Table 5 presents the classification accuracy for the combined data set using all extracted features and best  
394 features. Comparing the different classifiers, it is apparent from Table 5 that the RF classifier had the best  
395 classification accuracy among the five different types of classifiers. By using all extracted features, the RF  
396 classifier achieved the highest accuracy of 97.6% with a 2.56s window size, while the lowest accuracy was  
397 36.9% from the ANN classifier with a 0.32s window size (Table 5). Similarly, the RF classifier had the best  
398 accuracy (98.3%) with a 2.56s window size followed by the SVM, KNN, DT and ANN classifiers using the  
399 best features (Table 5). It was found that all classifiers tend to increase classification accuracy with increasing  
400 window size. [Compared with the findings of previous studies by using accelerometers for recognizing](#)  
401 [masonry activities, the classification performance of our results was higher, with the best result being 79.83%](#)  
402 [\(Joshua and Varghese 2010\), and 88.1% \(Ryu et al. 2018\). Although there are consistencies in adopting an](#)

403 overlap size of adjacent windows (i.e., 50%), the findings that were found based on the best window size and  
404 the best classifier were different from previous studies. In the study by Joshua and Varghese (2010), the  
405 classification accuracies of 79.83% (all extracted features) and 74% (best features) were obtained by using  
406 the multilayer perceptron neural network classifier with 256 samples (i.e., 4.23s window size) in an  
407 uninstructed environment. Alternatively, Ryu et al (2018) reported a classification accuracy of 88.1% using  
408 the multiclass SVM classifier with a 4s window size while classifying all the participants. In the present study,  
409 the classifiers had their highest classification accuracies with a 2.56s window size either by using all extracted  
410 features or best features (Table 5). Notably, the best accuracy achieved by the RF classifier demonstrates that  
411 both acceleration and foot plantar pressure distribution data captured by a wearable insole pressure system  
412 show unique patterns for recognizing the categories of activities. Compared with other classifiers as reported  
413 by previous studies (Joshua and Varghese 2010; Ryu et al. 2018; Yang et al. 2019), the RF classifier 1) is  
414 less sensitive to the selection of features and window sizes, 2) can reduce the computational time during data  
415 preprocessing; and 3) can minimize over-fitting issues (Pavey et al. 2017). Consequently, the findings of this  
416 study indicate that the RF classifier could be reliably used to recognize and classify overexertion-related  
417 workers' activities, which is one of the main causes of WMSDs among workers.

418 In order to investigate the classification results in each category of activity, a confusion matrix of 10-fold  
419 cross-validation from the best classifier (i.e., RF) with a 2.56s window size is presented in Fig. 4. As  
420 illustrated in Fig. 4, the rows show the percentage of true classes, and the columns reveal the percentage of  
421 predicted classes of each category of activity. Also, the diagonal represents the percentage of true positives  
422 (i.e., sensitivity) (Fig. 4). As shown in Fig. 4, each category of activity had more than 95% in positive  
423 detection of the classes using the best features. This classification results obtained from the RF classifier  
424 substantiates the hypothesis that each category of activity creates unique patterns of acceleration and foot  
425 plantar pressure distribution data, which enabled the detection and classification of the different categories  
426 of activities. It was found that the most accurately classified and detected category of activity was category-  
427 2-activity (99.3%) (Fig. 4). Alternatively, the most misclassified categories of activities are category-1-  
428 activities and category-4-activities (2.7%) (Fig. 4). These errors might be attributed to (1) activity durations,  
429 (2) the number of data samples (3) similarities in conducting these two categories of activities. Compared to

430 other categories of activities, category-1-activities and category-4-activities had shorter activity durations  
 431 and smaller data samples (Table 2). Sensor streams in shorter window size segments and smaller data samples  
 432 are not enough to differentiate categories of activities because they could contain similar acceleration and  
 433 foot plantar pressure distribution patterns. In particular, the signal patterns in shorter window size segments  
 434 are difficult to obtain unique patterns for each category of activity; as a result, they led to classification errors.  
 435

436 **Table 4.** Best Features for Participant I and Participant II

Rank	Participant I	Participant II
1	PP <sub>2</sub> Mean	PP <sub>2</sub> Mean
2	PP <sub>4</sub> Mean	PP <sub>4</sub> Mean
3	PP <sub>7</sub> Mean	PP <sub>7</sub> Mean
4	ACC <sub>28</sub> Mean	ACC <sub>28</sub> Mean
5	ACC <sub>32</sub> Mean	ACC <sub>32</sub> Mean
6*	PP <sub>68</sub> Max	PP <sub>70</sub> Max
7*	PP <sub>88</sub> Max	PP <sub>85</sub> Max
8*	ACC <sub>93</sub> Max	ACC <sub>91</sub> Max
9*	ACC <sub>94</sub> Max	ACC <sub>95</sub> Max
10	PP <sub>195</sub> RMS	PP <sub>195</sub> RMS
11	PP <sub>216</sub> RMS	PP <sub>216</sub> RMS
12	ACC <sub>220</sub> RMS	ACC <sub>220</sub> RMS
13	ACC <sub>222</sub> RMS	ACC <sub>222</sub> RMS
14	ACC <sub>224</sub> RMS	ACC <sub>224</sub> RMS
15	PP <sub>355</sub> PTI	PP <sub>355</sub> PTI
16	PP <sub>360</sub> PTI	PP <sub>360</sub> PTI
17	PP <sub>364</sub> PTI	PP <sub>364</sub> PTI
18	PP <sub>375</sub> PTI	PP <sub>375</sub> PTI
19	PP <sub>378</sub> PTI	PP <sub>378</sub> PTI
20	PP <sub>383A</sub> /P COP	PP <sub>383A</sub> /P COP
21	PP <sub>410M/L</sub> COP	PP <sub>410M/L</sub> COP
22	ACC <sub>431</sub> SDM <sub>L</sub>	ACC <sub>431</sub> SDM <sub>L</sub>
23	ACC <sub>432</sub> SDM <sub>R</sub>	ACC <sub>432</sub> SDM <sub>R</sub>
24	ACC <sub>433</sub> SVM <sub>L</sub>	ACC <sub>433</sub> SVM <sub>L</sub>
25	ACC <sub>434</sub> SVM <sub>R</sub>	ACC <sub>434</sub> SVM <sub>R</sub>
26	ACC <sub>435</sub> SMA <sub>L</sub>	ACC <sub>435</sub> SMA <sub>L</sub>
27	ACC <sub>436</sub> SMA <sub>R</sub>	ACC <sub>436</sub> SMA <sub>R</sub>

437 Note: Features marked in asterisk are distinct for each participant

438  
 439 **Table 5.** Classification Accuracy (%) for Combined Data of Participants Using All Extracted Features and Best  
 440 Features

Window size	All extracted features					Best features				
	ANN	DT	KNN	RF	SVM	ANN	DT	KNN	RF	SVM
0.32s	36.9	69.3	81.5	91.1	90.2	40.5	72.5	82.1	93.7	91.3
0.64s	40.2	72.4	83.3	94.3	91.4	48.7	75.4	86.9	95.6	92.9
1.28s	50.1	75.3	86.7	95.6	92.1	55.2	77.5	88.3	96.1	94.2
2.56s	55.6	78.2	89.8	97.6	93.9	60.3	80.6	91.9	98.3	95.6

	1	95.8%	1.2%	0.3%	2.7%
	2	0.1%	99.3%	0.6%	0.0%
True class	3	0.0%	1.9%	98.0%	0.1%
	4	1.5%	0.7%	0.5%	97.3%
		1	2	3	4
		Predicted class			

441 **Fig. 4.** Confusion matrix of the RF classifier for combined data set using the best features  
 442 with a 2.56s window size

443

444 *Classification Performance for Individualized Data Set of Each Participant*

445 In order to examine the variability of movement between participants the classification accuracies of the  
 446 types of classifiers, optimal selected features and window sizes were compared when both the training and  
 447 testing data sets were only attributed to a single participant. The best features of each participant are presented  
 448 in Table 4. It was found that each participant had 27 best features using the hybrid feature selection.

449 Table 6 presents the classification accuracy for individualized data set of each participant based on all  
 450 extracted features and best features. By using all extracted features, the classification accuracy based on the  
 451 different types of classifiers for each participant was highest in the RF classifier as compared to the other  
 452 classifiers (Table 6). Within each window size, the RF classifier had the highest accuracy in each participant  
 453 by using all extracted features, followed by the SVM, KNN, DT, and ANN classifiers (Table 6). The highest  
 454 accuracies of participant I and participant II based on the RF classifier with a 2.56s window size by using all  
 455 extracted features were 98.7% and 98.3%, respectively (Table 6). Similar results were found when using the  
 456 best features of each participant. Specifically, the RF classifier had the best accuracy by using the best  
 457 features of each participant, followed by the SVM, KNN, DT, and ANN classifiers (Table 6). The  
 458 aforementioned results were similar in each window size. [A previous study had reported an average](#)  
 459 [classification accuracy of 95.45% with a 6.4s window size for individualized data set based on the DT](#)  
 460 [classifier \(Zhang et al. 2018\).](#) Regardless of the optimal window size, these results indicate that with large  
 461 [samples of data sets, the RF classifier could be reliable for recognizing and classifying overexertion-related](#)

462 workers' activities when compared to the classifiers. On the other hand, the results, therefore, suggest that  
463 the ANN classifier requires a larger data set to optimize the classifier parameters. The highest accuracies of  
464 participant I and participant II based on the RF classifier with a 2.56s window size by using the best features  
465 were 99.3% and 99.1%, respectively (Table 6). These results suggest that a larger window size segment  
466 provides better classification performance when compared to a smaller window size segment, and these  
467 findings are consistent with reported findings of previous studies by using accelerometers for recognizing  
468 workers' activities (Joshua and Varghese 2010; Ryu et al. 2018; Zhang et al. 2018).

469 With regards to the different types of classifiers, best features, and optimal window size, the participant I had  
470 higher accuracies compared to participant II (Table 6). These results indicate that between-subject variations  
471 exist in recognizing overexertion-related workers' activities even though they performed similar tasks. It is  
472 therefore plausible to conclude that the participant I conducted activities with persistent working techniques  
473 similar to real-world situations as compared to participant II. Notably, the classification performances in  
474 different types of classifiers, optimal selected features and window sizes are higher for individualized data  
475 of each participant (Table 6) as compared to combined data set of participants (Table 5). Similar findings  
476 were reported in a previous study showing a decreased by 5.6% of classification accuracy for combined  
477 participants when compared to individual participants (Zhang et al. 2018). Taken together, there are two  
478 reasons to explain these findings. First, since there was a slight variation of data set between participants, the  
479 data set from one participant may be a noisy data to the other participant, thus resulting in lower accuracy  
480 when using combined data set from both participants. Second, using larger data samples may result in over-  
481 fitting of training data set with high computational time, thus, resulting in lower accuracy while using  
482 combined data set from both participants.

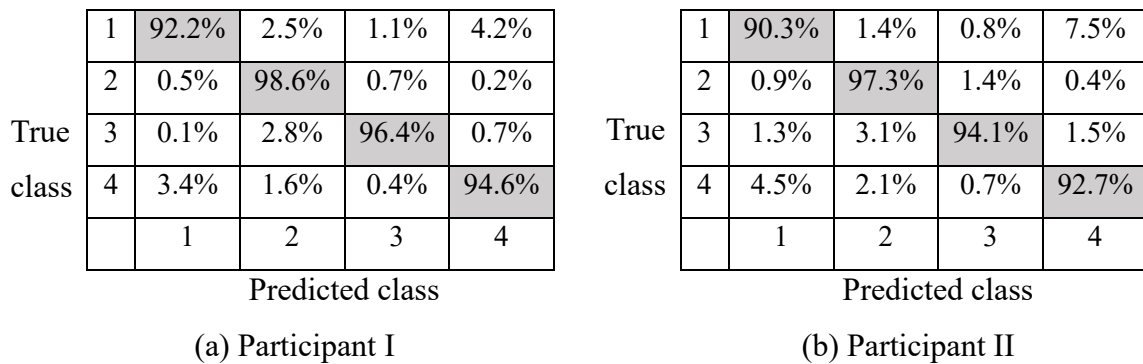
483 Again, confusion matrices of 10-fold cross-validation from the best classifier (i.e., RF) with a 2.56s window  
484 size of the participant I and participant II are presented in Fig. 5a and Fig. 5b, respectively. As shown in Fig.  
485 5a and Fig. 5b, the sensitivity of each category of activity was more than 92% and 90%, respectively. This  
486 result further confirms that there are between-participant variations among the two participants although they  
487 performed the same categories of activities. In addition, the most misclassified category of activities had

488 4.2% in participant I (Fig. 5a) and 7.5% in participant II (Fig. 5b). These misclassified categories of activities  
 489 were category-1-activity and category-4-activity in both participants.

490 **Table 6.** Classification Accuracy (%) for Individualized Data of Participants Based on All Extracted Features and Best  
 491 Features

Window size		All extracted features					Best features				
		ANN	DT	KNN	RF	SVM	ANN	DT	KNN	RF	SVM
0.32s	Participant I	72.3	82.4	85.8	91.6	90.9	74.4	84.8	87.9	92.6	91.7
	Participant II	72.1	82.1	85.5	91.2	90.5	74.0	84.3	87.6	92.2	91.2
0.64s	Participant I	74.9	81.7	82.7	94.6	91.7	76.6	83.6	85.8	95.6	92.4
	Participant II	74.5	80.8	82.4	94.3	91.5	76.1	83.4	85.4	95.1	92.2
1.28s	Participant I	75.5	85.8	86.7	97.9	92.9	78.7	87.7	88.7	98.8	93.8
	Participant II	75.2	85.4	86.4	97.5	92.4	78.2	87.4	88.1	98.2	93.2
2.56s	Participant I	78.7	89.5	90.8	98.7	94.9	80.8	90.5	91.7	99.3	96.7
	Participant II	78.3	89.1	90.1	98.3	94.5	80.1	90.4	91.2	99.1	96.5

492



493 **Fig. 5.** Confusion matrix of the RF classifier for each participant using the best features  
 494 with a 2.56s window size

495

496 ***Physical Intensity, Activity Duration and Frequency Estimation***

497 Table 7 shows the actual and estimated physical intensity, activity duration and frequency of each participant  
 498 in each category of activity. According to Table 7, the estimated physical intensity, activity duration and  
 499 frequency results of the participant I were within  $\pm 11.1\%$ ,  $\pm 2\%$ , and  $\leq -15.4\%$ , from the actual values  
 500 respectively. On the other hand, the estimated physical intensity, activity duration and frequency results of  
 501 participant II were within  $\pm 25\%$ ,  $\pm 5\%$ , and  $\leq -42.9\%$ , from the actual values respectively. Based on these  
 502 results, it could be concluded that the estimation of physical intensity, activity duration and frequency in  
 503 participant I was slightly accurate as compared to participant II.

504

505 **Table 7. Actual and Estimated Physical Intensity, Activity Duration and Frequency**

Participant	Activity category	Physical intensity			Activity duration			Frequency		
		Actual (kg)	Estimated (kg)	Error	Actual (s)	Estimated (s)	Error	Actual	Estimated	Error
PI	1	14	13	7.1%	330	325	1.5%	20	23	-15.0%
	2	18	20	-11.1%	2305	2303	0.1%	63	70	-11.1%
	3	25	24	4.0%	3600	3594	0.2%	72	76	-5.6%
	4	19	17	10.5%	550	561	-2.0%	13	15	-15.4%
PII	1	15	16	-6.7%	338	355	-5.0%	22	27	-22.7%
	2	16	19	-18.8%	2315	2322	-0.3%	60	69	-15.0%
	3	26	30	-15.4%	3620	3628	-0.2%	68	72	-5.9%
	4	16	12	25.0%	570	542	4.9%	14	20	-42.9%

506



507 *Ergonomic Risk Level Assessment*

508 Following the evaluation of actual and estimated physical intensity, activity duration and frequency  
509 information of each participant, the corresponding ergonomic risk levels are calculated. These calculated  
510 values are based on risk levels of the category of activities as presented in Table 3. Table 8 summarizes the  
511 calculation of overexertion-related ergonomic risk levels. According to Table 8, all estimated risk levels are  
512 similar to actual risk levels in each participant. It was found that the difference between actual and estimated  
513 physical intensity is negligible compared to the difference between physical intensity for two adjacent risk  
514 levels (Table 8). Similarly, there was no significant difference between actual and estimated risk levels for  
515 either duration per shift or frequency per minute (Table 8). Given above, it is plausible to conclude that the  
516 proposed approach is feasible to calculate the actual and the estimated risk levels of each category of activity,  
517 which are within the same level of risk for each participant. [Nath et al. \(2018\)](#) reported similar findings for  
518 [the actual and the corresponding estimated risk falls into the same level of risk by collecting time-stamped](#)  
519 [motion data from body-mounted built-in smartphone IMU sensors. Different from previous studies, the](#)  
520 [novelty of this study lies in estimating the physical intensity, activity duration, and frequency information for](#)  
521 [assessing the ergonomic risk levels of overexertion-related construction workers' activities by collecting](#)  
522 [acceleration and foot plantar pressure distribution data captured by a wearable insole pressure system.](#)

523 **Table 8.** Calculation of Overexertion-Related Ergonomic Risk Levels

Item	Activity category	Physical intensity		Risk level	Duration/Shift			Risk level	Frequency per minute			Risk level
		Actual	Estimated		Actual	Estimated	Diff.		Actual	Estimated	Diff.	
PI	1	> 5 kg or high effort	> 5 kg or high effort	H	5%	5%	0%	L	0.18	0.20	0.02	L
	2	8-23 kg	8-23 kg	M	34%	34%	0%	M	0.56	0.62	0.06	L
	3	>23 kg	>23 kg	H	53%	53%	0%	H	0.64	0.67	0.03	M
PII	1	> 5 kg or high effort	> 5 kg or high effort	H	5%	5%	0%	L	0.19	0.24	0.05	L
	2	8-23 kg	8-23 kg	M	34%	34%	0%	M	0.53	0.60	0.07	L
	3	>23 kg	>23 kg	H	53%	53%	0%	H	0.60	0.63	0.03	M

524

525 **Contributions, Potential Applications, and Practical Challenges**

526 This section discusses the contributions, potential applications and practical challenges of the proposed  
527 approach. First, overexertion-related workers' activities were conducted in a controlled laboratory setting to  
528 examine the feasibility of automated activity recognition and ergonomic risk assessment using acceleration  
529 and foot plantar pressure distribution data captured by a wearable insole pressure system. Cross-validation  
530 results showed that the RF classifier had the best classification accuracy of 98.3% and a sensitivity of each  
531 category of activities was above 95% with a 2.56s window size by using a combined data set of both  
532 participants. The results show that the proposed approach is reliable to autonomously and remotely monitor  
533 participants during simulated overexertion-related workers' activities. In other words, the results demonstrate  
534 that acceleration and foot plantar pressure distribution data captured by a wearable insole pressure system  
535 show unique patterns for recognizing different categories of activities. Since the conducted experiments are  
536 generally peculiar to several construction workers (e.g., masons, carpenters, rebar workers) and other workers  
537 in industrialized sectors (e.g., manufacturing, agriculture), the proposed approach has a great potential  
538 application not only to be used as personal protective equipment for individualized construction workers but  
539 also in similar occupational trades. Second, the current study extends the authors' earlier works on automated  
540 detection and classification of awkward working postures (Antwi-Afari et al. 2018f) and loss of balance  
541 events (Antwi-Afari et al. 2018e). Specifically, the feasibility to automatically recognize overexertion-related  
542 workers' activities as a potential risk factor for developing WMSDs in construction was investigated in  
543 greater details in the current study. Despite the existing ergonomic risk assessment methods such as self-  
544 reported, observational-based, and vision-based methods that have some limitations, the proposed approach  
545 can allow researchers and safety managers to continuously and objectively evaluate overexertion-related  
546 activities that may lead to WMSDs among construction workers. The automated recognition of overexertion-  
547 related workers' activities may enable construction managers to accurately identify ongoing construction  
548 activities and easily share information with other project stakeholders. In addition, the novel method may  
549 help safety officers and construction managers to proactively identify potential risk factors for developing  
550 WMSDs in construction so as to implement effective interventions to minimize the occurrences of these risk  
551 factors on construction sites. Third, this is the first study to estimate the physical intensity, activity duration,

552 and frequency information for assessing the ergonomic risk levels of overexertion-related workers' activities  
553 using a wearable insole pressure system. Our results found that the estimated ergonomics risk levels are  
554 similar to actual risk levels. As such, the proposed approach has a great potential application to replace  
555 subjective, time-consuming and interruptive approaches. The findings could be valuable for real-world  
556 implementations where it is possible to investigate whether the proposed approach (1) has the potential for  
557 recognizing and predicting workers' activities of new data collected in future instances to existing data  
558 storage; (2) is reliable and robust against the variability of movements among workers (e.g., directions of  
559 movement) while performing activities; (3) could be used to automate work-sampling process for evaluating  
560 workers' productivity.

561 Despite the aforementioned contributions and potential applications of the proposed approach, there are  
562 several practical challenges that need to be addressed when using it in a real-world setting. They include but  
563 not limited to (1) system design and development; (2) data collection, storage and processing; and (3) ethical  
564 and privacy issues. The effective use of a wearable insole pressure system on construction sites could be  
565 affected by design challenges from the hardware and software constraints arising from size and weight of the  
566 system, power efficiency and consumption. Due to the dynamic nature of the construction environment, the  
567 size and weight of pressure sensors must be small and lightweight to achieve a non-invasive and unobtrusive  
568 continuous monitoring of workers' activities. Compared to wearable IMU-based systems, wearable insole  
569 pressure system must be developed in different foot sizes to fit the safety boots of workers on site. The use  
570 of pressure sensor software programmes based on a desktop computer may interrupt with ongoing  
571 construction activities. As such, software manufacturers must incorporate it on smartphone, smartwatches or  
572 wrist band that can be easily worn by workers. With regards to power efficiency and consumption, a proposed  
573 method to address such issues is either by using a Bluetooth low energy (BLE), an ultralow-power technology  
574 for devices with limited battery capacity or Bluetooth 3.0 specification, which adopts the medium access  
575 control layers to a shared wireless medium (Soh et al. 2015). Unlike laboratory settings, collecting  
576 acceleration and foot plantar pressure data using a wearable insole pressure system at the workplace are  
577 expected to be affected by signal artifacts, missing data and high computational time issues. As such, filtering  
578 methods such as low pass filter, band-pass filter and notch filter need to be applied to remove signal artifacts

579 from collected data from construction sites. To prevent missing data problems, data collection by using a  
580 wearable insole pressure system must be stored either on a flash memory device or in cloud software. For  
581 easy accessibility and to reduce computation time, raw sensor data need to be processed and transmitted  
582 through a short range of standardized wireless communication networks such as Wi-Fi, Bluetooth, ANT +,  
583 and ZigBee. Lastly, ethical and privacy issues are mostly related to personal data protection and user  
584 confidentiality. To overcome the practical challenges arising from these issues, safety managers and  
585 construction institutions could provide subsidies and performance incentives as well as clear guidelines on  
586 privacy, confidentiality and proper use of a worker's information.

587

### 588 **Limitations and Future Directions**

589 Despite the findings of this study, some limitations should be addressed in future studies. First, the number  
590 of student participants who participated in this study was relatively small either comparable to or larger than  
591 similar previous studies (Antwi-Afari et al. 2018c; Kong et al. 2018; Nath et al. 2018). As such, the limited  
592 sample size of this study may not be enough to reflect the diverse physiological characteristics of construction  
593 workers. Besides, all the experiments were conducted in a laboratory setting. Future research is warranted to  
594 validate our experimental protocol by using a larger sample of experienced construction workers at the jobsite  
595 to generate a more robust evaluation and recognition of overexertion-related workers' activities and  
596 ergonomic risk assessment. Second, the current study was limited to the only overexertion-related workers'  
597 activities in construction, and therefore the results may not be generalized to other construction activities  
598 (e.g., sawing, installing rebar, hammering)—future research should consider different types of construction  
599 workers' activities. Such future studies would invariably help to further validate the proposed approach. Third,  
600 automated activity recognition by using a wearable insole pressure system can be integrated with other types  
601 of sensors such as depth sensors and physiological sensors to expand to other applications for construction  
602 workers. As such, automated overexertion-related workers' activities based on a wearable insole pressure  
603 system can be enhanced by integrating it with either oxygen consumption or heart rate monitoring sensors  
604 for an in-depth understanding of workers' physical conditions.

605

606 **Conclusions**

607 The current study examined the feasibility of using acceleration and foot plantar pressure distribution data  
608 captured by a wearable insole pressure system for automated recognition of overexertion-related workers'  
609 activities and assessing corresponding ergonomic risk levels. The proposed approach was tested in a  
610 laboratory setting by simulating overexertion-related workers' activities that may lead to developing WMSDs  
611 in construction. Cross-validation results found that the RF classifier had the best classification accuracy of  
612 98.3% and a sensitivity of more than 95.8% for each category of activities using the best features of combined  
613 data set with a 2.56s window size. Moreover, the results showed that the accuracy of each participant's data  
614 sets was higher than the combined data set using the best features. Furthermore, the actual and the  
615 corresponding estimated ergonomic risk levels fall within the same level of risk.

616 The findings from this study make significant contributions to research and practice. First, the current study  
617 shows that using acceleration and foot plantar pressure distribution data measured by a wearable insole  
618 pressure system is feasible for automated recognition of overexertion-related workers' activities. In particular,  
619 the proposed approach can continuously monitor and collect sensor data without interfering with ongoing  
620 activities on construction sites. In addition, it is non-intrusive and causes fewer constraints in body movement  
621 as well as minimizes discomfort. Furthermore, the outcome of using objective sensor data for recognizing  
622 overexertion-related workers' activities could help safety managers to reduce the shortcomings of existing  
623 activity recognition approaches. Second, a novel methodology to evaluate overexertion-related workers'  
624 activities which may lead to developing WMSDs in construction was presented. As a result, it extends the  
625 use of wearable sensing technologies for activity recognition and construction health and safety research. For  
626 example, it could be used to automate workers' productivity and safety hazards' detection. Third, this  
627 research study estimated the physical intensity, activity duration, and frequency information for assessing the  
628 ergonomic risk levels of different categories of activities. Consequently, the findings will enable a more  
629 comprehensive and meaningful analysis of ergonomic risks associated with overexertion. Overall, the  
630 findings would help develop a non-invasive wearable insole pressure system as a piece of personal protective  
631 equipment for continuous monitoring and activity recognition, which could assist researchers and safety

632 managers in understanding the causal relationship between overexertion-related ergonomic risk and WMSDs  
633 among construction workers.

634

#### 635 **Data Availability Statement**

636 All raw data and feature extraction codes generated or analyzed during the study are available from the  
637 corresponding author by request.

638

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645

#### 646 **Declarations of Interest**

647 None

648

#### 649 **References**

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