

## Single-machine scheduling with deteriorating jobs under a series-parallel graph constraint

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### Abstract

This paper considers single-machine scheduling problems with deteriorating jobs, i.e., jobs whose processing times are an increasing function of their starting times. In addition, the jobs are related by a series-parallel graph. It is shown that for the general linear problem to minimize the makespan, polynomial algorithms exist. It is also shown that for the proportional linear problem to minimize the total weighted completion time, polynomial algorithms exist, too.

*Keywords:* Scheduling; single machine; deteriorating jobs; series-parallel graph; makespan; total weighted completion time

## 1 Introduction

In classical scheduling theory it is assumed that the processing time of a job is constant. However, this assumption is invalid for the modelling of many modern industrial processes. There is a growing interest in the literature to study scheduling problems with *deteriorating jobs*, i.e., jobs whose processing times are an increasing function of their starting times. Such deterioration appears, e.g., in scheduling maintenance jobs or cleaning assignments, where any delay in processing a job is penalized and often implies additional time for accomplishing the job. Extensive surveys of different models and problems concerning deteriorating jobs can be found in Alidaee and Womer [1], and Cheng et al. [8].

Most of these studies focus on single-machine settings. Browne and Yechiali [4] considered a single-machine scheduling problem with deteriorating jobs. In this problem, the job processing time is a non-decreasing, start-time dependent linear function. They presented an optimal solution for makespan minimization. Mosheiov [12] considered the problem in which all the jobs are characterized by a common positive basic processing time. Using this basic assumption, Mosheiov

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proved that the optimal schedule to minimize flowtime is symmetric and has a V-shaped property with respect to the increasing rates of the job processing times. Mosheiov [13] considered the following objective functions: makespan, total flow time, sum of weighted completion times, total lateness, maximum lateness and maximum tardiness, and the number of tardy jobs. When the values of the normal processing time equal zero, all these problems can be solved polynomially. Sundararaghavan and Kunnathur [18] considered the single-machine scheduling problem in which the processing time is a binary function of a common start-time due date. The jobs have processing time penalties for starting after the due date, and the objective is to minimize the sum of weighted completion times. Three special cases of this problem can be solved optimally. Cheng and Ding [7] considered some problems with a decreasing linear model of the job processing times, but with ready time and deadline restrictions. They identified some interesting relationships between the linear models with decreasing and increasing start-time dependent parts. Bachman and Janiak [2] showed that the maximum lateness minimization problem under the linear deterioration assumption is NP-hard, and presented two heuristic algorithms. Bachman et al. [3] considered the problem of minimizing the total weighted completion time introduced by Browne and Yechiali [4]. They proved that the problem is NP-hard. Wu and Lee [20] considered the problem with deteriorating jobs to minimize the makespan on a single machine where the facility has an availability constraint. They showed that the problem can be solved by 0-1 integer programming. Hsu and Lin [10] considered a single-machine problem with deteriorating jobs to minimize the maximum lateness. They designed a branch-and-bound algorithm for deriving exact solutions by incorporating several properties concerning dominance relations and lower bounds.

Chen [6] and Mosheiov [14] considered scheduling linear deteriorating jobs on a group of parallel identical machines. Chen [6] considered minimum flow time and Mosheiov [14] studied makespan minimization. Mosheiov [15] considered makespan minimization and its computational complexity of flow shop, open shop and job shop problems. He introduced a polynomial-time algorithm for the two-machine flow shop and proved its NP-hardness when an arbitrary number of machines (three and above) is assumed. Wang and Xia [19] considered no-wait or no-idle flow shop scheduling problems with job processing times dependent on their starting times. In these problems the job processing time is a simple linear function of a job's starting time and some dominating relationships between machines can be satisfied. They showed that for the problems to minimize makespan or weighted sum of completion times, polynomial algorithms still exist. When the objective is to minimize maximum lateness, the solutions of a classical version may not hold.

In this paper we consider single-machine scheduling problems with deteriorating jobs under a series-parallel precedence constraints. The remaining part of the paper is organized as follows. In next section, a precise formulation of the problem with increasing job processing times is given.

The problems of minimizing the makespan and the total weighted completion time are studied in the third section and the fourth section, respectively. The last section contains some concluding remarks.

## 2 Basic notation, definition and observation

There are given a single machine and a set  $N = \{J_1, J_2, \dots, J_n\}$  of  $n$  independent and non-preemptive jobs. The schedule of the jobs must comply with a series-parallel graph precedence constraint imposed by a given digraph  $G = (N, A)$ . Each node  $J_j \in N$  is identified with a job. Job  $J_i$  precedes job  $J_j$  if there is a directed path from  $J_i$  to  $J_j$  in  $G$ . Let  $p_j$  denote the processing time of job  $J_j$  ( $j = 1, 2, \dots, n$ ). Throughout the paper, we will consider deteriorating processing times in two forms: general linear  $p_j(t) = p_j + \alpha_j t$ , and proportional linear  $p_j(t) = p_j(a + bt)$ , where  $p_j > 0, \alpha_j \geq 0, a \geq 0, b \geq 0$ , and  $t \geq 0$  is the job starting-time. For any  $j$ , the coefficients of  $p_j$  (or  $ap_j$ ) and  $\alpha_j$  (or  $bp_j$ ) are called the normal processing time and deterioration rate. All the jobs are available for processing at time  $t_0 \geq 0$ .

For any schedule  $\pi = [J_{\pi(1)}, J_{\pi(2)}, \dots, J_{\pi(n)}]$ , where  $J_{\pi(j)}$  means the  $j$ th job in schedule  $\pi$ ,  $C_j = C_j(\pi)$  represents the completion time of job  $J_j$ . The objective is to find a feasible schedule for which either the makespan  $C_{\max}$  is minimized or the total weighted completion time  $\sum_{j=1}^n w_j C_j$  is minimized. In the remaining part of the paper, all the problems considered will be denoted using the three-field notation scheme  $\alpha|\beta|\gamma$  introduced by Graham et al. [9].

## 3 Makespan problem

First, we need to introduce some notation and terminology; these will be the same as those used by Lawler [11] and Sidney [17] wherever possible.

**Definition 1** [11]. The class of *transitive series-parallel graphs* is defined recursively as follows:

1. A graph consisting of a single node, e.g.,  $G = (\{J_i\}, \emptyset)$ , is transitive series-parallel.
2. If  $G_1 = (N_1, A_1)$  and  $G_2 = (N_2, A_2)$ , where  $N_1 \cap N_2 = \emptyset$ , are transitive series-parallel, then:
  - (a) The graph

$$G = (N_1 \cup N_2, A_1 \cup A_2 \cup (N_1 \times N_2))$$

is also transitive series-parallel.  $G$  is said to be formed by the serial composition of  $G_1$  and  $G_2$ .

- (b) The graph

$$G = (N_1 \cup N_2, A_1 \cup A_2)$$

is also transitive series-parallel.  $G$  is said to be formed by the parallel composition of  $G_1$  and  $G_2$ .

A graph  $G$  is said to be series-parallel if and only if its transitive closure is transitive series-parallel. Given a series-parallel graph  $G$ , it is possible to repeatedly decompose  $G$  into series and parallel components, so as to show that the transitive closure of  $G$  is obtained by rules 1-2. The result is a rooted binary tree, which Lawer [11] called a decomposition tree, which is a binary tree with the leaves denoting jobs and the internal nodes denoting either a parallel or series composition of the two corresponding subtrees. Parallel and series composition of each internal node are labeled “ $P$ ” and “ $S$ ”, respectively, where by convention the left son precedes the right son in “ $S$ ”. Figure 2 shows a decomposition tree  $T$  for the graph  $G$  in Figure 1.

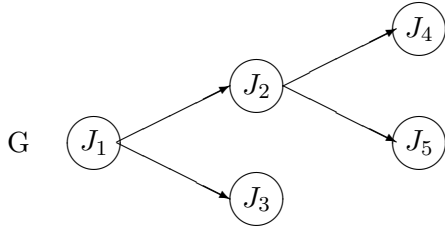


Figure 1 Series-parallel graph.

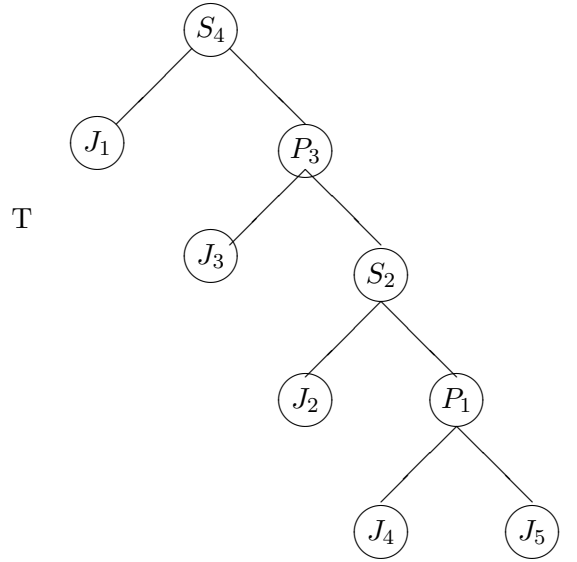


Figure 2. Decomposition tree.

**Definition 2 [17].** A non-empty subset  $M \subseteq N$  is a (job) module if, for each job  $J_j \in N - M$ , exactly one of the following three conditions holds:

- (a)  $J_j$  must precede every job in  $M$ ,
- (b)  $J_j$  must follow every job in  $M$ ,
- (c)  $J_j$  is not constrained with respect to any job in  $M$ .

**Definition 3 [17].** Let  $M$  be a module. A subset  $I \subseteq M$  is an initial set of  $M$ , if for each job  $J_j \in I$ , all the predecessors of  $J_j$  in  $M$  are also in  $I$ .

Suppose that  $\pi = [J_{\pi(1)}, J_{\pi(2)}, \dots, J_{\pi(n)}]$  is any schedule of  $N$  and  $U = \{J_{\pi(l)}, J_{\pi(l+1)}, \dots, J_{\pi(m)}\} \subset N$ , let

$$\rho(U, \pi) = \frac{\sum_{i=l}^m (1 + \alpha_{\pi(i)}) - 1}{\sum_{i=l}^m p_i \prod_{j=i+1}^m (1 + \alpha_{\pi(j)})}, \quad (1)$$

where  $\prod_{j=m+1}^m (1 + \alpha_{\pi(j)}) := 1$ .

Now, we define

$$\rho(U) = \sup_{\pi} \{\rho(U, \pi)\}, \quad (2)$$

the supremum being taken over all feasible schedules of  $N$ .

**Definition 4 [17].** Let  $M$  be a module. An initial set  $I$  of  $M$  is said to be  $\rho$ -maximal for  $G = (M, A)$  if  $\rho(I) \geq \rho(V)$  for any initial set  $V$  in  $M$ .

**Definition 5 [17].** Let  $M$  be a module. An initial set  $I^*$  of  $M$  is said to be  $\rho^*$ -maximal for  $G = (M, A)$  if

- (a)  $I^*$  is  $\rho$ -maximal for  $G$ ;
- (b) there is no proper subset  $V \subset M$  ( $V \neq I^*$ ) which is  $\rho$ -maximal for  $G$ .

Every module  $M$  admits at least one  $\rho$ -maximal initial set, possibly  $M$  itself.

**Lemma 1 [21]** For the problem  $1|p_j(t) = p_j + \alpha_j t|C_{\max}$ , if the sequence is  $\pi = [J_1, J_2, \dots, J_n]$  and the starting time of the first job is  $t_0 \geq 0$ , then the makespan is

$$C_{\max}(\pi) = \sum_{i=1}^n p_i \prod_{k=i+1}^n (1 + \alpha_k) + t_0 \prod_{k=1}^n (1 + \alpha_k),$$

where  $\prod_{k=n+1}^n (1 + \alpha_k) := 1$ .

For a given subschedule  $\pi = [J_1, J_2, \dots, J_m]$ , where  $\{J_1, J_2, \dots, J_m\}$  is any subset of  $N$ , let

$$\rho(\pi) = \rho([J_1, J_2, \dots, J_m]) = \frac{\sum_{i=1}^m (1 + \alpha_i) - 1}{\sum_{i=1}^m p_i \prod_{j=i+1}^m (1 + \alpha_j)}.$$

If job  $J_i$  must occur before job  $J_j$  in every feasible schedule, then we say that job  $J_i$  has precedence over job  $J_j$  and denote it by  $J_i \rightarrow J_j$ . For the problem  $1|chains, p_j + \alpha_j t|C_{\max}$ , we consider two chains of the jobs first. One chain, say  $L_1$ , consists of the jobs:

$$L_1 : J_1 \rightarrow J_2 \rightarrow \dots \rightarrow J_k,$$

and the other chain, say chain  $L_2$ , consists of the jobs:

$$L_2 : J_{k+1} \rightarrow J_{k+2} \rightarrow \dots \rightarrow J_n.$$

The next lemma is based on the assumption that if the scheduler decides to start processing jobs of one chain, he has to complete the entire chain before he is allowed to work on the jobs of the other chain.

**Lemma 2** [21] Consider two feasible schedules  $\alpha = [U, L_1, L_2, V]$  and  $\beta = [U, L_2, L_1, V]$ , where  $U$  and  $V$  are any subsequences.  $C_{\max}(\alpha) \leq C_{\max}(\beta)$  if and only if  $\rho(L_1) \geq \rho(L_2)$ .

**Proof.** Let the completion time of the last job in  $U$  be  $t$ . From Lemma 1, we have

$$C_{\max}([U, L_1, L_2]) = \sum_{i=k+1}^n p_i \prod_{l=i+1}^n (1 + \alpha_l) + \sum_{i=1}^k p_i \prod_{l=i+1}^k (1 + \alpha_l) \prod_{l=k+1}^n (1 + \alpha_l) + t \prod_{l=1}^n (1 + \alpha_l),$$

$$C_{\max}([U, L_2, L_1]) = \sum_{i=1}^k p_i \prod_{l=i+1}^k (1 + \alpha_l) + \sum_{i=k+1}^n p_i \prod_{l=i+1}^n (1 + \alpha_l) \prod_{l=1}^k (1 + \alpha_l) + t \prod_{l=1}^n (1 + \alpha_l).$$

$$C_{\max}(\alpha) \leq C_{\max}(\beta)$$

if and only if

$$C_{\max}([U, L_1, L_2]) \leq C_{\max}([U, L_2, L_1])$$

if and only if

$$\frac{\sum_{l=1}^k (1 + \alpha_l) - 1}{\sum_{i=1}^k p_i \prod_{l=i+1}^k (1 + \alpha_l)} \geq \frac{\sum_{l=k+1}^n (1 + \alpha_l) - 1}{\sum_{i=k+1}^n p_i \prod_{l=i+1}^n (1 + \alpha_l)},$$

i.e.,

$$\rho(L_1) \geq \rho(L_2).$$

This complete the proof. □

**Lemma 3** For any  $b > 0, d > 0$  and  $k \geq 0$ ,  $\frac{a}{b} > \frac{c}{d}$  if and only if  $\frac{a+kc}{b+kd} > \frac{c}{d}$ .

**Lemma 4** For any  $b > 0, d > 0$  and  $k > 0$ ,  $\frac{a}{b} > \frac{c}{d}$  if and only if  $\frac{a}{b} > \frac{kc+a}{kd+b}$ .

**Lemma 5** If  $J_1 \longrightarrow J_2 \longrightarrow \dots \longrightarrow J_u \longrightarrow J_{u+1} \longrightarrow \dots \longrightarrow J_{l^*}$  and

$$\rho([J_1, J_2, \dots, J_{l^*}]) > \rho([J_1, J_2, \dots, J_u]),$$

then, we can obtain

$$\rho([J_{u+1}, J_{u+2}, \dots, J_{l^*}]) > \rho([J_1, J_2, \dots, J_{l^*}]).$$

**Proof.** From  $\rho([J_1, J_2, \dots, J_{l^*}]) > \rho([J_1, J_2, \dots, J_u])$ , we have

$$\frac{\prod_{i=1}^{l^*} (1 + \alpha_i) - 1}{\sum_{j=1}^{l^*} p_j \prod_{i=j+1}^{l^*} (1 + \alpha_i)} > \frac{\prod_{i=1}^u (1 + \alpha_i) - 1}{\sum_{j=1}^u p_j \prod_{i=j+1}^u (1 + \alpha_i)}$$

$$\frac{(\prod_{i=1}^u (1 + \alpha_i) - 1) \prod_{i=u+1}^{l^*} (1 + \alpha_i) + \prod_{i=u+1}^{l^*} (1 + \alpha_i) - 1}{\sum_{j=1}^u p_j \prod_{i=j+1}^u (1 + \alpha_i) \prod_{i=u+1}^{l^*} (1 + \alpha_i) + \sum_{j=u+1}^{l^*} p_j \prod_{i=j+1}^{l^*} (1 + \alpha_i)} > \frac{\prod_{i=1}^u (1 + \alpha_i) - 1}{\sum_{j=1}^u p_j \prod_{i=j+1}^u (1 + \alpha_i)}$$

From Lemma 3, we have

$$\frac{\prod_{i=u+1}^{l^*} (1 + \alpha_i) - 1}{\sum_{j=u+1}^{l^*} p_j \prod_{i=j+1}^{l^*} (1 + \alpha_i)} > \frac{\prod_{i=1}^u (1 + \alpha_i) - 1}{\sum_{j=1}^u p_j \prod_{i=j+1}^u (1 + \alpha_i)}. \quad (3)$$

From (3) and Lemma 4, we have

$$\frac{\prod_{i=u+1}^{l^*} (1 + \alpha_i) - 1}{\sum_{j=u+1}^{l^*} p_j \prod_{i=j+1}^{l^*} (1 + \alpha_i)} > \frac{(\prod_{i=1}^u (1 + \alpha_i) - 1) \prod_{i=u+1}^{l^*} (1 + \alpha_i) + \prod_{i=u+1}^{l^*} (1 + \alpha_i) - 1}{\sum_{j=1}^u p_j \prod_{i=j+1}^u (1 + \alpha_i) \prod_{i=u+1}^{l^*} (1 + \alpha_i) + \sum_{j=u+1}^{l^*} p_j \prod_{i=j+1}^{l^*} (1 + \alpha_i)},$$

i.e.,

$$\rho([J_{u+1}, J_{u+2}, \dots, J_{l^*}]) > \rho([J_1, J_2, \dots, J_{l^*}]).$$

This completes the lemma.  $\square$

**Lemma 6** *If  $S = [J_1, J_2, \dots, J_u]$ ,  $I^* = [J_{u+1}, J_{u+2}, \dots, J_v]$ , and*

$$\rho(I^*) > \rho(S \cup I^*),$$

*then, we can obtain*

$$\rho(I^*) > \rho(S).$$

**Proof.** From  $\rho(I^*) > \rho(S \cup I^*)$ , we have

$$\frac{\prod_{i=u+1}^v (1 + \alpha_i) - 1}{\sum_{j=u+1}^v p_j \prod_{i=j+1}^v (1 + \alpha_i)} > \frac{\prod_{i=1}^v (1 + \alpha_i) - 1}{\sum_{j=1}^v p_j \prod_{i=j+1}^v (1 + \alpha_i)}$$

$$\frac{\prod_{i=u+1}^v (1 + \alpha_i) - 1}{\sum_{j=u+1}^v p_j \prod_{i=j+1}^v (1 + \alpha_i)} > \frac{(\prod_{i=1}^u (1 + \alpha_i) - 1) \prod_{i=u+1}^v (1 + \alpha_i) + \prod_{i=u+1}^v (1 + \alpha_i) - 1}{\sum_{j=1}^u p_j \prod_{i=j+1}^u (1 + \alpha_i) \prod_{i=u+1}^v (1 + \alpha_i) + \sum_{j=u+1}^v p_j \prod_{i=j+1}^v (1 + \alpha_i)}$$

From Lemma 4, we have

$$\frac{\prod_{i=u+1}^v (1 + \alpha_i) - 1}{\sum_{j=u+1}^v p_j \prod_{i=j+1}^v (1 + \alpha_i)} > \frac{\prod_{i=1}^u (1 + \alpha_i) - 1}{\sum_{j=1}^u p_j \prod_{i=j+1}^u (1 + \alpha_i)},$$

i.e.,

$$\rho(I^*) > \rho(S).$$

This completes the lemma.  $\square$

An important characteristic of chain  $L_1$  is defined as follows: Let  $l^*$  be the smallest integer satisfying

$$\rho^*(L_1) = \frac{\prod_{i=1}^{l^*} (1 + \alpha_i) - 1}{\sum_{j=1}^{l^*} p_j \prod_{i=j+1}^{l^*} (1 + \alpha_i)} = \max_{1 \leq s \leq k} \left\{ \frac{\prod_{i=1}^s (1 + \alpha_i) - 1}{\sum_{j=1}^s p_j \prod_{i=j+1}^s (1 + \alpha_i)} \right\}.$$

The ratio on the left-hand side is called the  $\rho^*$ -factor of chain  $L_1 : J_1 \rightarrow J_2 \rightarrow \dots \rightarrow J_k$ , which is denoted by  $\rho^*(L_1)$ . Job  $J_{l^*}$  is referred to as the job that determines the  $\rho^*$ -factor of the chain (Similar to the concept of  $\rho^*$ -factor of a chain in Pinedo [16], page 37). Suppose now that the chain can be interrupted by the jobs of other chains.

**Lemma 7** [21] *For the problem  $1|chains, p_j + \alpha_j t|C_{\max}$ , if job  $J_{l^*}$  determines  $\rho^*(L_1)$ , then there exists an optimal sequence that processes jobs  $J_1, J_2, \dots, J_{l^*}$  one after another without any interruption by the jobs of other chains.*

**Proof.** Similar to the proof of Pinedo [16] (page 37, Lemma 3.1.3). We assume that the theorem is false and show that such an assumption will lead to a contradiction. Here we assume that under the optimal sequence the processing of the subsequence  $J_1, J_2, \dots, J_{l^*}$  is interrupted by a job, say job  $J_v$ , from another chain. Let  $\pi = [J_1, J_2, \dots, J_u, J_v, J_{u+1}, \dots, J_{l^*}]$  be a subsequence of an optimal sequence. It is sufficient to show that either with subsequence  $\pi' = [J_v, J_1, J_2, \dots, J_{l^*}]$ , or with subsequence  $\pi'' = [J_1, J_2, \dots, J_{l^*}, J_v]$ , the makespan is less than that with subsequence  $\pi$ . If it is not less than that with the subsequence  $\pi'$ , then it has to be less than that with the subsequence  $\pi''$ , and vice versa. From Lemma 2, it follows that if the makespan of  $\pi$  is less than or equal to those with  $\pi'$  and  $\pi''$ , then

$$\frac{\prod_{i=1}^u (1 + \alpha_i) - 1}{\sum_{j=1}^u p_j \prod_{i=j+1}^u (1 + \alpha_i)} \geq \frac{\alpha_v}{p_v} \geq \frac{\prod_{i=u+1}^{l^*} (1 + \alpha_i) - 1}{\sum_{j=u+1}^{l^*} p_j \prod_{i=j+1}^{l^*} (1 + \alpha_i)}. \quad (4)$$

Since job  $J_{l^*}$  is the job that determines the  $\rho^*$ -factor of  $I^* : J_1, J_2, \dots, J_{l^*}$ , then

$$\frac{\prod_{i=1}^{l^*} (1 + \alpha_i) - 1}{\sum_{j=1}^{l^*} p_j \prod_{i=j+1}^{l^*} (1 + \alpha_i)} > \frac{\prod_{i=1}^u (1 + \alpha_i) - 1}{\sum_{j=1}^u p_j \prod_{i=j+1}^u (1 + \alpha_i)}. \quad (5)$$

From (5) and Lemma 5, we can obtain

$$\frac{\prod_{i=u+1}^{l^*} (1 + \alpha_i) - 1}{\sum_{j=u+1}^{l^*} p_j \prod_{i=j+1}^{l^*} (1 + \alpha_i)} > \frac{\prod_{i=1}^u (1 + \alpha_i) - 1}{\sum_{j=1}^u p_j \prod_{i=j+1}^u (1 + \alpha_i)}.$$

It is a contradiction to (4). The same argument can be applied if the interruption of the chain is caused by more than one job. We have proved the theorem.  $\square$

**Theorem 1** *Let  $M$  be a module of  $G = (N, A)$  and  $I^*$  be a  $\rho^*$ -maximal for  $(M, A)$ , then there exists an optimal schedule for  $N$  in which the jobs in  $I^*$  precede all the other jobs in  $M$ .*

**Proof.** In order to prove this theorem, let's consider the related network  $(M, A')$ , where  $A' = A - \{J_i \rightarrow J_j | J_i \in I^*, J_j \in M \setminus I^*\}$ . Obviously the set of feasible schedules for  $(M, A')$  contains the set of feasible schedules for  $(M, A)$ .



We assume that the theorem is false and show that such an assumption will lead to a contradiction. We assume that  $\pi = [S, I^*, T]$  is an optimal schedule for  $(M, A')$ , where  $S$  and  $T$  are disjoint subsets of  $M$  with  $S \cup T = M \setminus I^*$ . Then from Lemma 2, we have

$$\rho(S) \geq \rho(I^*) \geq \rho(T). \quad (6)$$

Obviously,  $S \cup I^*$  is initial in  $(M, A)$ , so from the  $I^*$  be a  $\rho^*$ -maximal, we have  $\rho(I^*) > \rho(S \cup I^*)$ . Then from Lemma 6, we have  $\rho(I^*) > \rho(S)$ . It is a contradiction to (6). This completes the proof.

□

**Theorem 2** *Let  $M$  be a module of  $G = (N, A)$  and  $I^*$  be a  $\rho^*$ -maximal, then  $I^*$  is a consecutive subschedule in every optimal schedule for  $G = (N, A)$ .*

**Proof.** It is the same as Lemma 7, except that: Here we assume that under the optimal sequence the processing of the subsequence  $I^* : J_1, J_2, \dots, J_{l^*}$  is interrupted by a job, say job  $J_v$ , from  $M \setminus I^*$ , and there is no precedence constraint between  $J_v$  and  $I^*$ . □

**Theorem 3** *Let  $M$  be a module of  $G = (N, A)$  and  $\sigma$  be an optimal schedule for  $M$ . Then there exists an optimal schedule for  $N$  that is consistent with  $\sigma$  (i.e., in which the jobs in  $M$  appear in the same order as in  $\sigma$ ).*

**Proof.** Similar to the proofs in Lawler [11] and Sidney [17]. □

Hence, from Theorems 1, 2 and 3, we can generalize the method of Lawler [11] and Brucker [5] to the problem  $1|sp - graph, p_j + \alpha_j t|C_{\max}$ .

To describe the algorithm in more details we need some notations. Let  $f$  be an internal node of the decomposition tree,  $M_f$  be the union of the two sets  $M_1$  and  $M_2$ . Similar to the algorithm of Lawler [11] and Brucker [5], we are going to proceed the algorithm from the bottom of the decomposition tree upward, finding an optimal sequence by using the series composition and parallel composition.

### Algorithm 1

1. WHILE there exists an internal node  $f$  with two leaves as sons Do
  - BEGIN
  2.  $J_i := \text{leftson}(f)$   $J_j := \text{rightson}(f)$ ;  $M_1 = \{J_i\}$ ,  $M_2 = \{J_j\}$ ;
  3. IF  $f$  has label  $P$  THEN
  4.  $M_f := M_1 \cup M_2$
  - Else

5.
  - 5.1 Find  $J_i \in M_1$  such that  $\rho(J_i) = \min\{\rho(J_k) | J_k \in M_1\}$  and  $J_j \in M_2$  such that  $\rho(J_j) = \max\{\rho(J_k) | J_k \in M_2\}$ . If  $\rho(J_i) > \rho(J_j)$ , let  $M_f = M_1 \cup M_2$  and halt. Otherwise, remove  $J_i$  from  $M_1$ ,  $J_j$  from  $M_2$  and form the composite  $J_k = (J_i, J_j)$ .
  - 5.2
    - 5.2.1 Find  $J_i \in M_1$  such that  $\rho(J_i) = \min\{\rho(J_k) | J_k \in M_1\}$ . If  $\rho(J_i) > \rho(J_k)$  ( $\rho(J_k)$  is computed by (1)), go to Step 5.3.1.
    - 5.2.2 Remove  $J_i$  from  $M_1$  and form the composite job  $J_k = (J_i, J_k)$ . Return to Step 5.2.1.
  - 5.3
    - 5.3.1 Find  $J_j \in M_2$  such that  $\rho(J_j) = \max\{\rho(J_k) | J_k \in M_2\}$ . If  $\rho(J_k) > \rho(J_j)$ , let  $M_f = M_1 \cup M_2 \cup \{J_k\}$  and halt.
    - 5.3.2 Remove  $J_j$  from  $M_2$  and form the composite job  $J_k = (J_k, J_j)$ . Go to Step 5.2.1.
6. Eliminate  $J_i$  and  $J_j$  and replace  $f$  by a leaf with label  $M_f$ .  
END {WHILE}
7. Construct  $\pi^*$  by concatenating all the subsequences of the single leaf in non-increasing order of  $\rho$ -values.

The following example illustrates the working of Algorithm 1.

**Example 1** Consider the problem with a precedence constraint given by graph  $G$  in Figure 1, and with normal processing times and deterioration rates as shown in Table 1.  $t_0 = 0$ .

Table 1. Values of  $p_j$  and  $\alpha_j$

jobs	$J_1$	$J_2$	$J_3$	$J_4$	$J_5$
$p_j$	3	4	7	2	5
$\alpha_j$	0.1	0.2	0.4	0.3	0.5

For  $P_1$ ,  $\rho(J_4) = 3/20 > \rho(J_5) = 1/10$ , hence  $P_1 : M_1 = \{J_4, J_5\}$ . For  $S_2$ ,  $\rho(J_2) = 1/20 < \rho(J_4) = 3/20$ , hence  $J_2$  and  $J_4$  form a composite job  $(J_2, J_4)$ ,  $\rho(J_2, J_4) = 14/165 < \rho(J_4) = 1/10$ , hence,  $S_2 : M_2 = \{(J_2, J_4), J_5\}$ . Similarly,  $P_3 : M_3 = \{(J_2, J_4), J_5, J_3\}$ ,  $S_4 : M_4 = \{(J_1, J_2, J_4, J_5), J_3\}$ . Hence, the optimal sequence is  $[J_1, J_2, J_4, J_5, J_3]$  and the optimal value of the makespan is 38.948.

## 4 Total weighted completion time problem

If  $\alpha_j = 0$ , the model  $p_j(t) = p_j + \alpha_j t$  is the classical model due to Lawler [11]; hence for arbitrary precedence constraints, the problem  $1|prec, p_j + \alpha_j t| \sum w_j C_j$  is NP-hard. In this section,

we consider a special case, namely  $p_j(t) = p_j(a + bt)$ .

Similar to Section 3, for the problem  $1|sp-graph, p_j(a + bt)| \sum w_j C_j$ , we can define the  $\rho$ -values as follows:

Suppose that  $\pi = [J_{\pi(1)}, J_{\pi(2)}, \dots, J_{\pi(n)}]$  is any schedule of  $N$  and  $U = \{J_{\pi(l)}, J_{\pi(l+1)}, \dots, J_{\pi(m)}\} \subset N$ , let

$$\rho(U, \pi) = \frac{\sum_{i=l}^m w_{\pi(i)} \prod_{j=l}^i (1 + bp_{\pi(j)})}{\prod_{j=l}^m (1 + bp_{\pi(j)}) - 1}. \quad (7)$$

Similar to Section 3, the problem  $1|sp-graph, p_j(a + bt)| \sum w_j C_j$  can be solved by Algorithm 1 with modified  $\rho$ -values given by (7).

The following example illustrates the working of the algorithm for the problem  $1|sp-graph, p_j(a + bt)| \sum w_j C_j$ .

**Example 2** Consider the problem with a precedence constraint given by graph  $G$  in Figure 1, and with normal processing times and weights as shown in Table 2.  $a = 1, b = 0.1, t_0 = 0$ .

Table 2. Values of  $p_j$  and  $w_j$

jobs	$J_1$	$J_2$	$J_3$	$J_4$	$J_5$
$p_j$	3	5	7	2	10
$w_j$	6	3	4	3	5

For  $P_1$ ,  $\rho(J_4) = 12 > \rho(J_5) = 10$ , hence  $P_1 : M_1 = \{J_4, J_5\}$ . For  $S_2$ ,  $\rho(J_2) = 9 < \rho(J_4) = 12$ , hence  $J_2$  and  $J_4$  form a composite job  $(J_2, J_4)$ ,  $\rho(J_2, J_4) = 99/8 > \rho(J_4) = 12$ , hence,  $S_2 : M_2 = \{(J_2, J_4), J_5\}$ . Similarly,  $P_3 : M_3 = \{(J_2, J_4), J_5, J_3\}$ ,  $S_4 : M_4 = \{J_1, (J_2, J_4), J_5, J_3\}$ . Hence, the optimal sequence is  $[J_1, J_2, J_4, J_5, J_3]$  and the optimal value of the total weighted completion time is 548.94.

## 5 Conclusions

In this paper we considered the problems of scheduling jobs with start-time increasing processing times (deterioration). The two objectives of the scheduling problems are to minimize the makespan and the total weighted completion time, respectively. Under the series-parallel graph precedence constraint assumption, the problems were proved to be polynomially solvable. In addition, we presented algorithms to solve these problems.

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