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Estimating Long-Term Time-Resolved Indoor PM_{2.5} of Outdoor and Indoor Origin using Easily-Obtainable Inputs

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Abstract

To evaluate the separate impacts on human health and establish effective control strategies, it is crucial to estimate the contribution of outdoor infiltration and indoor emission to indoor PM_{2.5} in buildings. This study used an algorithm to automatically estimate the long-term time-resolved indoor PM_{2.5} of outdoor and indoor origin in real apartments with natural ventilation. The inputs for the algorithm were only the time-resolved indoor/outdoor PM_{2.5} concentrations and occupants' window actions, which were easily obtained from the low-cost sensors. This study first applied the algorithm in an apartment in Tianjin, China. The indoor/outdoor contribution to the gross indoor exposure and time-resolved infiltration factor were automatically estimated using the algorithm. The influence of outdoor PM_{2.5} data source and algorithm parameters on the estimated results was analyzed. The algorithm was then applied in four other apartments located in Chongqing, Shenyang, Xi'an, and Urumqi to further demonstrate its feasibility. The results provided indirect evidence, such as the plausible explanations for seasonal and spatial variation, to partially support the success of the algorithm used in real apartments. Through the analysis, this study also identified several further development directions to facilitate the practical applications of the algorithm, such as robust long-term outdoor PM_{2.5} monitoring using low-cost light-scattering sensors.

1 **Practical Implications**

2 To establish effective control strategies, it is important to estimate the contribution of outdoor
3 infiltration and indoor emission to indoor PM_{2.5} in buildings. This study demonstrated an
4 algorithm for estimating long-term time-resolved indoor PM_{2.5} of outdoor and indoor origin in
5 real naturally ventilated apartments with only the time-resolved indoor/outdoor PM_{2.5}
6 concentrations and window behaviors. The proposed algorithm can be applied to automatically
7 estimate the indoor/outdoor contribution to the gross indoor exposure and time-resolved PM_{2.5}
8 infiltration factors in naturally ventilated buildings.

9

10 **Keywords:** indoor PM_{2.5} exposure, indoor emission, real building monitoring, I/O ratio, year-
11 round distribution, natural ventilation

12

13 **Running Title:** Estimate PM of Outdoor and Indoor Origin

1. Introduction

Exposure to particulate air pollution poses one of the greatest risks to human health around the world.¹ In recent decades, PM_{2.5} (particulate matter with a diameter less than 2.5 µm) has been proven to have a strong association with various diseases, on the basis of a large amount of epidemiological data.²⁻⁴ Given that people spend a significant fraction of their time in indoor environments,⁵ it is essential to reduce indoor exposure to PM_{2.5}. Many studies have used the outdoor PM_{2.5} concentration as an indicator to estimate the indoor exposure to PM_{2.5}.^{6,7} However, even when indoor PM_{2.5} originates outdoors, the concentration of outdoor PM_{2.5} is not a suitable indicator, because building-specific parameters such as air tightness and window-opening behavior would also influence the exposure.^{8,9} Moreover, the existence of indoor PM_{2.5} emissions, such as those from cooking¹⁰ and smoking¹¹, would further differentiate ambient PM_{2.5} and indoor PM_{2.5}.¹² Therefore, it is crucial to estimate the contribution of outdoor infiltration and indoor emissions to indoor PM_{2.5} for evaluating the separate risk effects on human health.

Furthermore, to effectively reduce indoor PM_{2.5}, it is necessary to differentiate indoor PM_{2.5} of outdoor and indoor origin. For example, in naturally ventilated buildings, opening windows is the most effective approach to diluting the indoor-emitted PM_{2.5}.^{13,14} If indoor PM_{2.5} emissions are detectable, occupants can open windows accordingly to accelerate the dilution. However, when the outdoor air is heavily polluted, the occupants should close the windows to reduce the infiltrated outdoor PM_{2.5}. In order to optimize the window-opening behavior for reducing indoor PM_{2.5}, it is important to differentiate the indoor PM_{2.5} of outdoor and indoor origin.

With the rapid development of low-cost light-scattering PM_{2.5} sensors, it is now straightforward to monitor time-resolved outdoor and indoor PM_{2.5} concentrations. However, for differentiation of indoor PM_{2.5} of outdoor and indoor origin, the infiltration factor, defined as the fraction of outdoor particles that penetrate indoors and remain suspended¹², must be determined. Numerous studies have measured the infiltration factor. For instance, Meng et al.¹⁵ measured time-series concentrations of outdoor and indoor PM_{2.5} and estimated the overall infiltration factor by least-trimmed squared regression. However, the real-time infiltration factor cannot be obtained by this method. Measuring outdoor and indoor sulfur concentrations is another approach to obtaining the infiltration factor, as sulfur sources are rarely found indoors.¹⁶⁻¹⁹ Unfortunately, instruments for low-cost, real-time sulfur measurement are not available on the market. Thus, direct measurement of the real-time infiltration factor is extremely challenging.

To avoid the need to directly measure the infiltration factor in real time, researchers have developed various methods for estimating the indoor PM_{2.5} of outdoor and indoor origin from the time-resolved concentrations of outdoor and indoor PM_{2.5}. For instance, Allen et al.²⁰ defined indoor emission of PM_{2.5} when the trend in outdoor PM_{2.5} concentration was not in line with the rapid increase in indoor PM_{2.5}. Chan et al.²¹ quantified the indoor PM_{2.5} emissions in

1 18 apartments in California using time-resolved monitoring data. In both studies, identification
2 of the indoor emissions required manual adjustments with visual observation of the data. To
3 circumvent the manual procedure, our previous study proposed an algorithm that automatically
4 differentiates the indoor PM_{2.5} of outdoor and indoor origin using time-resolved indoor-to-
5 outdoor PM_{2.5} concentration ratio and window status.²² The method was validated in a small-
6 scale chamber in a laboratory with a low relative error of 0.32%.

7
8 Although the accuracy of that developed differentiation method was satisfactory in the
9 laboratory setup, its performance in real buildings is still unclear. Real situations can be much
10 more complex than a well-controlled small-scale chamber experiment. First, the long-term
11 measurement of outdoor PM_{2.5} concentrations with low-cost portable PM_{2.5} sensors can be
12 obstructed by bad weather and an unstable power supply. To overcome these challenges, one
13 could instead use official data on outdoor PM_{2.5} concentrations from governmental monitoring
14 stations.²³ However, it is unclear whether the official data could be employed in the
15 differentiation method and yield reasonable results. Second, a real apartment always consists
16 of multiple rooms, such as a living room, bedroom, kitchen, and bathroom. The PM_{2.5}
17 concentrations in one room may be influenced by the adjacent rooms.²⁴ It is unclear whether
18 the differentiation method is feasible for an apartment with multiple rooms. Third, our previous
19 study used burning incense to simulate indoor particle emissions.²² However, actual indoor
20 PM_{2.5} emissions can be generated by many indoor activities such as cooking,¹⁰ smoking,¹¹
21 emission from the human body,²⁵ lint cleaning,²⁶ and walking-induced resuspension.²⁷ It is
22 unknown whether the developed method can accurately detect indoor emission of PM_{2.5} with
23 different emission strengths and durations. Therefore, to facilitate practical applications, it is
24 worthwhile to assess the performance of the method in differentiating indoor PM_{2.5} of outdoor
25 and indoor origin in real buildings.

26
27 This study aimed to differentiate the indoor PM_{2.5} of outdoor and indoor origin in real
28 apartments with natural ventilation to demonstrate the robustness of the differentiation method
29 proposed in our previous study.²² Three inputs, the time-resolved concentrations of outdoor
30 PM_{2.5} and indoor PM_{2.5} and window/door status, were monitored for a one-year period in 2017.
31 The concentrations of indoor and outdoor PM_{2.5} were monitored by a low-cost light-scattering
32 PM_{2.5} sensor, while official data from the national monitoring station near the target building
33 were also obtained as alternative for the concentrations of outdoor PM_{2.5}. The occupants'
34 window and door action was also monitored using low-cost sensors. Based on the
35 differentiation method, the time-resolved indoor PM_{2.5} of outdoor and indoor origin and their
36 contributions to the total indoor exposure were estimated. The time-resolved infiltration factors
37 were also obtained.

2. Methods and materials

2.1. Original data

This study first focused on a naturally ventilated apartment located in Tianjin, China. The apartment was on the 16th floor of an 18-floor residential building. The indoor and outdoor PM_{2.5} concentrations were recorded in the living room and the neighborhood, respectively, from January to December of 2017 using two low-cost light-scattering sensors with a time resolution of 1 min. In addition, the window/door-opening/closing actions were monitored with window/door sensors. The details of the monitoring setup can be found in a previous study.²³ However, it was found that a significant amount of data were missing from the outdoor low-cost PM_{2.5} sensor due to bad weather and unstable power supply. Therefore, as an alternative, the outdoor PM_{2.5} concentrations with a time resolution of 2 h were also obtained from the nearest official monitoring station, Binshui West Road station, operated by the China National Environmental Monitoring Center.

2.2. Data pre-processing

2.2.1. Indoor PM_{2.5}

The low-cost light-scattering sensor for indoor PM_{2.5} monitoring was first calibrated by a standard gravimetric instrument under a controlled environment. Since previous studies found that an increase in relative humidity can result in an increase in PM_{2.5} concentration as measured by a light-scattering sensor,^{28–30} the indoor PM_{2.5} concentrations were further calibrated by:²³

$$C_{modified} = \frac{C_{measured}}{F_m} \quad (1)$$

where $C_{measured}$ and $C_{modified}$ are the measured and calibrated indoor PM_{2.5} concentrations ($\mu\text{g}/\text{m}^3$), respectively. Here F_m is the calibration factor:²³

$$F_m = \begin{cases} 1, & RH < 50\% \\ 8.35 \cdot RH^2 - 7.72 \cdot RH + 2.8, & RH \geq 50\% \end{cases} \quad (2)$$

where RH is the relative humidity (%). The details of the sensor calibration can be found in the previous study.²³

Note that the original indoor PM_{2.5} data were recorded once every minute. However, our previous study found that a time step size smaller than 10 minutes would result in significant errors in the differentiation algorithm.²² Therefore, after the calibration, the concentrations of indoor PM_{2.5} were averaged every 10 minutes, so that the time step size was in line with that

of the differentiation algorithm. The sensitivity analysis about the time step size will be discussed in Section 3.4. In general, the low-cost sensor used indoors was stable. Over 94% of the indoor PM_{2.5} data were successfully recorded throughout the year.

2.2.2. Outdoor PM_{2.5}

The low-cost light-scattering sensor for outdoor PM_{2.5} monitoring was calibrated using the same approach as the indoor sensor. The concentrations of outdoor PM_{2.5} were also averaged every 10 minutes. Note that, due to the relatively harsh environment, around 60% of the outdoor PM_{2.5} data from the low-cost sensor were missing. Only were the data in February to April relatively complete for the analysis. As an alternative, this study also obtained the outdoor PM_{2.5} data recorded once every two hours from the official monitoring station. To comply with the differentiation algorithm, linear interpolation was used to convert the official monitoring outdoor PM_{2.5} data to that with a time step size of 10 minutes. To provide a comprehensive analysis, this study first used both outdoor PM_{2.5} data from the low-cost sensor and the official monitoring station to estimate the indoor PM_{2.5} of outdoor and indoor origin in February to April, and discussed the differences. We then used the outdoor PM_{2.5} data from the official monitoring station to calculate the year-round indoor PM_{2.5} of outdoor and indoor origin as a full demonstration of the proposed algorithm.

2.2.3. Effective window behavior

There are three windows and a door in the living room of the apartment with the window/door sensors installed. Since the windows in the corridor of the building are usually open, the PM_{2.5} concentration in the corridor was close to that in the neighborhood. Therefore, the door was also considered as an exterior window in this study, and the term “window” in this paper refers to both the windows and the door. According to the window-behavior sensor, window-opening or -closing actions occurred 3.8 times per day on average in the living room, considering both the door and the window. Note that, in some cases, a short-interval window action occurred, less than 10 minutes after the previous action. Since the time step size for the differentiation algorithm was set at 10 minutes, this study counted as effective window behavior only those opening/closing actions with a time interval longer than 10 minutes from the previous and subsequent actions. We considered a window-opening angle larger than 15° as “open window” status, because an opening angle smaller than 15° would introduce less than 30% of the airflow that occurs when the window is fully open.^{14,31}

2.2.4. Other considerations in data pre-processing

Note that the differentiation algorithm applies to naturally ventilated buildings without air cleaners.²² Therefore, any time periods with mechanical ventilation or air cleaners turned on were removed. Furthermore, this study applied the differentiation algorithm to each day individually. However, after removal of the inapplicable data, the time-series data became discontinuous on some days. Although the differentiation algorithm could still be applied to

each short period, the results would be unsatisfactory for periods shorter than four hours.²² Therefore, this study removed the data that were recorded in any period shorter than four hours. Furthermore, if the results from the differentiation algorithm indicated that indoor PM_{2.5} emissions occurred continuously throughout a whole day, there was no way to estimate the indoor PM_{2.5} of outdoor and indoor origin,²² thus, such days were also removed. With these considerations, there were 40 days with valid input data for the analysis using the outdoor PM_{2.5} data measured by the low-cost sensor in February to April. For the year-round estimation using the official monitoring outdoor PM_{2.5} data, there were 275 days with valid inputs in this study.

2.3. Differentiation algorithm

After the data pre-processing, the three inputs, concentrations of outdoor PM_{2.5} and indoor PM_{2.5} and window action, were used with the differentiation algorithm to estimate indoor PM_{2.5} of outdoor and indoor origin. This sub-section briefly describes the differentiation algorithm developed in our previous study.²²

2.3.1 Step 1. Obtain indoor-to-outdoor PM_{2.5} ratio

To consider the change in concentrations of outdoor and indoor PM_{2.5} simultaneously, this study utilized the indoor-to-outdoor ratio time-resolved PM_{2.5} concentration (I/O ratio), IO(t), to start the differentiation method:

$$IO(t) = \frac{C_{in}(t)}{C_{out}(t)} \quad (3)$$

where C_{in}(t) and C_{out}(t) (µg/m³) are the averaged indoor and outdoor PM_{2.5} concentrations, respectively, in the tth time step. The size of time step was set at 10 minutes.²²

2.3.2 Step 2. Process change-point analysis

Normally, indoor PM_{2.5} emissions can affect indoor PM_{2.5} concentrations. The method of change-point analysis was used to detect significant changes in the time-series I/O ratios statistically.³² The method also provided the confidence level for each change point. The details of the change-point analysis method can be found in Xia and Chen.²² Note that except for indoor emission of PM_{2.5}, window actions and fluctuations in infiltration rate can make a difference in the time-series I/O ratios and result in the change points as well.²² Therefore, this step was taken mainly to identify candidates for change points due to indoor PM_{2.5} emissions.

2.3.3 Step 3. Handle time periods no window status change

For the periods without window actions, significant increases in the I/O ratio were ascribed to either the indoor emission of PM_{2.5} or the change of infiltration rate. To differentiate these two

scenarios, three criteria were employed. First, when the I/O ratio was greater than 1, the period must have had an indoor emission of PM_{2.5}. Second, if the outlier was more than 1.5 interquartile over the third quartile in the I/O ratio, the period was considered to contain an indoor emission.

Third, a detected change might arise from either a sudden increase in infiltration rate or an indoor PM_{2.5} emission. Sudden increase in infiltration rate would increase the indoor concentration smoothly, while an indoor emission would increase the concentration with relatively strong fluctuations.²² In a large-scale simulation, Shi et al.⁹ obtained the infiltration rate distribution in Beijing residences with a 15th percentile of 0.09 h⁻¹ and an 85th percentile of 0.32 h⁻¹. Considering a relatively extreme case in which the infiltration rate suddenly increased from 0.09 to 0.32 h⁻¹, the infiltration factor would increase by 0.22 (from 0.40 to 0.62), assuming the penetration factor and deposition rate to be 0.8 and 0.09 h⁻¹, respectively⁸. Namely, if a detected change is caused by a sudden increase in infiltration rate, it is unlikely that the I/O ratio would increase by 0.22. Therefore, when the difference between the maximum and minimum values of the I/O ratio in the period was over an empirical threshold of 0.22, the period was regarded as containing an indoor PM_{2.5} emission.

2.3.4 Step 4. Handle time periods having window status change

For the periods with window behavior, the I/O ratio would follow an exponential regression deducted from the mass balance equation without indoor particle emission:¹²

$$IO(t) = c_1 + c_2 \cdot e^{-c_3(t-t_0)} \quad (4)$$

where c_1 (unitless), c_2 (unitless), and c_3 (h⁻¹) are constants as a function of the air exchange rate, PM_{2.5} deposition rate and penetration factor. If the time-series I/O ratio fitted very well with Eq. (4), it is likely that there was no indoor source. Therefore, the R² value of the regression was used to determine the existence of indoor emission of PM_{2.5}. If the data fitting yielded a satisfactory R² value above 0.8, an empirical value according to Xia and Chen,²² then the period was regarded as free of indoor-generated PM_{2.5}. Otherwise, there existed indoor emission of PM_{2.5}.

2.3.5 Step 5. Estimate the indoor PM_{2.5} of outdoor and indoor origin

For the periods without indoor PM_{2.5} emissions, the infiltration factor, F_{in} , was equal to the I/O ratio. For the periods with indoor PM_{2.5} emissions, the infiltration factor was estimated with the use of Eq. (4), as demonstrated by Xia and Chen.²² The indoor PM_{2.5} of outdoor origin, $C_{in,out}$, in the periods with indoor PM_{2.5} emissions was then calculated by:

$$C_{in,out}(t) = F_{in}(t) \cdot C_{out}(t) \quad (5)$$

The indoor PM_{2.5} of indoor origin, $C_{in,in}$, can be expressed as:

$$C_{in,in}(t) = C_{in}(t) - C_{in,out}(t) \quad (6)$$

To compare the contributions of outdoor infiltrated PM_{2.5} and indoor emitted PM_{2.5}, we calculated the ratio of indoor exposure to PM_{2.5} of outdoor and indoor origin, respectively, to the gross indoor exposure for each day, denoted as the “indoor contribution” and “outdoor contribution”, respectively, as follows:

$$\frac{E_{in,in}}{E_{in}} = \frac{\int_{t_{start,d}}^{t_{end,d}} C_{in,in}(t) dt}{\int_{t_{start,d}}^{t_{end,d}} C_{in}(t) dt} \quad (7)$$

$$\frac{E_{in,out}}{E_{in}} = \frac{\int_{t_{start,d}}^{t_{end,d}} C_{in,out}(t) dt}{\int_{t_{start,d}}^{t_{end,d}} C_{in}(t) dt} \quad (8)$$

where $E_{in,out}$ and $E_{in,in}$ (($\mu\text{g} \cdot 10\text{min}$)/ m^3) are the daily indoor exposure to PM_{2.5} of outdoor and indoor origin, respectively, and E_{in} (($\mu\text{g} \cdot 10\text{min}$)/ m^3) is the daily gross indoor exposure to PM_{2.5}. The start time, $t_{start,d}$, and end time, $t_{end,d}$, of the daily gross indoor exposure are the start and end of an effective day. Here it was assumed that the occupant stayed indoors all the time. For different occupancy schedules, the corresponding exposures can be calculated accordingly based on the estimated concentrations of indoor PM_{2.5} of outdoor and indoor origin.

Note that the indoor PM_{2.5} sensor was placed in the living room. The indoor PM_{2.5} emissions that occurred in other rooms, e.g., the kitchen and bedroom, may have contributed to the PM_{2.5} concentration in the living room. In the differentiation algorithm, although the non-living-room PM_{2.5} emissions were also detected, the estimated emission strength was equivalent to the portion that actually influenced the living room. In other words, these PM_{2.5} emissions were also regarded as indoor sources that were located in the living room.

3. Results and discussion

3.1. Examples of estimated indoor PM_{2.5} of outdoor and indoor origin

Figure 1 illustrates the estimated time-resolved concentrations of indoor PM_{2.5} of outdoor and indoor origin and the infiltration factor on Feb 21, Feb 14, and Mar 19. The inputs, outdoor and indoor PM_{2.5} concentrations, are also shown in the figure. The area under the estimated indoor

1 PM_{2.5} of outdoor origin line (in orange) represents the daily indoor exposure to PM_{2.5} of outdoor
2 origin ($E_{in,out}$). The area under the indoor PM_{2.5} line (in green) represents the daily gross indoor
3 exposure to PM_{2.5} (E_{in}). The total area of the four purple shaded zones represents the daily
4 indoor exposure to PM_{2.5} of indoor origin ($E_{in,in}$). Eqs. (7) and (8) were used to calculate the
5 daily indoor and outdoor contribution to the total indoor exposure, respectively. On Feb 21,
6 four indoor emission events were detected with the differentiation algorithm, as shown in
7 Figure 1(a). The latter three detected PM_{2.5} emissions were likely attributed to cooking
8 considering the normal time periods for preparing breakfast, lunch, and dinner. In this
9 apartment, the occupants often prepare late-night snacks. Therefore, the first emission might
10 be from a late-night cooking activity. Based on the algorithm, the daily indoor and outdoor
11 contribution was 32.5% and 67.5%, respectively. However, it should be noted that the first
12 detected emission was weak, which might be a misclassification. If this weak emission was not
13 considered as a real emission, the daily indoor and outdoor contribution would be altered by
14 only 1.7%. Namely, the detected small emission did not alter the results of indoor/outdoor
15 contribution in a major way. By characterizing the indoor PM_{2.5} emission, the differentiation
16 algorithm can then calculate the time-resolved infiltration factor ($F_{in}(t)$). As shown in Figure
17 1(a), the real-time infiltration factor fluctuated in a wide range from 0.16 to 0.51. The daily
18 averaged infiltration factor was 0.34 ± 0.09 . Similar results can be found on Feb 14, as shown
19 in Figure 1(b). The indoor emission events were also likely from cooking activities for late-
20 night snack, breakfast, lunch, and dinner. After breakfast and lunch, there might be cleaning or
21 other activities leading to emissions. The estimated daily indoor and outdoor contribution was
22 19.1% and 80.9%, respectively, and the averaged infiltration factor was 0.23 ± 0.08 . On Mar 19,
23 the algorithm only detected one indoor emission event, which was likely from preparing the
24 lunch. Since Mar 19 was a weekend, the occupants might get up late and skip the breakfast,
25 and have their dinner in a restaurant. The estimated daily indoor and outdoor contribution was
26 3.0% and 97.0%, respectively, and the averaged infiltration factor was 0.45 ± 0.11 . The plausible
27 explanation for the detected indoor emissions in these examples can partially support the
28 feasibility of the algorithm.

29

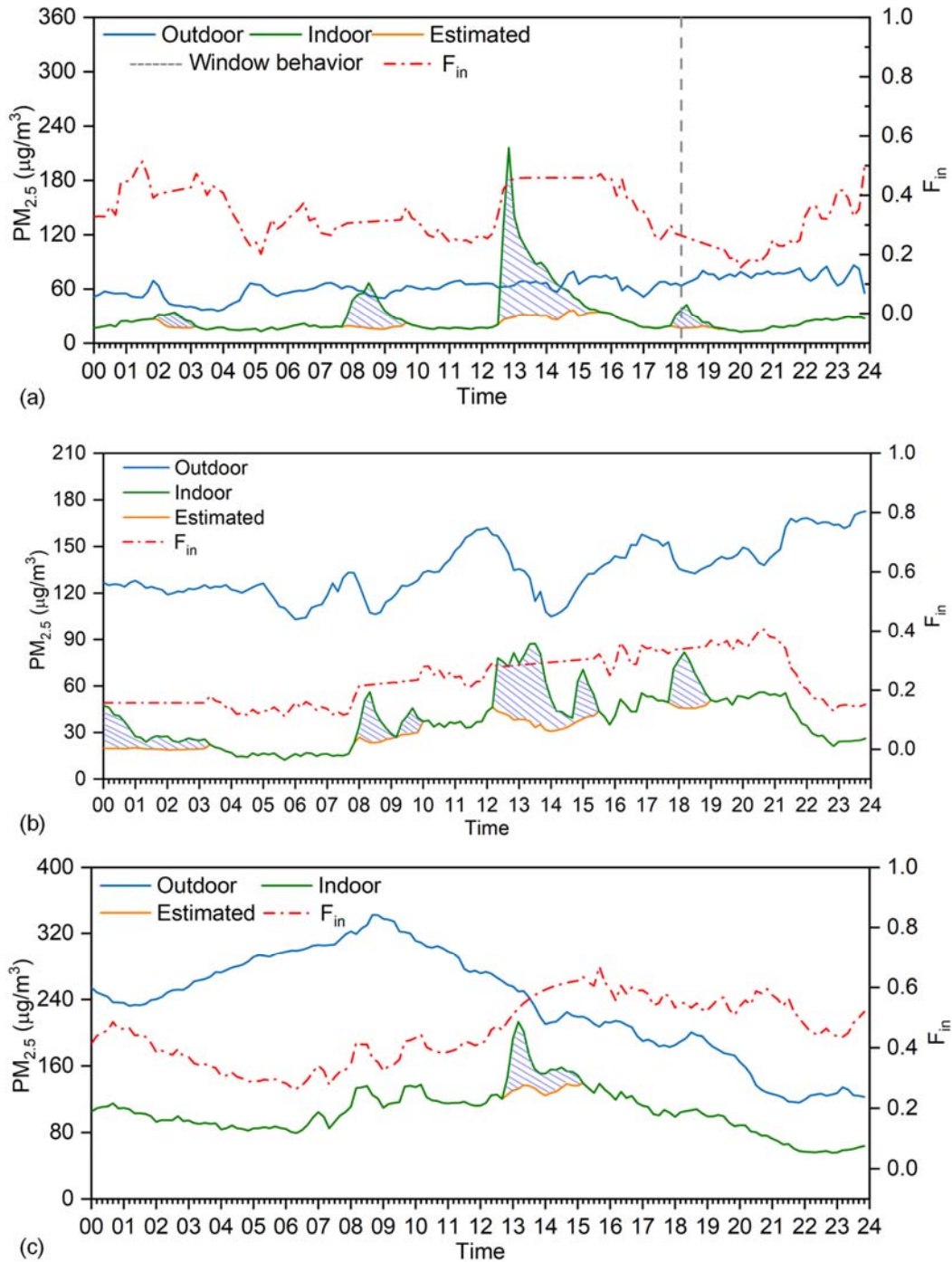


Figure 1. Estimated concentrations of indoor PM_{2.5} of outdoor and indoor origin and infiltration factor on (a) Feb 21, (b) Feb 14, and (c) Mar 19 using the differentiation algorithm. (The purple shading represents indoor exposure to PM_{2.5} of indoor origin.)

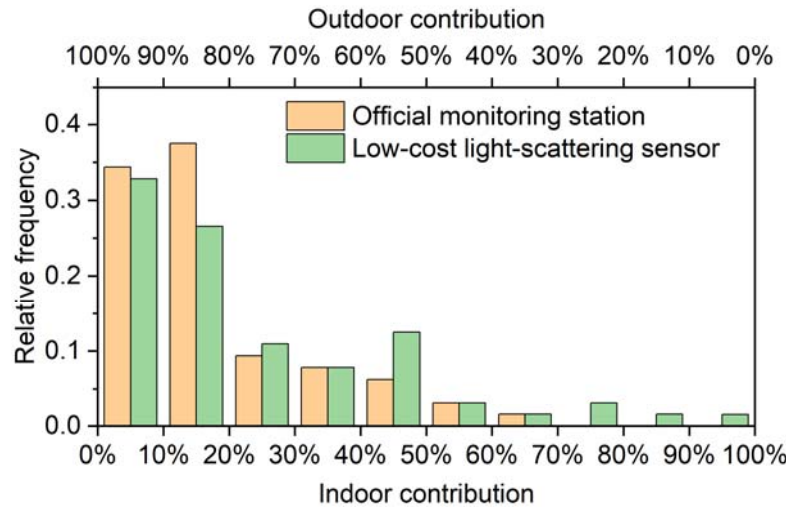
Although the algorithm could effectively estimate indoor PM_{2.5} of outdoor and indoor origin in most case, it encountered some challenges under certain scenarios. Figure S1 shows the estimated indoor PM_{2.5} of outdoor and indoor origin and infiltration factor on Feb 10. From the

observation, the outdoor PM_{2.5} concentration was lower than 7 µg/m³ throughout the day, and there was a strong indoor emission during the dinner time. Although the algorithm successfully detected the strong emission started at 17:30, it also classified the other time periods as with indoor emissions. This was because both indoor and outdoor PM_{2.5} concentrations were very low, and the low-cost light-scattering sensors could have significant measurement uncertainties at low concentrations. Consequently, the I/O ratios fluctuated in a wide range and were often greater than 1. Therefore, there were a lot of misclassifications of the small indoor emissions. However, considering these potential misclassifications only led to 4.5% difference in the daily indoor/outdoor contribution, the algorithm may be still acceptable when estimating the indoor/outdoor contribution with low concentration. Figure S2 shows the estimated indoor PM_{2.5} of outdoor and indoor origin and infiltration factor on Feb 03. The results indicated continuous indoor emissions from 01:00 to 14:40 since the I/O ratios were all greater than 1 in this period. During the night, the emissions might be from continuous burning incense, while the emissions in the daytime might be from cooking and other activities. With long continuous indoor emissions, the time periods without indoor emissions were relatively short in a day. Consequently, the data available for the regression of Eq. (4) in *Step 5* were few and the results might not be reliable. Therefore, the long continuous indoor emissions could lead to the challenge in correctly estimating the infiltration factor.

3.2. Comparison of results based on outdoor low-cost sensor and official monitoring station

As discussed in Section 2.2.2., due to bad weather and unstable power supply, the outdoor PM_{2.5} data from the low-cost light-scattering sensor were only available in February to April. The alternative was the outdoor PM_{2.5} data recorded from the nearest official monitoring station. The mean ± standard deviation of the outdoor PM_{2.5} data measured by the light-scattering sensor in February to April (68.9 ± 71.4 µg/m³) was close to that measured by the official monitoring station (69.4 ± 60.7 µg/m³). As shown in Figure S3, the probabilistic distribution of the outdoor PM_{2.5} concentration by the light-scattering sensor was reasonably correlated with that by the official monitoring station. However, the outdoor PM_{2.5} data tended to be under-reported by the light-scattering sensor when the concentration was low. This study first compared the results based on the 1-min outdoor low-cost sensor and 2-h official monitoring station in February to April. Both datasets were averaged or interpolated to a 10-min resolution. Figure 2 compares the probabilistic distribution of the daily indoor/outdoor contribution estimated based on the two outdoor PM_{2.5} datasets. The general distributions were similar, but discrepancies can also be observed. It was estimated that, on average, the indoor PM_{2.5} emissions and outdoor PM_{2.5} infiltration contributed 23.2% and 76.8% of the daily total indoor exposure, respectively, if the outdoor PM_{2.5} data from the low-cost sensor were used. When using the data from the official monitoring station, the average indoor and outdoor contribution was estimated to be 17.8% and 82.2%, respectively. Interestingly, the indoor contribution over 70% only occurred when the low-cost light-scattering sensor was used and the outdoor PM_{2.5} concentrations were low. As shown in Figure S3, the outdoor PM_{2.5} concentrations at the low level tended to be under-reported by the light-scattering sensor, which would result in a higher

1 indoor contribution. The under-reported outdoor $PM_{2.5}$ concentration by the low-cost light-
 2 scattering sensor could be another possible reason for the long continuous indoor emission
 3 identified in Figure S2. In conclusion, the proposed algorithm can effectively differentiate
 4 indoor $PM_{2.5}$ of outdoor and indoor origin and estimate their contributions to the total indoor
 5 exposure. However, the average results of daily indoor/outdoor contributions estimated based
 6 on the two outdoor $PM_{2.5}$ datasets had an around 5% difference.



7
 8 Figure 2. Comparison of the probabilistic distribution of the daily indoor/outdoor contribution
 9 estimated based on the outdoor $PM_{2.5}$ data from the low-cost sensor and official monitoring
 10 station in February to April, 2017.

11
 12 Figure 3 compares the probabilistic distribution of the time-resolved infiltration factor
 13 estimated based on the outdoor $PM_{2.5}$ data from the low-cost sensor and official monitoring
 14 station in February to April. Again, the general distributions were similar, but discrepancies
 15 can be observed. The average infiltration factor estimated using the outdoor $PM_{2.5}$ data from
 16 the low-cost sensor was 0.46, which was equal to that estimated based on the official
 17 monitoring data, 0.46. Therefore, the proposed algorithm can effectively calculate the time-
 18 resolved infiltration factor using only the inputs of time-series indoor/outdoor $PM_{2.5}$
 19 concentrations and window behavior. Furthermore, the average infiltration factors obtained
 20 from the two outdoor $PM_{2.5}$ datasets were similar, but discrepancies can be observed in terms
 21 of the probabilistic distribution.

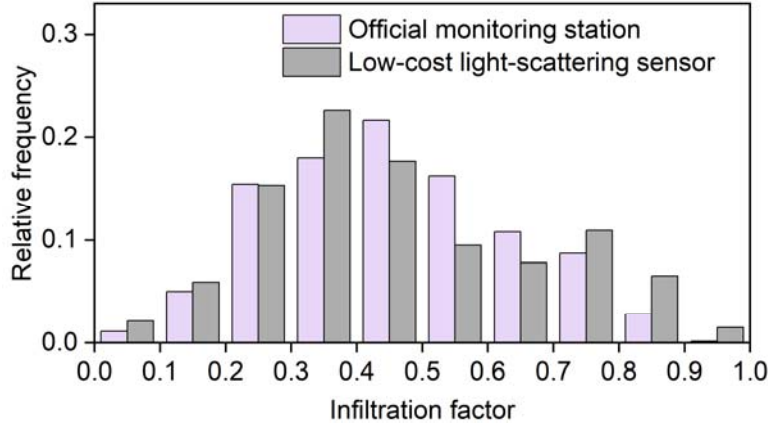


Figure 3. Comparison of the probabilistic distribution of the time-resolved PM_{2.5} infiltration factor estimated based on the outdoor PM_{2.5} data from the low-cost sensor and official monitoring station in February to April, 2017.

Theoretically, using the same light-scattering sensors with careful calibration for both indoor and outdoor PM_{2.5} monitoring would yield more accurate results than using the official monitoring outdoor data. This is because, first, the light-scattering sensor can effectively capture the peak outdoor PM_{2.5} concentration with a 10-min time step size as set for the algorithm, but the official monitoring data with a 2-h sampling interval cannot. Second, monitoring indoor and outdoor PM_{2.5} using the same light-scattering sensors would make the indoor/outdoor data more comparable as the sensors were the same and went through the same calibration. Third, sometimes the nearest official monitoring station may still be far away from the target building, which would result in inaccurate input of outdoor PM_{2.5}. Therefore, from the theoretical perspective, we would recommend to use the same low-cost light-scattering sensors with careful calibration for both indoor and outdoor PM_{2.5} monitoring.

However, using the low-cost light-scattering sensor to monitor long-term outdoor PM_{2.5} in a neighborhood is practically challenging for general customer use. Several problems were identified in the monitoring of this study. First, the current low-cost light-scattering sensors available on the market suffers from severe data loss due to bad weather, unstable power supply, or even accidental damage. The general users, such as the participants in this study, would not spend time on regular maintenance for the outdoor sensor. Furthermore, most of them do not have the technical skills to fix a light-scattering sensor. Second, the outdoor sensor should be placed somewhere in the neighborhood which is a public area. Thus, the outdoor monitoring requires the permission from the neighborhood committee, which would become impractical if a lot of residents request a public area for outdoor monitoring. Therefore, from the practical perspective, we would recommend to use the outdoor PM_{2.5} data from the nearest official monitoring station as the input for the algorithm if the year-around results are to be obtained.

1 In the future, efforts should be made in the following aspects to facilitate the practical
2 application of the proposed algorithm by using low-cost light-scattering sensor for outdoor
3 PM_{2.5} monitoring. First, the sensors should be further developed for robust and stable long-
4 term measurements in relatively harsh environments. Currently, there are some well-designed
5 PM_{2.5} monitors specifically for outdoor monitoring available on the market. However, the cost
6 would be too high for general customer use. Low-cost solutions would significantly facilitate
7 the practical applications. Second, the neighborhood-based outdoor PM_{2.5} monitoring should
8 be conducted by the neighborhood property manager and the data should be shared in real-time
9 with all the residents in the neighborhood. This would require both technical development in
10 terms of data sharing and policy development in terms of neighborhood-based air quality
11 monitoring.

13 **3.3. Year-round results**

14 Based on the discussion above, this study then used the outdoor PM_{2.5} data from the official
15 monitoring station to calculate the year-round indoor PM_{2.5} of outdoor and indoor origin as a
16 full demonstration of the proposed algorithm. Furthermore, the seasonal characteristics were
17 analyzed in addition to the year-round results. Division of the time into four seasons was based
18 on the five-day moving average temperature according to the definition of climatic season in
19 Chinese national standard QX/T 152-2012.³⁴ According to this standard, in 2017, spring in
20 Tianjin was from March 16 to May 10, summer from May 11 to October 2, autumn from
21 October 3 to November 11, and winter from January 1 to March 15 and November 12 to
22 December 31.

24 *3.3.1. Daily indoor/outdoor contribution for the whole year*

25 Figure 4 displays the year-round distribution of the daily indoor/outdoor contribution for the
26 275 days, with a wide range from 0 to 94.2%. On average, the indoor PM_{2.5} emissions and
27 outdoor PM_{2.5} infiltration contributed 26.3% and 73.7% of the daily total indoor exposure,
28 respectively. In other words, for most of the time, the outdoor PM_{2.5} infiltration contributed to
29 the indoor PM_{2.5} more than the indoor emission did. The results demonstrated that the proposed
30 algorithm can automatically differentiate indoor PM_{2.5} of indoor and outdoor origin and
31 estimate their contributions to the total indoor exposure, even for a whole year. The automated
32 estimation of indoor and outdoor contributions would support the large-scale exposure and
33 health risk assessment as well as the development of effective strategies for controlling indoor
34 particulate air pollution.

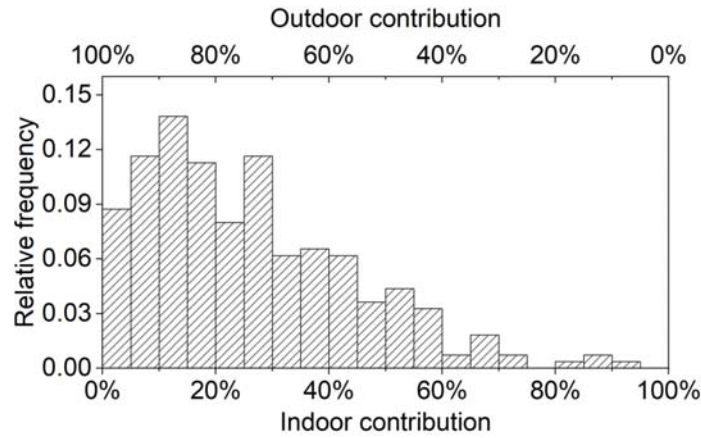


Figure 4. Year-round probabilistic distribution of the daily indoor/outdoor contribution to total indoor exposure in 2017.

Based on the season division for Tianjin in 2017, the probabilistic distributions of the daily indoor/outdoor contributions for the four seasons are shown in Figure S4. It is apparent that these contributions were distributed differently from season to season. The most frequent daily indoor contribution fell in the 10–15% range in spring, the 25–30% range in summer and autumn, and the 15–20% range in winter. Figure 5 shows the box plots of the seasonally-averaged indoor contributions. The lowest seasonally-averaged indoor contribution was in spring ($19.5\% \pm 16.9\%$). Summer ($30.4\% \pm 19.1\%$) and autumn ($30.8\% \pm 17.1\%$) had comparable seasonally-averaged indoor contributions, which were higher than spring and winter. This is partially because the outdoor $PM_{2.5}$ concentration was higher in winter and spring (heating season) than in summer and autumn. Consequently, the relative contribution of indoor $PM_{2.5}$ emissions to the gross exposure was lower in winter and spring than in summer and autumn. The plausible explanation for the differences in the seasonal indoor contribution can partially support the feasibility of the algorithm.

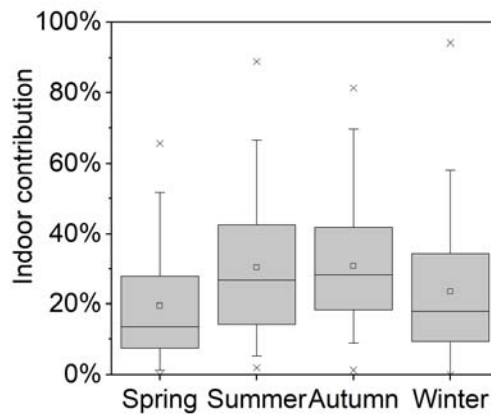


Figure 5. Box plots of seasonally-averaged indoor contributions to the total indoor exposure in 2017. (The top and bottom lines of each box present the 75th and 25th percentiles. Within the box, the square hollow dot is the mean value and the line is the median value. The whiskers go to the 5th and 95th percentiles. The crosses represent the maximum and minimum.)

3.3.2. Infiltration factor for the whole year

Figure 6 shows the year-round probabilistic distribution of the time-resolved $\text{PM}_{2.5}$ infiltration factor with a mean value \pm standard deviation of 0.56 ± 0.22 . The median value was 0.55. The results were comparable to the annual-averaged infiltration factor for residences in Beijing, 0.48 ± 0.07 .⁹ The year-round infiltration factor showed a great span ranging from 0.001 to 0.993 in the same apartment. The great variation in the infiltration factor was attributed to the window behavior, outdoor wind speed, etc. Note that measuring time-resolved infiltration factor in a real building with indoor $\text{PM}_{2.5}$ sources is very challenging using the existing methods in the literature.¹² However, with the approach proposed in this study, the real-time $\text{PM}_{2.5}$ infiltration factors can be obtained by using only the concentrations of outdoor $\text{PM}_{2.5}$ and indoor $\text{PM}_{2.5}$ and window actions.

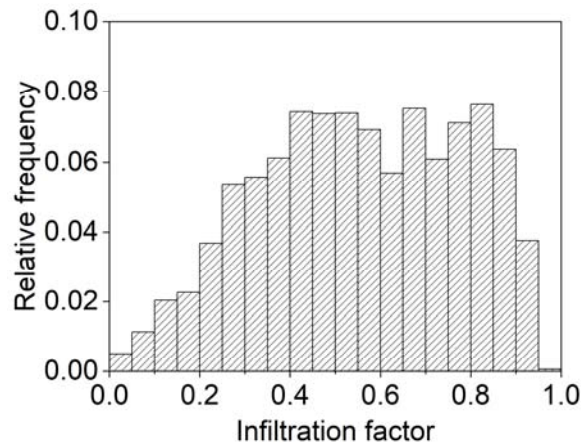


Figure 6. Year-round probabilistic distribution of the time-resolved $\text{PM}_{2.5}$ infiltration factor in 2017.

Figures S5 and 7 shows the seasonal probabilistic distributions and the boxplots for the time-resolved $\text{PM}_{2.5}$ infiltration factors, respectively. The patterns were different from the seasons. Autumn had the highest seasonal-averaged infiltration factor (0.71 ± 0.17) with the negative skewed distribution. This is because the residents tend to open windows frequently in autumn to introduce more fresh air. Since the $\text{PM}_{2.5}$ infiltration factor is positively correlated with the air exchange rate, the infiltration factor in autumn was greater than that in other seasons. The seasonal-averaged infiltration factor in winter was the lowest (0.47 ± 0.22) with the positive skewed distribution. Tianjin is located in the cold climate zone where residents tend to close windows for a long time in winter to keep warm. The seasonally-averaged infiltration factor in summer was 0.61 ± 0.21 , which was lower than that in autumn. This is because the residents tend to turn on air conditioners in summer with a high outdoor temperature. Consequently, the windows were closed, and thus the air exchange rate decreased. Again, the plausible explanation for the differences in the seasonal infiltration factor can also partially support the feasibility of the algorithm.

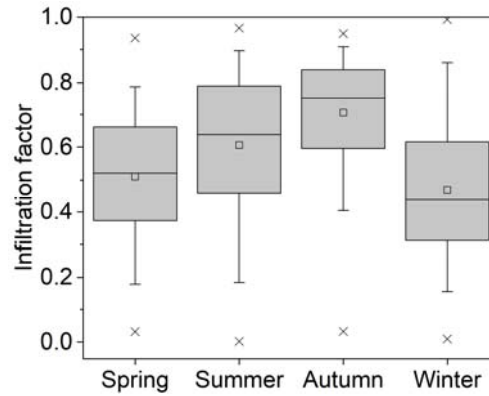


Figure 7. Box plots of the time-resolved PM_{2.5} infiltration factor in the spring, summer, autumn, and winter of 2017. (In each box, the top and bottom lines are the 75th and 25th percentiles. Within the box, the square hollow dot is the mean value and the solid line is the median value. The whiskers go to the 5th and 95th percentiles. The crosses represent the maximum and minimum.)

3.4. Sensitivity analysis

The sensitivity analysis in this study was to test how the empirically determined setting parameters, i.e., time step size, infiltration factor range (in *Step 3*), and R^2 value (in *Step 4*), would alter the results of indoor/outdoor contribution and infiltration factor based on the outdoor low-cost sensor data shown in Section 3.2.

3.4.1. Time step size

In general, a smaller time step size would result in greater uncertainties due to data fluctuation, while a larger time step size would result in greater error in quantifying indoor emission. The validation using the ground truth data in the laboratory tests in our previous study²² indicated that the time step size of 10 min yielded the best estimation of the indoor/outdoor contribution. This study further tested how the time step size of 2, 5, 10, 15, and 20 min affected the results in the Tianjin apartment. As shown in Figure S6, the average daily indoor contribution increased with the time step size, while the infiltration factor decreased. The change point analysis in Step 2 may generate more change points with a smaller time step size due to data fluctuation. If a real indoor emission was divided into several time periods by the additional change points, the algorithm might misclassify these short time periods as without emission. Consequently, the average daily indoor contribution would be underestimated, while the infiltration factor would be overestimated. On the other hand, a larger time step size might result in the overestimation of indoor contribution when calculating the integral in the numerator of Eq. (7). As a result, the average daily indoor contribution would be overestimated, while the infiltration factor would be underestimated. When the time step size ranged from 5 to 15 min, the average daily indoor contribution in the range of 21.3% to 24.1% with an absolute difference of 2.8%, and the average infiltration factor was in the range of 0.47 to 0.50 with an absolute difference of 3%. Therefore, if an uncertainty of 5% in indoor/outdoor contribution is acceptable, the time step size can be set between 5 to 15 min. Furthermore, the

time step size between 5 to 15 min is also suitable considering the light-scattering PM_{2.5} sensor performance and typical indoor emission duration²².

3.4.2. Infiltration factor range threshold

The infiltration factor range threshold of 0.22 in Step 3 was determined according to the reasonable inputs from the literature. The validation using the ground truth data in the laboratory tests²² also indicated that the threshold of 0.22 yielded the best estimation of the indoor/outdoor contribution. This study tested how the threshold of 0.15, 0.19, 0.22, 0.28, and 0.35 affected the results in the Tianjin apartment in February to April. These values corresponded to the 75th/25th, 80th/20th, 85th/15th, 90th/10th, and 95th/5th percentiles of the upper/lower limits of the infiltration rate, respectively⁹. A larger infiltration factor range threshold resulted in a lower the indoor contribution and a higher infiltration factor. As shown in Figure S7, when the infiltration factor range threshold ranged from 0.15 to 0.35, the average daily indoor contribution was in the range of 21.7% to 24.8% with an absolute difference of 3.1%, and the average infiltration factor was in the range of 0.47 to 0.48 with an absolute difference of only 0.01. Therefore, the results were insensitive to the infiltration factor range threshold between 0.15 and 0.35.

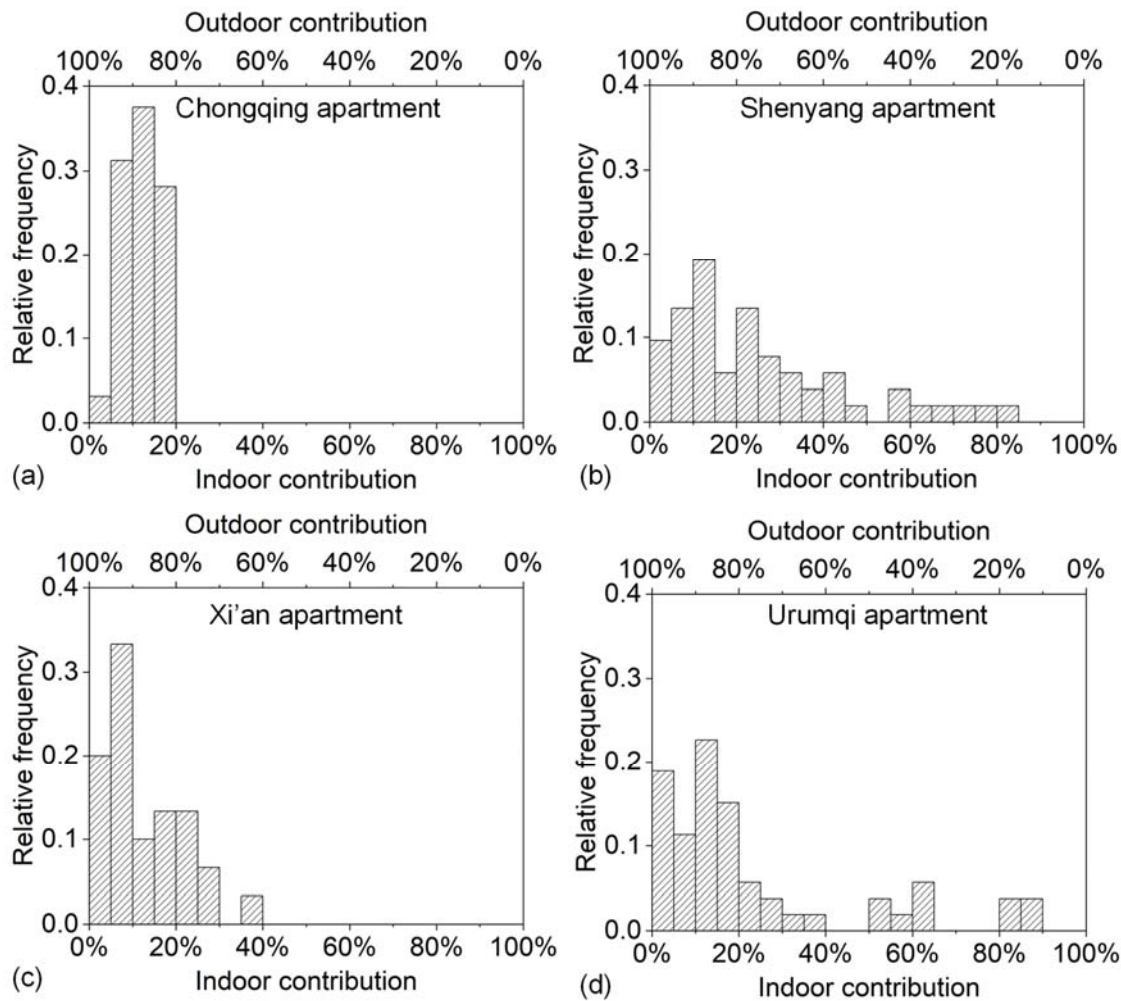
3.4.3. R² value

The algorithm used an R² value of 0.8 in the data regression analysis in Step 4 for identifying whether there was PM_{2.5} emission in a period with a window-opening action. Again, the validation using the ground truth data in the laboratory tests²² also indicated that the R² value of 0.8 yielded the best estimation of the indoor/outdoor contribution. This study tested how the R² value of 0.65, 0.7, 0.8, 0.9, and 0.95 affected the results in the Tianjin apartment in February to April. As shown in Figure S8, when the R² value range threshold ranged from 0.65 to 0.95, both the average daily indoor contribution and the average infiltration factor almost remain unchanged. Therefore, the results were insensitive to the R² value in the range of 0.65 to 0.95.

3.5. Demonstration of the algorithm in more apartments

To further demonstrate the feasibility of the algorithm, this study also estimated the indoor PM_{2.5} of indoor and outdoor origin in four more apartments located in Chongqing, Shenyang, Xi'an, and Urumqi. The indoor/outdoor PM_{2.5} concentrations were monitored in March and April, 2017 using the same low-cost light-scattering sensors. The window behaviors were also recorded using the low-cost window sensors. Using the proposed method, the indoor PM_{2.5} of indoor and outdoor origin and their contributions to the total indoor exposure were automatically estimated. The time-resolved infiltration factors were also obtained for the four apartments. The results of the indoor/outdoor contributions and infiltration factors are shown in Figures 8 and 9, respectively. With different climates, occupants' behaviors, and building characteristics, the results in the four apartments were quite different. Interestingly, the average indoor contribution in the Chongqing apartment was 12.0%, significantly lower than that in the Shenyang and Urumqi apartments (26.0% and 23.2%, respectively). Furthermore, the average

1 infiltration factor in the Chongqing apartment was 0.85, significantly greater than that in the
2 Shenyang and Urumqi apartments (0.71 and 0.62, respectively). This was mainly because the
3 occupants in the Chongqing apartment opened the windows for much longer time (74% of time)
4 than those in the Shenyang and Urumqi apartments (46% and 37% of time), as Chongqing
5 (typically 13 to 25 °C) was much warmer than Shenyang (typically -4 to 16 °C) and Urumqi
6 (typically -2 to 18 °C) in March and April. For the Xi'an apartment, the window opening time
7 was very long (93% of time) under the relatively mild weather (typically 6 to 24 °C). However,
8 since the average infiltration factor in the Xi'an apartment was not high (0.63), the natural
9 ventilation rate tended to be low probably due to the window was open only for a small area.
10 The plausible explanation for the comparison results can also partially support the feasibility
11 of the algorithm.



12
13 Figure 8. Probabilistic distribution of the daily indoor/outdoor contribution estimated in the
14 four apartments located in (a) Chongqing, (b) Shenyang, (c) Xi'an, and (d) Urumqi in March
15 and April, 2017.

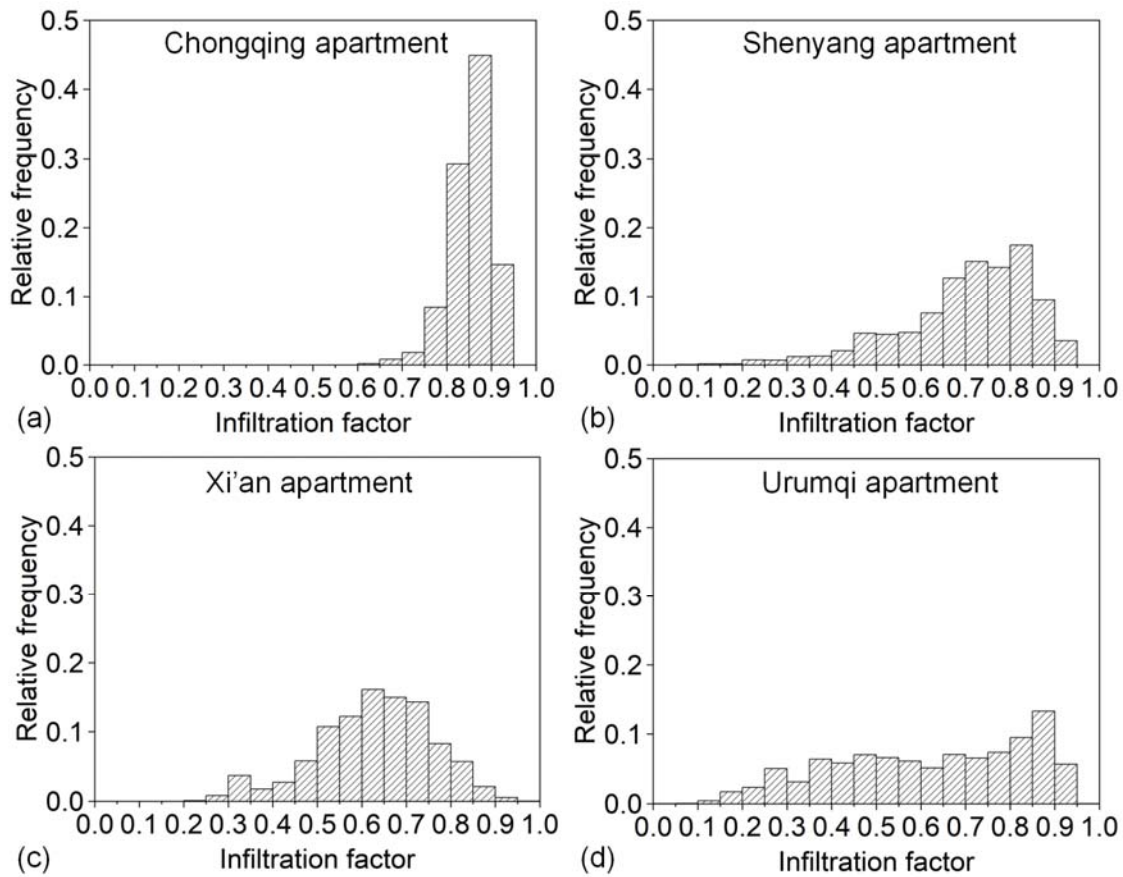


Figure 9. Probabilistic distribution of the time-resolved $PM_{2.5}$ infiltration factor in the four apartments located in (a) Chongqing, (b) Shenyang, (c) Xi'an and (d) Urumqi in Mar and Apr 2017.

4. Limitations and prospects

Several limitations exist in this study. First, this study could not provide direct evidence to prove the accuracy of the differentiation algorithm due to the lack of ground truth data about indoor $PM_{2.5}$ emissions in the real apartment. It is impractical to request the participants to record the indoor $PM_{2.5}$ emission events and measure the air exchange rates throughout the year. Therefore, in addition to the validation using the ground truth data in the laboratory tests in our previous study,²² this study only provided indirect evidence, such as the plausible explanations for seasonal and spatial variation, to partially demonstrate the feasibility of using the algorithm in real apartments. Second, theoretically the algorithm cannot differentiate whether a detected indoor emission did occur in the apartment or was contributed from the adjacent apartments through the corridor. In this study, since the windows in the corridor are usually open in the building, the contribution from the adjacent apartments might be limited. To identify which apartment is really emitting $PM_{2.5}$, the indoor concentrations in the adjacent apartments need to be monitored as well, and an improved algorithm should be developed. Third, this study assumed that the indoor air in the living room was well mixed. In future monitoring, a

representative measuring location should be identified through the testing of several points in the room.

This study focused on the differentiation of indoor PM_{2.5} of outdoor and indoor origin in buildings with natural ventilation. When the contribution of indoor PM_{2.5} emissions to the gross exposure is large, the windows should be opened; otherwise, the windows should remain closed. A follow-up step would be to integrate the differentiation algorithm into a smart home system to automatically operate the windows and thus minimize the indoor PM_{2.5} levels. Furthermore, as mentioned in Section 2, when estimating the total exposures, this study assumed that the occupant stayed indoors all the time, which may not be applicable for other cases. In future applications, the occupancy should be monitored and integrated into the system to better estimate and reduce the exposures. However, although natural ventilation can dilute indoor PM_{2.5} emissions, the entry of outdoor PM_{2.5} into indoor environments cannot be avoided, especially on highly polluted days. Indoor air quality can be improved through the use of air cleaners equipped with high-efficiency filters,³⁶ and it would be worthwhile to develop an improved differentiation algorithm for dealing with more complex situations. In addition, as discussed in Section 3.2, low-cost light-scattering PM_{2.5} sensor should be further developed for robust and stable long-term measurements in relatively harsh outdoor environments, which would facilitate the practical application of the proposed algorithm.

5. Conclusions

This study used an indoor/outdoor PM_{2.5} differentiation algorithm in real residential apartments to automatically estimate the long-term time-resolved indoor PM_{2.5} of outdoor and indoor origin. The inputs for the differentiation algorithm were only the concentration values of outdoor and indoor PM_{2.5} and occupants' window actions, which were easily obtained from the low-cost sensors. The indoor/outdoor contribution to the gross indoor exposure and the time-resolved infiltration factor were calculated using the algorithm. Within the scope of this study, the following conclusions can be made:

1. The proposed algorithm can automatically estimate the long-term time-resolved indoor PM_{2.5} of outdoor and indoor origin in naturally ventilated buildings using only the inputs of time-resolved indoor/outdoor PM_{2.5} concentrations and window behavior.
2. The indoor/outdoor contribution to the gross indoor exposure and time-resolved infiltration factor can also be automatically estimated using the algorithm.
3. The results provided indirect evidence, such as the plausible explanations for seasonal and spatial variation, to partially demonstrate the feasibility of using the algorithm in real apartments.
4. This study identified several directions for further development, such as robust long-term outdoor PM_{2.5} monitoring using low-cost light-scattering sensors, which would facilitate the practical applications of the algorithm.

Conflict of Interest Statement

None.

Author Contributions

Tongling Xia: Conceptualization (lead), Methodology (lead), Investigation (lead), Writing - original draft (lead), Writing - review & editing (supporting). **Qi Yue:** Data curation (equal), Investigation (supporting). **Xilei Dai:** Data curation (equal), Investigation (supporting). **Jiuyu Liu:** Data curation (Supporting). **Can Xiao:** Data curation (Supporting) **Ruoyu You:** Methodology (supporting), Writing - review & editing (supporting). **Dayi Lai:** Methodology (supporting), Writing - review & editing (supporting). **Junjie Liu:** Conceptualization (supporting), Supervision (lead), Writing - review & editing (supporting). **Chun Chen:** Conceptualization (lead), Supervision (lead), Writing - review & editing (lead), Funding acquisition(lead).

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